Aim: To understand the working principle of Artificial Neural network with feed forward and feed backward principle.

Program: Build an Artificial Neural Network by implementing the Backpropagation algorithm and test the same using appropriate data sets.

BACKPROPAGATION Algorithm

BACKPROPAGATION (training_example, η , n_{in} , n_{out} , n_{hidden})

Each training example is a pair of the form (\vec{x}, \vec{t}) , where (\vec{x}) is the vector of network input values, (\vec{t}) and is the vector of target network output values.

 η is the learning rate (e.g., .05). n_i , is the number of network inputs, n_{hidden} the number of units in the hidden layer, and n_{out} the number of output units.

The input from unit i into unit j is denoted x_{ji} , and the weight from unit i to unit j is denoted w_{ji}

- Create a feed-forward network with n_i inputs, n_{hidden} hidden units, and n_{out} output units.
- · Initialize all network weights to small random numbers
- Until the termination condition is met, Do
 - For each (\vec{x}, \vec{t}) , in training examples, Do

Propagate the input forward through the network:

1. Input the instance \vec{x} , to the network and compute the output o_u of every unit u in the network.

Propagate the errors backward through the network:

2. For each network output unit k, calculate its error term δ_k

$$\delta_k \leftarrow o_k (1 - o_k)(t_k - o_k)$$

3. For each hidden unit h, calculate its error term δ_h

$$\delta_h \leftarrow o_h(1 - o_h) \sum_{k \in outputs} w_{h,k} \delta_k$$

4. Update each network weight wji

$$w_{ji} \leftarrow w_{ji} + \Delta w_{ji}$$

Where

$$\Delta w_{\rm ji} = \eta \delta_j x_{i,j}$$

Training Examples:

Example	Sleep	Study	Expected % in Exams
1	2	9	92
2	1	5	86
3	3	6	89

Normalize the input

Example	Sleep	Study	Expected % in Exams
1	2/3 = 0.66666667	9/9 = 1	0.92
2	1/3 = 0.333333333	5/9 = 0.5555556	0.86
3	3/3 = 1	6/9 = 0.66666667	0.89

import numpy as np

 $X = np \cdot array(([2, 9], [1, 5], [3, 6]), dtype=float)$

 $y = np \cdot array(([92], [86], [89]), dtype=float)$

X = X/np.amax(X,axis=0) # maximum of X array longitudinally

y = y/100

Sigmoid Function

def sigmoid (x):

return 1/(1 + np.exp(-x))

```
# Derivative of Sigmoid Function
def derivatives_sigmoid(x):
```

```
return x * (1 - x)
```

Variable initialization

```
epoch=500 # Setting training iterations

lr=0.1 # Setting learning rate

inputlayer_neurons = 2 # number of features in data set

hiddenlayer_neurons = 3 # number of hidden layers neurons

output_neurons = 1 # number of neurons at output layer
```

weight and bias initialization

```
wh=np.random.uniform(size=(inputlayer_neurons,hiddenlayer_neurons))
bh=np.random.uniform(size=(1,hiddenlayer_neurons))
wout=np.random.uniform(size=(hiddenlayer_neurons,output_neurons))
bout=np.random.uniform(size=(1,output_neurons))
```

draws a random range of numbers uniformly of dim x*y

for i **in** range(epoch):

Forward Propogation

```
hinp1=np.dot(X,wh)
hinp=hinp1 + bh
hlayer_act = sigmoid(hinp)
outinp1=np.dot(hlayer_act,wout)
outinp= outinp1+ bout
output = sigmoid(outinp)
```

#Backpropagation

```
EO = y-output
  outgrad = derivatives_sigmoid(output)
  d_output = EO* outgrad
  EH = d_output.dot(wout.T)
  #how much hidden layer wts contributed to error
  hiddengrad = derivatives_sigmoid(hlayer_act)
  d_hiddenlayer = EH * hiddengrad
  # dot product of next layer error and current layer output
  wout += hlayer_act.T.dot(d_output) *lr
  wh += X.T.dot(d_hiddenlayer) *lr
print("\n Input: \n" + str(X))
print("\n Actual Output: \n" + str(y))
print("\n Predicted Output: \n" ,output)
Input:
[[0.66666667 1.
                    1
[0.33333333 0.55555556]
        0.66666667]]
[1.
Actual Output:
[[0.92]]
[0.86]
[0.89]]
Predicted Output:
[[0.89511671]
[0.8828429]
```