

# Brian Sun

✉ [briansun997@gmail.com](mailto:briansun997@gmail.com) | 💻 [brians99.github.io](https://brians99.github.io) | 🐙 [github.com/brians99](https://github.com/brians99) | 🔗 [linkedin.com/in/briansun1](https://linkedin.com/in/briansun1)

## EDUCATION

### University of British Columbia

Sep 2019 – May 2024 (Expected)

*Bachelor of Applied Science in Engineering Physics*

*Vancouver, BC*

**Coursework:** Instrument Design, Software Construction, Machine Learning, Digital Systems and Microcomputers

## SKILLS

**Languages:** Java, C, C++, Python, JavaScript, Bash, PowerShell, Matlab

**Frameworks:** React, Node.js, Spring Boot, MongoDB, ROS, OpenCV, JUnit, GTest

**Tools/Environment:** Git, Azure, Linux, VS Code, Visual Studio, IntelliJ, Jupyter, Arduino IDE

## EXPERIENCE

### Site Reliability Engineer Intern

Jan 2021 – Apr 2021

*Oxford Properties Group*

*Toronto, ON*

- Developed scalable and well-tested automation code using Python and Powershell and deployed on Azure DevOps.
- Automated employee off-boarding using a script to improve process efficiency by up to 200%.
- Renovated security across DevOps code base of over 8000 lines by implementing Azure Key Vault authentication.
- Managed projects of 10 other developers following Agile principles, using Jira to organize work.

### Software Developer

Sep 2020 – Present

*UBC Thunderbots Design Team*

*Vancouver, BC*

- Developed soccer-playing AI in C++ on Linux OS while collaborating with over 15 developers.
- Built unit testing frameworks using GTest for firmware primitives to increase code coverage by 35%.
- Implemented a view reset button for robot simulator, improving debugging efficiency by 25% for software team.
- Revamped playing tactics to follow competition rules, making robots drive slowly when referee stops game.

## PROJECTS

### Self-Driving Car Simulation | *Python, ROS, OpenCV, TensorFlow, Linux*

Jan 2022 - Feb 2022

- Developed algorithm in Python using OpenCV for lane following, traffic avoidance, and reading license plates.
- Built robot model and simulation in ROS and implemented 3 plugins such as a camera.
- Performed testing and evaluated over 15 driving algorithms in Gazebo.

### NwHacks 2022 - Education Website | *React, Spring Boot, Node.js, MongoDB, Auth0*

Jan 2022

- Developed full-stack web application allowing users to create, view, and study interactive lessons.
- Spearheaded front-end design with React and created over 10 components, including a multiple-choice quiz editor.
- Developed RESTful APIs to serve the React front-end, and which interact with a MongoDB database.
- Implemented Auth0 API to authenticate users, which allows for a personalized UI.

### Sample-Retrieving Robot | *C++, STM32 BluePill, VS Code, PlatformIO*

May 2021 - Aug 2021

- Designed and fabricated 3 autonomous robots including writing software, designing and soldering controller boards, and manufacturing mechanical parts.
- Developed a Finite State Machine software architecture, allowing robot to drive, operate arm, and drop-off cans.
- Implemented and tuned a PID driving algorithm to read from 2 sensors and make robot follow a tape path.
- Placed 3rd place in final competition out of 16 teams based on robot performance.

### Helper Discord Bot | *JavaScript, Node.js, VS Code*

Dec 2020

- Developed a Discord bot using JavaScript on VSCode to interact with the Discord API and moderate 2 servers.
- Incorporated over 5 functionalities such as displaying menus, math calculations, and custom replies.
- Analyzed documentation of discord.js library to debug and ensure the implementation is correct.

### Virtual World Simulation | *Java, JUnit, IntelliJ*

Sep 2020 - Oct 2020

- Built Java program that supports a virtual world in which 10+ entities interact with one another on a 2D field.
- Developed AI for fox and rabbit entity to maximize survival rate and scored in the top 25% of the competition.
- Wrote unit testing frameworks using JUnit for over 8000+ lines of code and used a GUI to visualize the world.