TITLE

Automatic Control
Electronic Engineering for Intelligent Vehicles
University of Bologna

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Abstract

Here briefly detail the aims of the project.

Chapter 1

Introduction

1.0.1 Linearization

$$
\begin{aligned}
\dot{x} &= f(x, u) \quad x(t_0) = x_0 \\
y &= h(x, u)
\end{aligned}
\tag{1.1}
$$