# CSC 212: Data Structures and Abstractions Dynamic Arrays

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## Arrays

## Quick notes

- Review Pointers and Dynamic Memory Allocation
- Programming Assignment
  - r can use vector of pairs std::vector<std::pair> >
  - √ due on Friday
  - ✓ no extensions

### Arrays

- An array is a **contiguous** sequence of elements of the **same type**
- Each element can be accessed using its **index**

array name: A array length: n

0 1 2 3 n-1
A[0] A[1] A[2] A[3] ... A[n-1]

all elements of the same data type

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### Declaration

```
// array declaration by specifying size
int myarray1[100];

// can also declare an array of
// user specified size
int n = 8;
int myarray2[n];

// can declare and initialize elements
double arr[] = { 10.0, 20.0, 30.0, 40.0 };
// compiler figures the right size

// a different way
int arr[5] = { 1, 2, 3 };
// compiler creates an array of length 5 and
// initializes first 3 elements
```

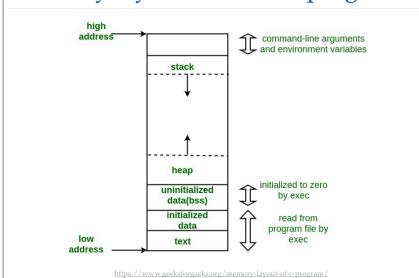
### Static arrays

the heap (still fixed length)

So far ... we have seen examples of arrays, allocated in the stack (fixed length)
 // array declaration by specifying size int myarray1[100];
 You can allocate memory dynamically, allocated in

```
int *myarray = new int [100];
// ...
// work with the array
// ...
delete [] myarray;
```

## Memory layout of C/C++ programs



Live coding demo (static arrays — stack and heap)

```
C++ (gcc 4.8, C++11)
                                      EXPERIMENTAL! known limitations
                              1 int main() {
                                    float var1;
                                     double var2:
                                    int static_array[10];
                                  int *static_array_heap = new int [20];
                                 // work with the array
                                    delete [] static array heap;
                            10 }
                                              Edit this code
                  line that just executed
                  next line to execute
main
static array heap
                                    credit: pythontutor.com
```

#### A few notes ...

- Creating variables in the stack:
  - √ variables are automatically created and freed
  - √ variables only exist while the function is running
  - ✓ faster and good for small local variables
- Allocating memory in the heap:
  - √ memory is allocated at runtime
  - √ programmer is responsible for allocating / deallocating memory
  - √ variables can be accessed globally (in the program)
  - √ memory may become fragmented
  - ✓ slower but good for large variables

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### What if ...?

- We don't know the max size of an array before running the program
  - ✓ user specified inputs/decisions
  - ✓ e.g. read an image or video and display
- The sequence changes over time (during the execution of the program)
  - ✓ e.g. you develop a text editor and represent the sequence of characters as an array

Which data structure (studied so far) would you use on each case?

Dynamic Arrays (resizing, growing)

### Dynamic Arrays

- Dynamically allocated arrays that change their size over time
  - ✓ can **grow** automatically
  - ✓ can **shrink** automatically
- · Operations on arrays (we could have more, but these are enough for the purposes of this lecture)
  - √ append
  - √ remove\_last
  - $\sqrt{\text{get}} \Theta(1)$
  - $\checkmark$  set  $-\Theta(1)$

First try ...

- · Start with an empty array
- · For every append:
  - ✓ increase the size of the array by 1 then write the new element
- For every remove\_last:
  - ✓ remove the last element and then decrease the size of the array by 1
- Demo ...

## Analyzing the cost (grow by 1)

- · Count array accesses (reads and writes) of adding first *n* elements
  - will ignore the cost of allocating/deallocating arrays

append	copy

each row indicates the number of reads and writes necessary for appending an element into an existing array of length n

$$n + \sum_{i=0}^{n-1} 2i = n + n^2 - n$$

$$\Theta(n^2)$$

$$\Theta(n^2)$$

### Lets try again ...

- If array is **full**, create an array of **twice the size** √ repeated doubling
- If array is **one-quarter full**, halve the size
  - √ more efficient
  - ✓ why not halving when array is one-half full?

append - remove - append - remove - append - remove...

Demo ...

## Analyzing the cost (doubling the array)

· Count array accesses (reads and writes) of adding first  $n = 2^i$  elements

will ignore the cost of allocating/deallocating arrays

n	append	сору

each row indicates the number of reads and writes necessary for appending an element into an existing array of length n

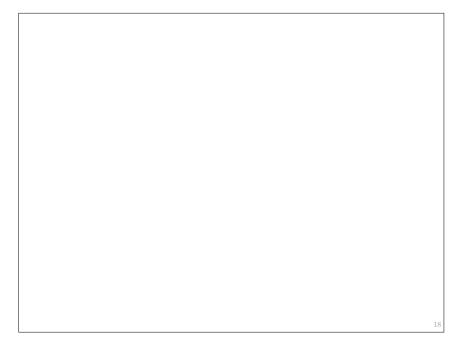
$$n + \sum_{i=1}^{\log n} 2^i = n + 2^{\log n + 1} - 1$$

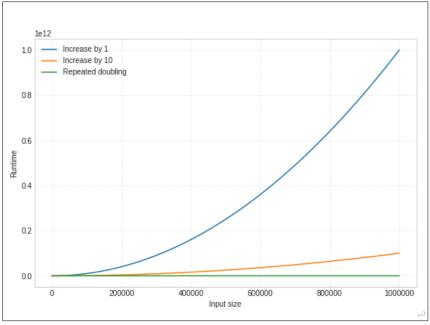
$$\Theta(n)$$

$$\sum_{i=0}^{n} c^i = \frac{c^{n+1} - 1}{c - 1}$$



$$\sum_{i=0}^{n} c^{i} = \frac{c^{n+1} - 1}{c - 1}$$





## Worst-case and average-case

Analysis for appending a single element using increase-by-1

· Analysis for appending a single element using repeated doubling

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