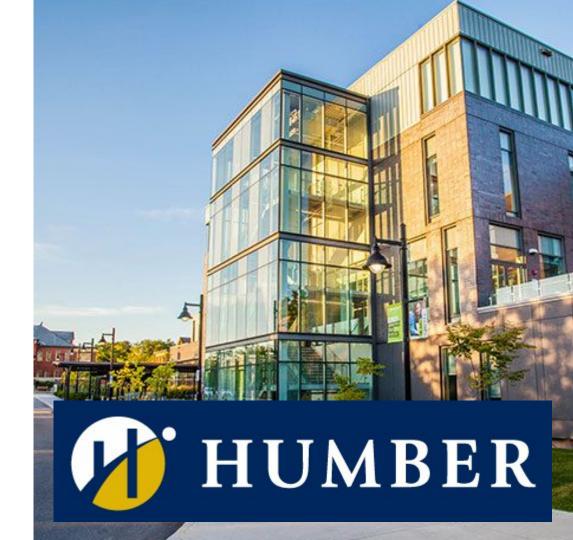
## Lifting Bridge Group 1

Hannah Quintos Melissa De Leon Surbhi Singhania Lovepreet Singh Nhi Nguyen Khushiben Patel



# Functionality and Dependency

Lifting Bridge will connect to EV3

This system will be dependent on the GPS system

**GPS** will have access to location of ships and trains

Lifting bridge will have access to the GPS

Lifting bridge will connect to spike hubs (audio, lights, motors, sensors)



# **Dependency**

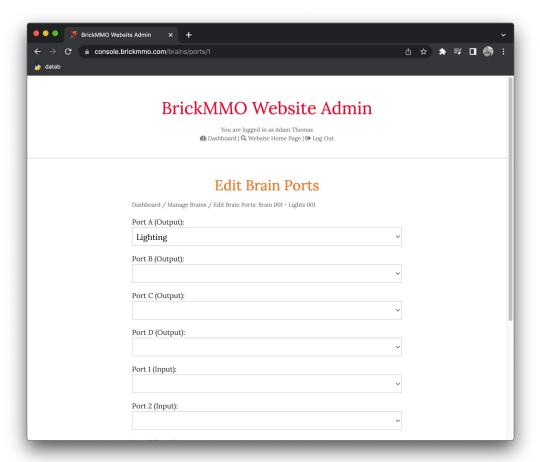
This system will be dependent GPS system.



# 3. Settings and Info

#### **Module: GPS**

This module can be connected to ship distance.

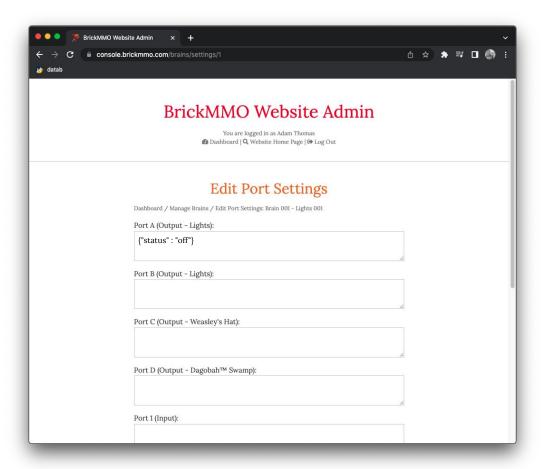


#### **Module Settings**

The bridge can be set to on off.

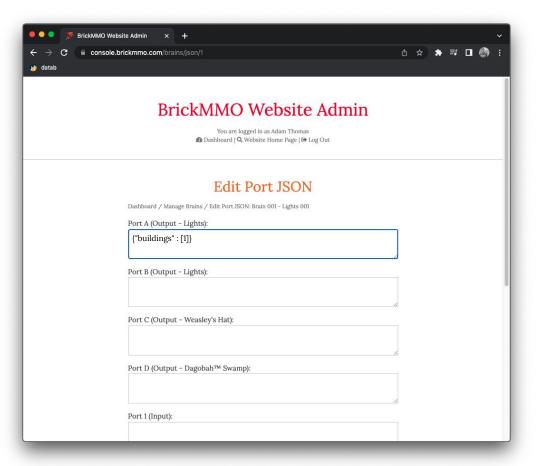
When ships have a certain distance to cross, the bridge have connected to the port and the bridge will be turned on.

The bridge will turn on sound to notify to cars about lifting up.



#### **Module JSON**

Additional information will include lights, motors, audio, and sensors connected to the lifting bridge port.



# 4. Ports, Motors, and Settings

### **Sensors and Motors**

Audio Port

3x3 Light Matrix

Large Motor

Ultrasonic Sensor

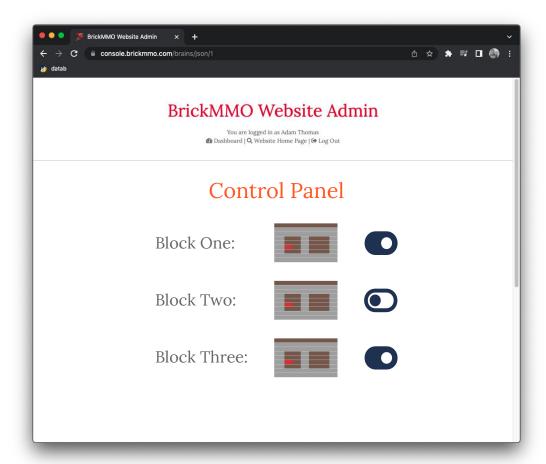


#### **Control Panel**

Lights could have different types: Blinking and On/Off

Sound will have an on and off function

Motor for the bridge will be on and off



# 5. Pseudocode

### **IOT Loop**

Opening time = bridge opening time + red signal time and barricade opening time

if(ship direction is towards bridge){

Calculate time to reach the bridge(reach time)

}

if(opening time + buffer time) == reach time){

Turns the signal yellow -> red; delay;

barricade opens; delay;

Check( if any vehicle on the bridge)

Open bridge

if( ship crosses the bridge){
 delay;
 Close bridge;
 Barricade opens;
 Light turns green;
}