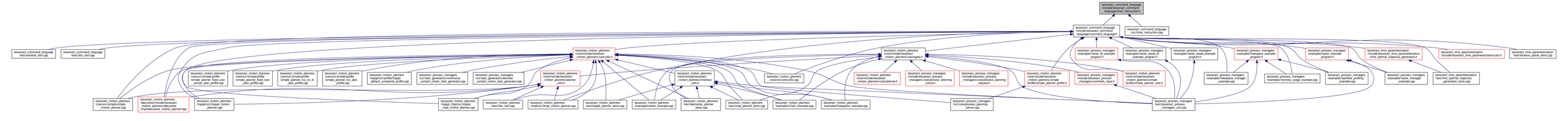
tesseract_command_language /include/tesseract_command_language/serialize_instruction.h
tesseract_command_language /include/tesseract_command_language/command_language.h
tesseract_command_language /src/serialize_instruction.cpp
tesseract_command_language /test/serialize_test.cpp
tesseract_command_language /test/utils_test.cpp
tesseract_motion_planners /include/tesseract_motion_planners/core/utils.h
tesseract_motion_planners /include/tesseract_motion_planners/core/types.h
tesseract_process_managers /include/tesseract_process_managers/task_input.h
tesseract_process managers /examples/freespace_example /program.h
tesseract_process managers /examples/cartesian_example /program.h
tesseract_process managers /examples/simple_example /program.h
tesseract_process managers /examples/freespace_example /program.h
tesseract_process managers /examples/cartesian_example /program.h
tesseract_process managers /examples/simple_example /program.h
tesseract_time_parameterization /include/tesseract_time_parameterization/time_optimal_trajectory_generation.h
tesseract_time_parameterization /include/tesseract_time_parameterization/utils.h
tesseract_time_parameterization /test/iterative_spline_tests.cpp
tesseract_motion_planners /core/src/simple/profile /simple_planner_fixed_size /assign_plan_profile.cpp
tesseract_motion_planners /core/src/simple/profile /simple_planner_fixed_size /plan_profile.cpp
tesseract_motion_planners /core/src/simple/profile /simple_planner_lvs_no_lp /plan_profile.cpp
tesseract_motion_planners /core/src/simple/profile /simple_planner_lvs_no_lp /assign_plan_profile.cpp
tesseract_motion_planners /trajopt_ros/profile/trajopt /default_composite_profile.cpp
tesseract_process_managers /src/task_generators/continuous /contact_check_task_generator.cpp
tesseract_process_managers /src/task_generators/discrete /contact_check_task_generator.cpp
tesseract_motion_planners /core/include/tesseract_motion_planners/planner /utils.h
tesseract_motion_planners /core/include/tesseract_motion_planners/interface /utils.h
tesseract_motion_planners /core/src/core/utils.cpp
tesseract_motion_planners /include/tesseract_process managers/core/process_planning /future.h
tesseract_process managers /include/tesseract_process managers/core/process_planning /request.h
tesseract_motion_planners /core/include/tesseract_motion_planners/simple /profile/simple_planner_profile.h
tesseract_process managers /include/tesseract_process managers/core/task_input.h
tesseract_motion_planners /core/include/tesseract_motion_planners/simple /profile/simple_planner_utils.h
tesseract_motion_planners /core/src/simple/simple /motion_planner.cpp
tesseract_motion_planners /descartes/include/tesseract_motion_planners/descartes /impl/descartes_motion_planner.hpp
tesseract_motion_planners /trajopt_ros/trajopt /motion_planner.cpp
tesseract_motion_planners /trajopt_ros/trajopt /flat_motion_planner.cpp
tesseract_motion_planners /test/trajopt_test.cpp
tesseract_motion_planners /simple/src/simple_motion_planner.cpp
tesseract_motion_planners /test/trajopt_planner_tests.cpp
tesseract_motion_planners /examples/raster_example.cpp
tesseract_motion_planners /test/simple_planner_tests.cpp
tesseract_motion_planners /test/simple_planner_tests.cpp
tesseract_motion_planners /examples/chain_example.cpp
tesseract_motion_planners /examples/freespace_example.cpp
tesseract_process managers /src/core/process_planning /server.cpp
tesseract_process managers /test/tesseract_process_managers_unit.cpp
tesseract_process managers /examples/freespace_example /example.cpp
tesseract_process managers /examples/memory_usage_example.cpp
tesseract_process managers /examples/taskflow_profiling /example.cpp
tesseract_process managers /examples/raster_manager /example.cpp
tesseract_time_parameterization /test/time_optimal_trajectory_generation_tests.cpp