

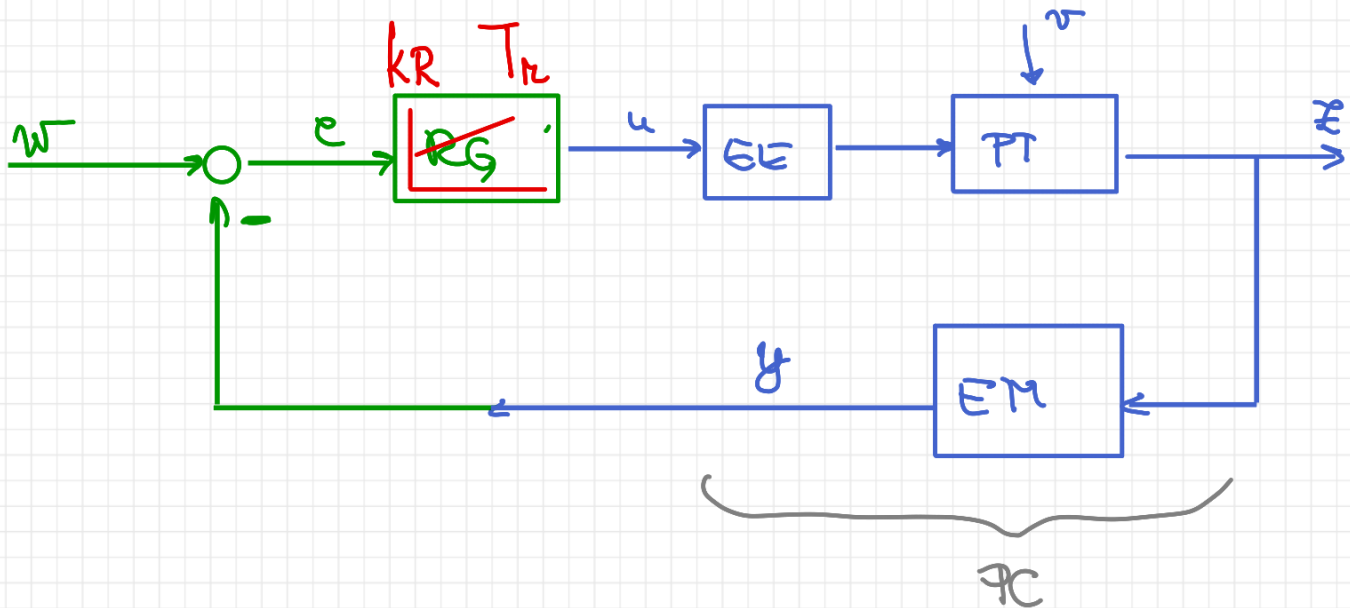
$$H_{PC}(s) = \frac{0.5}{0.7s^2 + 0.3s + 1} = \frac{k_R}{(1+sT_1)(1+sT_2)} \quad (PT2)$$

$T_1 > T_2$

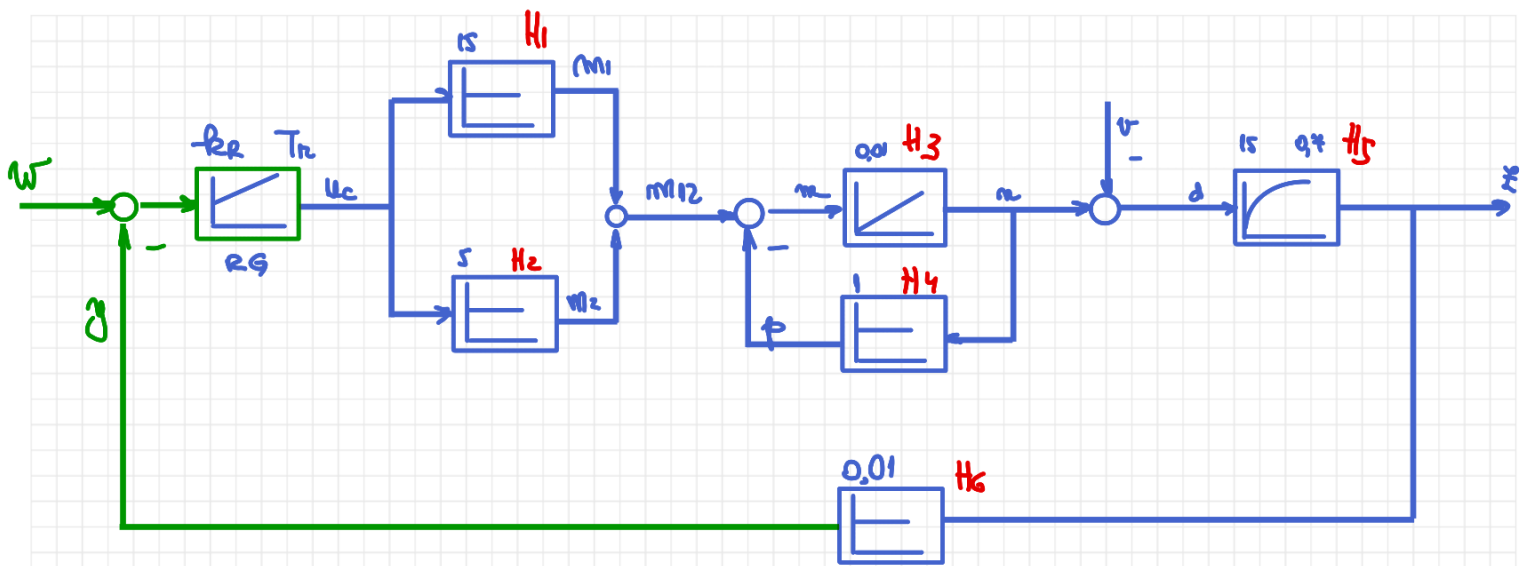
↓  
Oit modulului

$$RG - PI : H_{RG}(s) = \frac{k_R}{s} (1+sT_R)$$

$$k_R = \frac{1}{2k_{PC} \cdot T_2} ; T_R = T_1$$



$$k_R = k_R \cdot T_R \Rightarrow H_{RG}(s) = \frac{k_R}{s \cdot T_R} (1+sT_R)$$



$$\begin{array}{l|l|l} H_1 = 15 & H_3 = \frac{1}{100s} & H_5 = \frac{15}{1+0.4s} \\ H_2 = 5 & H_4 = 1 & H_6 = 0.01 \end{array}$$

$H_1, H_2 \rightarrow \text{parallel} \Rightarrow H_{12} = H_1 + H_2 = 20.$

$$H_3, H_4 \rightarrow \text{negative} \Rightarrow H_{34} = \frac{H_3}{1 + H_3 H_4} = \frac{\frac{1}{100s}}{1 + \frac{1}{100s} \cdot 1} = \frac{1}{100s + 1}$$

$$H_{12}, H_{34}, H_5, H_6 \rightarrow \text{serie} \Rightarrow H_{y4} = H_{12} \cdot H_{34} \cdot H_5 \cdot H_6 =$$

$$= 20 \cdot \frac{1}{100s + 1} \cdot \frac{15}{0.4s + 1} \cdot 0.01 =$$

$$= \frac{3}{(100s + 1)(0.4s + 1)} \Rightarrow \begin{array}{l} k_{pc} = 3 \\ T_1 = 100 \\ T_2 = 0.4 \end{array}$$

$$\Rightarrow H_{RG}(s) = \frac{k_R}{s \cdot T_n} (1 + s \cdot T_n) =$$

$$\Rightarrow k_R = k_h \cdot T_n = \frac{1}{2 \cdot k_{pc} \cdot T_2} \cdot T_n = \frac{1}{2 \cdot 3 \cdot 0.4} \cdot 100 = \frac{100}{4.2} = \frac{100}{4.2}$$

$$\Rightarrow H_{RG}(s) = \frac{\frac{100}{4.2}}{s \cdot 100} (1 + s \cdot 100) = \frac{1 + 100s}{4.2s}$$



V.R.S.C. → valori de regim Stationar constant

• P, PT<sub>1</sub>, PDT<sub>1</sub>

$$y_{\infty} = K \cdot u_{\infty}$$

de pe bloc

$$u_{\infty} = \text{const}$$

$$y_{\infty} = \text{const}$$

• D, PD, DT<sub>1</sub>



$$u_{\infty} = \text{const.}$$

$$y_{\infty} = (u_{\infty})' = 0.$$

• I, PI, PID



$$y_{\infty} = \text{const.}$$

$$u_{\infty} = (y_{\infty})' = 0.$$

→ avem in=0, out=ct.



STATISMUL NATURAL:

$$\gamma_m = \left. \frac{y_{\infty}}{v_{\infty}} \right|_{u_{\infty}=0} = \frac{k_N}{1+k_0}, \text{ sau } \gamma_m = \left. \frac{z_{\infty}}{v_{\infty}} \right|_{u_{\infty}=0} = \frac{k_N}{1+k_0}$$

• la reglatoroare de tip I, PI, PID :  $e_{\infty} = 0$  și  $\gamma_m = 0$ . (fără stațion, ASTATIC)

• la reglatoroare de tip P, PT<sub>1</sub>, PDT<sub>1</sub> :  $e_{\infty} \neq 0$  și  $\gamma_m \neq 0$  (cu stațion)