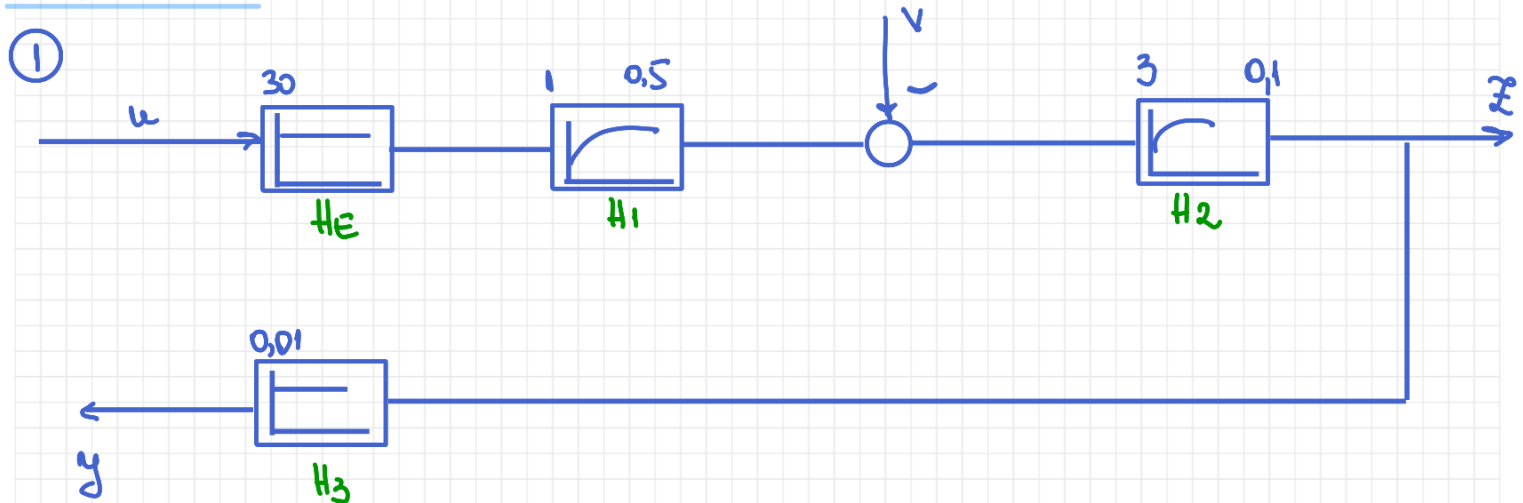


- ① Construiți schema bloc - informațională
- ② Funcțiile de tranș: y_u, y_v
- ③ Construire, punem la reglatorul
- ④ Stabilitatea
- ⑤ VRSC

$$⑥ H(z) = \frac{1+0,9z}{z^3+0,5z^2+0,4z+0,2}$$

REZOLVARE:



②

$$H_E = 30, \quad H_1 = \frac{1}{1+0,55}, \quad H_2 = \frac{3}{1+0,15}, \quad H_3 = 0,01$$

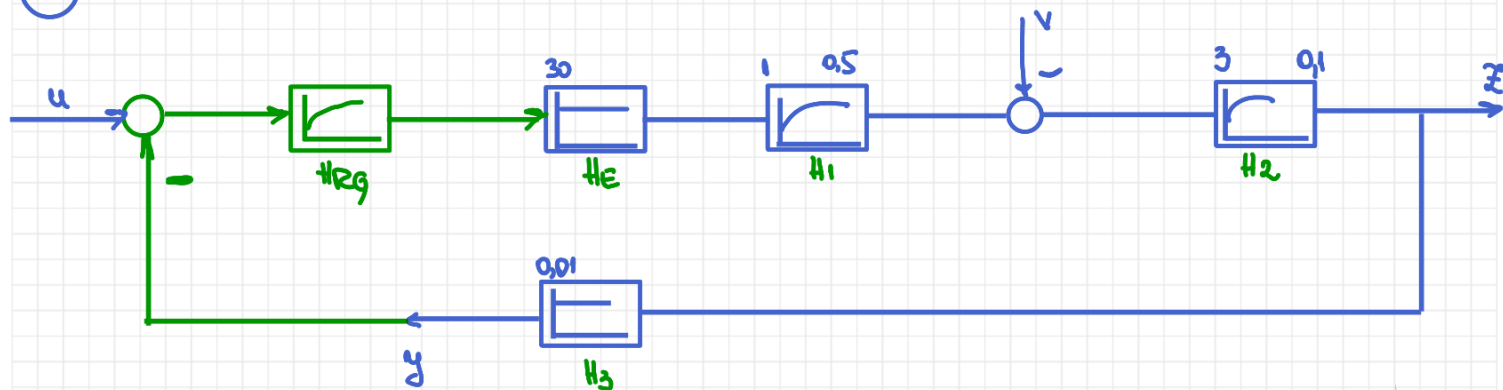
H_{y_u} $H_E, H_1, H_2, H_3 \rightarrow \text{serie} \Rightarrow$

$$\Rightarrow H_{y_u} = H_E \cdot H_1 \cdot H_2 \cdot H_3 = 30 \cdot \frac{1}{1+0,55} \cdot \frac{3}{1+0,15} \cdot 0,01 = \frac{0,9}{(1+0,55)(1+0,15)}$$

H_{y_v} $H_2, H_3 \rightarrow \text{serie}, \text{ minus la } v \Rightarrow$

$$\Rightarrow H_{y_v} = -H_2 \cdot H_3 = -\frac{0,03}{1+0,15}$$

3



$$\Rightarrow H_{PC} = \frac{0,9 = K_{PC}}{(1+0,55s)(1+0,15s)}$$

\uparrow \uparrow
 T_1 T_2

$$\Rightarrow K_R = \frac{1}{2 \cdot K_{PC} \cdot T_2} = \frac{1}{2 \cdot 0,9 \cdot 0,1} = 5,56$$

$T_R = 0,5$

$$\Rightarrow K_R = K_R \cdot T_R = 2,78$$

RG-PI: $H_{RG-PI}(s) = \frac{0,3}{s} (1+13s)$

$$H_w = \frac{H_{RG} \cdot H_{PC}}{1 + H_{RG} \cdot H_{PC}} = \frac{\frac{0,3(1+13s)}{s} \cdot \frac{0,9}{(1+0,55s)(1+0,15s)}}{1 + \frac{0,3(1+13s)}{s} \cdot \frac{0,9}{(1+0,55s)(1+0,15s)}}$$

$$= \frac{0,27(1+13s)}{s(1+0,55s)(1+0,15s) + 0,27(1+13s)}$$

$$\Delta(s)=0 \Rightarrow (s+0,55s^2)(1+0,15s) + 0,27 + 3,51s = 0$$

$$\Rightarrow \underline{s} + \underline{0,55s^2} + \underline{0,1s^2} + \underline{0,05s^3} + \underline{0,27} + \underline{3,51s} = 0$$

$$\Rightarrow 0,05s^3 + 0,6s^2 + 4,51s + 0,27 = 0$$

$$\bullet H_1 - PT_1 \Rightarrow n_{\infty} = 1 \cdot m_{\infty} \Rightarrow \underline{m_{\infty} = 333,33}$$

$$\bullet H_E - P \Rightarrow m_{\infty} = \varepsilon_{\infty} \cdot 30 \Rightarrow \underline{\varepsilon_{\infty} = 11,111}$$

$$\textcircled{6} H(z) = \frac{1 + 0z}{z^3 + 0,5z^2 + 0,7z + 0,2}$$

$\underbrace{1}_{a_3} \quad \underbrace{0}_{a_2} \quad \underbrace{0,5}_{a_1} \quad \underbrace{0,7}_{a_0}$

$n=3 \Rightarrow \text{impar}$

Cond: 0: $a_3 = 1 > 0 \quad \checkmark$

1: $\Delta(1) = 1 + 0,5 + 0,7 + 0,2 = 2,4 > 0 \quad \checkmark$

2: $\Delta(-1) = -1 + 0,5 - 0,7 + 0,2 = -1 < 0 \quad \checkmark$

3: $|a_0| < a_3 \Rightarrow 0,2 < 1 \quad \checkmark \rightarrow \text{matricea Jury:}$

	z^0	z^1	z^2	z^3
Lin 1	0,2	0,7	0,5	1
Lin 2	1	0,5	0,7	0,2
Lin 3	-0,96	-0,36	-0,6	—
Lin 4	-0,6	-0,36	-0,96	—

$$b_0 = \begin{vmatrix} a_0 & a_3 \\ a_3 & a_0 \end{vmatrix} = \begin{vmatrix} 0,2 & 1 \\ 1 & 0,2 \end{vmatrix} = -0,96$$

$$b_1 = \begin{vmatrix} a_0 & a_2 \\ a_3 & a_1 \end{vmatrix} = \begin{vmatrix} 0,2 & 0,5 \\ 1 & 0,7 \end{vmatrix} = -0,36$$

$$b_2 = \begin{vmatrix} a_0 & a_1 \\ a_3 & a_2 \end{vmatrix} = \begin{vmatrix} 0,2 & 0,7 \\ 1 & 0,5 \end{vmatrix} = -0,6$$

$\Rightarrow |0,96| > |0,6| \Leftrightarrow 0,96 > 0,6$ adeci \Rightarrow sistemul este
stabil din criteriul
lui Jury

