

实验 4

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学校地图

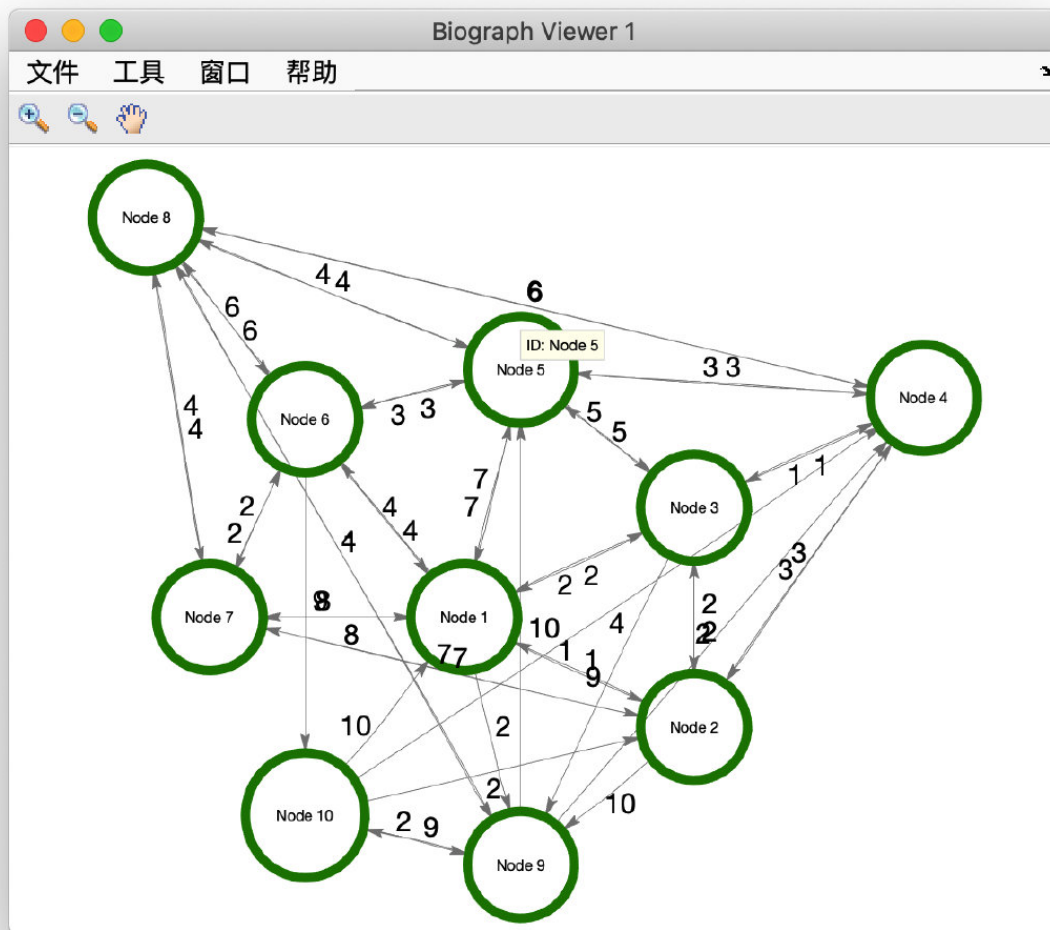
matlab

```
1  clc;clear;
2  n=10;    %设置矩阵大小
3  temp=1;  %设置起始点
4  m=zeros(n);%定义n阶零矩阵
5  %设置矩阵中非零非无穷的值
6  m(1,2)=1;m(1,3)=2;m(1,5)=7;m(1,6)=4;m(1,7)=8;m(1,9)=2;
7  m(2,1)=1;m(2,3)=2;m(2,4)=3;m(2,7)=7;m(2,9)=10;
8  m(3,1)=2;m(3,2)=2;m(3,4)=1;m(3,5)=5;m(3,9)=9;
9  m(4,2)=3;m(4,3)=1;m(4,5)=3;m(4,8)=6;
10 m(5,1)=7;m(5,3)=5;m(5,4)=3;m(5,6)=3;m(5,8)=4;
11 m(6,1)=4;m(6,5)=3;m(6,7)=2;m(6,8)=6;m(6,10)=9;
12 m(7,1)=8;m(7,2)=7;m(7,6)=2;m(7,8)=4;
13 m(8,4)=6;m(8,5)=4;m(8,6)=6;m(8,7)=4;m(8,9)=4;
14 m(9,4)=2;m(9,5)=10;m(9,8)=1;m(9,10)=9;
15 m(10,9)=12;m(10,1)=10;m(10,2)=2;m(10,4)=4;m(10,9)=2;
16 IDS={'A','B','C','D','E','F','G','H','I','J','K'};
17
18  bg=biograph(m,IDS);
19
20  set(bg.nodes,'shape','circle','color',[1,1,1],'lineColor',[0.1,0.5,0]);
21
22  set(bg,'layoutType','radial');
23
24  bg.showWeights='on';
25
26  set(bg.nodes,'textColor',[0,0,0],'lineWidth',5,'fontSize',8);
27
28  set(bg,'arrowSize',5,'edgeFontSize',15);
29
30  get(bg.nodes,'position')
31
32  view(bg);
33  for i=1:n
34      for j=1:n
35          if(m(i,j)==0)
36              m(i,j)=inf;
37          end
38      end
```

```

39     end
40
41     for i=1:n
42         m(i,i)=0;
43     end
44     pb(1:length(m))=0;pb(temp)=1;%求出最短路径的点为1，未求出的为0
45     d(1:length(m))=0;%存放各点的最短距离
46     path(1:length(m))=0;%存放各点最短路径的上一点标号
47
48     while sum(pb)<n %判断每一点是否都已找到最短路径
49         tb=find(pb==0);%找到还未找到最短路径的点
50         fb=find(pb);%找出已找到最短路径的点
51         min=inf;
52         for i=1:length(fb)
53             for j=1:length(tb)
54                 plus=d(fb(i))+m(fb(i),tb(j)); %比较已确定的点与其相邻未确定点的距离
55                 if((d(fb(i))+m(fb(i),tb(j)))<min)
56                     min=d(fb(i))+m(fb(i),tb(j));
57                     lastpoint=fb(i);
58                     newpoint=tb(j);
59                 end
60             end
61         end
62         d(newpoint)=min;
63         pb(newpoint)=1;
64         path(newpoint)=lastpoint;%最小值时的与之连接点
65     end
66
67
68     % help biograph
69     d
70     path
71
72

```



$d =$

0 1 2 3 6 4 6 3 2 11

path =

0 1 1 3 4 1 6 9 1 9