
IT2070 – Data Structures and Algorithms

Lecture 08

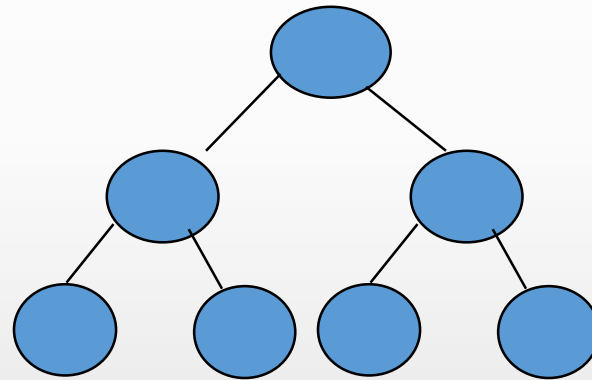
Heap Sort Algorithms

Contents for Today

- **Tree**
- **Binary Tree**
- **Complete Binary Tree**
- **Heaps**
- **Heap Algorithms**
 - Maintaining Heap Property
 - Building Heaps
 - HeapSort Algorithms

Height of a Full Binary Tree

- A Full binary tree of height **h** that contains exactly $2^{h+1}-1$ nodes

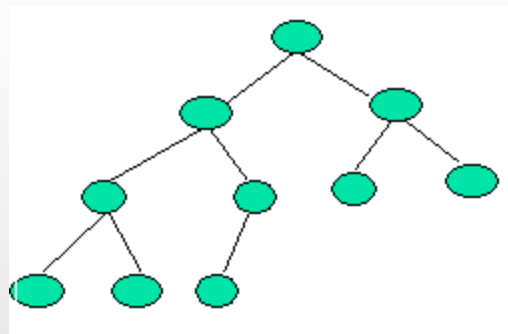


Height, **h** = 2, nodes = $2^{2+1}-1=7$

Height of a complete binary tree

Height of a complete binary tree that contains n elements is $\lfloor \log_2(n) \rfloor$

Example



- Above is a Complete Binary Tree with height = 3
- No of nodes: $n = 10$
- Height = $\lfloor \log_2(n) \rfloor = \lfloor \log_2(10) \rfloor = 3$

Heaps

Heap is an array object that can be viewed as a complete binary tree. There are two kinds of heaps

max heaps and **min heaps**

In both case, values in the nodes satisfy **Heap Property** which depend on the kind of heap

max-heap → max-heap property:

The value of each node is greater than or equal to those of its children.

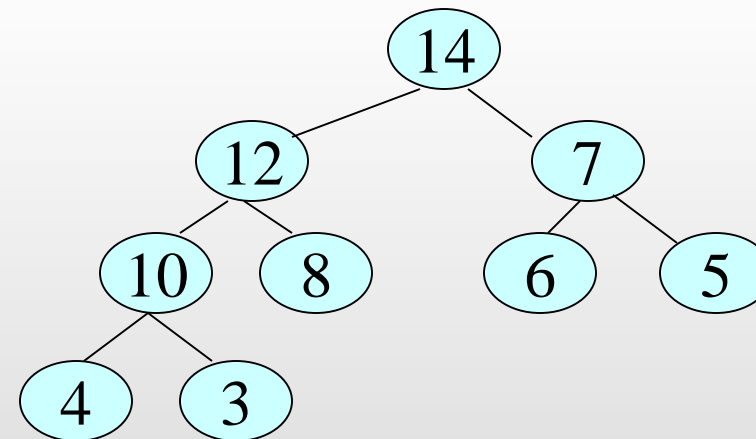
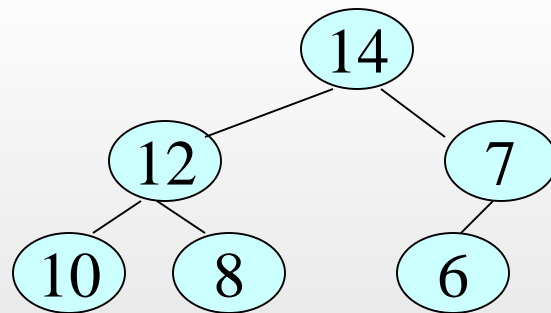
min-heap → min-heap property:

The value of each node is less than or equal to those of its children.

Max-heaps are used in heapsort algorithm

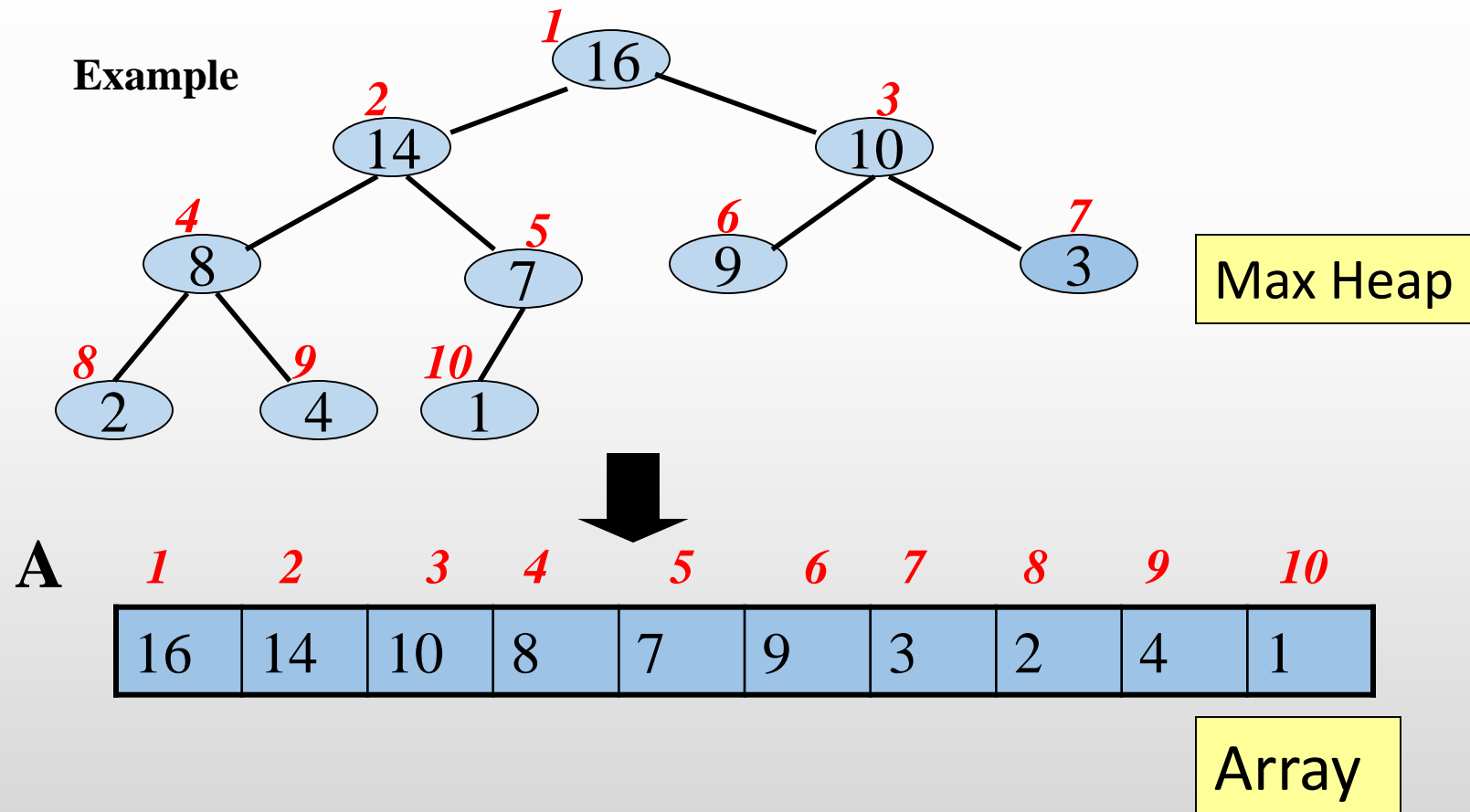
Heaps

Complete Binary Tree with the max-heap property - examples



Heaps (contd.)

- A heap can be represented in a one-dimensional array



Heaps (contd.)

After representing a heap using an array **A**

- Root of the tree is **A[1]**

| | | | | | | | | | | |
|---|----|----|----|---|---|---|---|---|---|----|
| A | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 |
| | 16 | 14 | 10 | 8 | 7 | 9 | 3 | 2 | 4 | 1 |

Given node with index i ,

- **PARENT(i)** is the index of parent of i ;
$$\text{PARENT}(i) = \lfloor i/2 \rfloor$$
- **LEFT_CHILD(i)** is the index of left child of i ;
$$\text{LEFT_CHILD}(i) = 2 \times i$$
- **RIGHT_CHILD(i)** is the index of right child of i ;
$$\text{RIGHT_CHILD}(i) = 2 \times i + 1$$

Heap Algorithms

- **MAX_HEAPIFY:**

To maintain max-heap property

$$A[PARENT(i)] \geq A[i]$$

- **BUILD_MAX_HEAP**

To build max-heap from an unsorted input array

- **HEAPSORT**

Sorts an array in place.

MAX_HEAPIFY

- The MAX_HEAPIFY algorithm checks the heap elements for violation of the heap property and restores max-heap property;

$$A[PARENT(i)] \geq A[i]$$

- Input:** An array **A** and index i to the array. $i = 1$ if we want to heapify the whole tree. Subtrees rooted at $LEFT_CHILD(i)$ and $RIGHT_CHILD(i)$ are heaps
- Output:** The elements of array **A** forming subtree rooted at i satisfy the heap property.

Maintaining the Heap Property

MAX_HEAPIFY (A, i)

1. $l = \text{LEFT}(i);$
2. $r = \text{RIGHT}(i);$
3. if $l \leq A.\text{heap_size}$ and $A[l] > A[i]$
4. $\text{largest} = l;$
5. else $\text{largest} = i;$
6. if $r \leq A.\text{heap_size}$ and $A[r] > A[\text{largest}]$
7. $\text{largest} = r;$
8. if $\text{largest} \neq i$
9. exchange $A[i]$ with $A[\text{largest}]$
10. **MAX_HEAPIFY** ($A, \text{largest}$)

Example

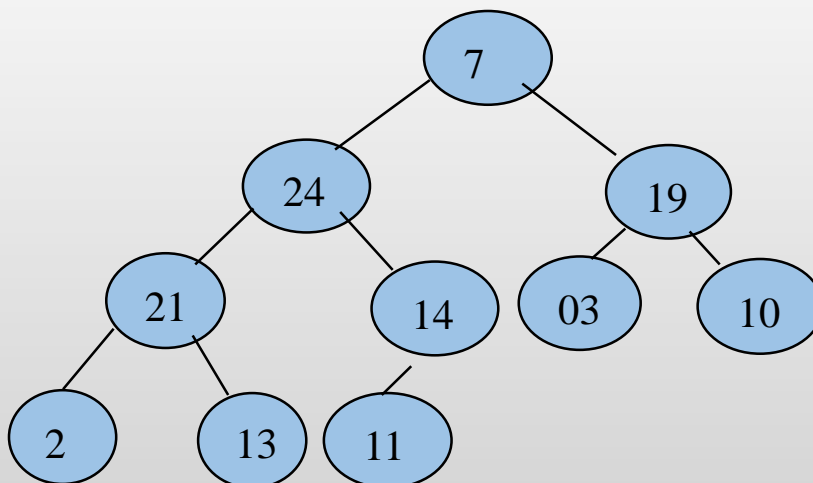
You are given the following array

A *1* *2* *3* *4* *5* *6* *7* *8* *9* *10*

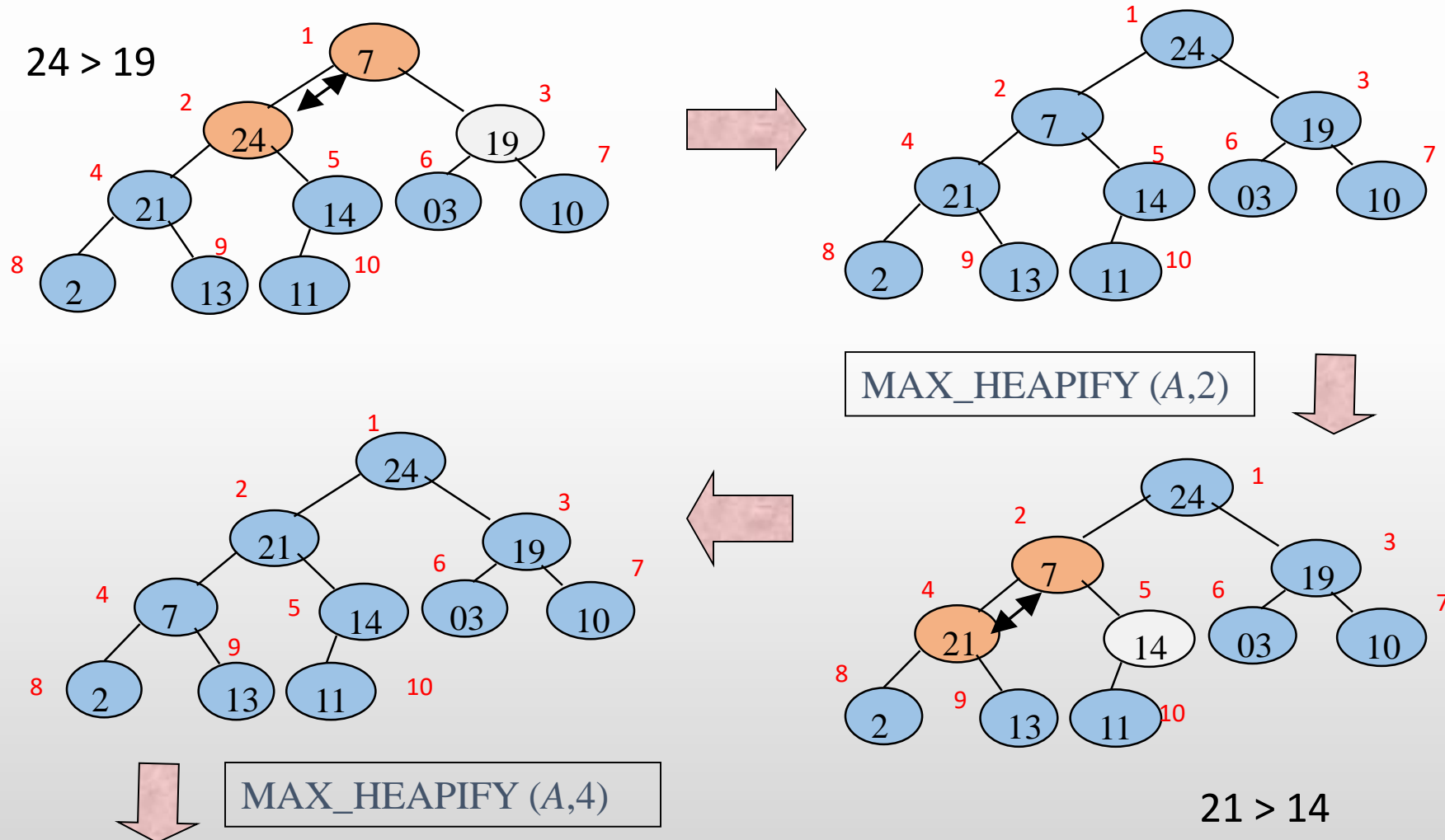
| | | | | | | | | | |
|---|----|----|----|----|----|----|---|----|----|
| 7 | 24 | 19 | 21 | 14 | 03 | 10 | 2 | 13 | 11 |
|---|----|----|----|----|----|----|---|----|----|

Now we are going to maintain the max-heap property

Drawing a heap would make our work easy

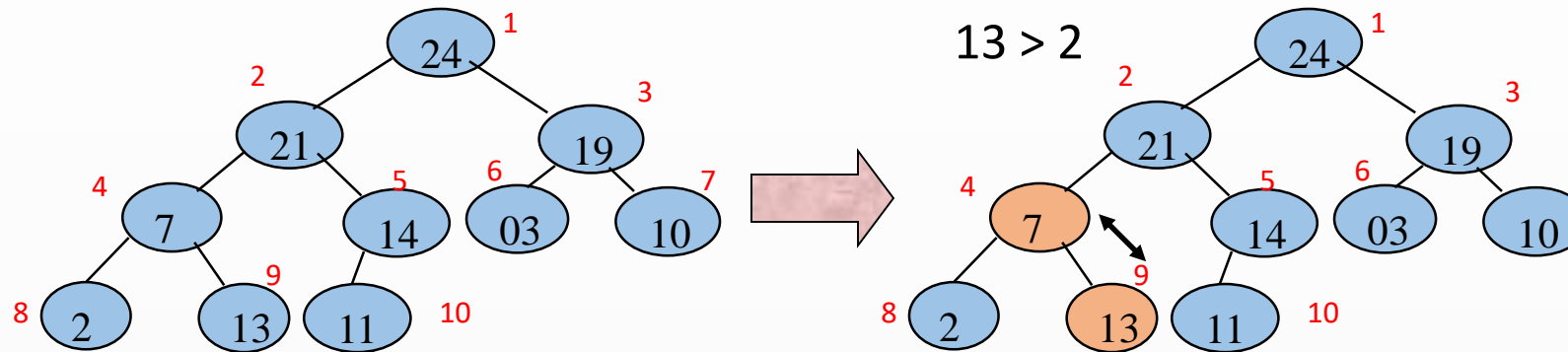


MAX_HEAPIFY (A,1)



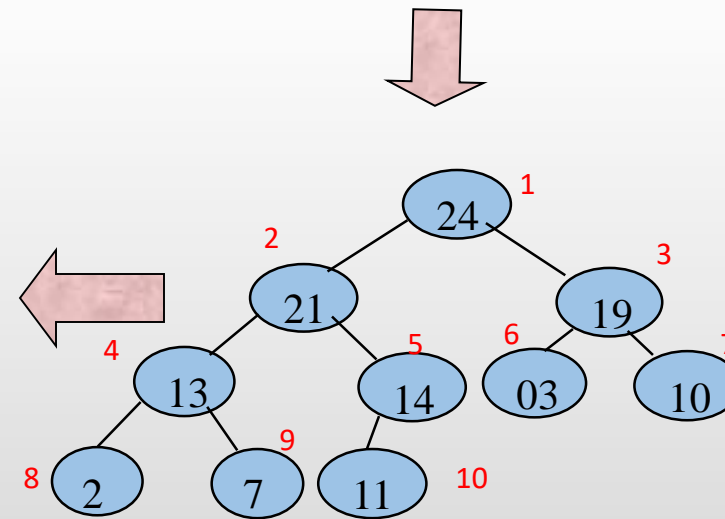
To be contd.

MAX_HEAPIFY (A,1) (contd.)



MAX_HEAPIFY (A,4)

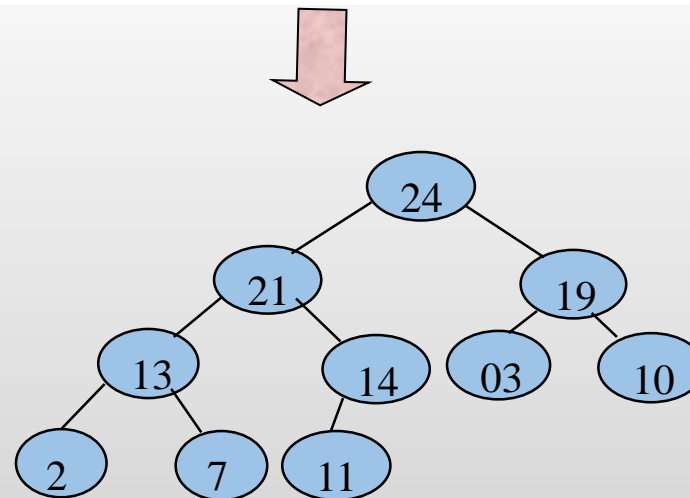
Important point Although we represent this process using a heap actually all the task is done on the input array



Resulting Heap

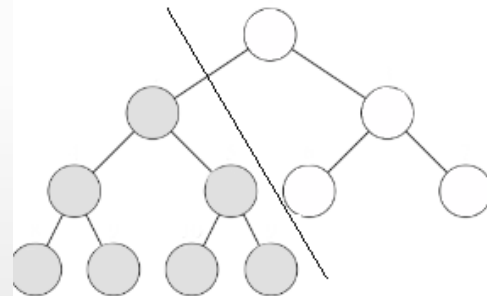
Array view of MAX_HEAPIFY Algorithm

| | | | | | | | | | |
|----------|-----------|----|-----------|----|----|----|----|-----------|----|
| <u>7</u> | <u>24</u> | 19 | 21 | 14 | 03 | 10 | 02 | 13 | 11 |
| 24 | <u>7</u> | 19 | <u>21</u> | 14 | 03 | 10 | 02 | 13 | 11 |
| 24 | 21 | 19 | <u>07</u> | 14 | 03 | 10 | 02 | <u>13</u> | 11 |
| 24 | 21 | 19 | 13 | 14 | 03 | 10 | 02 | 07 | 11 |



Analysis of Heapify Algorithm.

- The running time of MAX-HEAPIFY on a subtree of size n rooted at given node i is the $\Theta(1)$ time plus the time to run MAX-HEAPIFY on a subtree rooted at one of the children of node i .
- The children's subtrees -the worst case occurs when the last row of the tree is exactly half full



- Alternatively, we can characterize the running time of MAX-HEAPIFY on a node of height h as $O(h)$.

The solution to this recurrence is

$$T(n) = O(\lg n)$$

BUILD_HEAP

Input : An array A of size $n = A.length$, $A.heap_size$

Output : A heap of size n

BUILD_MAX_HEAP (A)

1. $A.heap_size = A.length$
2. **for** $i = \lfloor A.length/2 \rfloor$ **downto** 1
3. MAX_HEAPIFY(A, i)

Exercise: We are given the following unordered array to build the heap.

| A | <i>1</i> | <i>2</i> | <i>3</i> | <i>4</i> | <i>5</i> | <i>6</i> | <i>7</i> | <i>8</i> | <i>9</i> | <i>10</i> |
|----------|----------|----------|----------|----------|----------|----------|----------|----------|----------|-----------|
| | 4 | 1 | 3 | 2 | 16 | 9 | 10 | 14 | 8 | 7 |

Solution

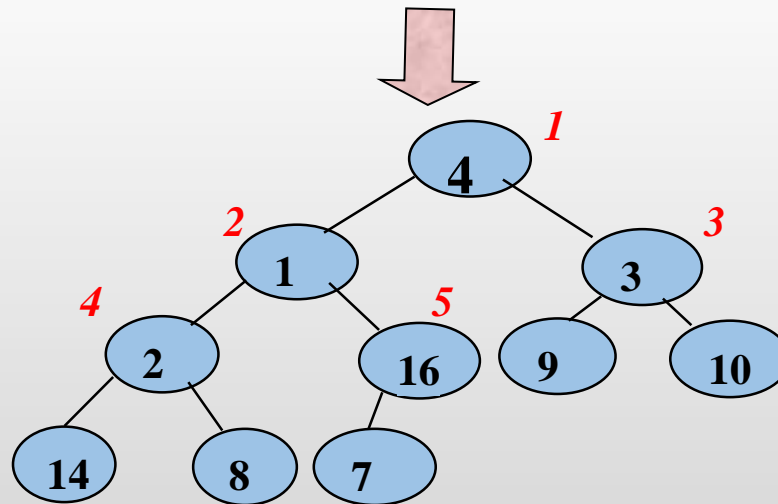
Step1

$$i = \lfloor \text{length}[A]/2 \rfloor = \lfloor 10/2 \rfloor = 5$$

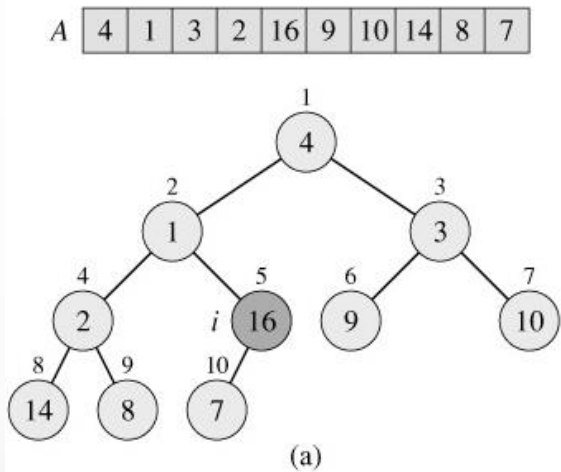
MAX_HEAPIFY(A,5)

A

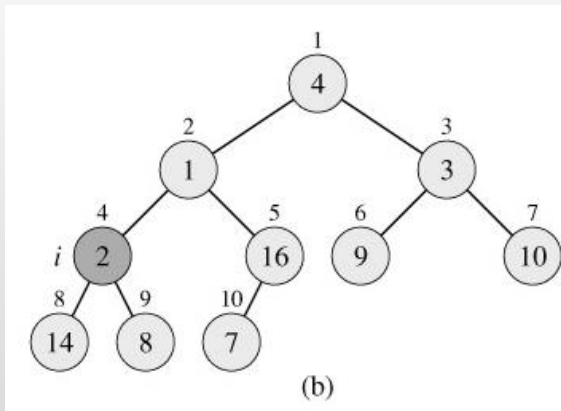
| | | | | | | | | | |
|----------|----------|----------|----------|----------|----------|----------|----------|----------|-----------|
| <i>1</i> | <i>2</i> | <i>3</i> | <i>4</i> | <i>5</i> | <i>6</i> | <i>7</i> | <i>8</i> | <i>9</i> | <i>10</i> |
| 4 | 1 | 3 | 2 | 16 | 9 | 10 | 14 | 8 | 7 |



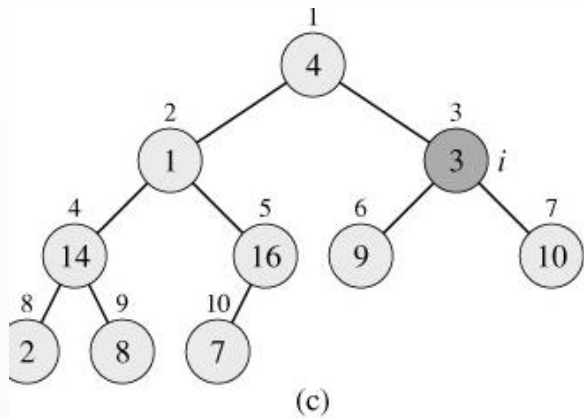
Solution (Contd.)



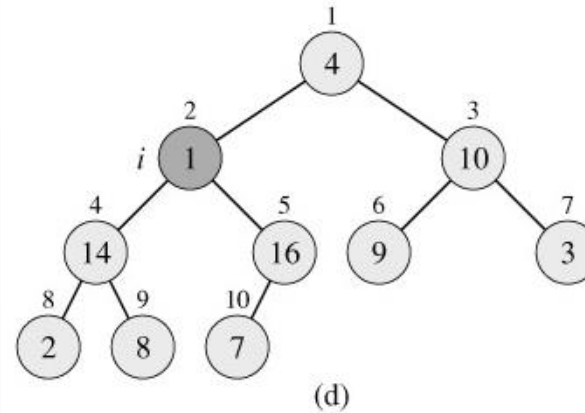
loop index i refers to node 5



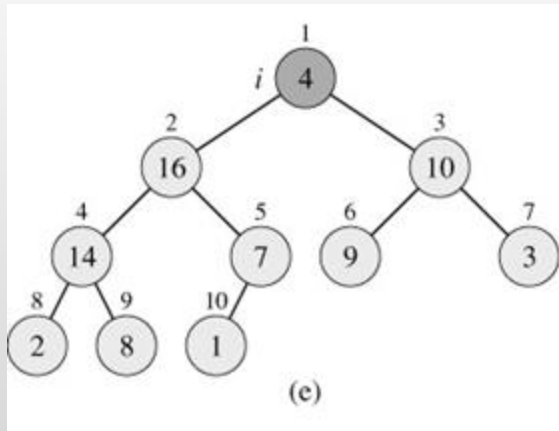
loop index i for the next iteration refers to node 4



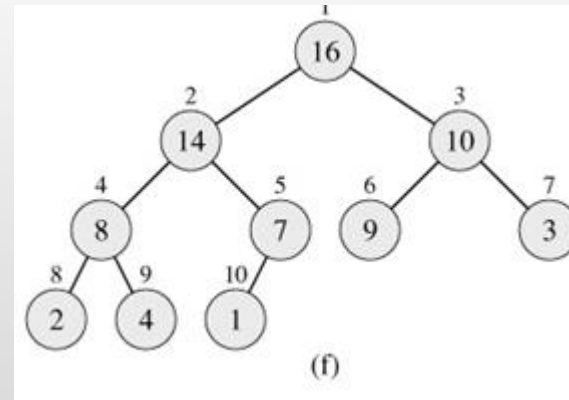
loop index i refers to node 3



loop index i refers to node 2



loop index i refers to node 1



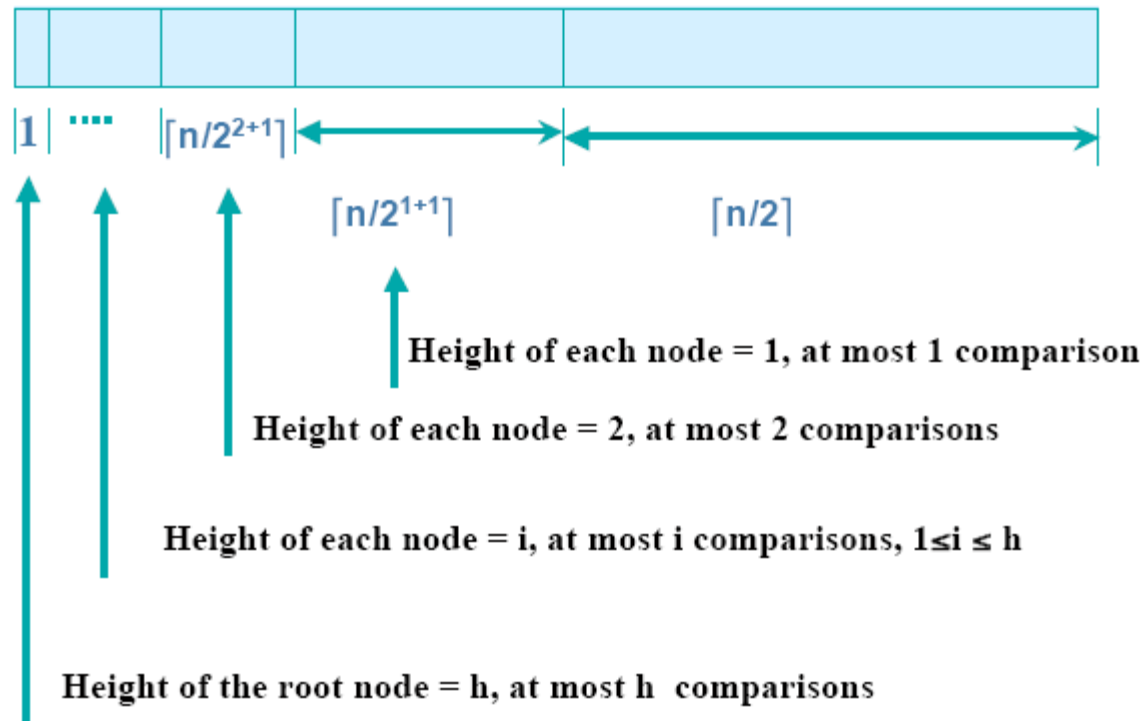
max-heap after BUILD-MAX-HEAP finishes.

Analysis of Build Max Heap Algorithm.

Time for MAX-HEAPIFY to run at a node varies with the height of the node in the tree, and the heights of most nodes are small.

- n -element heap has height $\lfloor \lg n \rfloor$
and
- at most $\lceil n/2^{h+1} \rceil$ nodes of any height h .

Analysis of Build Max Heap Algorithm.



Complexity analysis of Build-Heap (1)

- For each height $0 < h \leq \lg n$, the number of nodes in the tree is at most $n/2^{h+1}$
- For each node, the amount of work is proportional to its height h , $O(h) \rightarrow n/2^{h+1} \cdot O(h)$
- Summing over all heights, we obtain:

$$T(n) = \sum_{h=0}^{\lfloor \lg n \rfloor} \left\lceil \frac{n}{2^{h+1}} \right\rceil \cdot O(h) = O\left(n \sum_{h=0}^{\lfloor \lg n \rfloor} \left\lceil \frac{h}{2^{h+1}} \right\rceil \right)$$

Complexity analysis of Build-Heap (2)

- We use the fact that $\sum_{k=0}^{\infty} kx^k = \frac{x}{(1-x)^2}$ for $|x| < 1$

$$\sum_{h=0}^{\infty} \left\lceil \frac{h}{2^h} \right\rceil = \frac{1/2}{(1-1/2)^2} = 2$$

- Therefore:

$$T(n) = O\left(n \sum_{h=0}^{\lceil \lg n \rceil} \left\lceil \frac{h}{2^{h+1}} \right\rceil\right) = O\left(n \sum_{h=0}^{\infty} \left\lceil \frac{h}{2^h} \right\rceil\right) = O(n)$$

- Building a heap takes only linear time and space!

The HEAPSORT Algorithm

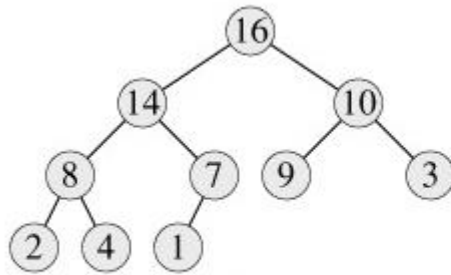
Input : Array $A[1 \dots n]$, $n = A.length$

Output : Sorted array $A[1 \dots n]$

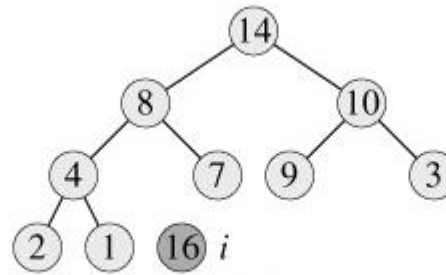
HEAPSORT(A)

1. BUILD_MAX_HEAP[A]
2. for $i = A.length$ down to 2
3. exchange $A[1]$ with $A[i]$
4. $A.heap_size = A.heap_size - 1$;
5. MAX_HEAPIFY(A, 1)

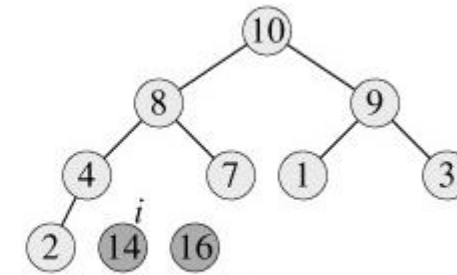
The operation of HEAPSORT.



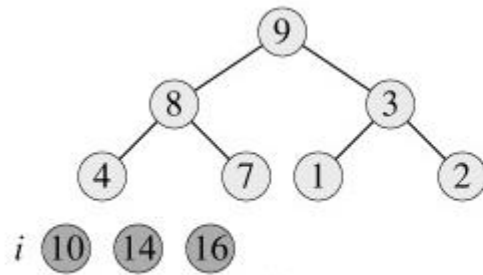
(a)



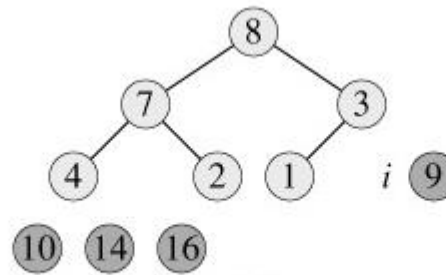
(b)



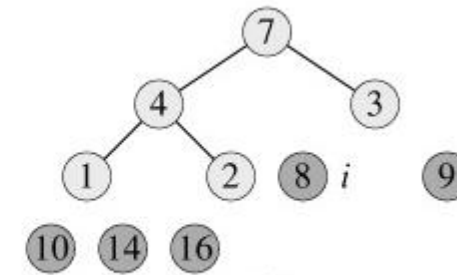
(c)



(d)

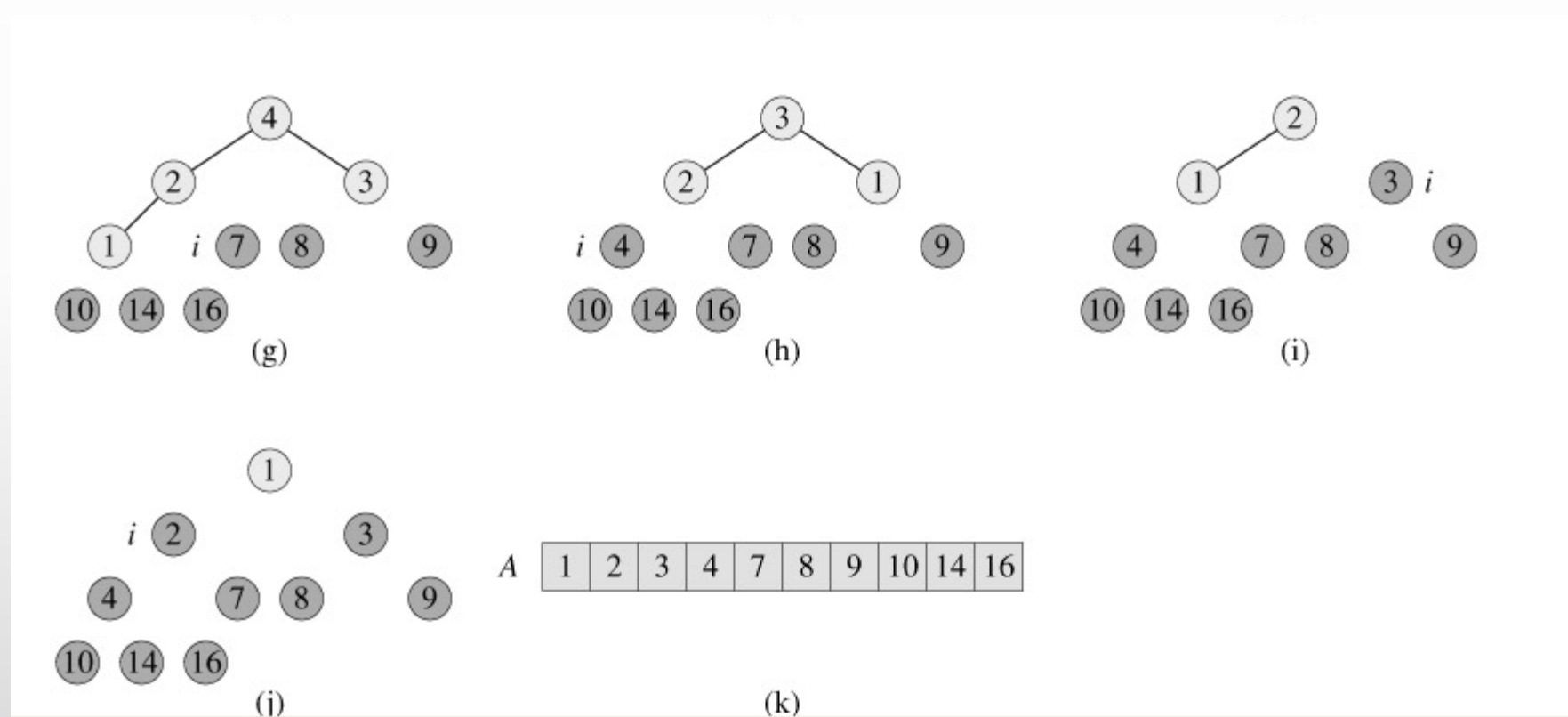


(e)



(f)

The operation of HEAPSORT.



Heapsort Complexity

Running Time:

Step1 : BUILD_MAX_HEAP takes $O(n)$

Step 2 to 5 : MAX_HEAPIFY takes $O(\log n)$ and there are $(n - 1)$ calls

Running Time is $O(n \log n)$

Priority Queues

- Heap data structure itself has many uses.
- One of the most popular applications of a heap: its use as an efficient **priority queue**.
- As with heaps, there are two kinds of priority queues:
 - max-priority queues
 - min-priority queues
- We will focus here on how to implement **max-priority queues**, which are in turn based on max-heaps

Priority queues.

- **priority queue** is a data structure for maintaining a set S of elements, each with an associated value called a **key**. A **max-priority queue** supports the following operations.
- $\text{INSERT}(S, x)$ inserts the element x into the set S . This operation could be written as $S = S \cup \{x\}$.
- $\text{EXTRACT-MAX}(S)$ removes and returns the element of S with the largest key.

Priority queues.

- One application of max-priority queues is to schedule jobs on a shared computer.

The max-priority queue keeps track of the jobs to be performed and their relative priorities. When a job is finished or interrupted, the highest-priority job is selected from those pending using EXTRACT-MAX. A new job can be added to the queue at any time using INSERT.

HEAP_EXTRACT_MAX

HEAP_EXTRACT_MAX(A[1 .. n])

This will remove the maximum element from heap and return it

Input : heap(A)

Output : Maximum element or root, heap(A[1..n-1])

1. if A.heap_size \geq 1
2. max = A[1]
3. A[1] = A[A.heap_size]
4. A.heap_size = A.heap_size - 1
5. MAX_HEAPIFY(A,1)
6. return max

Running time : $O(\log n)$

HEAP_INSERT

HEAP_INSERT(A, key)

This will add a new element to the heap

Input : heap(A[1..n]), key - the new element

Output : heap(A[1..n+1]), with k in the heap

1. A.heap_size = A.heap_size + 1
2. i = A.heap_size // assume $A[i] = -\infty$
3. while $i > 1$ and $A[\text{PARENT}(i)] < \text{key}$
4. $A[i] = A[\text{PARENT}(i)]$
5. $i = \text{PARENT}(i)$
6. $A[i] = \text{key}$

Running time : $O(\lg n)$

Summary

- Complete binary Tree
- Heap property
- Heap
- Maintaining heap Property(HEAPIFY)
- Building Heaps
- HeapSort Algorithm
- Priority queues.
- Heap Extract Max.
- Heap Insert.