Deep Learning Using Bayesian Optimization as Hyperparameter Tuning

This exercise shows how to apply Bayesian optimization to deep learning and find optimal network hyperparameters and training options for convolutional neural networks.

Choose Variables to Optimize

Choose which variables to optimize using Bayesian optimization, and specify the ranges to search in. Also, specify whether the variables are integers and whether to search the interval in logarithmic space. Optimize the following variables:

```
optimVars = [
   optimizableVariable('SectionDepth',[1 3],'Type','integer')
   optimizableVariable('InitialLearnRate',[1e-2 1],'Transform','log')
   optimizableVariable('Momentum',[0.8 0.98])];
%optimizableVariable('L2Regularization',[1e-10 1e-2],'Transform','log')];
```

Perform Bayesian Optimization

Create the objective function for the Bayesian optimizer, using the training and validation data as inputs. The objective function trains a convolutional neural network and returns the classification error on the validation set. This function is defined at the end of this script. Because bayesopt uses the error rate on the validation set to choose the best model, it is possible that the final network overfits on the validation set. The final chosen model is then tested on the independent test set to estimate the generalization error. Data is from the previous exercise.

```
ObjFcn = makeObjFcn(xTrain,xTest,label_Train,label_Test);
```

Perform Bayesian optimization by minimizing the classification error on the validation set.

```
BayesObject = bayesopt(ObjFcn,optimVars, ...
'MaxTime',14*60, ...
'IsObjectiveDeterministic',false, ...
'UseParallel',false);
```

- 1	======						=======================================		
	Iter	Eval result	Objective 	Objective runtime	BestSoFar (observed)	BestSoFar (estim.)	SectionDepth 	InitialLearn- Rate	Momentur
i	1	Best	0.15348	13.161	0.15348	0.15348	3	0.058902	0.8591
İ	2	Accept	0.16949	21.636	0.15348	0.1547	3	0.015911	0.96962
	3	Accept	0.22316	14.053	0.15348	0.15712	1	0.027601	0.8293
	4	Best	0.14972	12.642	0.14972	0.14973	1	0.043581	0.96663
	5	Best	0.14595	10.555	0.14595	0.14595	2	0.045768	0.9625
	6	Accept	0.28531	10.621	0.14595	0.14595	2	0.21711	0.96098
	7 '	Accept	0.14783	10.508	0.14595	0.14595	2	0.010001	0.94697
	8	Accept	0.43503	10.854	0.14595	0.14613	2	0.9911	0.9404
	9	Best	0.11488	11.103	0.11488	0.11493	2	0.070365	0.9780
	10	Accept	0.19774	11.03	0.11488	0.15207	2	0.078393	0.9799
	11	Accept	0.21751	10.758	0.11488	0.16732	2	0.046533	0.9799
	12	Accept	0.17891	10.857	0.11488	0.16692	2	0.010065	0.95963

	14	Accept	0.12994	10.972	0.10829	0.14655	2	0.010001	0.9612
	15	Accept	0.27119	10.633	0.10829	0.14547	2	0.44695	0.94809
	16	Accept	0.23164	10.907	0.10829	0.14496	2	0.31323	0.9436
	17	Accept	0.14124	11.562	0.10829	0.1431	2	0.012423	0.9548
	18	Accept	0.20245	12.938	0.10829	0.15456	2	0.66652	0.94929
	19	Accept	0.12712	18.281	0.10829	0.15531	2	0.12381	0.9684
ļ	20	Best	0.078154	18.422	0.078154	0.11001	2	0.11076	0.8066
===	====						======================================		========
It	er	Eval	Objective	Objective	BestSoFar	BestSoFar	SectionDepth	InitialLearn-	Momentur
ļ		result		runtime	(observed)	(estim.)		Rate	
===	====						=========		========
	21	Accept	0.16573	11.75	0.078154	0.1325] 2	0.10911	0.9402
	22	Accept	0.14313	11.83	0.078154	0.11824	2	0.11837	0.9476
	23	Accept	0.078154	14.917	0.078154	0.090146	3	0.12348	0.8017
	24	Accept	0.20621	8.9339	0.078154	0.1407	1	0.12117	0.8007
	25	Accept	0.15819	9.1411	0.078154	0.11081	1	0.16192	0.8007
	26	Accept	0.17514	12.703	0.078154	0.14519	3	0.12109	0.85919
	27	Accept	0.2194	8.243	0.078154	0.14296	1	0.034236	0.8025
	28	Accept	0.28154	8.9059	0.078154	0.1435	1	0.020841	0.8025
	29	Accept	0.15725	8.4708	0.078154	0.14405	1	0.099437	0.8033
	30	Accept	0.18267	8.8419	0.078154	0.13705	1	0.545	0.8028

0.10829 |

0.15252

0.010052 |

0.950

Optimization completed.

13 | Best |

MaxObjectiveEvaluations of 30 reached.

Total function evaluations: 30

Total elapsed time: 364.5757 seconds

Total objective function evaluation time: 356.2276

0.10829

10.997

Best observed feasible point:

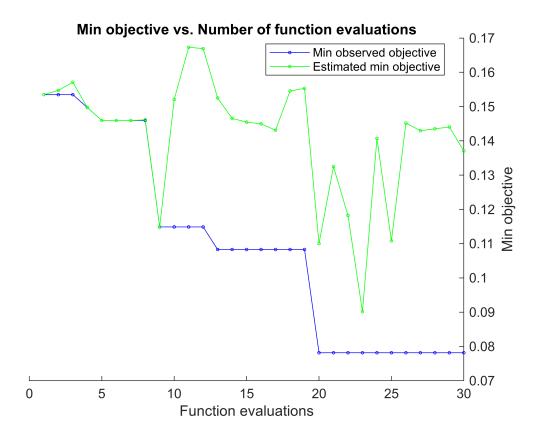
SectionDepth	InitialLearnRate	Momentum	
2	0.11076	0.80662	

Observed objective function value = 0.078154 Estimated objective function value = 0.13705 Function evaluation time = 18.422

Best estimated feasible point (according to models):

SectionDepth	InitialLearnRate	Momentum
2	0.11076	0.80662

Estimated objective function value = 0.13705 Estimated function evaluation time = 18.1864



Evaluate Final Network

Load the best network found in the optimization and its validation accuracy.

```
bestIdx = BayesObject.IndexOfMinimumTrace(end);
fileName = BayesObject.UserDataTrace{bestIdx};
savedStruct = load(fileName);
valError = savedStruct.valError

valError = 0.0782

scoresTest = minibatchpredict(savedStruct.trainedNet,xTest);
YPredicted = onehotdecode(scoresTest,classNames,2);
accuracy = mean(YPredicted == label_Test)

accuracy = 0.9218
```

Export best selection to ONNX

```
exportONNXNetwork(savedStruct.trainedNet, "hpo_1.onnx");
```

Objective Function for Optimization

Define the objective function for optimization.

```
function ObjFcn = makeObjFcn(XTrain,YTrain,XValidation,YValidation)
ObjFcn = @valErrorFun;
    function [valError,cons,fileName] = valErrorFun(optVars)
        imageSize = [8 8 1];
        numClasses = numel(unique(YValidation));
        classnames = unique(YValidation);
        numF = round(16/sqrt(optVars.SectionDepth));
        layers = [
            imageInputLayer(imageSize)
            % The spatial input and output sizes of these convolutional
            % layers are 8-by-8, and the following max pooling layer
            % reduces this to 4-by-4.
            convBlock(3,numF,optVars.SectionDepth)
            maxPooling2dLayer(1, 'Stride', 2, 'Padding', 'same')
            % The spatial input and output sizes of these convolutional
            % layers are 16-by-16, and the following max pooling layer
            % reduces this to 8-by-8.
            convBlock(3,2*numF,optVars.SectionDepth)
            maxPooling2dLayer(1, 'Stride', 2, 'Padding', 'same')
            % The spatial input and output sizes of these convolutional
            % layers are 8-by-8. The global average pooling layer averages
            % over the 8-by-8 inputs, giving an output of size
            % 1-by-1-by-4*initialNumFilters. With a global average
            % pooling layer, the final classification output is only
            % sensitive to the total amount of each feature present in the
            % input image, but insensitive to the spatial positions of the
            % features.
            convBlock(3,4*numF,optVars.SectionDepth)
            averagePooling2dLayer(2)
            % Add the fully connected layer and the final softmax and
            % classification layers.
            fullyConnectedLayer(numClasses)
            softmaxLayer];
        options = trainingOptions("sgdm", ...
            ExecutionEnvironment="cpu", ...
            InitialLearnRate = optVars.InitialLearnRate, ...
            Momentum = optVars.Momentum, ...
            ValidationData={YTrain, YValidation}, ...
            MaxEpochs = 10, ...
            LearnRateSchedule='piecewise', ...
            LearnRateDropPeriod = 40, ...
            LearnRateDropFactor = 0.1, ...
            Verbose=false);
```

```
imageAugmenter = imageDataAugmenter('RandRotation',[-90,90]);
        datasource =
augmentedImageDatastore(imageSize,XTrain,XValidation,'DataAugmentation',imageAugment
er);
       trainedNet = trainnet(datasource, layers, "crossentropy", options);
        close(findall(groot, 'Tag', 'NNET_CNN_TRAININGPLOT_UIFIGURE'))
        scoresTest = minibatchpredict(trainedNet,YTrain);
       %YPredicted = onehotdecode(scoresTest,int8(classnames),2);
       YPredicted = scores2label(scoresTest,classnames);
       valError = 1 - mean(YPredicted == YValidation);
       fileName = num2str(valError) + ".mat";
        save(fileName, 'trainedNet', 'valError', 'options')
        cons = [];
    end
end
function layers = convBlock(filterSize,numFilters,numConvLayers)
layers = [
    convolution2dLayer(filterSize,numFilters,'Padding','same')
    batchNormalizationLayer
    reluLayer];
layers = repmat(layers,numConvLayers,1);
end
```