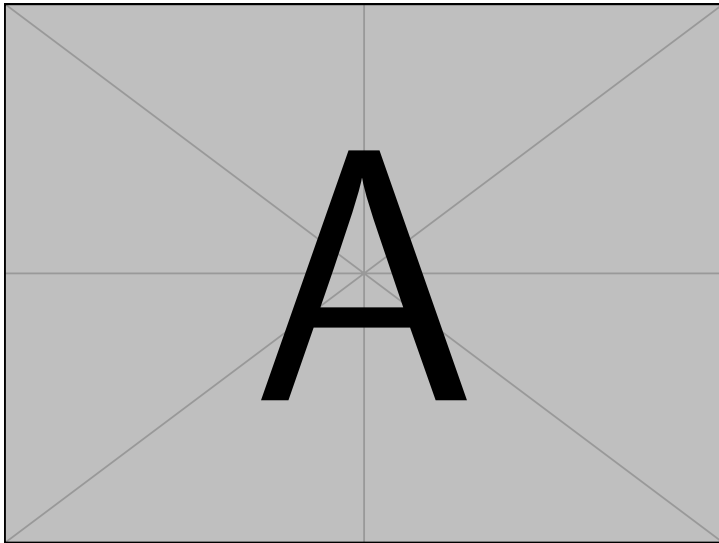


CEE212—Engineering Dynamics

Rigid Body Dynamics

Subtitle



GITMECHANICS

Brian Chevalier

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1 Section One

```
for i in range(3):  
    print(i)
```

```
0  
1  
2
```

2 Integrating Python

```
import matplotlib.pyplot as plt  
import numpy as np
```