

# Bertini Home Page

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**Bertini™: Software for Numerical Algebraic Geometry**  
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Software for solving **polynomial systems**

## Facts in brief:

- **Purpose:** The numerical solution of systems of polynomial equations.
- **Approach:** Homotopy continuation.
- **Authors:** [Daniel J. Bates](#), [Jonathan D. Hauenstein](#), [Andrew J. Sommese](#), [Charles W. Wampler](#)
- **Background:** Bertini is a general-purpose solver, written in C, that was created for research about polynomial continuation.
- **Cost:** Bertini is distributed free of charge on an "as is" basis with no warranties, implied or otherwise, that it is suitable for any purpose. Its intended usage is educational, so that the user may gain a greater understanding of numerical homotopy continuation for solving systems of polynomial equations. Any other use is strictly the user's responsibility.

## Key features:

- Finds isolated solutions using total-degree start systems, multihomogeneous-degree start systems, and also user defined homotopies.
- Implements parameter continuation for families of systems, such as the inverse kinematics of six-revolute serial-link arms, or the forward kinematics of Stewart-Gough parallel-link robots.
- Adaptive multiprecision implemented for finding isolated solutions and for the numerical irreducible decomposition.
- Treats positive-dimensional solutions by computing witness sets.
- Has automatic differentiation which preserves the straightline quality of an input system.
- Uses homogenization to accurately compute solutions "at infinity."
- Provides endgames to accurately compute singular roots.
- Allows for subfunctions.
- Allows for witness set manipulation via both sampling and membership testing.
- Accepts underdetermined, exactly determined, and overdetermined systems (i.e., the number of variables and equations do not have to be equal).

**[Bertini download page](#)**

**[Bertini2 GitHub repository](#) (ongoing**

**development using a [GPLv3](#) license)**

**[Bertini book page](#)**

**[Polynomials, Kinematics, and Robotics: A conference honoring Charles Wampler](#)**

**[Workshop on Software and Applications of Numerical Algebraic Geometry](#)**

**[Other links](#)**

**[Policy and citation of Bertini](#)**

**[Users Manual](#)**

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- Unique visitors: average 8.6 per day
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