

#### Finger parts (rigid):

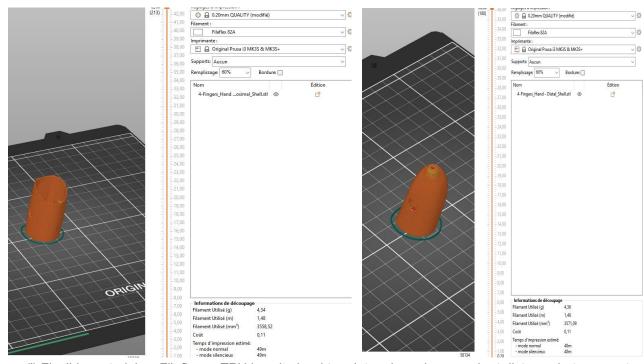
#### Support needed for:

- Gimbal
- Link
- Proximal
- Distal

High robustness required



PLA 0.2 layers at least 80% infill



## Finger parts (flex):

No support needed

Flexibility required



0.2 layers between 40 & 70% infill

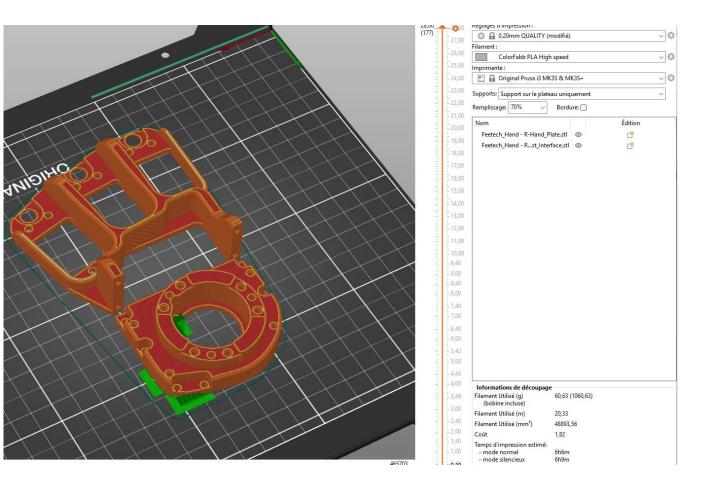
/!\ Flexible material as Filaflex or TPU is quite hard to print and need a very short distance between extruder and hot end.

Print parameters are specific for each filament and 3D printing machine, so several tests should be needed to obtain perfect result. Be strong!

In general:

- Don't fill to much the part, it will increase his stiffness
- Don't use support, it's often a mess to retire it
- Print parts one by one, to avoid unwanted bridges
- Deactivate "fill gaps" parameters, it could create over thickness randomly
- Try to minimize retractation needed for printing, it could create thin wires that are difficult to remove

Sometimes it's not possible to respect all these tips, you will have to be patient and precocious to clean flexible parts... Flexible has strong adhesion to printer bed, remember to remove the part quickly after it is finished to prevent bed damages.

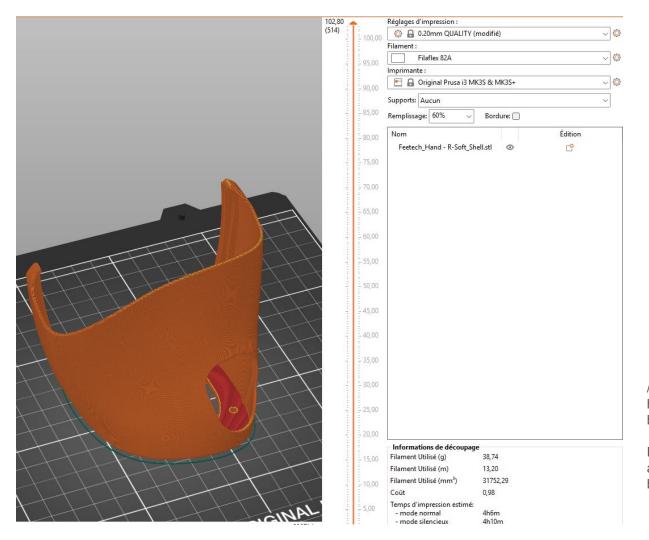


## Hand parts (rigid):

Support needed for - Wrist interface

Robustness required





### Hand shell (flex):

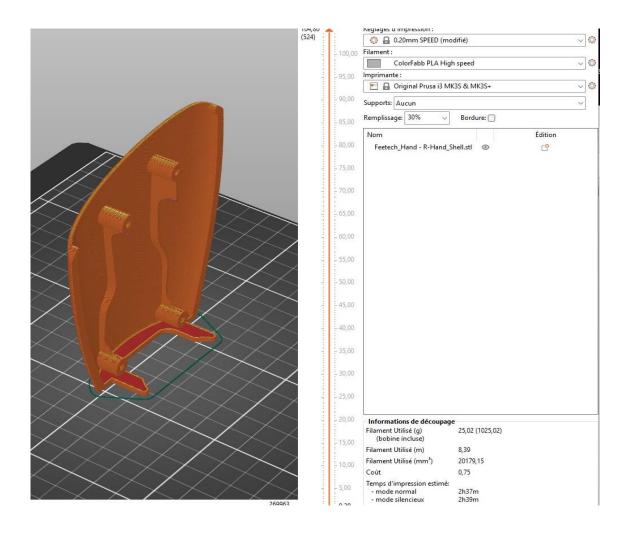
No support needed

Flexibility required



/!\ Flexible material as Filaflex or TPU is quite hard to print and need a very short distance between extruder and hot end.

Print parameters are specific for each filament and 3D printing machine, so several tests should be needed to obtain perfect result. Be strong!



# Hand shell (rigid):

No support needed No robustness required



between 20 & 40% infill