

# A Generalizable Framework for Automated Cloud Configuration Selection

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## **Abstract**

Outline of the project using at most 250 words

## Declaration

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# 1 Introduction

Describe the problem you set out to solve and the extent of your success in solving it. You should include the aims and objectives of the project in order of importance and try to outline key aspects of your project for the reader to look for in the rest of your report.

## 1.1 Background

## 1.2 Aims and Objectives

Algorithm Multiple cloud providers Latency/response tests from a separate machine Concurrent jobs to reduce search time

## 1.3 Contributions

## 1.4 Dissertation Overview

# 2 Literature Survey

Surveying the context, the background literature and any recent work with similar aims. The context survey describes the work already done in this area, either as described in textbooks, research papers, or in publicly available software. You may also describe potentially useful tools and technologies here but do not go into project-specific decisions.

# 3 Requirements Specification

Capturing the properties the software solution must have in the form of requirements specification. You may wish to specify different types of requirements and given them priorities if applicable.

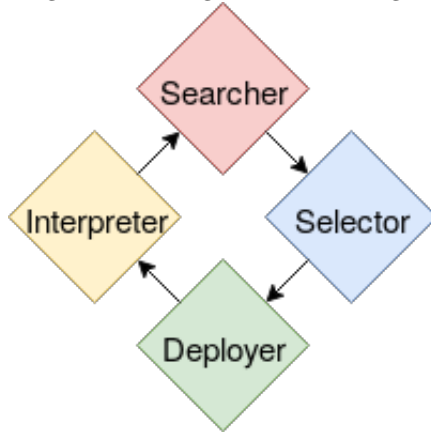
Previous solutions to the problem of automated cloud configuration selection have focused on specific use-cases or application types, and have not provided a functional implementation. Our design should be generalisable to any form of application deployed on the cloud, and should be able to recreate previous solutions. This paper should also come with an associated implementation, which can at least perform a Bayesian Optimization-based search for a given docker container containing a batch job or benchmark.

### 3.1 Use-case

## 4 Design

Indicating the structure of the system, with particular focus on main ideas of the design, unusual design features, etc.

Figure 1: A diagram of the design.



Optimisation is the process of minimising or maximising the value of some objective function by adjusting its input variables or parameters. Any optimisation algorithm begin with an initial guess of these variables and iterate through improved estimates until they terminate, hopefully providing an estimated solution. [1] In the generalized case, the optimisation method and objective function are both unknown, but we know that our objective function will always involve selecting some cloud configuration based on the inputs, deploying some application onto this configuration, and interpreting its performance to give some objective measure.

This process can be broken down into four components: A Searcher, which runs the optimisation algorithm, testing out various inputs in an attempt to maximise or minimise the objective function; a Selector, which interprets the inputs to determine what cloud configuration is being tested; a Deployer, which deploys the application onto this cloud configuration and returns any required logs from it; and an Interpreter, which takes these logs to calculate the objective measure which is returned to the Searcher as the returned value for the objective function. A diagram of this breakdown is shown in figure 1.

It is assumed that in the vast majority of cases, the user would provide their own Interpreter and Selector, that in some cases they must provide their own Deployer, and that only in rare cases would the user be required to provide their own Searcher. This is because optimization algorithms can be applied to

any deployments, with only small modifications necessary in rare cases for specific cases. Deployments can often be contained within Docker containers, and aside from occasional setup, for example in multi-node clusters, a Deployer which provisions a given configuration from a given provider, and then deploys and attaches to a user-provided docker image to collect its logs will be sufficient. Interpreters and Selectors, on the other hand, are very dependent on the form these logs will take, and the form the search space will take, and are extremely hard to generalise. For this reason, the modular design of our solution should make it simple for any component to be supplied or replaced by the user.

## 4.1 Searcher

The Searcher component performs an optimisation algorithm, such as Bayesian optimization, coordinate descent, random search, or exhaustive search, and drives the optimization process by iterating through potential input variables. For each set of these inputs, it take a sample from a single 'job,' and run through a single loop of the other three components. The constraints for these input variables must be specified, by describing their type (integer, float, categorical) and limits. A description of how to model cloud configurations into a set of variables is done in the Selector section.

Here we describe and compare the design considerations of two important examples of searchers which will be used for the evaluation of our implementation.

### 4.1.1 Exhaustive search

In an exhaustive search, every possible combination of the inputs is sampled, giving a complete analysis of the entire search space. This obviously takes many samples,  $n * \prod_{i=1}^J x_i$  where  $x_i$  is the number of options for the  $i$ th of  $J$  variables, and  $n$  is the number of samples taken from each configuration. This results in a large or even infinite search cost and time, but is almost certain to return the optimal result, depending on the amount of randomness involved in sampling.

### 4.1.2 Bayesian Optimization

Bayesian Optimization is an optimization method specifically designed for situations where the objective functions itself is unknown beforehand but can be directly observed through experiments. It models the objective function as a stochastic process, a 'prior function,' and computes its confidence intervals based on samples. Using these confidence intervals and a pre-defined acquisition function it decides future samples to take based on where there it estimates there to be the most potential gain. By this process Bayesian Optimization can find optimal or near-optimal solutions for any non-parametric problem in a



relatively small number of samples compared to other optimization methods. In addition, whereas other methods, such as exhaustive search, may handle uncertainty through sampling results from the same inputs multiple times, Bayesian Optimization can incorporate this uncertainty into its estimates, further reducing the number of samples needed.

There are a number of possible prior functions, acquisition functions, and stopping conditions that can be used with BO, and the Cherrypick paper goes into detail on the reasoning behind which options are best for cloud testing specifically. Some notable differences in our case, however, is that CherryPick was specifically focused on batch jobs, where what is measured is simply a function of an instance type's cost and its time taken to perform a given job. Its acquisition function is specified to this purpose, minimizing costs but biased towards configurations which satisfy a soft performance constraint by performing the batch job within a given time. In our case, our acquisition function must be more general, and we will therefore be relying on the user to ensure that whatever objective measure it returned by their Interpreter has already taken into account soft performance constraints such as this.

## 4.2 Selector

The Selector interprets the variables provided by the Searcher component into the form of a cloud configuration that can be deployed. Cloud configurations have a number of variables that can describe them, such as vCPU number, memory amount, disk speed, number of instances, instance category, machine type, and cloud provider. The selector must use whatever combination of these is provided and find either the exact or most similar cloud configuration available, passing this information on to the Deployer. For finding an exact match, the Selector can simply lookup the appropriate instance type from a dataset according to the input variables stored as each instance type's attributes. Looking for a closest match rather than an exact one gives more flexibility in how the input variables can be encoded, but means more complicated decisions such as attribute priority must be made, and extra assurances made to not repeat unnecessary samples when multiple sets of inputs describe the same closest input type.

Whether using exact or closest match, deciding how to encode cloud configurations into a set of input variables is not a trivial task. The problem can be further complicated when setting inputs to certain variables may exclude others, as is often the case in cloud computing. Large amounts of memory is often only available on machines with more vCPUs, and providers may offer different available configurations. Google Cloud Platform allows users to specify custom machine types, but even these do not allow any possible combination (for example, Memory constraints are tied to vCPU number, and vCPU number must be divisible by 2).

Instance Type	Provider	Category	vCPU Number
n1-standard-2	GCE	General	2
n1-standard-4	GCE	General	4
n1-standard-8	GCE	General	8
c5.large	EC2	CPU	2
c5.xlarge	EC2	CPU	4
c5.2xlarge	EC2	CPU	8

Table 1: A possible way of separating instance types into 3 variables, each with its own optimal value. Providers were either the Google Compute Engine (GCE) or the Amazon Elastic Compute Cloud (EC2)

Despite these problems, clear patterns prevail throughout leading cloud providers, such as separating machine types into categories equivalent to 'Compute-optimised', 'Memory-optimised', and 'Storage-optimized,' each with a set of machines with between 2 and 96 CPUs. In lieu of a cross-provider service to match a given specification to a specific cloud instance type, something which would be outside the scope of this project, these industry-standard categorisations can be used to encode the search space in a reasonable manner. Table 1 shows an example of how we have used these patterns to encode 6 instance types into a set of 3 easily interpreted variables; Provider, vCPU number, and machine category. A searcher tool could easily filter a dataset of this form to find the instance-type for a set of input variables.

In the end, however, the important features and constraints for the search space will differ for each user, and it may be beneficial to run multiple experiments in different search spaces before settling on a final decision for an instance type. While we provide in our associated implementation an example of how to encode and select available cloud configurations for our Bayesian Optimization tool, we think it best to ultimately leave it to the user to design and implement a Selector system that works well for their specific use-case.

### 4.3 Deployer

The Deployer deploys the user-provided application, batch job, or benchmark onto the selected cloud configuration, and collect any necessary analysis from it. Typically this will involve provisioning the necessary machines from the given provider, followed by deploying the given application onto these machines, and either collecting logs from them or from a networked instance or cluster.

#### 4.3.1 VM Provision

Aside from in serverless computing, the first step of any deployment is likely to be to provision the virtual machines themselves from the cloud provider. The Deployer should be capable of requesting any virtual machine chosen by the Selector, regardless of provider. This can be simplified using Infrastructure as

code (IaC) tools such as Terraform or Chef, which offer the ability to codify the APIs from many different providers into declarative configuration files. As long as configuration files and credentials for use by an IaC tool are supplied for each possible provider, then a Deployer can call the corresponding IaC tool to provision the machines. For whatever IaC tool is used, there are several requirements. As instance type and number of machines will be supplied by the Selector, and therefore cannot be known until the machines are provisioned, either they must be declarable as variables when the tool is run, or the configuration files must be editable just beforehand. Along with this, the tool must support multiple concurrent tasks of with their own specifications and outputs, if we are to allow the Searcher to take multiple samples at once.

#### **4.3.2 Docker Deployment**

Once the virtual machines themselves have been provisioned, the application must be deployed onto them. We have assumed that the application being tested is available in the form of a Docker image, and that the machine(s) provisioned operate as either a Kubernetes based cluster or a single instance. While other forms of application or cluster architecture may be used, ready-made Kubernetes clusters are available on several major cloud providers. The modular design allows users to implement their own Deployers to deal with alternative situations.

Both Kubernetes and Docker offer remote APIs. For Kubernetes clusters available on cloud providers, no set up is required, while for single machines the VM provisioner must install Docker and direct it to a public-facing port. The remote APIs can be utilized as long as the VM Provisioner is capable of returning public facing IP of the provisioned machines, and that security credentials are provided. The Deployer must attach to any deployment, or wait for its completion, and obtain and return any and all logs it produces, for use by the Interpreter.

#### **4.3.3 Simulated Deployment**

It may be advantageous, especially during debugging or if using a 'closest match' approach to configuration selection, to simulate the response from provisioning and deployment of an application. To this end, it may be useful to ensure full logs of any deployment are stored so that, if desired, future calls to 'Deploy' an already sampled configuration for a given application can simply be responded with a randomly distributed value based on previous results from the same configuration.

## 4.4 Interpreter

The Interpreter must interpret whatever logs and other information is returned by the Deployer, along with the cost of the cloud configuration provided by the Selector, in order to return an objective measure for the sampled cloud configuration. It is this returned value that the Searcher will be attempting to minimise or maximize. We leave it to the user to develop an Interpreter for their use-case, incorporating an extraction of relevant information from their application logs with their specific cost and time constraints.

## 5 Implementation

**How the implementation was done and tested, with particular focus on important / novel algorithms and/or data structures, unusual implementation decisions, novel user interface features, etc.**

### 5.1 Searcher

For the sake of generalizability, the available implementation of spearmint was found to be outdated and incompatible with the latest versions of various python modules planned to be used in later steps. Because of this, spearmint was first updated to be compatible with Python 3 and newer versions of its dependencies such as Google Protocol Buffers. This implementation of spearmint has been made available.<sup>1</sup>

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<sup>1</sup><https://github.com/briggsby/spearmint3>

## 5.2 Selector

## 5.3 Deployer

### 5.3.1 vBench

### 5.3.2 Cloudsuite3

### 5.3.3 Sysbench

### 5.3.4 Example - Ping server

## 5.4 Interpreter

# 6 Evaluation

**You should evaluate your own work with respect to your original objectives. You should also critically evaluate your work with respect to related work done by others. You should compare and contrast the project to similar work in the public domain, for example as written about in published papers, or as distributed in software available to you.**

To demonstrate the effectiveness of the implementation of our framework, we wanted to show that it could replicate the methods set out in the Cherrypick paper [?] by performing Bayesian Optimization to attempt to find an optimal configuration for a given deployment. We then wanted to use the same implementation to perform multiple exhaustive searches so that the results from Bayesian Optimization could be properly compared to the real average results.

The deployment to be used was originally planned to be Cloudsuite3's media streaming benchmark, however this was found to be extremely variable and dependent entirely on network bandwidth, and so instead the vBench video transcoding benchmark was used. Our objective function measured an instance type's relative rate of transcoding of a single 5 second 1920x1080 video file, returning a score of 0 if the quality was below a given threshold, divided by the hourly price of that instance. Effectively, we maximised the rate of transcoding a unit of video length at a sufficient quality per hourly cost. We had hoped to show that incorporating the soft constraint on video quality within the value returned by the Interpreter, rather than within the Acquisition function as was done in Cherrypick, did not hinder the optimization process, however no instance type tested failed to achieve the threshold video quality in any case.

For choosing the boundaries of the search space, we decided to reduce costs by using only machines ranging from 2 vCPUs to 8 vCPUs. This was also convenient as to use more powerful machines would

	Provider	
Machine Category	Amazon EC2	Google Compute Engine
General	n1-standard	m5
Memory	n1-highmem	r5
CPU	n1-highcpu	c5

Table 2: Machine types corresponding to different instance categories for the two providers

have required requesting additional raised quotas from the providers used, and so would be less easily replicable. Using exact match, and as we wanted to show that the implementation worked with multiple providers, we could not rely on Google cloud platform’s custom machine types and had to find some way to categorize possible variables. Rather than including memory as a variable, CPU instead was coded as a categorical variable (2, 4, or 8), along with machine category (General, Memory, CPU), each with a different amount of memory. Table 2 show which machine types corresponded to each option.

For realistic situations, the search space could follow this same pattern, with the CPU variable extended, possibly instead as an integer between 1 and 6 which 2 is raised to the power of to determine vCPU number, as this covers many of the available CPU options.

The 18 machine types decided upon (3 vCPU numbers for 3 machine categories for the 2 providers) were stored in a single dataset for use with the ‘Exact match’ instance selector. The vBench deployer was used which utilized Terraform to provision a single instance of the given machine type, on which the remote docker api was used to deploy and collect logs from an docker image containing vBench. The vBench interpreter then isolated the vBench score from these logs, and divided it by the hourly cost of that machine type to return the final value.

Where not otherwise specified, statistical results are quoting the p-values returned from a Tukey’s Honest Significant differences test to correct for multiple comparisons.

The results of the exhaustive search are shown in figures 2 and 3. The raw scores (time taken to transcode relative to the reference) show clear overlap between many possible configurations, and in general show a significant difference between 2 vCPUs and either 4 ( $P < .001$ ) or 8 ( $P < .001$ ) vCPUs, with a larger number of vCPUs increasing the score, but show less clear differences between 4 and 8 ( $P = .066$ ), dependent on the provider and machine category, suggesting either diminishing returns or a limit of the benchmark to utilize all vCPU cores.

However, once the scores are instead given relative to the machine’s hourly costs, there is much less overlap. A clear optimal configuration can be seen in the c5.large machine type, if one is purely interested in getting the most video transcoding for a given cost. The c5.large machine was significantly better than the next best option, the n1-highcpu-2 ( $P < .001$ ). Amazon EC2’s machine types consistently

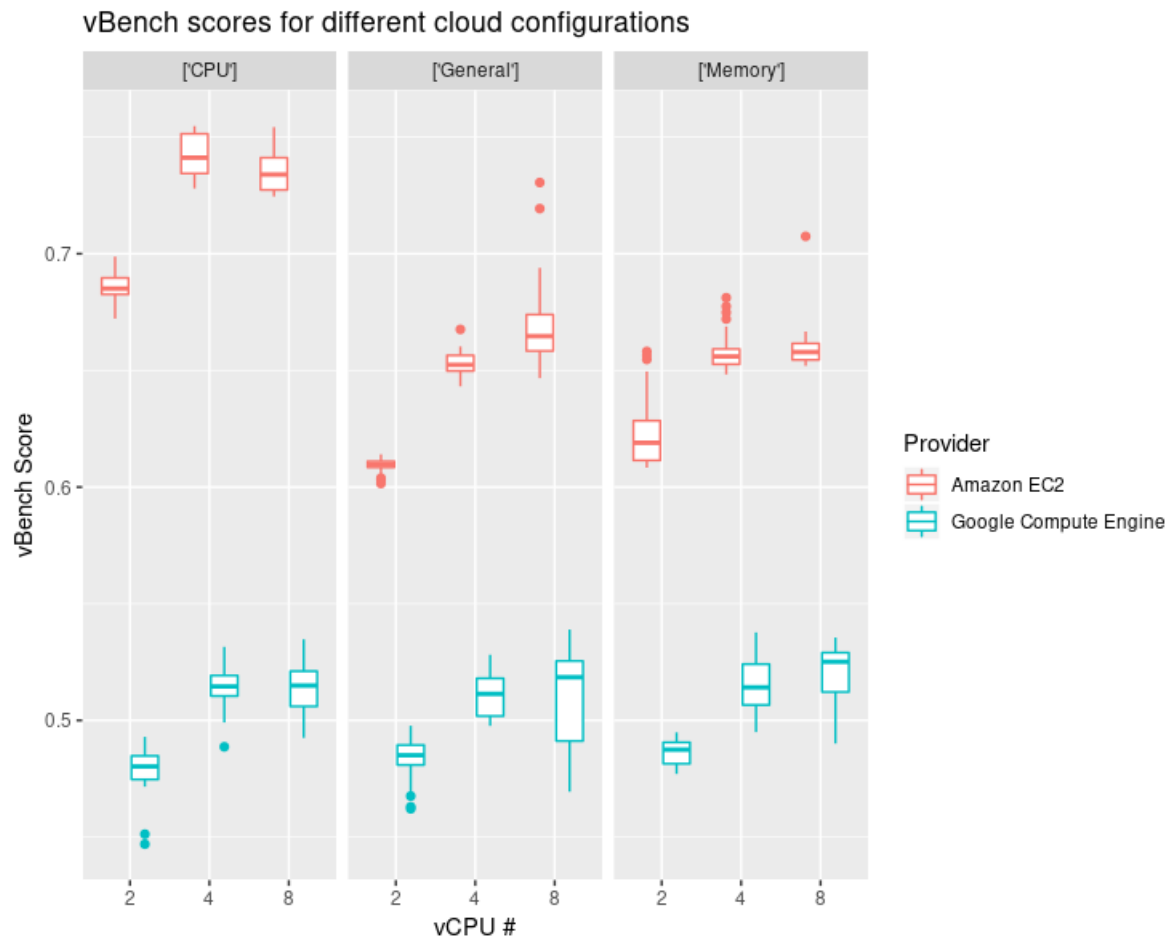


Figure 2: Distribution of vBench scores



Figure 3: Distribution of objective function values



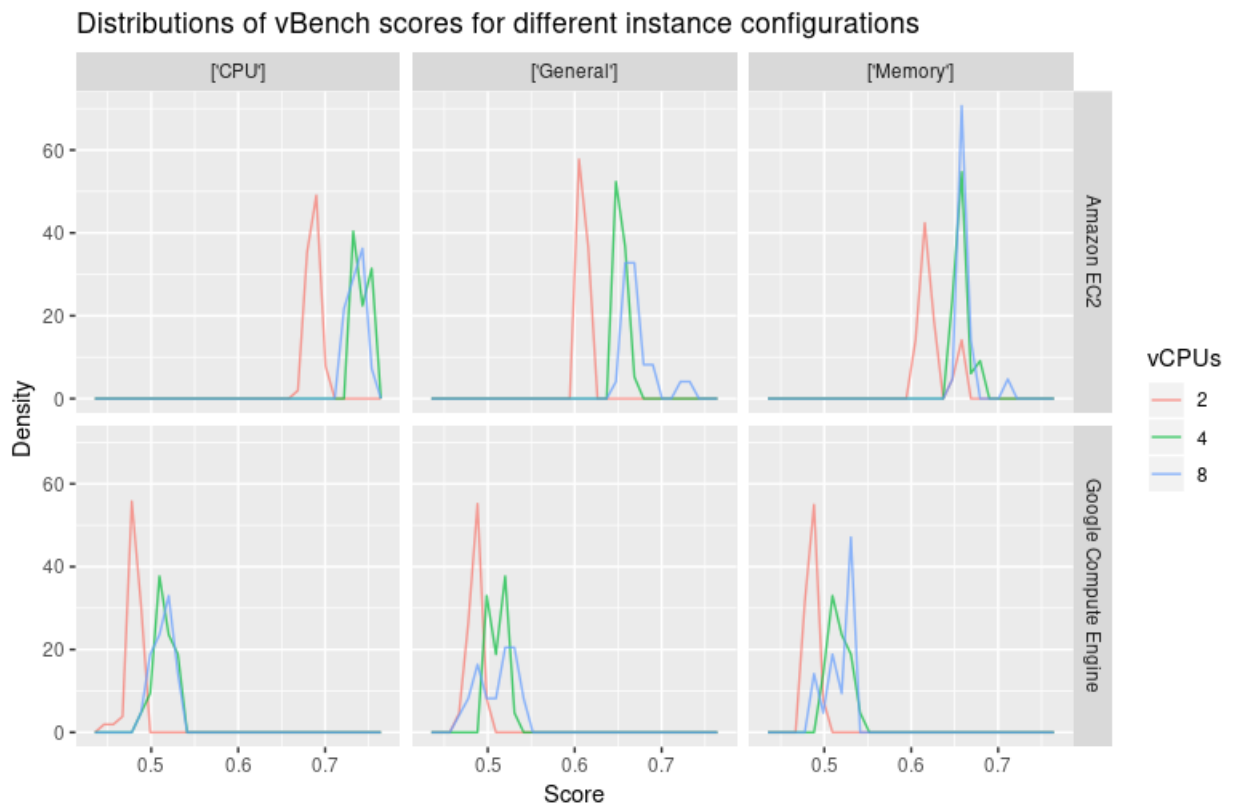
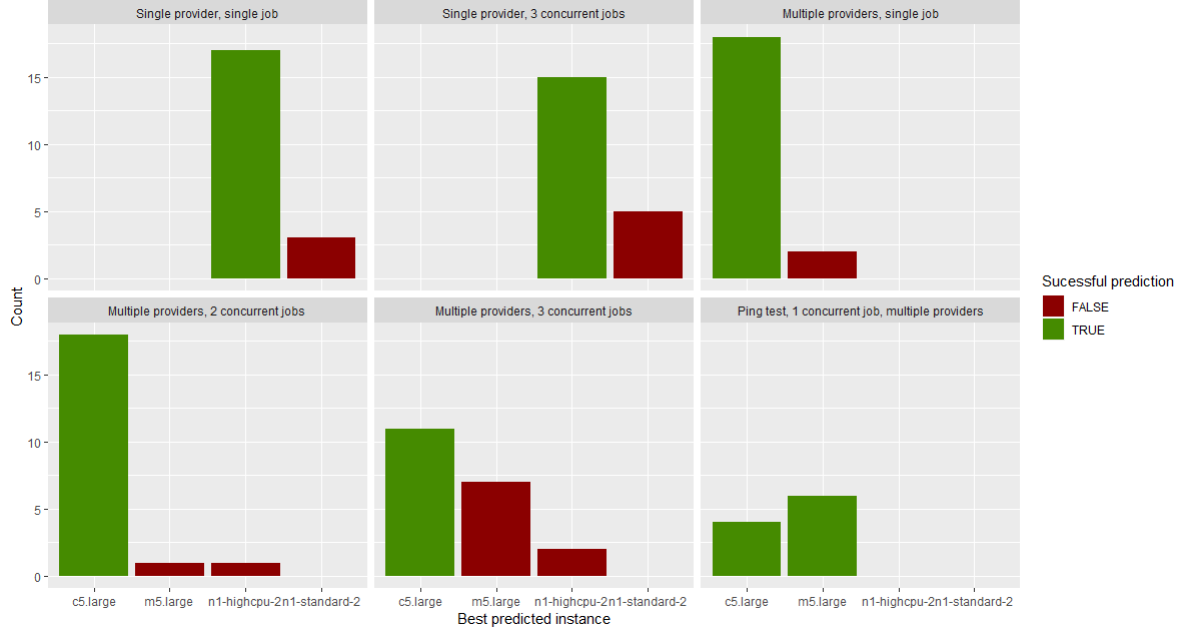


Figure 4: Distribution of vBench scores in frequency polygons

Figure 5: Optimal configurations suggested after convergence for Bayesian Optimization searches

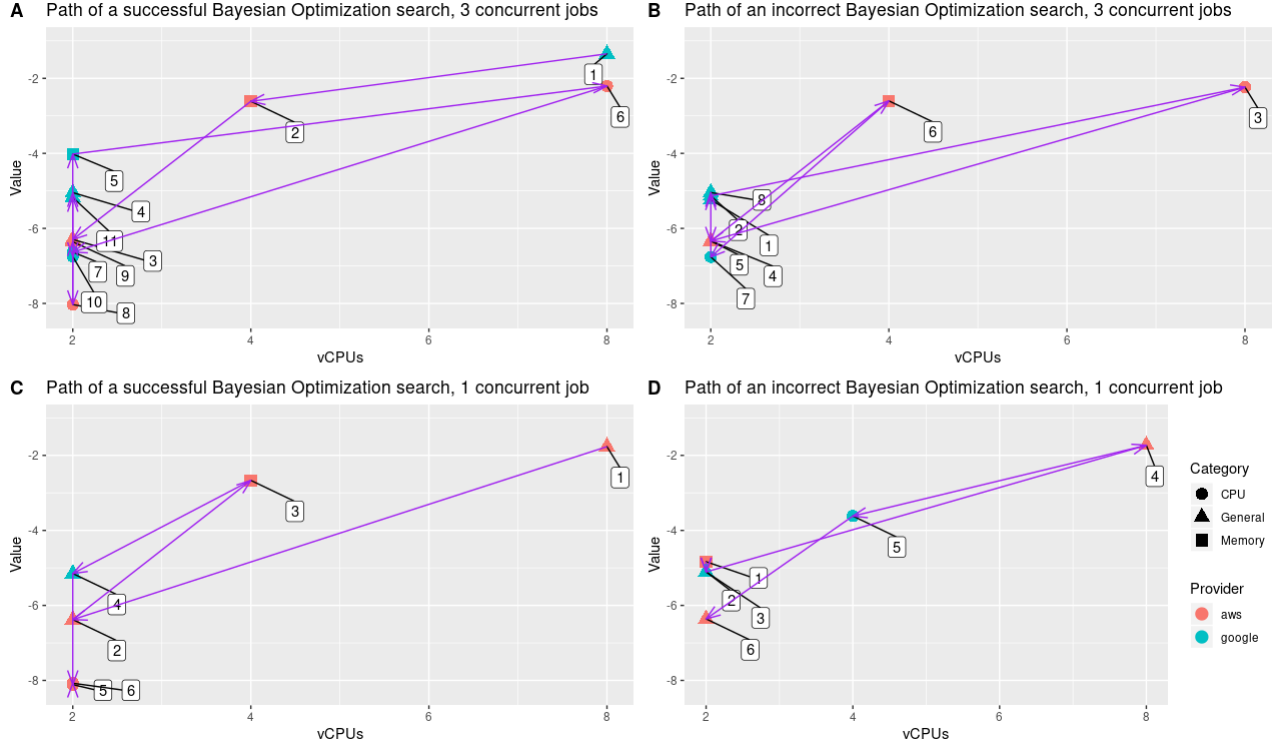


outperformed Google Compute Engine’s equivalents of the same category and vCPU number at both raw score (Anova,  $F = 32111.456, P < .001$ ) and value for money (Anova,  $F = 22710.7, P < .001$ ). However, despite this general trend, the provider seemed to be the least important factor in determining the optimal configuration. For example, the n1-highcpu-2 still gave significantly better values than the m5.large ( $P < .001$ ), or the c5.xlarge ( $P < .001$ ) making it the second most cost-efficient option.

With the exhaustive search complete, we then used a Spearmint based searcher to perform a Bayesian Optimization search, assuming low noise (-1 to 1) and using the same stopping conditions as used by default in the Cherrypick paper [?], namely when the Expected improvement (EI) is less than 10%, and at least 6 samples have been taken. We were able to successfully run this experiment with both multiple and single providers, as well as with both single jobs and multiple concurrent jobs. The results from these experiments are shown in figure 5, while examples of the job paths taken during them are shown in figure 6.

With only a single concurrent job running, we were able to replicate the previous results, with the correct optimal instance predicted in 8 out of 10 evaluations. It is interesting to note, however, that the incorrectly predicted instance in both failed cases was not the second but third best choice, resulting in a reduction in the score/cost value by 21.3%.

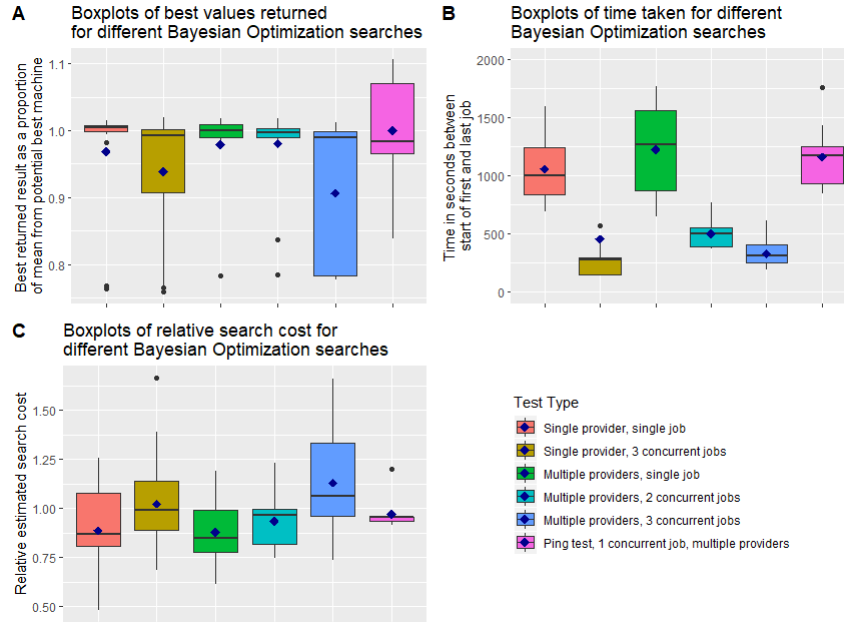
While running multiple concurrent jobs could dramatically decrease the search time, it did come at a cost to accuracy. With the same stopping conditions, a successful prediction was made only 12 out of



20 experiments (60%). This suggests that multiple concurrent jobs is only a good choice when reducing search time is more important than reducing search cost, as more stringent stopping conditions should be used. Unsurprisingly, reducing the search space to a single provider increased the likelihood of making correct predictions with multiple concurrent jobs, leading to 15 correct predictions out of 20 repeats (75%).

Having performed evaluation on our implementation for a deployment of a simple docker container, effectively corresponding to running a single batch job or benchmark and interpreting the results, we then wanted to evaluate the same technique applied to an web-based application, which may be better evaluated through its responses to a client. For this a single 5-node Kubernetes cluster was set up for the same of sending repeated requests to the evaluated deployment, as described for the 'Pingserver' deployer and interpreter. This experiment is much more intensive to perform exhaustive search for, as it would require separate pinging clusters to be set up for every sample. The mean response time for requests of a normally distributed load was divided by the hourly cost of the instance to give maximised value. From the samples taken during 10 repetitions of this experiment, it seemed that there were no significant difference between the two optimal configurations of c5.large and m5.large ( $\Delta\bar{x} = 0.0001, P \approx 1.000$ ), which the predictions correctly converged upon in all cases.

Figure 7: Values, search costs and times for different Bayesian Optimization searches. Single large outlier removed from search time graph from Single provider, 3 concurrent jobs.



## 6.1 Related Work

## 7 Critical discussion

You should evaluate your own work with respect to your original objectives. You should also critically evaluate your work with respect to related work done by others. You should compare and contrast the project to similar work in the public domain, for example as written about in published papers, or as distributed in software available to you.

As mentioned, the evaluation above likely does not correspond to comparisons with which to base real deployment decisions on. In reality, a small increase in transcoding speed may lead to a far greater increase in customer uptake, rather than the effectively 1:1 ratio between price and transcoding speed assumed in the experiment. However, the evaluation shows that the methodology works very well with a given objective score measure, and it would be trivial for a new objective function to be implemented with a different relationship between the score, price, and 'value' of a given configuration.

## 7.1 Future extensions

# 8 Conclusions

You should summarise your project, emphasising your key achievements and significant drawbacks to your work, and discuss future directions your work could be taken in.

## References

- [1] J. Nocedal and S. Wright, *Numerical Optimization 2nd Ed.* No. 9781447122234 in Springer Series in Operations Research and Financial Engineering, Springer New York, 2006.

## Appendices

Testing Summary

User Manual