

$$\dot{x} = f(x, u, w)$$

$$f := \begin{bmatrix} v \\ -\frac{k}{m}(p-l_0) - \frac{\beta}{m}v^3 + \frac{1}{m}u + \frac{1}{m}L - g \end{bmatrix} =: \begin{bmatrix} f_1(x, u, w) \\ f_2(x, u, w) \end{bmatrix}$$

$$y = h(x, u, w) := p + r \quad x := \begin{bmatrix} p \\ v \end{bmatrix}, d := \begin{bmatrix} L \\ g \end{bmatrix}, w := \begin{bmatrix} d \\ r \end{bmatrix}$$

$$e = h_e(x, u, w) := p + r - r$$

$$A(x, u, w) := \frac{\partial f}{\partial x} = \begin{bmatrix} \frac{\partial f_1}{\partial p} & \frac{\partial f_1}{\partial v} \\ \frac{\partial f_2}{\partial p} & \frac{\partial f_2}{\partial v} \end{bmatrix} = \begin{bmatrix} 0 & 1 \\ -\frac{k}{m} & -\frac{3\beta}{m}v^2 \end{bmatrix}$$

$$= \begin{bmatrix} 0 & 1 \\ -\frac{k}{m} & -\frac{3\beta}{m}v^2 \end{bmatrix}$$

$$B_1(x, u, w) := \frac{\partial f}{\partial u} = \begin{bmatrix} 0 \\ \frac{1}{m} \end{bmatrix} \quad B_2(x, u, w) := \frac{\partial f}{\partial w} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ \frac{1}{m} & -1 & 0 & 0 \end{bmatrix}$$

$$C(x, u, w) := \frac{\partial h}{\partial x} = \begin{bmatrix} 1 & 0 \end{bmatrix}$$

$$D_1(x, u, w) := \frac{\partial h}{\partial u} = 0 \quad D_2(x, u, w) := \frac{\partial h}{\partial w} = \begin{bmatrix} 0 & 0 & 1 & 0 \end{bmatrix}$$

$$C_e(x, u, w) := \frac{\partial h_e}{\partial x} = \begin{bmatrix} 1 & 0 \end{bmatrix}$$

$$D_{e1}(x, u, w) := \frac{\partial h_e}{\partial u} = 0 \quad D_{e2}(x, u, w) := \frac{\partial h_e}{\partial w} = \begin{bmatrix} 0 & 0 & 1 & -1 \end{bmatrix}$$

EQUILIBRIUM TRIPLET

$$\dot{x}^* = f(x^*, u^*, w^*) = 0$$

$$f := \begin{bmatrix} v^* \\ -\frac{k}{m} (p^* - l_0) - \frac{B}{m} [v^*]^2 + \frac{1}{m} u^* + \frac{1}{m} [-g^*] \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$v^* = 0$$

$$e^* = h_e(x^*, u^*, w^*) := \underset{r}{p^*} + \underset{v}{v^*} - r^* = 0 \quad \dot{r}^* = 0$$

$$\text{GIVEN } r^* \Rightarrow p^* = r^* \Rightarrow e^* = 0 \text{ if } \dot{r}^* = 0$$

$$-\frac{k}{m} (p^* - l_0) - \frac{B}{m} [v^*]^2 + \frac{1}{m} u^* + \frac{1}{m} [-g^*] = 0$$

$$\cancel{\frac{m}{m}} u^* = - \left[\underset{\parallel}{-\frac{k}{m} (p^* - l_0)} - \underset{\parallel}{\frac{B}{m} [v^*]^2} + \frac{1}{m} [-g^*] \right] m$$

\parallel
 r^* \parallel
 0

$$u^* = k(r^* - l_0) - L^* + m g^*$$

$$g^* \approx 9.8 \text{ m/s}^2$$

$$L^* = 0$$