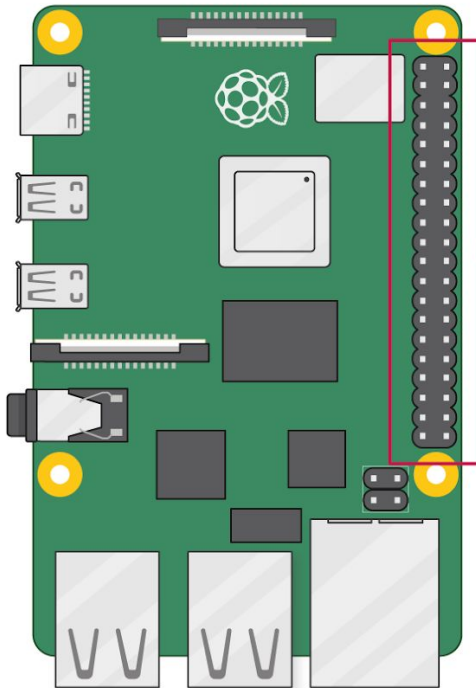


# Sistemas Operacionais Embarcados

## GPIO Polling

# Pinos GPIO

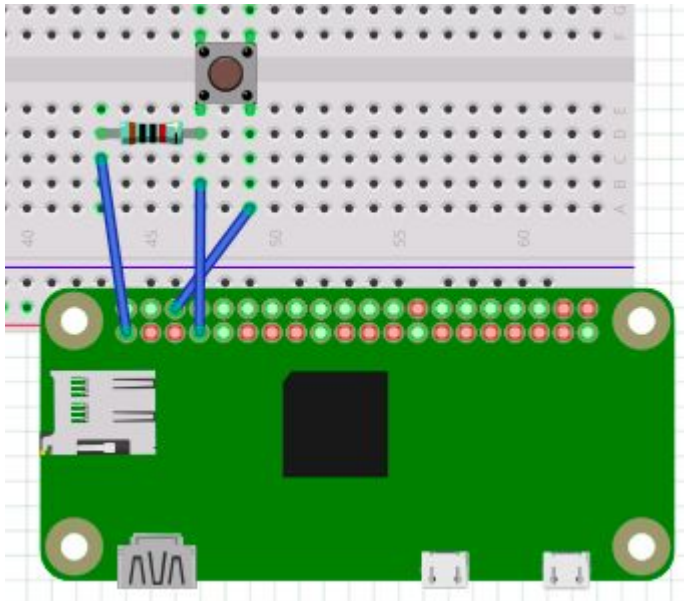


3V3 power	1	2	5V power
GPIO 2 (SDA)	3	4	5V power
GPIO 3 (SCL)	5	6	Ground
GPIO 4 (GPCLK0)	7	8	GPIO 14 (TXD)
Ground	9	10	GPIO 15 (RXD)
GPIO 17	11	12	GPIO 18 (PCM_CLK)
GPIO 27	13	14	Ground
GPIO 22	15	16	GPIO 23
3V3 power	17	18	GPIO 24
GPIO 10 (MOSI)	19	20	Ground
GPIO 9 (MISO)	21	22	GPIO 25
GPIO 11 (SCLK)	23	24	GPIO 8 (CE0)
Ground	25	26	GPIO 7 (CE1)
GPIO 0 (ID_SD)	27	28	GPIO 1 (ID_SC)
GPIO 5	29	30	Ground
GPIO 6	31	32	GPIO 12 (PWM0)
GPIO 13 (PWM1)	33	34	Ground
GPIO 19 (PCM_FS)	35	36	GPIO 16
GPIO 26	37	38	GPIO 20 (PCM_DIN)
Ground	39	40	GPIO 21 (PCM_DOUT)

- Pinos GPIO trabalham em 3,3V
- RPi 1A e 1B têm somente os 26 pinos superiores da lista
- Legendas em parênteses indicam funções alternativas para o mesmo pino

# Sistema sysfs + poll ()

- Através dos arquivos `/sys/class/gpio/gpioN/direction` e `/sys/class/gpio/gpioN/value`, é possível testar se um botão ligado ao pino GPION foi pressionado
- No entanto, a leitura constante do arquivo `/sys/class/gpio/gpioN/value` é ineficiente
- Podemos usar a função `poll ()` \* para o sistema operacional testar o pino



```
/sys/class/gpio/  
|--export  
|--unexport  
|--gpiochip0  
|--gpiochip100  
|--gpioN  
    |--direction  
    |--value  
    |--edge  
    |--active_low
```

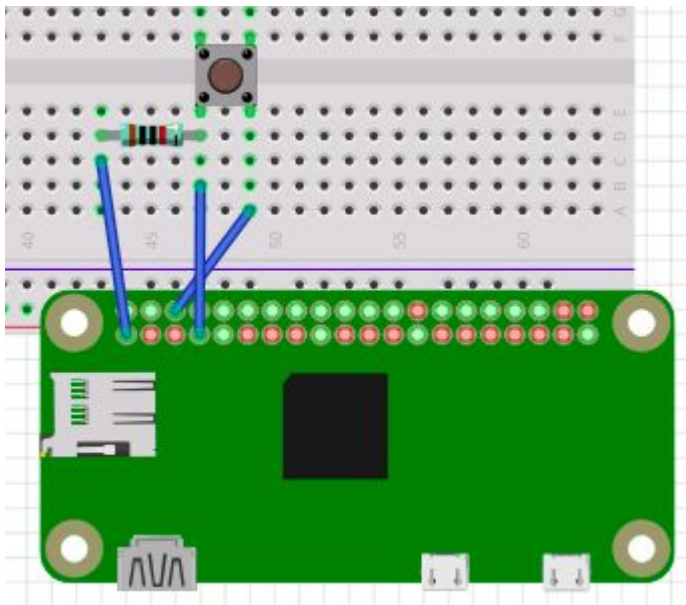
\* <https://man7.org/linux/man-pages/man2/poll.2.html>

# Sistema sysfs + poll()

```
#include <poll.h>
```

```
struct pollfd {  
    int    fd;           /* file descriptor */  
    short  events;        /* requested events */  
    short  revents;       /* returned events */  
};
```

```
int poll(struct pollfd *fds, nfds_t nfd, int timeout);
```



```
/sys/class/gpio/  
|--export  
|--unexport  
|--gpiochip0  
|--gpiochip100  
|--gpioN  
    |--direction  
    |--value  
    |--edge  
    |--active_low
```

# Sistema sysfs + poll()

```
#include <poll.h>
```

```
struct pollfd {
```

```
    int
```

```
    shd
```

```
    shd
```

```
};
```

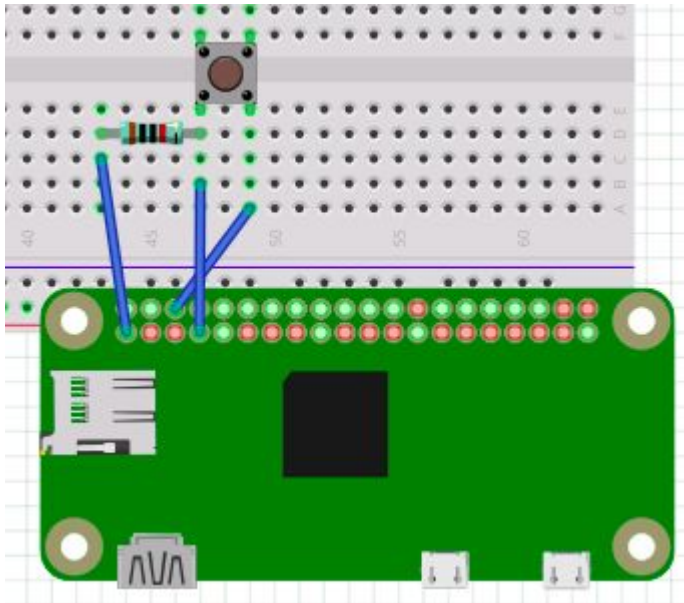
A função `poll()` espera acontecer um evento em um arquivo previamente aberto

```
    int fd; /* descriptor */
```

```
    short events; /* events to wait for */
```

```
    short revents; /* events that occurred */
```

```
int poll(struct pollfd *fds, nfds_t nfds, int timeout);
```



```
/sys/class/gpio/  
|--export  
|--unexport  
|--gpiochip0  
|--gpiochip100  
|--gpioN  
    |--direction  
    |--value  
    |--edge  
    |--active_low
```

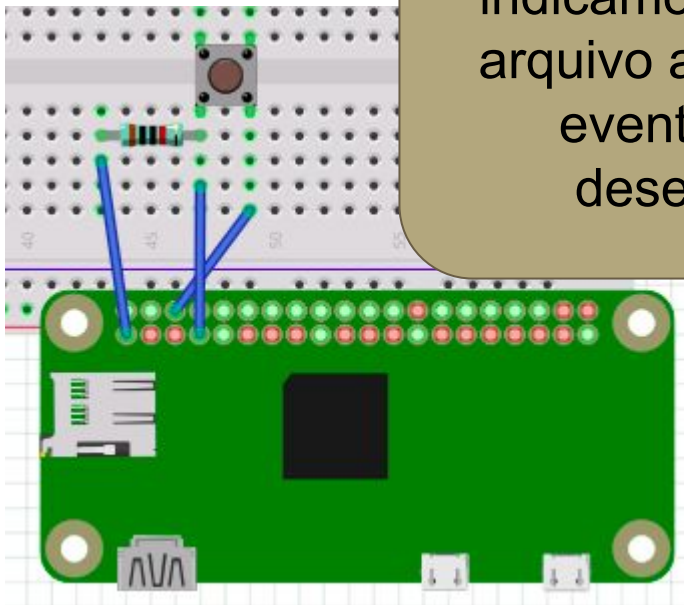
# Sistema sysfs + poll()

```
#include <poll.h>
```

```
struct pollfd {  
    int    fd;           /* file descriptor */  
    short  events;        /* requested events */  
    short  revents;       /* returned events */  
};
```

```
int poll(struct pollfd pollfd[], int nfds, int timeout);
```

Na estrutura `pollfd`,  
indicamos o descritor `fd` do  
arquivo aberto e os tipos de  
eventos `events` que  
desejamos detectar



```
pin 0  
--gpiochip100  
--gpioN  
--direction  
--value  
--edge  
--active_low
```



Na estrutura `pollfd`,  
indicamos o descritor `fd` do  
arquivo aberto e os tipos de  
eventos `events` que  
desejamos detectar

The bits that may be set/returned in `events` and `revents` are defined in `<poll.h>`:

**POLLIN** There is data to read.

**POLLPRI**

There is some exceptional condition on the file descriptor. Possibilities include:

- There is out-of-band data on a TCP socket (see `tcp(7)`).
- A pseudoterminal master in packet mode has seen a state change on the slave (see `ioctl_tty(2)`).
- A `cgroup.events` file has been modified (see `cgroups(7)`).

**POLLOUT**

Writing is now possible, though a write larger than the available space in a socket or pipe will still block (unless **O\_NONBLOCK** is set).

**POLLRDHUP** (since Linux 2.6.17)

Stream socket peer closed connection, or shut down writing half of connection. The `_GNU_SOURCE` feature test macro must be defined (before including *any* header files) in order to obtain this definition.

**POLLERR**

Error condition (only returned in `revents`; ignored in `events`). This bit is also set for a file descriptor referring to the write end of a pipe when the read end has been closed.

**POLLHUP**

Hang up (only returned in `revents`; ignored in `events`). Note that when reading from a channel such as a pipe or a stream socket, this event merely indicates that the peer closed its end of the channel. Subsequent reads from the channel will return 0 (end of file) only after all outstanding data in the channel has been consumed.

**POLLNVAL**

Invalid request: `fd` not open (only returned in `revents`; ignored in `events`).

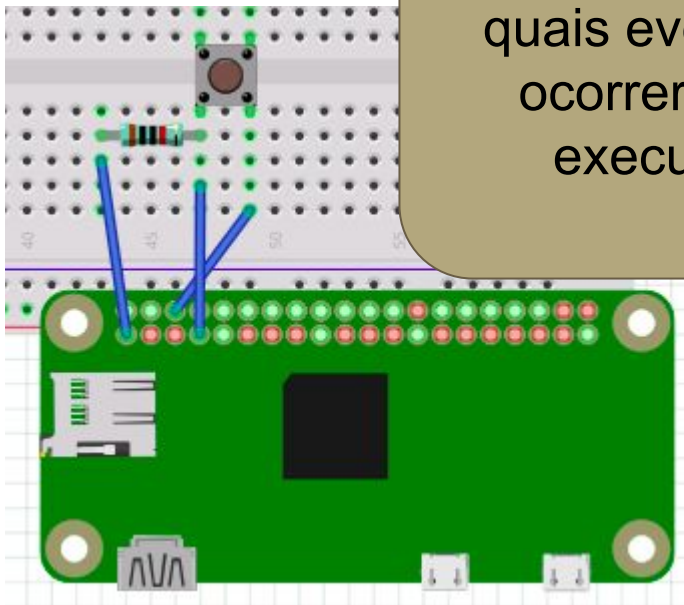
# Sistema sysfs + poll()

```
#include <poll.h>
```

```
struct pollfd {  
    int    fd;          /* file descriptor */  
    short  events;       /* requested events */  
    short  revents;      /* returned events */  
};
```

```
int poll(struct pollfd *fds, nfds_t nfds, int timeout);
```

A variável `revents` indica  
quais eventos efetivamente  
ocorreram após o fim da  
execução de `poll()`



```
pin0  
|--gpiochip100  
|--gpioN  
|--direction  
|--value  
|--edge  
|--active_low
```



# Sistema sysfs + poll()

```
#include <poll.h>

struct pollfd

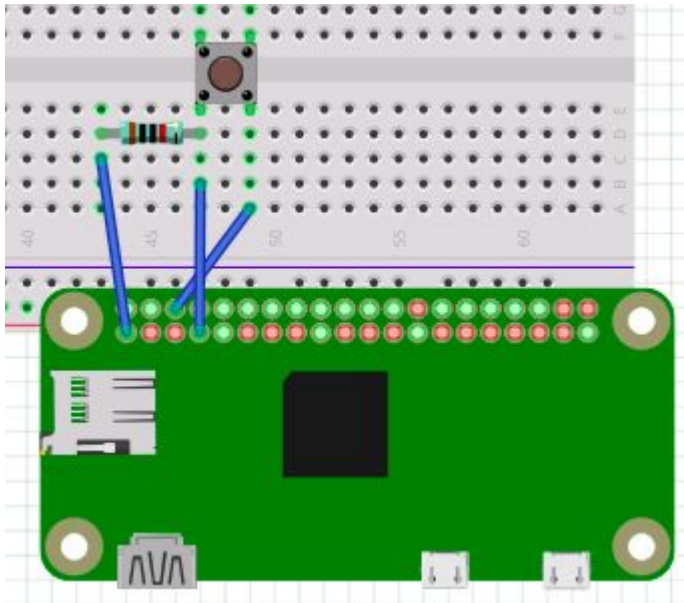
};
```

`poll()` recebe:

- `*fds`: um vetor de estruturas do tipo `pollfd` (para acompanharmos mais de um arquivo simultaneamente)
- `nfds`: o tamanho desse vetor
- `timeout`: o tempo máximo de espera pelos eventos

```
* /
* /
* /
```

```
int poll(struct pollfd *fds, nfds_t nfds, int timeout);
```



```
/sys/class/gpio/
|--export
|--unexport
|--gpiochip0
|--gpiochip100
|--gpioN
    |--direction
    |--value
    |--edge
    |--active_low
```

# Sistema sysfs + poll()

```
#include <poll
```

```
struct pollfd
```

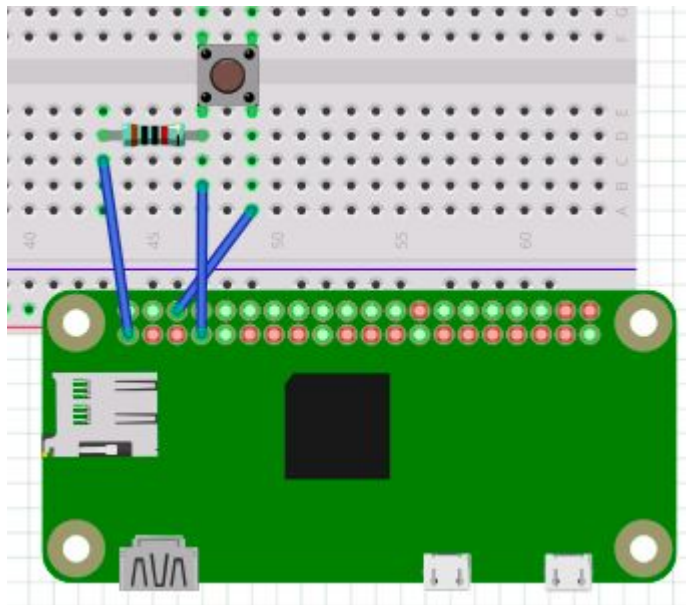
```
};
```

```
int poll(struct
```

Para monitorarmos o pino GPION no RPi, devemos escrever no arquivo

/sys/class/gpio/gpioN/edge qual  
borda queremos detectar: “rising”, “falling”,  
“both” ou “none”

O arquivo a ser monitorado por poll() é  
/sys/class/gpio/gpioN/value

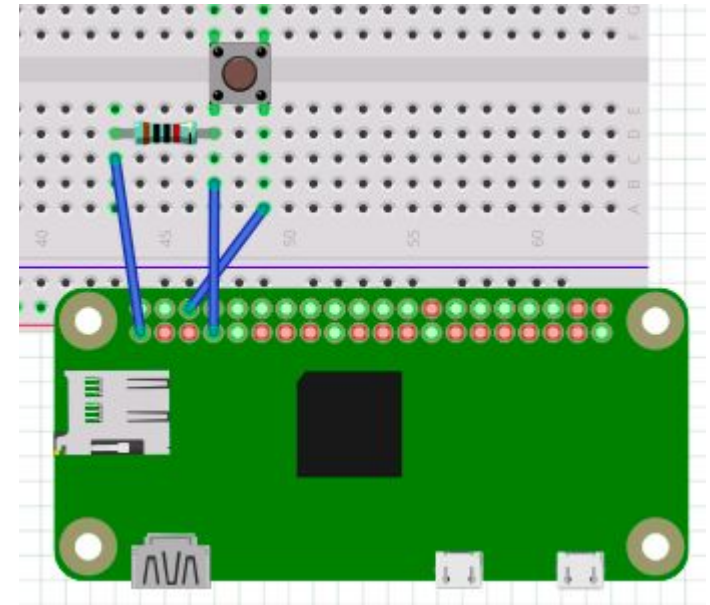


```
/sys/class/gpio/  
|--export  
|--unexport  
|--gpiochip0  
|--gpiochip100  
|--gpioN  
    |--direction  
    |--value  
    |--edge  
    |--active_low
```

# Sistema sysfs + poll ()

De acordo com a documentação da interface sysfs para GPIO\*:

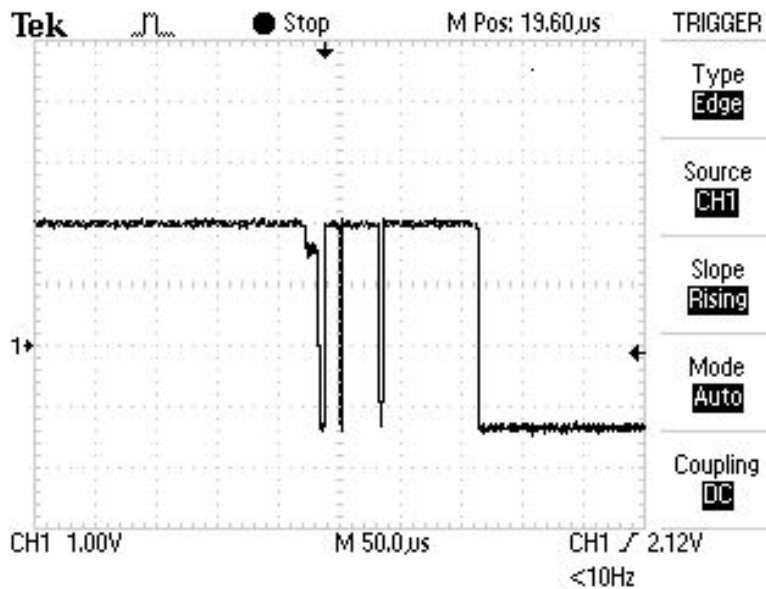
- Para monitorarmos o pino **GPION** no RPi, devemos escrever no arquivo `/sys/class/gpio/gpioN/edge` qual borda queremos detectar: “rising”, “falling”, “both” ou “none”
- O arquivo a ser monitorado por `poll ()` é `/sys/class/gpio/gpioN/value`
- É necessário ler o arquivo `value` antes de fazer o `poll ()` dele
- O `poll ()` deve ser feito considerando os eventos `POLLPRI` e `POLLERR`



```
/sys/class/gpio/  
|--export  
|--unexport  
|--gpiochip0  
|--gpiochip100  
|--gpioN  
    |--direction  
    |--value  
    |--edge  
    |--active_low
```

\* <https://www.kernel.org/doc/Documentation/gpio/sysfs.txt>

# Debouncing



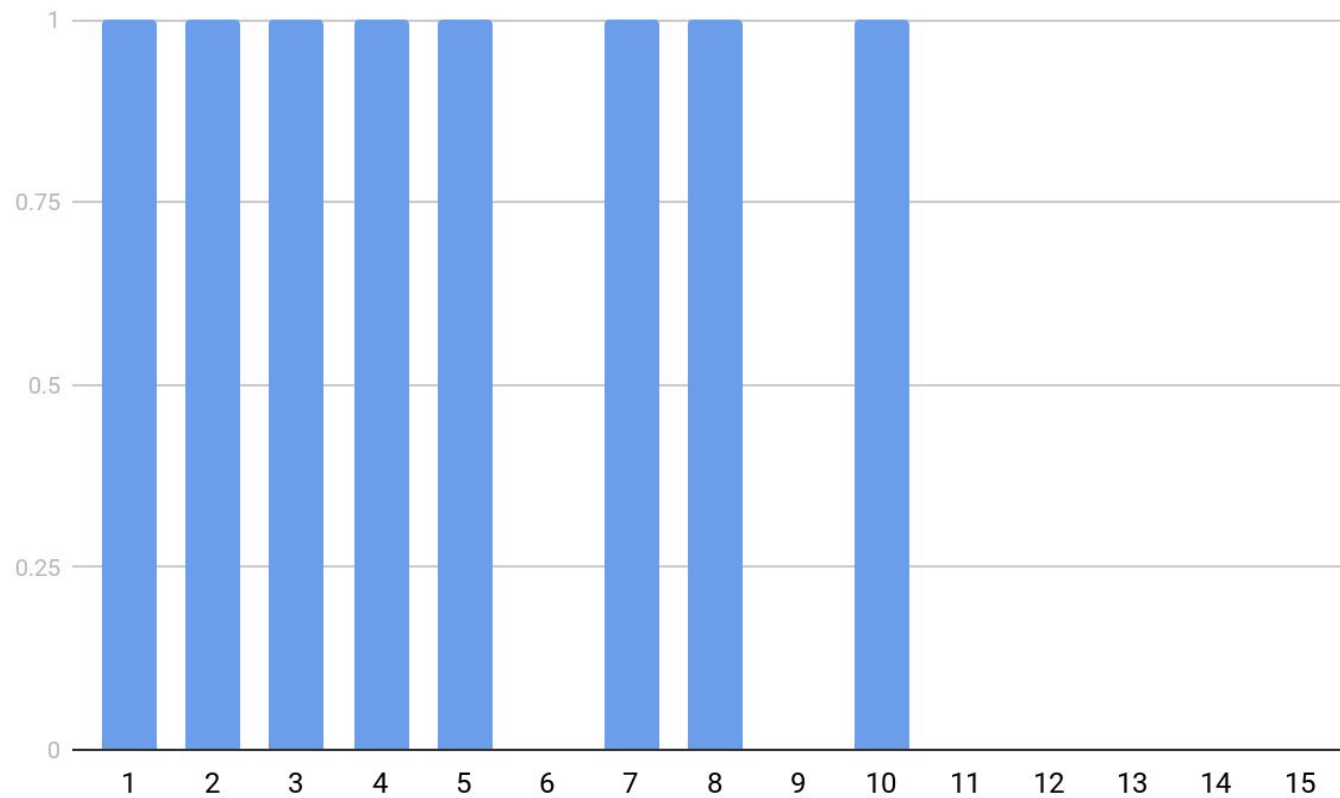
Botões e chaves mecânicas tipicamente sofrem com o problema de *bouncing*, causando leituras espúrias

Dentre as diversas formas de resolver este problema, podemos:

- Acrescentar um atraso fixo após a detecção de uma borda
- Fazer um filtro média-móvel

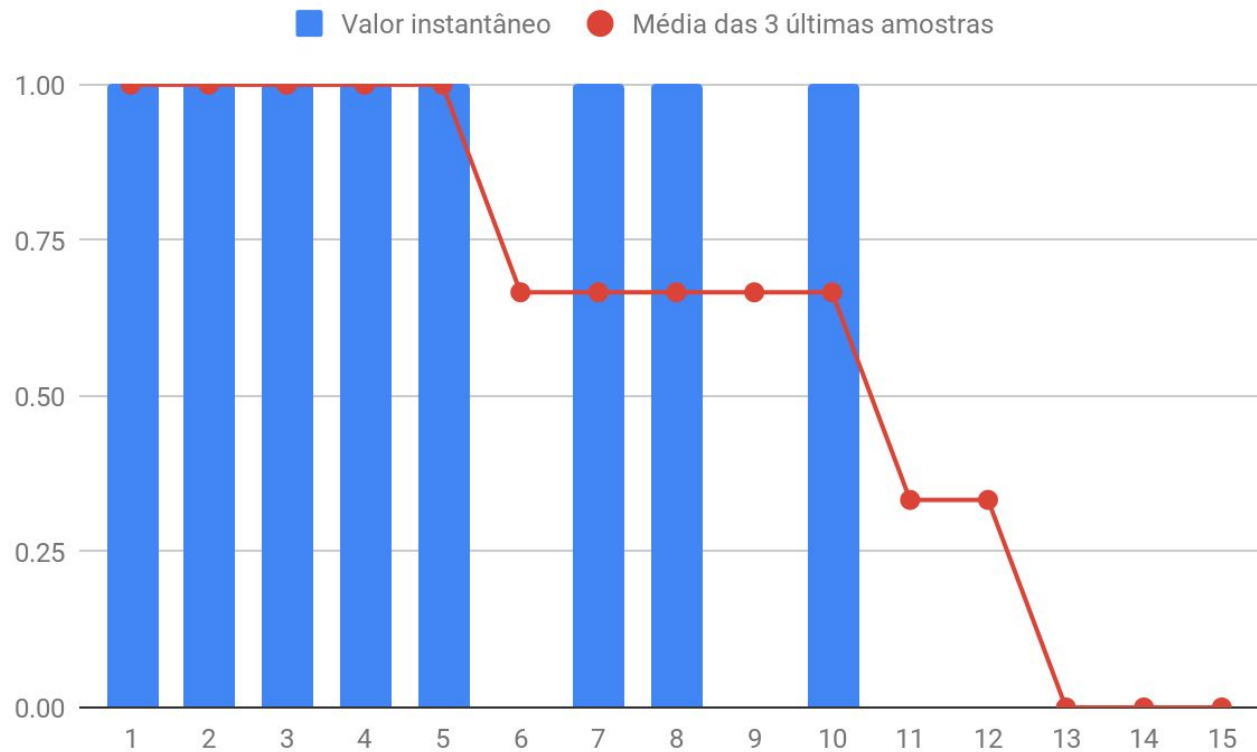
# Filtro média móvel

Considere o sinal digital a seguir:



# Filtro média móvel

Ao invés de usarmos os valores instantâneos, podemos calcular a média das últimas N amostras para decidirmos se o botão foi pressionado





# Filtro média móvel

Ao invés de usarmos os valores instantâneos, podemos calcular a média das últimas N amostras para decidirmos se o botão foi pressionado

