# 空气与气体动力学

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### 回顾: 准一维可压内流

$$d(\rho uA) = 0$$
  $dp = -\rho udu$   $dh + udu = 0$ 

$$dh + udu = 0$$

### 1.速度面积关系式: $\frac{dA}{A} = (Ma^2 - 1)\frac{du}{u}$

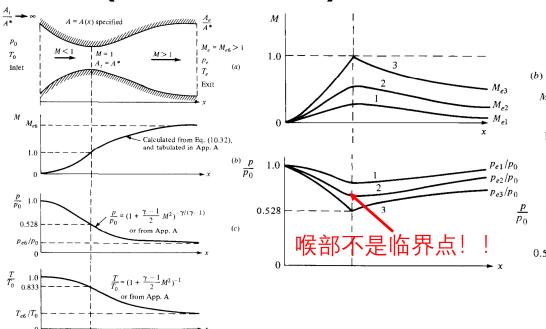
$$\frac{dA}{A} = (Ma^2 - 1)\frac{du}{u}$$

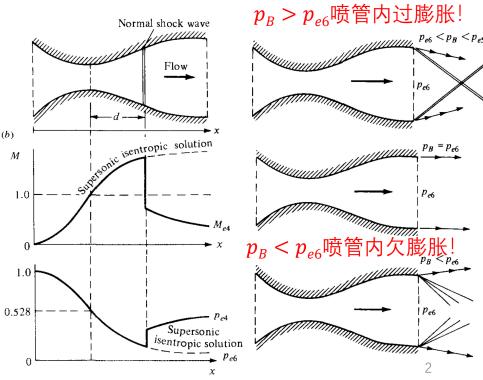
0 < Ma < 1时,

Ma > 1时,

dA > 0 du < 0,  $A \uparrow u \downarrow \qquad dA > 0$  du > 0,  $A \uparrow u \uparrow$ 

### 2.喷管(减压、增速):





### 12.3扩压器(9.4)

扩压器(diffuser): 减速、增压。

等熵:  $s_1 = s_2, p_{02} = p_{01}$ , 可用能不变。 $s_1$ 

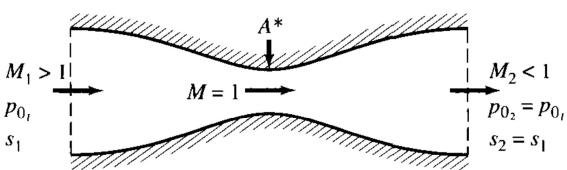
超声速气流等熵减速——极不可能!

壁面内折——斜激波;

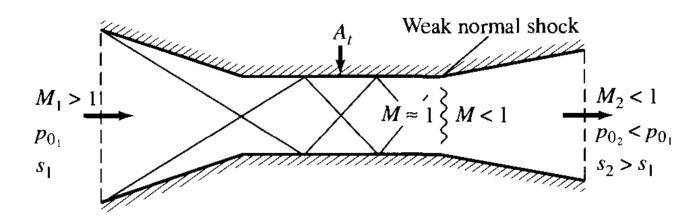
边界层——粘性损失。

 $p_0$ , 可用功减小!

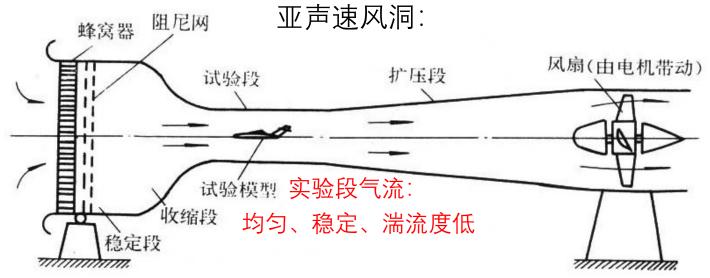
扩压器设计:提高 $\frac{p_{02}}{p_{01}}$ 。

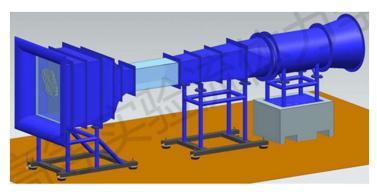


(a) Ideal (isentropic) supersonic diffuser

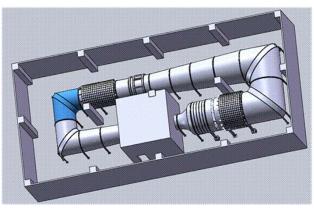


(b) Actual supersonic diffuser

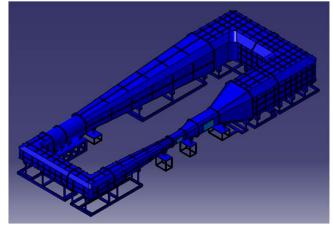




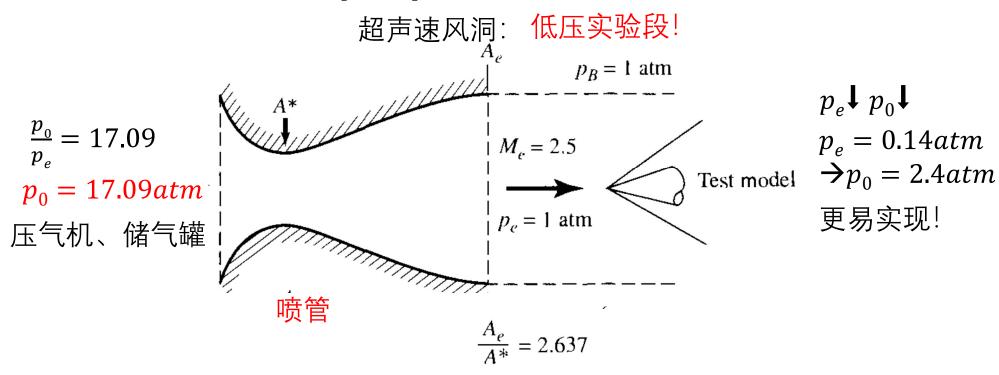


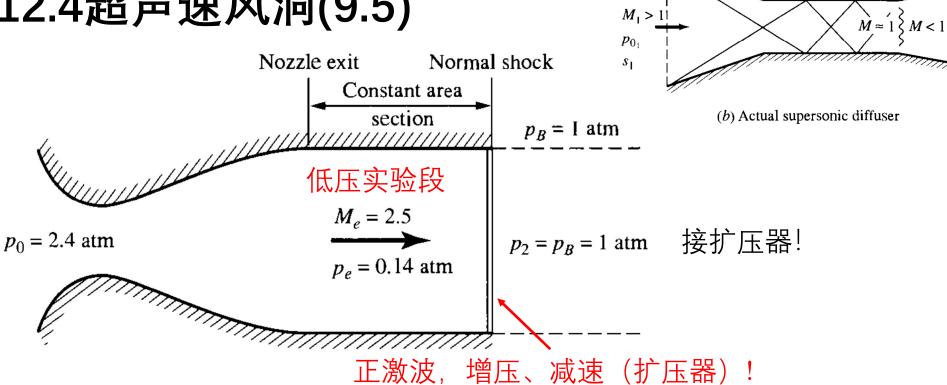


回流式



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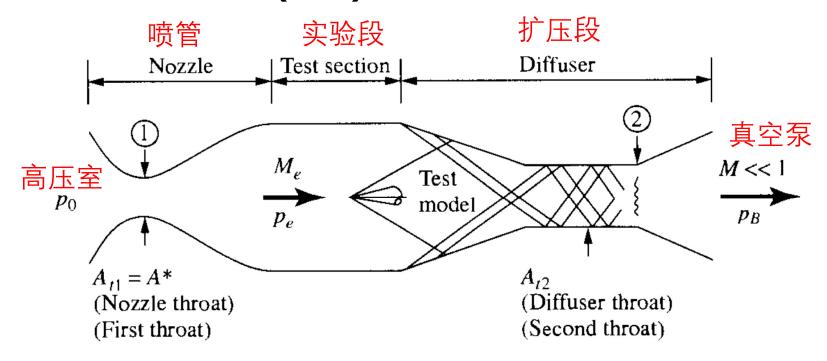
正激波耗散大,不稳定。

Weak normal shock

 $M_2 < 1$ 

 $p_{0_2} < p_{0_1}$ 

 $s_2 > s_1$ 



损失:模型表面、扩压段——激波; 边界层粘性流动。 7.1 超声速风洞的储气罐内的温度为288k,实验段速度为450m/s。1段定风洞中气流为绝热流动,计算实验段Ma.

解: 
$$a = \sqrt{\gamma RT} = \sqrt{1.4 \times 287 \times 288} = 340.1 \text{ m/s}$$
  
::  $Ma = \frac{V}{a} = \frac{450}{340.17} = 1.32$ 

7.1解, 
$$To=288K$$
,  $V=460m/s$   
能是键:  $CpTo=CpT+\frac{V^2}{2}$   
 $T=To-\frac{V^2}{2Cp}=1882K$ .  
实验段  $a=\sqrt{bPT}=274.2 m/s$   
 $Ma=\frac{V}{a}=1.64$ .

储气罐内为滞止参数!! 总温 7.2 -结定巨气液心温度为300K、压力为1,20tm、速度为对0m/s. 计算液点处的高压、高温、临界压力、临界温度和特征3碳高解; a= NVRT=N1.4x287x300=347、2 m/s.

 $Ma = \frac{1}{4} = \frac{1}{14} \frac{1}{12} = 0.72.$   $F = 1 + \frac{1}{2} | Ma^{2} | \Rightarrow (0 = (1 + \frac{1}{2} | Ma^{2}).T = (1 - \frac{0.4}{2} | 0.72^{2}) 300.$  = 268.9 K  $F^{0} = (1 + \frac{1}{2} | Ma^{2})^{\frac{1}{12}} \Rightarrow P_{0} = (1 + \frac{1}{2} | Ma^{2})^{\frac{1}{12}} P = (1 - \frac{0.4}{2} | 0.72^{2})^{\frac{1}{12}} R.$ 

 $\frac{17}{70} = 0.833 \implies (7 = 0.833 \times 268.9 = 223.99 \text{ K.}$   $\frac{17}{70} = 0.128 \implies P^* = 0.128 \times 0.818 = 0.432 \text{ atm}$   $\frac{17}{70} = 0.128 \implies P^* = 0.128 \times 0.818 = 0.432 \text{ atm}$   $\frac{17}{70} = 0.128 \implies P^* = 0.128 \times 0.818 = 0.432 \text{ atm}$   $\frac{17}{70} = \frac{17}{70} = \frac{17}{70} = 0.833.$ 

滞止压力、温度求错!

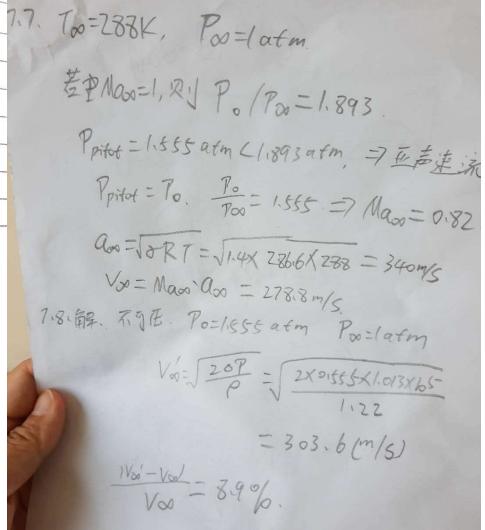
7.2. 
$$\beta = 0.72$$
 $Ma = \sqrt{a} = 0.72$ 
 $Ma = 0.72$ 
 $Po = 1.694 \text{ a.f.} To = 331.2 \text{ K.}$ 
 $Po = 1.694 \text{ a.f.} To = 331.2 \text{ K.}$ 
 $Po = 0.833 \cdot T^* = 275.9 \text{ K.} To = 332.95 \text{ M.}$ 
 $Po = 0.528 \quad P^* = 0.814 \text{ a.f.}$ 
 $Po = 0.528 \quad P^* = 0.814 \text{ a.f.}$ 
 $Po = 0.528 \quad P^* = 0.814 \text{ a.f.}$ 
 $Po = 0.528 \quad P^* = 0.814 \text{ a.f.}$ 

7.6 如果通过激波似质增为199.5 J/(h/k), 向来流马稀数为约?  $05=52-51=Cu/n.\{[\frac{2+(y+1)Ma_1}{(y+1)Ma_1}]^Y[]+\frac{2V}{V+1}/Ma_1-1)]\}$  Ma=L09

#### 计算过程??

7.6 \( \frac{1}{12} \); 
$$S_2 - S = -P \left( \frac{Poz}{Pq} = 199.5 \) \( \frac{1}{12} \); \( \frac{Poz}{Pq} = \frac{1}{2} \) \( \frac{1}{2} \); \( \frac{1}{2} \); \( \frac{Poz}{Pol} - \frac{1}{2} \); \( \frac{87}{Pol} - \frac{87}{2} \); \( \frac{1}{2} \); \( \frac{1$$

不可压??



## 十三. 绕翼型可压缩流动(空10)



b: 79.8m

 $S: 845m^2$ 

 $\chi=33.5^{\circ}$ 

Ma<sub>巡納</sub>=0.85

巡航时气动特性如何??

0.3< *Ma* <1:

 $C_l, C_d$  ??

Ma > 1 激波产生??

Ma < 0.3:

不可压势流

$$\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0$$

可压势流 $\phi$ ??

### 13.1速度势方程(10.2)

无粘可压无旋流——存在势函数 $\phi$ 。  $\vec{\Omega} = \vec{v} \times \vec{v} = 0$  若:  $\vec{v} \times \vec{v} = 0$ ,则 $\vec{v} = \vec{v} \phi$ 

定常、无旋、等熵、2D:  $\vec{V} = \vec{\nabla} \phi$ ,  $u = \frac{\partial \phi}{\partial x}$ ,  $v = \frac{\partial \phi}{\partial y}$ 

连续性方程: 
$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} = 0$$
 不可压:  $\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} = 0$ 

$$\rho \frac{\partial u}{\partial x} + u \frac{\partial \rho}{\partial x} + \rho \frac{\partial v}{\partial y} + v \frac{\partial \rho}{\partial y} = 0$$

$$\rho \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial \phi}{\partial x} \frac{\partial \rho}{\partial x} + \rho \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial \phi}{\partial y} \frac{\partial \rho}{\partial y} = 0$$

欧拉方程: 
$$dp = -\rho V dV = -\frac{\rho}{2} dV^2 = -\frac{\rho}{2} d(u^2 + v^2)$$

等熵: 
$$\frac{dp}{d\rho} = a^2$$
  $\rightarrow$   $dp = a^2 d\rho$ 

$$d\rho = -\frac{\rho}{2a^2}d(u^2 + v^2) = -\frac{\rho}{2a^2}d\left[\left(\frac{\partial\phi}{\partial x}\right)^2 + \left(\frac{\partial\phi}{\partial y}\right)^2\right]$$
 (2)

### 13.1速度势方程(10.2) $d\rho = -\frac{\rho}{2a^2}d\left[\left(\frac{\partial \phi}{\partial x}\right)^2 + \left(\frac{\partial \phi}{\partial y}\right)^2\right]$

$$d\rho = -\frac{\rho}{2a^2}d\left[\left(\frac{\partial\phi}{\partial x}\right)^2 + \left(\frac{\partial\phi}{\partial y}\right)^2\right]$$
 (2)

$$\frac{\partial 2}{\partial x}: \quad \frac{\partial \rho}{\partial x} = -\frac{\rho}{2a^2} \frac{\partial}{\partial x} \left[ \left( \frac{\partial \phi}{\partial x} \right)^2 + \left( \frac{\partial \phi}{\partial y} \right)^2 \right] = -\frac{\rho}{a^2} \left( \frac{\partial \phi}{\partial x} \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial \phi}{\partial y} \frac{\partial^2 \phi}{\partial y \partial x} \right)$$
 (3)

$$\frac{\partial 2}{\partial y}: \qquad \frac{\partial \rho}{\partial y} = -\frac{\rho}{2a^2} \frac{\partial}{\partial y} \left[ \left( \frac{\partial \phi}{\partial x} \right)^2 + \left( \frac{\partial \phi}{\partial y} \right)^2 \right] = -\frac{\rho}{a^2} \left( \frac{\partial \phi}{\partial x} \frac{\partial^2 \phi}{\partial x \partial y} + \frac{\partial \phi}{\partial y} \frac{\partial^2 \phi}{\partial y^2} \right) \tag{4}$$

$$\frac{\partial(\rho u)}{\partial x} + \frac{\partial(\rho v)}{\partial y} = 0 \quad \Rightarrow \quad \rho \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial \phi}{\partial x} \frac{\partial \rho}{\partial x} + \rho \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial \phi}{\partial y} \frac{\partial \rho}{\partial y} = 0 \tag{1}$$

 $(3)+(4)\rightarrow(1)$ :

$$\left[1 - \frac{1}{a^2} \left(\frac{\partial \phi}{\partial x}\right)^2\right] \frac{\partial^2 \phi}{\partial x^2} + \left[1 - \frac{1}{a^2} \left(\frac{\partial \phi}{\partial y}\right)^2\right] \frac{\partial^2 \phi}{\partial y^2} - \frac{2}{a^2} \left(\frac{\partial \phi}{\partial x}\right) \left(\frac{\partial \phi}{\partial y}\right) \frac{\partial^2 \phi}{\partial x \partial y} = 0$$

$$a^2 = a_0^2 - \frac{\gamma - 1}{2} V^2 = a_0^2 - \frac{\gamma - 1}{2} \left[\left[\left(\frac{\partial \phi}{\partial x}\right)^2 + \left(\frac{\partial \phi}{\partial y}\right)^2\right]^2$$

$$(5)$$

关于 $\phi$ 的非线性偏微分方程!! (Ma > 0.3)  $Ma < 0.3 : \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial x^2} = 0$ 

$$Ma < 0.3 : \frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} = 0$$

t、f、 $\alpha$ 较小时,翼型周围=来流+小扰动

$$u = V_{\infty} + \hat{u}, v = \hat{v}$$
 û,  $\hat{v}$  扰动速度

$$\phi = V_{\infty} x + \hat{\phi}$$
,  $\hat{\phi}$  扰动速度势  $\hat{u} = \frac{\partial \hat{\phi}}{\partial x}$ ,  $\hat{v} = \frac{\partial \hat{\phi}}{\partial x}$ 

$$\frac{\partial \phi}{\partial x} = V_{\infty} + \frac{\partial \widehat{\phi}}{\partial x}$$

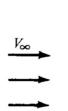
$$\frac{\partial \phi}{\partial x} = \frac{\partial \widehat{\phi}}{\partial x}$$

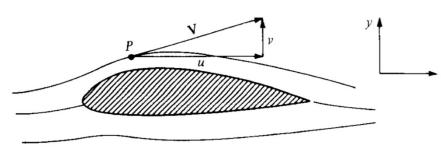
$$\frac{\partial^{2} \phi}{\partial x^{2}} = \frac{\partial^{2} \widehat{\phi}}{\partial x^{2}}$$

$$\frac{\partial^{2} \phi}{\partial x^{2}} = \frac{\partial^{2} \widehat{\phi}}{\partial x^{2}}$$

$$\phi$$
 扰动速度势

$$\frac{\partial x}{\partial y} = \frac{\partial \widehat{\phi}}{\partial y} \qquad \frac{\partial x}{\partial y} \qquad \frac{\partial x^2}{\partial y^2} = \frac{\partial x^2}{\partial y^2}, \quad \frac{\partial^2 \phi}{\partial x \partial y} = \frac{\partial^2 \widehat{\phi}}{\partial x \partial y}$$





代入速度势方程⑤ →

$$\left[a^{2}-(V_{\infty}+\frac{\partial\widehat{\phi}}{\partial x})^{2}\right]\frac{\partial^{2}\widehat{\phi}}{\partial x^{2}}+\left[a^{2}-\left(\frac{\partial\widehat{\phi}}{\partial y}\right)^{2}\right]\frac{\partial^{2}\widehat{\phi}}{\partial y^{2}}-2(V_{\infty}+\frac{\partial\widehat{\phi}}{\partial x})(\frac{\partial\widehat{\phi}}{\partial y})\frac{\partial^{2}\widehat{\phi}}{\partial x\partial y}=0$$

$$[a^{2} - (V_{\infty} + \hat{u})^{2}] \frac{\partial \hat{u}}{\partial x} + (a^{2} - \hat{v}^{2}) \frac{\partial \hat{v}}{\partial y} - 2(V_{\infty} + \hat{u}) \hat{v} \frac{\partial \hat{u}}{\partial y} = 0$$
能量: 
$$\frac{a_{\infty}^{2}}{y-1} + \frac{V_{\infty}^{2}}{2} = \frac{a^{2}}{y-1} + \frac{(V_{\infty} + \hat{u})^{2} + \hat{v}^{2}}{2}$$

小扰动(细长体、小攻角): 
$$\frac{\hat{u}}{v_{\infty}}, \frac{\hat{v}}{v_{\infty}} <<1$$
  $\frac{\hat{u}^2}{v_{\infty}^2}, \frac{\hat{v}^2}{v_{\infty}^2} <<1$ 

1. 
$$Ma_{\infty} \leq 0.8$$
或 $Ma_{\infty} > 1.2$ 时:  $A << (1-Ma_{\infty}^2) \frac{\partial \widehat{u}}{\partial x}$ 

2. 
$$Ma_{\infty} < 5$$
:  $B << \frac{\partial \hat{v}}{\partial v}$   $C \approx 0$ 

$$(1-Ma_{\infty}^{2})\frac{\partial \hat{u}}{\partial x} + \frac{\partial \hat{v}}{\partial y} = 0 线性偏微分方程!!$$

$$(1 - Ma_{\infty}^2) \frac{\partial^2 \widehat{\phi}}{\partial x^2} + \frac{\partial^2 \widehat{\phi}}{\partial y^2} = 0$$

$$(1 - M\alpha_{\infty}^2) \frac{\partial^2 \widehat{\phi}}{\partial x^2} + \frac{\partial^2 \widehat{\phi}}{\partial y^2} = 0$$

适用条件: ①小扰动(薄体、小攻角)

②亚、超声速:  $Ma_{\infty} \leq 0.8$ ,  $Ma_{\infty} > 1.2$ ,  $Ma_{\infty} < 5$ 

不适用: ①厚体、跨声速 $(0.8 < Ma_{\infty} < 1.2)$ 

②高超声速( $Ma_{\infty} > 5$ )

### 13.2线化速度势方程(10.3) $C_p \sim \hat{u}, \hat{v}, \hat{\phi}$ ??

$$C_p \sim \hat{u}, \hat{v}, \hat{\phi}$$
 ??

$$ightharpoons$$
 压力系数线化:  $C_p = rac{p-p_{\infty}}{rac{1}{2}
ho_{\infty}V_{\infty}^2}$   $rac{1}{2}
ho_{\infty}V_{\infty}^2 = rac{1}{2}rac{\gamma p_{\infty}}{\gamma p_{\infty}}
ho_{\infty}V_{\infty}^2$ 

$$\frac{1}{2}\rho_{\infty}V_{\infty}^{2} = \frac{1}{2}\frac{\gamma p_{\infty}}{\gamma p_{\infty}}\rho_{\infty}V_{\infty}^{2}$$

$$= \frac{\gamma}{2}p_{\infty}\frac{\rho_{\infty}}{\gamma p_{\infty}}V_{\infty}^{2} \qquad a_{\infty}^{2} = \frac{\gamma p_{\infty}}{\rho_{\infty}}$$

$$= \frac{\gamma}{2}p_{\infty}Ma_{\infty}^{2}$$

$$C_p = (p - p_{\infty}) \frac{2}{\gamma p_{\infty} M a_{\infty}^2} = (\frac{p}{p_{\infty}} - 1) \frac{2}{\gamma M a_{\infty}^2}$$
 (1)

能量: 
$$T + \frac{V^2}{2C_p} = T_{\infty} + \frac{V_{\infty}^2}{2C_p}$$

$$T - T_{\infty} = \frac{V_{\infty}^2 - V^2}{\frac{2\gamma}{(\gamma - 1)}R}$$

$$\frac{T}{T_{\infty}} - 1 = \frac{\gamma - 1}{2} \frac{V_{\infty}^2 - V^2}{\gamma R T_{\infty}} = \frac{\gamma - 1}{2} \frac{V_{\infty}^2 - V^2}{a_{\infty}^2} = -\frac{\gamma - 1}{2} \frac{(\hat{u}^2 + \hat{v}^2 + 2\hat{u}V_{\infty})}{a_{\infty}^2}$$
$$V^2 = (V_{\infty} + \hat{u})^2 + \hat{v}^2$$

### 13.2线化速度势方程(10.3) $C_p = (\frac{p}{p_n} - 1) \frac{2}{\gamma M a_{\infty}^2}$

$$\frac{T}{T_{\infty}} = 1 - \frac{\gamma - 1}{2} \frac{(\widehat{u}^2 + \widehat{v}^2 + 2\widehat{u}V_{\infty})}{a_{\infty}^2}$$

等熵: 
$$\frac{p}{p_{\infty}} = \left(\frac{T}{T_{\infty}}\right)^{\frac{\gamma}{\gamma-1}} = \left[1 - \frac{\gamma-1}{2} \frac{(\hat{u}^2 + \hat{v}^2 + 2\hat{u}V_{\infty})}{a_{\infty}^2}\right]^{\frac{\gamma}{\gamma-1}}$$
$$= \left[1 - \frac{\gamma-1}{2} M a_{\infty}^2 \left(\frac{2\hat{u}}{V_{\infty}} + \frac{\hat{u}^2 + \hat{v}^2}{V_{\infty}^2}\right)\right]^{\frac{\gamma}{\gamma-1}}$$

$$\varepsilon = \frac{\gamma - 1}{2} M a_{\infty}^2 \left( \frac{2\widehat{u}}{V_{\infty}} + \frac{\widehat{u}^2 + \widehat{v}^2}{V_{\infty}^2} \right)$$

小扰动: 
$$\frac{\hat{u}}{V_{\infty}} << 1 \quad \frac{\hat{u}^2}{V_{\infty}^2}, \frac{\hat{v}^2}{V_{\infty}^2} << 1$$

$$\frac{p}{p_{\infty}} = (1 - \varepsilon)^{\frac{\gamma}{\gamma - 1}} \approx 1 - \frac{\gamma}{\gamma - 1} \varepsilon + \dots = 1 - \frac{\gamma}{2} M a_{\infty}^2 \left(\frac{2\widehat{u}}{V_{\infty}} + \frac{\widehat{u}^2 + \widehat{v}^2}{V_{\infty}^2}\right)$$
 (2)

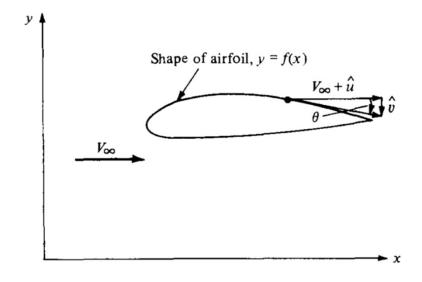
①+② 
$$\rightarrow C_p = -\frac{2\hat{u}}{V_{\infty}} - \frac{\hat{u}^2 + \hat{v}^2}{V_{\infty}^2} \approx -\frac{2\hat{u}}{V_{\infty}}$$
 线化压力系数!

$$\begin{cases} (1 - Ma_{\infty}^{2}) \frac{\partial^{2} \hat{\phi}}{\partial x^{2}} + \frac{\partial^{2} \hat{\phi}}{\partial y^{2}} = 0 & \Rightarrow \hat{\phi}, \hat{u} \Rightarrow C_{p} \\ C_{p} \approx -\frac{2\hat{u}}{V_{\infty}} \end{cases}$$

边界条件:  $@ \circ \hat{\phi} = \text{constant}, \hat{u} = \hat{v} = 0$ 

$$\tan\theta = \frac{v}{u} = \frac{\hat{v}}{V_{\infty} + \hat{u}}$$

$$\hat{u} << V_{\infty}$$
  $\rightarrow \hat{v} = V_{\infty} \tan \theta = V_{\infty} (\frac{dy}{dx})_s$  
$$\frac{\partial \hat{\phi}}{\partial y} = V_{\infty} \tan \theta \text{ $ b \in \mathcal{V}_{\infty} \in \mathcal$$



### 13.3Prandtl-Glauert压缩性修正(10.4)

1904-1940, 低Ma飞行, 不可压空气动力学, 低速翼型理论、实验;

- 二战期间, Ma<sup>↑</sup>, 高速翼型理论, 可压流动, 压缩性修正。
- 1. Prandtl-Glauert方法

(基于线化扰动速度势方程,薄翼、小攻角、Ma <0.7)

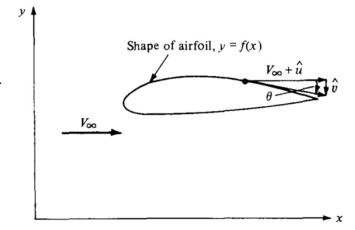
亚声速、可压、无粘流:

$$(1-Ma_{\infty}^2)\frac{\partial^2\widehat{\phi}}{\partial x^2} + \frac{\partial^2\widehat{\phi}}{\partial y^2} = 0$$
  $Ma < 1$ 椭圆型方程

$$\beta^2 \frac{\partial^2 \widehat{\phi}}{\partial x^2} + \frac{\partial^2 \widehat{\phi}}{\partial y^2} = 0 \qquad \beta^2 = 1 - M\alpha_{\infty}^2$$

$$\beta^2 = 1 - Ma_{\infty}^2$$

$$Ma < 1$$
:  $\left| \frac{\partial^2 \widehat{\phi}}{\partial x^2} + \frac{\partial^2 \widehat{\phi}}{\partial y^2} \right| = 0$  美联? ?



### 13.3Prandtl-Glauert压缩性修正(10.4)

$$\beta^2 \frac{\partial^2 \widehat{\phi}}{\partial x^2} + \frac{\partial^2 \widehat{\phi}}{\partial y^2} = 0$$

仿射变换:  $\xi = x, \eta = \beta y$  引入:  $\bar{\phi}(\xi, \eta) = \beta \hat{\phi}(x, y)$ 

$$\frac{\partial \xi}{\partial x} = 1, \frac{\partial \xi}{\partial y} = 0$$

$$\frac{\partial \eta}{\partial x} = 0, \frac{\partial \eta}{\partial y} = \beta$$

$$\frac{\partial \widehat{\phi}}{\partial x} = \frac{1}{\beta} \frac{\partial \overline{\phi}}{\partial \xi} \frac{\partial \xi}{\partial x} = \frac{1}{\beta} \frac{\partial \overline{\phi}}{\partial \xi} \qquad \qquad \frac{\partial^2 \widehat{\phi}}{\partial x^2} = \frac{1}{\beta} \frac{\partial^2 \overline{\phi}}{\partial \xi^2} \frac{\partial \xi}{\partial x} = \frac{1}{\beta} \frac{\partial^2 \overline{\phi}}{\partial \xi^2}$$

$$\frac{\partial \widehat{\phi}}{\partial y} = \frac{1}{\beta} \frac{\partial \overline{\phi}}{\partial \eta} \frac{\partial \eta}{\partial y} = \frac{\partial \overline{\phi}}{\partial \eta} \qquad \qquad \frac{\partial^2 \widehat{\phi}}{\partial y^2} = \frac{\partial^2 \overline{\phi}}{\partial \eta^2} \frac{\partial \eta}{\partial y} = \beta \frac{\partial^2 \overline{\phi}}{\partial \eta^2}$$

$$\beta^{2} \frac{\partial^{2} \hat{\phi}}{\partial x^{2}} + \frac{\partial^{2} \hat{\phi}}{\partial y^{2}} = 0 \qquad \Longrightarrow \qquad \beta^{2} \frac{1}{\beta} \frac{\partial^{2} \bar{\phi}}{\partial \xi^{2}} + \beta \frac{\partial^{2} \bar{\phi}}{\partial \eta^{2}} = 0$$

$$\frac{\partial^{2} \bar{\phi}}{\partial \xi^{2}} + \frac{\partial^{2} \bar{\phi}}{\partial \eta^{2}} = 0 \qquad \nabla^{2} \bar{\phi} = 0 \quad \text{不可压势方程!} \quad !$$