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Date Submitted: 10/12/18
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Task 01:
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Youtube Link: https://www.youtube.com/watch?v=q9By8sZAZBw
Modified Code:
   • In main, turn on timer1 and ADC:
int main(void) {
    task0Setup(); // does everything from task0
    SysCtlPeripheralEnable(SYSCTL PERIPH TIMER1);
    // turn on timer 1 for 0.5 second intervals
    TimerConfigure(TIMER1_BASE, TIMER_CFG_PERIODIC);
    TimerLoadSet(TIMER1_BASE, TIMER_A, 20000000-1);
    IntEnable(INT TIMER1A);
    TimerIntEnable(TIMER1 BASE, TIMER TIMA TIMEOUT);
    // configure ADC for Sequence 1
    SysCtlPeripheralEnable(SYSCTL_PERIPH_ADC0);
    ADCSequenceConfigure(ADC0 BASE, 1, ADC TRIGGER PROCESSOR, 0);
    ADCSequenceStepConfigure(ADC0_BASE, 1, 0, ADC_CTL_TS);
    ADCSequenceStepConfigure(ADC0 BASE, 1, 1, ADC CTL TS);
    ADCSequenceStepConfigure(ADC0_BASE, 1, 2, ADC_CTL_TS);
    ADCSequenceStepConfigure(ADC0 BASE,1,3,ADC CTL TS|ADC CTL IE|ADC CTL END);
    TimerEnable(TIMER1_BASE, TIMER_A); // turn on Timer
    while (1) //let interrupt handler do the UART echo function
    {
       // i
    }
}

    Inside the Timer Interrupt function, turn on ADC and grab the ADC values. Once

      it's done, convert values to C and F. Once that's done, convert the int value
      to a string and then send it through UART:
void Timer1IntHandler(void)
    uint32 t TVals[4]; // Values for temperature
    uint32_t TempF, TempC, Avg, i;
    char buff[20];
    //clear flags
    TimerIntClear(TIMER1 BASE, TIMER TIMA TIMEOUT);
    ADCIntClear(ADC0 BASE, 1);
    //start ADC
    ADCSequenceEnable(ADC0 BASE, 1);
    ADCProcessorTrigger(ADC0_BASE, 1);
    while(!ADCIntStatus(ADC0_BASE, 1, false))
```

```
{
    // poll until ADc is done
}

ADCSequenceDataGet(ADC0_BASE, 1, TVals); // get adc values
Avg = (TVals[0] + TVals[1] + TVals[2] + TVals[3] + 2) / 4;
TempC = (1475 - ((2475 * Avg)) / 4096) / 10; // convert to C
TempF = ((TempC * 9) + 160) / 5; // convert to F

ltoa(TempF, buff); // convert int to a string
i = 0;
while(buff[i] != '\0')
{
    UARTCharPut(UART0_BASE, buff[i]); // send all characters through UART
    i++;
}
UARTCharPut(UART0_BASE, '\r'); // put new line and carraige return
UARTCharPut(UART0_BASE, '\n');
ADCSequenceDisable(ADC0_BASE, 1); // turn off ADC
}
```

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## Task 02:

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Youtube Link: https://www.youtube.com/watch?v=uT3MOn4XEKE
Modified Code:

    The first thing I did was create a function that can send a string through

      UART so that I don't have to constantly do UARTCharPut for each letter:
void sendString(char text[])
    int i = 0;
    while(text[i] != '\0') // sends until NULL is found
        UARTCharPut(UART0_BASE, text[i]);
        i++;
    }
}

    In main, the only thing changed was to enable portF for the LEDs as an output

      and then ask for a command:
int main(void) {
    task1Setup(); // does everything from task 0 and 1
    SysCtlPeripheralEnable(SYSCTL PERIPH GPIOF); // enable LED's as output
    GPIOPinTypeGPIOOutput(GPIO PORTF BASE, GPIO PIN 1 | GPIO PIN 2 | GPIO PIN 3);
    GPIOPinWrite(GPIO_PORTF_BASE, GPIO_PIN_1 | GPIO_PIN_2 | GPIO_PIN_3, 0);
    // send string through UART
    sendString("Enter Command: ");
    while (1) //let interrupt handler do the UART echo function
    {
       //
    }
}
```

- In the UART interrupt, it will get the char value passed through and check which letter was passed. For R, G, B, and their lowercase versions, it sent back to letter to echo, then turned on/off their respective light.
- For 'T' it turns on ADC, gets the temperature values and converts them to C and F. Then it will send everything over using the sendString function.
- If an unknown char is sent, then the help prompt will be sent that says what can letters do what.

```
void UARTIntHandler(void)
{
    uint32 t ui32Status;
    ui32Status = UARTIntStatus(UARTO BASE, true); //get interrupt status
    UARTIntClear(UART0 BASE, ui32Status); //clear the asserted interrupts
    uint32_t Vals[4];
    uint32_t Avg;
    uint32 t TempC, TempF;
    char Cel[10];
    char Far[10];
    char command;
    command = UARTCharGet(UART0_BASE);
    if (command == 'R') { // turn on red LED
        UARTCharPut(UART0_BASE, command); // echo back letter
        GPIOPinWrite(GPIO_PORTF_BASE, GPIO_PIN_1, GPIO_PIN_1); } // turn on light
    else if (command == 'B'){ // same as above
        UARTCharPut(UART0 BASE, command);
        GPIOPinWrite(GPIO PORTF BASE, GPIO PIN 2, GPIO PIN 2); }
    else if (command == 'G') {
        UARTCharPut(UART0_BASE, command);
        GPIOPinWrite(GPIO_PORTF_BASE, GPIO_PIN_3, GPIO_PIN_3); }
    else if (command == 'r') { // turn off red LED
        UARTCharPut(UART0_BASE, command);
        GPIOPinWrite(GPIO_PORTF_BASE, GPIO_PIN_1, 0); } // turn off light
    else if (command == 'b') { // same as above
        UARTCharPut(UART0_BASE, command);
        GPIOPinWrite(GPIO PORTF BASE, GPIO PIN 2, 0); }
    else if (command == 'g') {
        UARTCharPut(UART0_BASE, command);
        GPIOPinWrite(GPIO PORTF BASE, GPIO PIN 3, 0); }
    else if (command == 'T') { // send temperature through UART
        UARTCharPut(UART0 BASE, command); // echo command
        ADCIntClear(ADC0_BASE, 1); // clear flag
        ADCSequenceEnable(ADC0 BASE, 1); // enable ADC
        ADCProcessorTrigger(ADC0_BASE, 1);
        while(!ADCIntStatus(ADC0_BASE, 1, false))
        {
        ADCSequenceDataGet(ADC0 BASE, 1, Vals); // get the 4 values
        Avg = (Vals[0] + Vals[1] + Vals[2] + Vals[3] + 2) / 4;
        // convert to C and F
        TempC = (1475 - ((2475 * Avg)) / 4096) / 10;
        TempF = ((TempC * 9) + 160) / 5;
        // convert int to string
        ltoa(TempF, Far);
        ltoa(TempC, Cel);
        // send statement through UART
        sendString("\r\nTemp = ");
        sendString(Cel);
```