

Algorithm Engineering Lab Assignment 6

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1. Name some characteristics of the instructions sets: SSE, AVX(2) and AVX-512.

SSE is one of the first vector instruction sets. It was released first in 1999. Due to a maximal vector size of 128 bit, operations on vectors within four single-precision floating-point scalars can be executed at once. By reading the produced assembler code of a program, SSE vectors can be identified. The appropriate register names are xmm0 to xmm15.

AVX is available since 2011, and the extended version of **AVX2** since 2013. They enable the use of vector registers with a size of 256 bits. Thus AVX allows working with vectors containing up to eight floating-point scalars. AVX vectors can be identified by the register names ymm0 to ymm15 in assembly.

AVX-512 is the third version of AVX. Processors released after 2017 may support this instruction set. It provides vectors with a length of 256 bits. These vectors can be spotted in assembler code by the registers ymm0 to ymm31.

2. How can memory aliasing affect performance?

Memory aliasing occurs if two pointers are pointing to overlapping memory locations. When the compiler does not know whether memory aliasing is possible or not, it has to consider that it happens. That disables optimizations of the compiler, such as vectorization and thus slows down the program.

3. What are the advantages of unit stride (stride-1) memory access compared to accessing memory with larger strides (for example, stride-8)?

Operating with unit stride access is described by working sequentially with each element of an array. It allows using the full memory bandwidth in contrast to accessing memory in larger strides. That is essential when an algorithm is memory intensive. Unit stridden memory access also enables vectorization. To execute vector operations with larger strided memory access, the vector has to be gathered first.

4. When would you prefer arranging records in memory as a Structure of Arrays?

Structures of arrays (SoA) are favourable when an algorithm operates more often on a specific variable of a structure and less often on whole structures. For example, if the goal is to determine the average for every single variable of a structure, using the SoA approach should deliver results faster. That can be explained by having a look at the different memory usage.

A typical field of application for **array of structures** (AoS) is object-oriented programming. In this case, the structures correspond to the classes. Code written in this style is often easier to understand. AoS is often used when performance does not matter that much or is not critical sections.