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MKS TFT28 Wifi Communication Instruction

Link: TCP socket

Communication instruction

- 1. Each instruction ends with Enter button;
- All gcode instruction forwards directly to the motherboard, in addition to special instruction in attached list, but go back to "ok\r\n";
- 3. Send-receive explanation on special instruction format:

Instruction Type	Corresponding operation
Modify the current file	 Return to "ok\r\n"
system:	2. Invoke connector of alter file system, the
M998 0: set the file system	parameter is 0 or 1
as U disk	
M998 1: set the file system	
as SD card	
Get the printer's current state:	Return state:
M997	1. "M997 IDLE\r\n": free
	2. "M997 PRINTING\r\n": printing
	3. "M997 PAUSE\r\n": pause printing
List gcode file:	 Return to "ok\r\n"
M20 xxx	2. If xxx is empty, it means that lists the
	files in the root directory of the current
	system; otherwise, list the file by xxx
	designating
	3. Return to "Begin file list\r\n"
	4. return to filelist
	5. Return to "End file list\r\n"
Choose the specified	 Return to "ok\r\n"
file (folder)	2. Invoke connector of the specified file,
M23 xxx.gcode	the parameter is xxx.gcode

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Start(recover) file printing M24 2.Invoke connector of starting(recovering) printing Pause file printing M25 2. Invoke connector of pause file printin Cancel file printing M26 Report process of printing M27 M27 2. Invoke connector of canceling printing 1. Return to "ok\r\n" 2. Invoke connector of canceling printing 1. Return to "ok\r\n" 2. Invoke connector on process report of printing and return to it by "M27 xxx\r\n" format Delete file 1. Return to "ok\r\n"	g file
printing Pause file printing 1. Return to "ok\r\n" 2. Invoke connector of pause file printing M26 Report process of printing M27 M27 Pause file printing 1. Return to "ok\r\n" 2. Invoke connector of canceling printing 1. Return to "ok\r\n" 2. Invoke connector on process report of printing and return to it by "M27 xxx\r\n" format	g file
Pause file printing M25 Cancel file printing M26 Report process of printing M27 M27 A Return to "ok\r\n" 1. Return to "ok\r\n" 2. Invoke connector of canceling printing 1. Return to "ok\r\n" 2. Invoke connector of canceling printing 1. Return to "ok\r\n" 2. Invoke connector on process report of printing and return to it by "M27 xxx\r\n" format	file
 M25 Cancel file printing M26 Report process of printing M27 Acturn to "ok\r\n" Return to "ok\r\n" Return to "ok\r\n" Return to "ok\r\n" Acturn to "ok\r\n"<!--</td--><td>file</td>	file
Cancel file printing M26 Report process of printing M27 M27 And the printing of the print	file
M26 Report process of printing M27 2. Invoke connector of canceling printing 1. Return to "ok\r\n" 2. Invoke connector on process report of printing and return to it by "M27 xxx\r\n" format	
Report process of printing M27 2.Invoke connector on process report of printing and return to it by "M27 xxx\r\n" format	
M27 2.Invoke connector on process report of print and return to it by "M27 xxx\r\n" format	ting,
and return to it by "M27 xxx\r\n" format	ting,
Delete file 1. Return to "ok\r\n"	
M30 xxx.gcode 2. Invoke connector of deleting file,	the
parameter is xxx.gcode	
Choose and print the 1. Return to "ok\r\n"	
specified file 2. Invoke connector of the specified	file,
M32 xxx.gcode the parameter is xxx.gcode	
3. Invoke connector of starting file print	ng
Start writing the specified file 1. Return to "ok\r\n"	
to current directory 2. Invoke connector of opening file	and
M28 xxx.gcode create file, the parameter is xxx.gcode	
3. Write the Data received into the file	by
additional data	
Check temperature: 1. Return to temperature string	
M105	
Turn off motor Return to "ok\r\n"	
M84	
Modify motion coordinates to Return to "ok\r\n"	
absolute coordinates	
G91	
Modify motion coordinates to Return to "ok\r\n"	
relative coordinates	
G90	
Control X-axis motion xxx is moving distance, unit: mm	
G1 X xxx F yyy yyy is moving speed, unit: mm/min	
Control Y-axis motion xxx is moving distance, unit: mm	
G1 Y xxx F yyy yyy is moving speed, unit: mm/min	
Control Z-axis motion xxx is moving distance, unit: mm	
G1 Z xxx F yyy yyy is moving speed, unit: mm/min	
X-axis go back to zero Return to "ok\r\n"	
G28 X0	

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Y-axis back to zero	Return to "ok\r\n"
G28 Y0	
Z-axis back to zero	Return to "ok\r\n"
G28 Z0	
Tri-axial back to zero	Return to "ok\r\n"
G28	
Control the printhead out	xxx is extrusive distance , unit: mm
G1 Exxx Fyyy	yyy is extrusive speed, unit: mm/min
Set printhead temperature	xxx is degree centigrade
M104 Sxxx	
Set heated-bed temperature	xxx is degree centigrade
M140 Sxxx	