

# MapReduce on a Chord Distributed Hash Table

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# Background

- Google's MapReduce [1] paradigm is integral to data processing.
- Popular platforms for MapReduce, such as Hadoop [2], are designed to be used in datacenters with a degree of centralization.
- Until recently, analysis and optimization of MapReduce has largely remained constrained to that context.

# Goals

- We wanted build a more abstract system for MapReduce.
- We remove core assumptions [3]:
  - The system is centralized.
  - Processing occurs in a static network.
- The resulting system must be:
  - Fault tolerant.
  - Scalable.
  - Completely decentralized.

# Features of ChordReduce

ChordReduce is a decentralized framework for distributed computing:

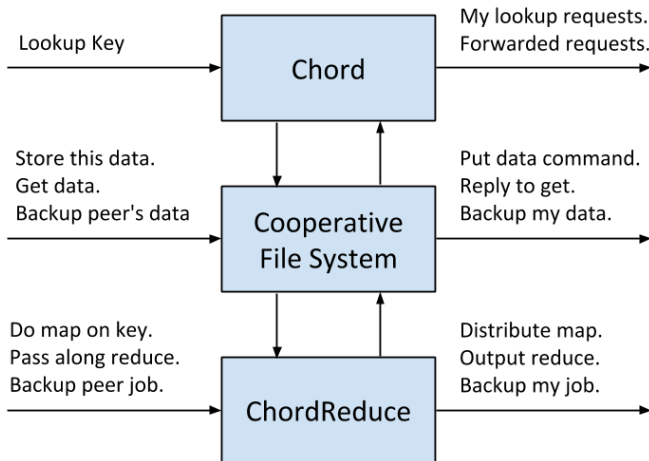
- Scalable.
- Load-Balancing.
  - Data and tasks are evenly distributed across the network.
  - Joining nodes are automatically assigned data and tasks.
- Decentralized:
  - No centralized node is needed to maintain metadata.
  - No central coordinator for tasks.
- Fault tolerant:
  - The loss of multiple nodes does not impact integrity.
  - The network can adjust to churn, the effects of nodes entering and leaving.

# System Architecture

ChordReduce has three layers:

- Chord [4], which handles routing and lookup.
- The Cooperative File System (CFS) [5], which handles storage and data replication.
- The MapReduce layer.

# System Architecture



# Chord

Chord is a peer-2-peer lookup service, where the nodes in the network are arranged in a ring overlay.

- Nodes and files are assigned an  $m$ -bit key (typically  $m = 160$ ).
- Nodes know their predecessor and successor in the ring.
- Nodes are responsible for files with keys between their predecessor's key and their own key.
- To speed routing, nodes maintain a table of  $m$  shortcuts, called fingers.
- The fingers allow a high probability  $\log_2 N$  lookup time for any key.



# A Chord Network

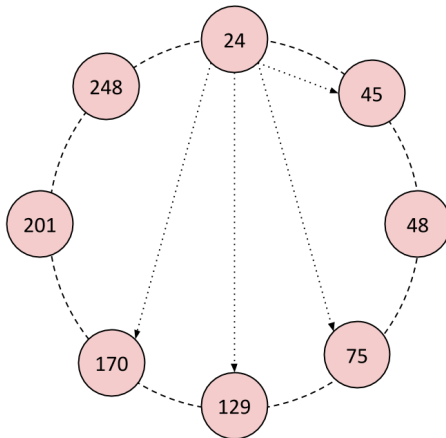


Figure: An 8-node Chord ring where  $m = 8$ . Node 24's fingers are shown.

# CFS

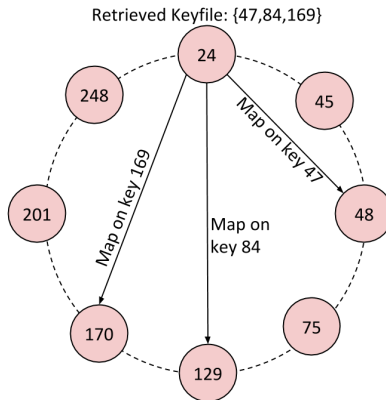
The Cooperative File System runs on top of Chord.

- Files are split up, each block given a key based on their contents.
- Each block is stored according to their key.
- The hashing process guarantees that the keys are distributed near evenly among nodes.
- A keyfile is created and stored where the whole file would have been found.
- To retrieve a file, the node gets the keyfile and sends a request for each block listed in the keyfile.

# Fault Tolerance

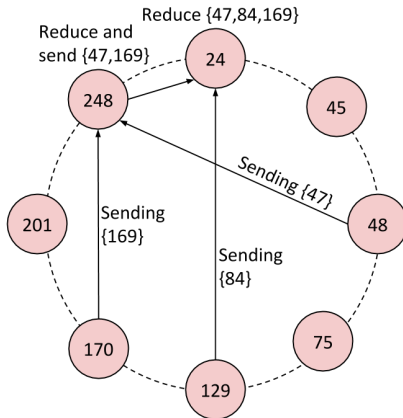
- Each node maintains a list of its  $s$  closest successors.
- Nodes back up data they're responsible for to their successors.
- When a node's predecessor fails, the node can immediately take over.
- If a node detects a new predecessor, it sends the predecessor all the data it should be responsible for.

# Mapping Data



**Figure:** The stager sends a map task for each key in the keyfile. In larger networks, this process is streamlined by recursively bundling keys and sending them to the best finger.

# Reducing Results



**Figure:** Results are sent back via the overlay. If a node receives multiple results, they are reduced.

# Fault Tolerance of Map Jobs

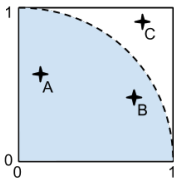
- Each node backups their map tasks; removes it when the task is processed.
- If the immediate successor detects the node's failure, it takes over the task.
- If a node detects a new predecessor responsible for a key and map task pair in it's queue, it sends it to the predecessor.
- This allows node to further distribute the work during execution.

## Fault Tolerance of Reduces

- Individual reduces are backed up in a similar manner; if the original holder of the reduce fails before the reduce is sent, his successor sends his backup.
- Results are sent back to a key, rather than to a specific node.
- This ensures that if node receiving the data fails, his successor will take over.

# Experiment Details

Our initial test was a Monte Carlo approximation of  $\pi$ .



**Figure:** The node chooses random  $x$  and  $y$  between 0 and 1. If  $x^2 + y^2 < 1^2$ , the “dart” landed inside the circle.

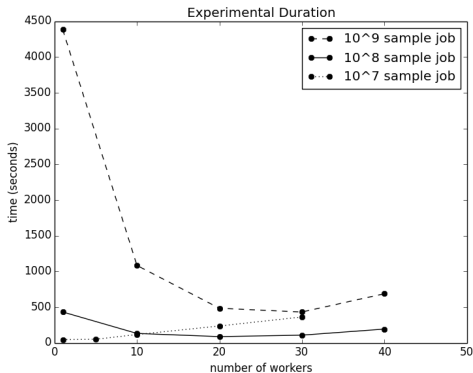
- Map jobs were sent to randomly generated hash addresses.
- The ratio of hits to generated results approximates  $\frac{\pi}{4}$ .
- Reducing the results was a matter of combining the two fields.



# Variables

We ran the experiment using Amazon's Elastic Cloud Compute [6] and varied the following:

- Network size.
- Problem size.
- Rate of churn.



**Figure:** For a sufficiently large job, it was almost always preferable to distribute it. When the job is too small, such as with the  $10^7$  data set, our runtime is dominated by the overhead. Our results are what we would expect when overhead grows logarithmically to the number of workers.

# Churn Results

Churn rate per second	Average runtime (s)	Speedup vs 0% churn
0.8%	191.25	2.15
0.4%	329.20	1.25
0.025%	431.86	0.95
0.00775%	445.47	0.92
0.00250%	331.80	1.24
0%	441.57	1.00

**Table:** The results of calculating  $\pi$  by generating  $10^8$  samples under churn. Churn is the chance for each node to join or leave the network. The large speedup is from joining nodes acquiring work during experimental runtime.






# Conclusions

Our experiments established:

- ChordReduce can operate under high rates of churn.
- Execution follows the desired speedup.
- Speedup occurs on sufficiently large problem sizes.

This makes ChordReduce an excellent platform for distributed and concurrent programming in cloud and loosely coupled environments.

Questions?

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