

tesseract\_planning  
::TaskGenerator



```
graph BT; A[tesseract_planning::FixStateBoundsTaskGenerator] --> B[tesseract_planning::TaskGenerator];
```

The diagram illustrates an inheritance relationship. A light gray box at the bottom represents the base class, `tesseract_planning::FixStateBoundsTaskGenerator`. A dark blue arrow points vertically from the top center of this box to the bottom center of a white box above it. The white box represents the derived class, `tesseract_planning::TaskGenerator`.

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