

# MiniOS CS499 Fall 24

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# Agenda

- Lay out the project goals, requirements, and deliverables.
- Demo the OS.
- Give a quick overview on some of the technical internals/achievements.
- Offer some advice to the customer.
- Reflect on the solution that has been delivered.

# Project Goals and Requirements

- “Our group will deliver an i386 OS capable of running on QEMU; this can further be separated into three main deliverables: source code, kernel documentation, and a prebuilt .iso file”.
- Input/Output, Data, Security
- Virtual Memory, Interrupts, Processes/Scheduling, Filesystem, System Calls, Userspace Utilities.

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# Technical Achievements

- OS Development requires quite a few complex components:
- Bootloader (GRUB), build system (linker, cross-compiler, qemu), GDT, IDT, interrupt handlers, multiple memory allocators, keyboard driver, round robin scheduler, blocking logic, ipc (ringbuffers), system calls, simple paging, terminal output code, libc, hardware interrupt controller configuration, stack management, shell and other programs...
- Some of these are “better” than others, but they’re all there.

# Syscalls

- `send`, `recv`, `exit`, `spawn`, `spawn_bg`, `pid`.
- The programmer tailors a structure according to one of the above, triggers a software interrupt, and the OS then handles the syscall.
- `send` sends a message over IPC, etc.
- We've produced an accompanying developer document that introduces each syscall and how run programs on MiniOS.

# Reflection on Syscalls

- At the end when attempting to debug bidirectional IPC, we realized we had to extend them to include “sender” data.
- Didn’t implement the POSIX interface; prevents porting of real applications.
- Designing this interface well is *extremely important*; whoever purchases the OS will write programs via this interface.

# Processes and Scheduling

- As show by the demo, we can spawn processes that can block or run unblocked.
- Accomplished with a round-robin scheduler that records what specifically a process is blocking on (whether that be STDIN or waiting on an IPC message).
- Was difficult to debug: non-deterministic, multi-processing, interacts with the underlying hardware, have to reason about the code the compiler produces, etc.

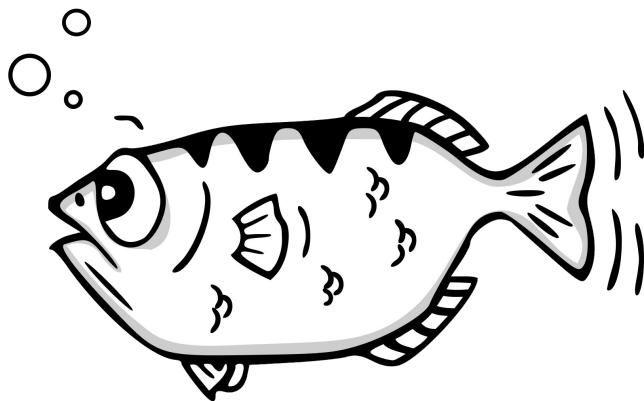
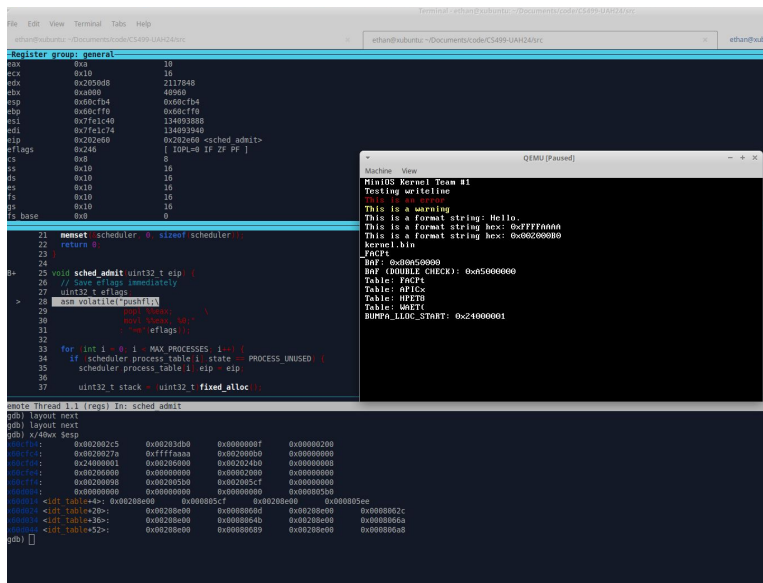


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# Testing and Debugging Cont.

- There are some portions that can be tested: `ringbuffer_t` is tested with unit tests.
- Other “tests” can be seen on the screen on bootup and have to be verified by a user.
- Interacting with the OS is often the easiest way to find and fix multiprocessing bugs.

# Testing and Debugging Cont.

- The OS is filled with bugs; as an example, bidirectional IPC is broken.
- These bugs are the result of OS development being an *very* difficult problem.

# Recommendations to the Customer

- Don't use this OS in production! Use our experience and mistakes to inform what you should do next.
- Constrain the requirements: maybe you don't need dynamic memory allocation, a keyboard driver, or a complex scheduler.
- Buy an embedded OS off the shelf – we've got enough knowledge now to maybe extend that.



# Reflections on the MiniOS Project

- Debugging these low-level, multiprocessing, hardware-adjacent problems is absolutely hell.
- It's important to be skilled with your tools: being more comfortable with GDB could have sped up iteration and debugging.
- It's one thing to learn OS “theory”, proper implementation is another thing entirely.