Team 2:

Yash Modi

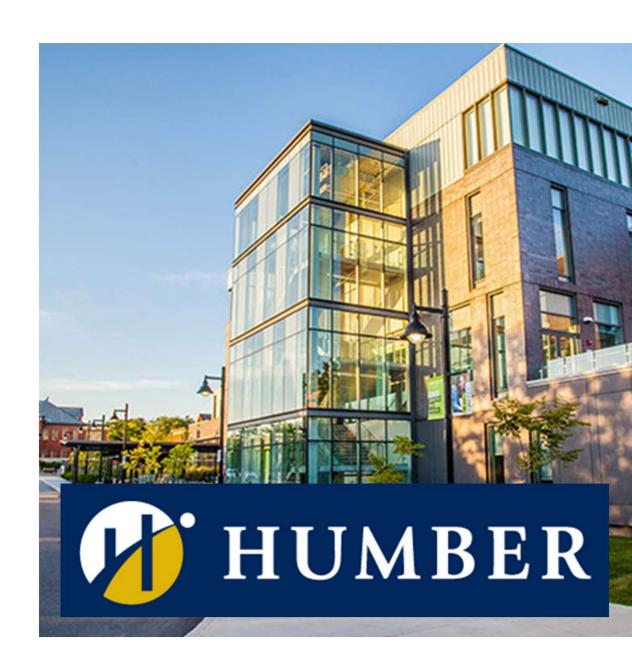
Owen Laing

Bailey Liang

Abbas Vaziri

Milin Vaniyawala

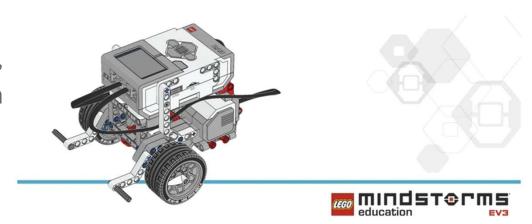
Hanze Liu



Autonomous Driving Cars

Functionality

This will be a core system useable by other systems in BrickMMO. This system lets a user point a location to the vehicle, then the vehicle will drive to that location automatically.



Dependency

This system will be dependant on :

GPS System
Charging system
Speed-Control system



3. Settings and Info

Settings & State

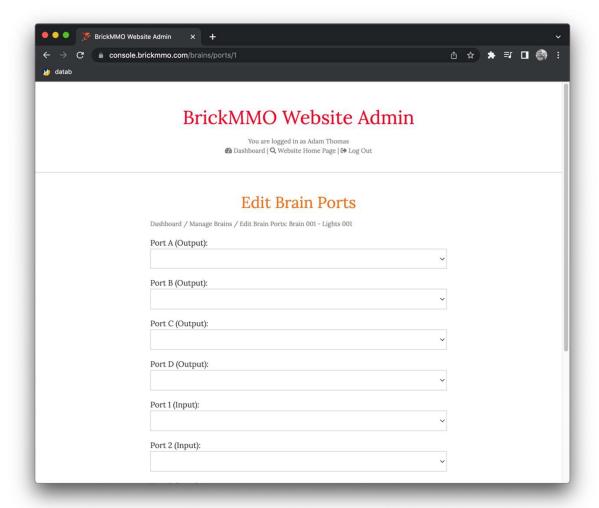
Vehicle ID: Unique ID for API calls

Vehicle state: On / Off

Destination: GPS Location

Route Traffic: Retrieve from GPS

Battery Level: 0 - 100%



Module Input / Output

Inputs

Destination: GPS Location

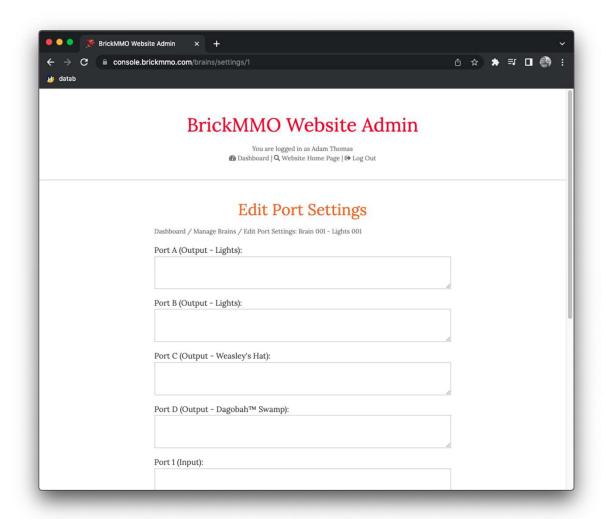
Outputs

Shortest Path to Destination: Route

Estimated time to Destination : Integer

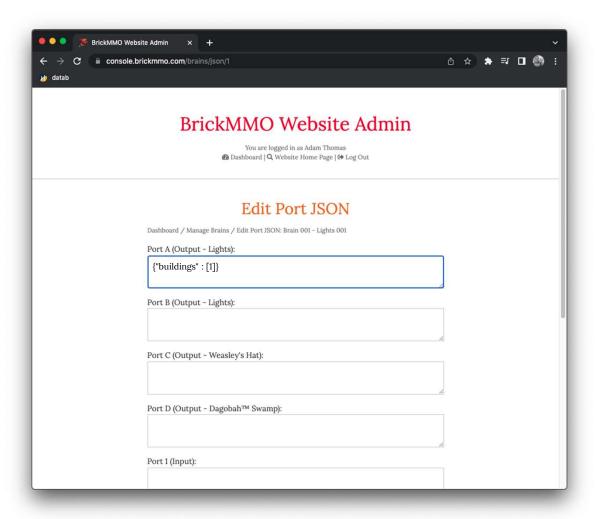
Has enough charge to reach Destination

: Boolean



Possible Integrations

This core system can possibly be integrated into a future public transit system, or ride share like Uber.



4. Ports, Motors, and Settings

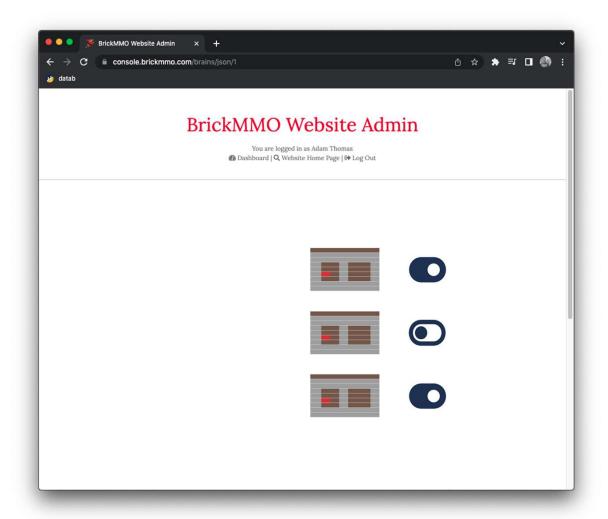
Sensors and Motors

- EV3 Hub (Brain, receives inputs)
- EV3 Medium Motor to turn infrared sensor
- EV3 Large Motor for accelerating / stopping / turning
- Infrared Sensors / Radar (Measure distance to nearby objects, aid in maneuvering)



Admin Control Panel

- 1. Managing vehicle condition
 - Checking battery
 - Checking sensor
- 1. Parking spot



5. Pseudocode

IOT Loop

if carCharged:
set coordinates;

while reachedToCoordinates: if obstacle || traffic

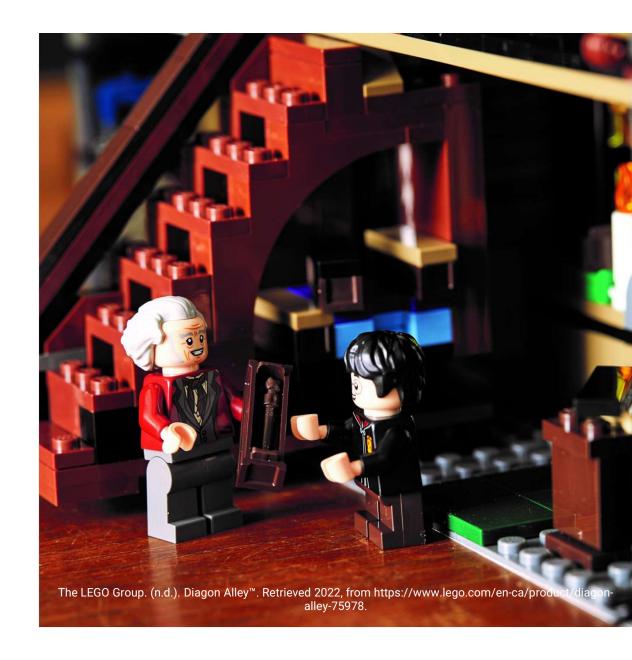
signal

slowDown or stop; else if emptyRoad

maintainSpeed;

else:

Use chargingStation;



API Endpoints

/api/vehicle/info/{vehicle-id}

Returns the vehicle information of the specified vehicle. E.g Battery

Percentage, Estimated time to location, etc.

/api/vehicle/destination/[vehicle-id]/{gps-location}/

Tells the specified vehicle id to goto the specified location.

