

EE230 TERM PROJECT

2.1.

$$a) R = E[R_t] = 20P_G + 5P_M + 0P_B = 20P_G + 5P_M$$

$$\text{Var}(R_t) = E[R_t^2] - (E[R_t])^2$$

$$E[R_t^2] = 400P_G + 25P_M$$

$$(E[R_t])^2 = 400P_G^2 + 200P_GP_M + 25P_M^2$$

$$\text{Var}(R_t) = 400P_G + 25P_M - 400P_G^2 - 200P_GP_M - 25P_M^2$$

$$b) E[R^T] = E\left[\frac{1}{T} \sum_{t=1}^T R_t\right] = \frac{1}{T} E\left[\sum_{t=1}^T R_t\right]$$

$$= \frac{1}{T} E[R_1 + R_2 + \dots + R_T] = \frac{1}{T} (E[R_1] + E[R_2] + \dots + E[R_T])$$

↑
expectation is linear

$$= \frac{1}{T} (20P_G + 5P_M) \cdot T = 20P_G + 5P_M$$

$$\text{Var}(R^T) = \text{Var}\left(\frac{R_1 + R_2 + \dots + R_T}{T}\right) = \text{Var}\left(\frac{R_1}{T}\right) + \text{Var}\left(\frac{R_2}{T}\right) + \dots + \text{Var}\left(\frac{R_T}{T}\right)$$

↑
Variance is linear since R_1, R_2, \dots, R_T are independent

$$\text{Var}\left(\frac{R_t}{T}\right) = \frac{1}{T^2} \text{Var}(R_t) = \frac{1}{T^2} (400P_G + 25P_M - 400P_G^2 - 200P_GP_M - 25P_M^2)$$

$$\text{Var}(R^T) = \sum_{t=1}^T \frac{1}{T^2} \text{Var}(R_t) = \frac{1}{T^2} \text{Var}(R_t) \cdot T = \frac{1}{T} \text{Var}(R_t)$$

$$= \frac{1}{T} (400P_G + 25P_M - 400P_G^2 - 200P_GP_M - 25P_M^2)$$

e) If x takes only nonnegative values, then

$$P(X \geq a) \leq \frac{\langle x \rangle}{a}. \text{ To prove,}$$

$$\langle x \rangle = \int_0^{\infty} x P(x) dx = \int_0^a x P(x) dx + \int_a^{\infty} x P(x) dx$$

$$\langle x \rangle = \int_0^{\infty} x P(x) dx + \int_a^{\infty} x P(x) dx \geq \int_a^{\infty} x P(x) dx \geq \int_a^{\infty} a P(x) dx$$

$$\int_a^{\infty} P(x) dx = a P(X \geq a) = \langle x \rangle \Rightarrow P(X \geq a) = \frac{\langle x \rangle}{a}$$

Let $a = k^2$. $P[(x-M)^2 \geq k^2] \leq \frac{\overbrace{\langle (x-M)^2 \rangle}^{\text{expectation}}}{k^2} = \frac{\underbrace{\sigma^2}_{\text{variance}}}{k^2}$

$P(|x-M| \geq k) \leq \frac{\sigma^2}{k^2} \Rightarrow$ Putting $k\sigma$ into $k \Rightarrow$

$P(|x-M| \geq k\sigma) \leq \frac{1}{k^2}$ Let $R^T = \frac{1}{T} \sum_{t=1}^T R_t$

$R^T = \frac{R_1 + R_2 + \dots + R_T}{T}$

Since P_G, P_M, P_B are independent and identically distributed random variables, each R_1, R_2, \dots, R_T have a mean μ and a standard deviation σ .

So, $\langle R^T \rangle = \frac{1}{T} (\langle R_1 \rangle + \langle R_2 \rangle + \dots + \langle R_T \rangle)$

$= \frac{1}{T} \cdot (M \cdot T) = M //$

$\text{Var}(R^T) = \text{Var}\left(\frac{R_1 + R_2 + \dots + R_T}{T}\right) \stackrel{\text{independence}}{=} \text{Var}\left(\frac{R_1}{T}\right) + \text{Var}\left(\frac{R_2}{T}\right) + \dots + \text{Var}\left(\frac{R_T}{T}\right)$

$= \frac{\sigma^2}{T^2} \cdot T = \frac{\sigma^2}{T} //$

f) Since an outage event lasts longer than k frames for $k \geq 1$, where $(1-P_B)$ term denotes the exit from outage event,

$\sum_{m=k+1}^{\infty} P_B^m (1-P_B)$

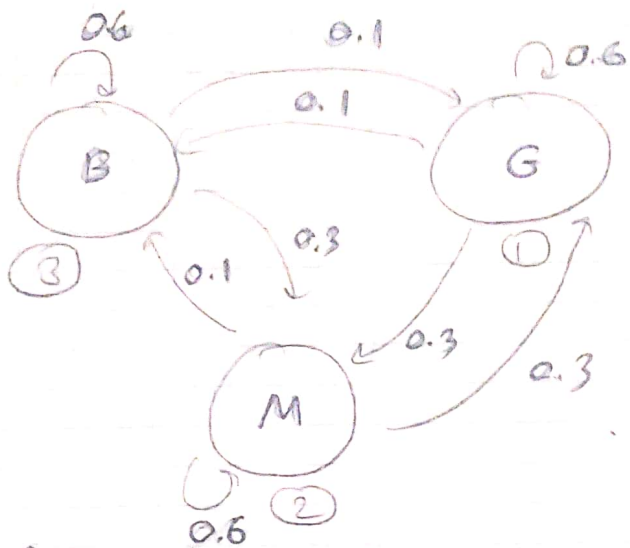
$= \sum_{m=0}^{\infty} P_B^{m+k+1} (1-P_B) = P_B^{k+1} \cdot (1-P_B) \sum_{m=0}^{\infty} P_B^m$

$= P_B^{k+1} (1-P_B) \left(\frac{1}{1-P_B} \right)$

$\boxed{\sum_{m=k+1}^{\infty} P_B^m (1-P_B) = \underline{\underline{P_B^{k+1}}}}$

2.2

a)



$$P_{BB} = 0.6$$

$$P_{BM} = 0.3$$

$$P_{BG} = 0.1$$

$$P_{MG} = 0.3$$

$$P_{MB} = 0.1$$

$$P_{GB} = 0.1$$

$$P_{GM} = 0.3$$

$$P_{GG} = 0.6$$

$$P_{MM} = 0.6$$

b)

$$P = \begin{matrix} & \begin{matrix} (G) & (M) & (B) \end{matrix} \\ \begin{matrix} (G) \\ (M) \\ (B) \end{matrix} & \begin{bmatrix} 0.6 & 0.3 & 0.1 \\ 0.3 & 0.6 & 0.1 \\ 0.1 & 0.3 & 0.6 \end{bmatrix} \end{matrix}$$

$$P^2 = \begin{bmatrix} 0.46 & 0.39 & 0.15 \\ 0.37 & 0.48 & 0.15 \\ 0.24 & 0.39 & 0.4 \end{bmatrix}$$

c)

$$P^{10} = \begin{bmatrix} 0.3716 & 0.4286 & 0.1998 \\ 0.3716 & 0.4286 & 0.1998 \\ 0.3706 & 0.4286 & 0.2008 \end{bmatrix}$$

$$P^{20} = \begin{bmatrix} 0.3714 & 0.4286 & 0.2 \\ 0.3714 & 0.4286 & 0.2 \\ 0.3714 & 0.4286 & 0.2 \end{bmatrix}$$

Difference between P^{10} and P^{15} can be seen in long format,

$$P^{25} = \begin{bmatrix} 0.3714 & 0.4286 & 0.2 \\ 0.3714 & 0.4286 & 0.2 \\ 0.3714 & 0.4286 & 0.2 \end{bmatrix}$$

but since we want to find what they are converging it is not necessary.

They are converging to $\boxed{0.3714, 0.4286, 0.2}$.

d) $\pi = \pi \cdot P$ let $\pi = [a \ b \ c]$ then, we have to

use two linearly independent vectors from P and $a+b+c=1$ equation

$$\pi = [a \ b \ c] \begin{bmatrix} 0.6 & 0.3 & 0.1 \\ 0.3 & 0.6 & 0.1 \\ 0.1 & 0.3 & 0.6 \end{bmatrix}$$

$$\Rightarrow \pi = \left[\overbrace{0.6a + 0.3b + 0.3c}^a \quad \overbrace{0.3a + 0.6b + 0.3c}^b \quad \overbrace{0.1a + 0.1b + 0.6c}^c \right]$$

$$-0.4a + 0.3b + 0.1c = 0$$

$$0.1a + 0.1b - 0.4c = 0$$

$$a + b + c - 1 = 0$$

\rightarrow

$$a = 0.3714$$

$$b = 0.4286$$

$$c = 0.2$$

$$\pi = [0.3714 \ 0.4286 \ 0.2]$$

Steady State

Probability Vector

$$a = P_G \quad b = P_M \quad c = P_B$$

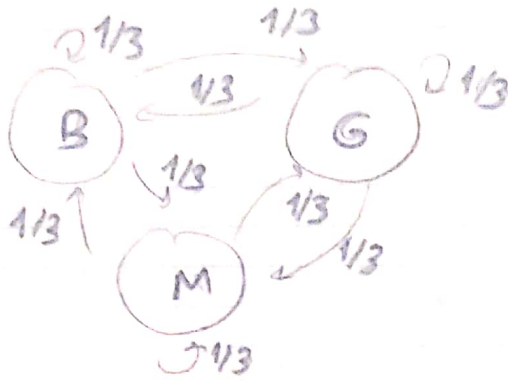
e) $\sum_{k=1}^{\infty} k \cdot p_{BB}^{(k-1)} \cdot (1 - p_{BB}) = E[T]$ T: Duration of an outage

Since it is a geometric series $E[T] = \frac{1}{1 - p_{BB}} = \frac{10}{6}$

$$\text{Var}(T) = \frac{1 - (p_{BB})}{(p_{BB})^2} = \frac{0.4}{0.36} = \frac{10}{9}$$

f)

2.2 - 9



$$P = \begin{bmatrix} 1/3 & 1/3 & 1/3 \\ 1/3 & 1/3 & 1/3 \\ 1/3 & 1/3 & 1/3 \end{bmatrix}$$

$$P^2 = \begin{bmatrix} 1/3 & 1/3 & 1/3 \\ 1/3 & 1/3 & 1/3 \\ 1/3 & 1/3 & 1/3 \end{bmatrix}$$

All values are same for all steps and they are $1/3$.

$$\pi = \pi \cdot P \quad \text{Let } \pi = [a \ b \ c]$$

$$\left. \begin{aligned} \frac{a}{3} + \frac{b}{3} + \frac{c}{3} &= a \\ \frac{a}{3} + \frac{b}{3} + \frac{c}{3} &= b \\ a + b + c &= 1 \end{aligned} \right\} a = b = c = 1/3$$

$$\frac{a}{3} + \frac{b}{3} + \frac{c}{3} = b$$

$$a + b + c = 1$$

$$\pi = [1/3 \ 1/3 \ 1/3]$$

Steady state probability vector

$$E[T] = \sum_{k=1}^{\infty} (P_{BB})^{k-1} \cdot (1 - P_{BB}) = \frac{1}{P_{BB}} = 3$$

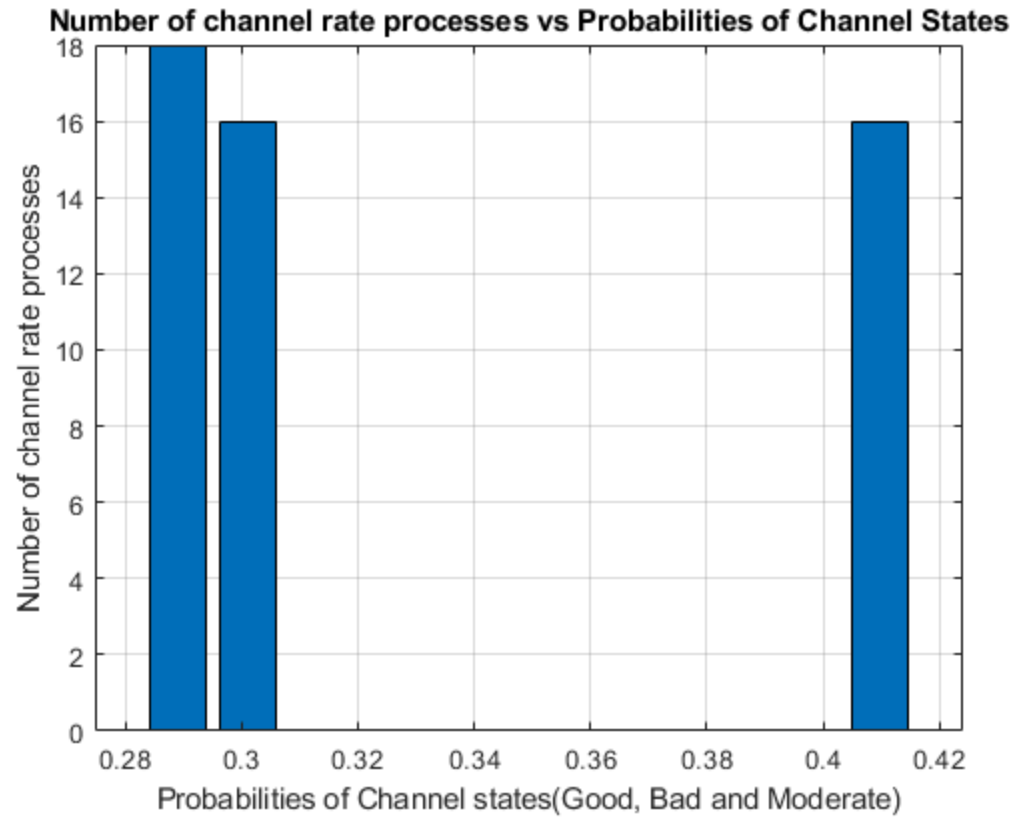
$$\text{Var}(T) = \frac{1 - P_{BB}}{(P_{BB})^2} = \frac{2/3}{1/9} = 6$$

```
%2.1-part-c
x=rand(2,1);
a=x(1,1);
b=x(2,1);

while (a+b) > 1%%we generate two variable until their sum is lower
    than 1

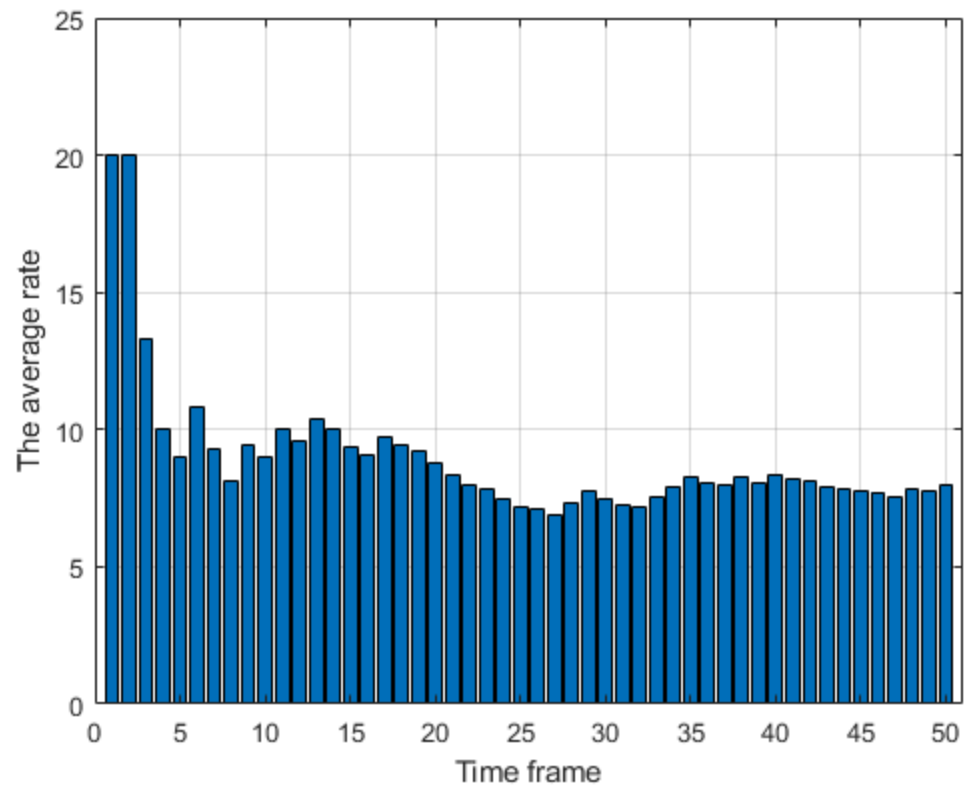
        x=rand(2,1);
        a=x(1,1);
        b=x(2,1);

    continue
end
c=1-a-b;%Then by using these two variables we get 3 random
probabilities.
p=zeros(3,1);
p=[a;b;c];%Probability vector
Y1=rand(1,50);%Frame vector
R=zeros(3,1);%Number of Good, Bad and Moderate vector(R(1,1)=#Good,
R(2,1)=#Bad R(3,1)=#Moderate)
Y1=Y1.';
Y2=zeros(50,1);
for i=1:50
    if 0<Y1(i,1) && Y1(i,1)<=a
        R(1,1)=R(1,1)+1;
        Y2(i,1)=20;
    else if a<Y1(i,1) && Y1(i,1)<=b+a
        R(2,1)=R(2,1)+1;
        Y2(i,1)=5;
    else
        R(3,1)=R(3,1)+1;
        Y2(i,1)=0;
    end
end
end
figure(1)
bar(p,R);
grid on;
ylabel('Number of channel rate processes');
xlabel('Probabilities of Channel states(Good, Bad and Moderate)');
title('Number of channel rate processes vs Probabilities of Channel
States')
```



```
%2.1-part-d
Y3=zeros(50,1);%Running time average vector
for T=1:50
    for i=1:T
        Y3(T,1)=Y3(T,1)+Y2(i,1);
    end
    Y3(T,1)=Y3(T,1)/T;

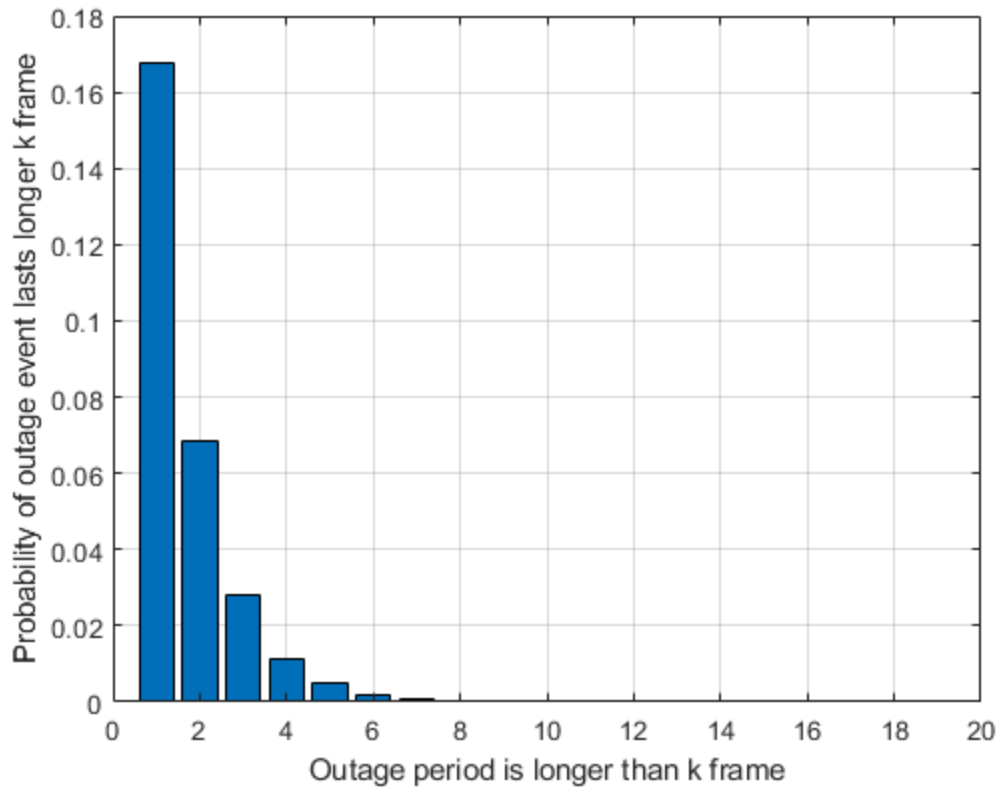
end
T1=[1:50];
figure(2)
bar(T1,Y3);
grid on
ylim([0 25]);
xlim([0 51]);
xlabel('Time frame');
ylabel('The average rate');
```



```
%part 2.1-f
B=zeros(50,1);%outage vector

for k=1:50
    for m=k:50
        B(k,1)=B(k,1)+((b^(m+1))*(1-b)); %b=outage probability
    end
end

u=[1:50];
figure(3)
bar(u, B);
grid on;
xlim([0,20]);
xlabel('Outage period is longer than k frame');
ylabel('Probability of outage event lasts longer k frame');
```

```
%Analysis of the Indoor Link
%2.2-part c
P1=[.6, .3, .1; .3, .6, .1; .1, .3, .6];%Transition probability matrix
n=25;
X1=P1^n;%X1=P1^25.
A=[-0.4, 0.3, 0.1; 0.1, 0.1, -0.4; 1 1 1];
Y=[0; 0; 1];
K=inv(A)*Y %K steady state probability vector
```

K =

```
0.3714
0.4286
0.2000
```

```
%2.2 part-f
F=NaN(500,1);
k=rand();%We define the first state
if 0<k<=1/3
    F(1,1)=0;%G=0
end
if 1/3<k && k<2/3
    F(1,1)=1;%B=1
else
    F(1,1)=2;%M=2
```

```

end

for i=2:500
    if F(i-1,1)==0%We are stating ith state according to i-1th state
        k=rand();

        if 0<=k && k<=0.6
            F(i,1)=0;%G
        end
    elseif 0.6<k && k<=0.7

        F(i,1)=1;

    else F(i,1)=2;

end

if F(i-1,1)==1%We are stating ith state according to i-1th state
    k=rand();

    if 0<=k && k<=0.6
        F(i,1)=1;

    elseif 0.6<k && k<=0.7

        F(i,1)=0;
    else
        F(i,1)=2;

    end
end

if F(i-1,1)==2%We are stating ith state according to i-1th state
    k=rand();

    if 0<=k && k<=0.6
        F(i,1)=2;

    elseif 0.6<k && k<=0.7

        F(i,1)=1;

    else F(i,1)=0;
    end
end

end

for i=1:160%In F vector I got NaN values so I randomly assign values
    for specific NaN's.

```

```

        if F(i,1)~= 1 && F(i,1)~=0 && F(i,1)~=2
            F(i,1)=1;
        end
    end
    for i=161:320
        if F(i,1)~= 1 && F(i,1)~=0 && F(i,1)~=2
            F(i,1)=0;
        end
    end
    for i=321:500
        if F(i,1)~= 1 && F(i,1)~=0 && F(i,1)~=2
            F(i,1)=2;
        end
    end

    q=0;
    for i=1:500
        if F(i,1)==1
            q=i;%First index of B
            break;
        end

    end
    k3=0;
    for i=1:500

        if F(501-i,1)==1
            k3=501-i;%last index of B

        break;
    end

    end
    q3=0;
    for i=1:500
        if F(i,1)==1
            q3=q3+1;%number of B
        end

    end

    j=(k3-q)/(q3-1)%Expected duration of the period between two outages.

    j =

        5.1263

```

Published with MATLAB® R2018b

```
P1=[1/3, 1/3, 1/3; 1/3, 1/3, 1/3; 1/3, 1/3, 1/3];%Transition
probability matrix
n=25;
X1=P1^n;%X1=P1^25.

K=[1/3; 1/3; 1/3] %K steady state probability vector

K =

    0.3333
    0.3333
    0.3333

%2.2 part-f
F=NaN(500,1);
k=rand();%We define the first state
if 0<k<=1/3
    F(1,1)=0;%G=0
end
if 1/3<k && k<2/3
    F(1,1)=1;%B=1
else
    F(1,1)=2;%M=2
end

for i=2:500
    if F(i-1,1)==0%We are stating ith state according to i-1th state
        k=rand();

        if 0<=k && k<=1/3
            F(i,1)=0;%G
        end
    elseif 1/3<k && k<=2/3

        F(i,1)=1;

    else F(i,1)=2;

end

if F(i-1,1)==1%We are stating ith state according to i-1th state
    k=rand();

    if 0<=k && k<=1/3
        F(i,1)=1;

    elseif 1/3<k&& k<=2/3

        F(i,1)=0;

    else
```

```

        F(i,1)=2;

    end
end

if F(i-1,1)==2%We are stating ith state according to i-1th state
    k=rand();

    if 0<=k && k<=1/3
        F(i,1)=2;

    elseif 1/3<k && k<=2/3

        F(i,1)=1;

    else F(i,1)=0;
        end
    end

end

for i=1:160%In F vector I got NaN values so I randomly assign values
    for specific NaN's.
        if F(i,1)~= 1 && F(i,1)~=0 && F(i,1)~=2
            F(i,1)=1;
        end
    end
for i=161:320
    if F(i,1)~= 1 && F(i,1)~=0 && F(i,1)~=2
        F(i,1)=0;
    end
end
for i=321:500
    if F(i,1)~= 1 && F(i,1)~=0 && F(i,1)~=2
        F(i,1)=2;
    end
end

q=0;
for i=1:500
    if F(i,1)==1
        q=i;%First index of B
        break;
    end
end

```

```
end
k3=0;
for i=1:500

    if F(501-i,1)==1
        k3=501-i;%last index of B

    break;
end

end
q3=0;
for i=1:500
    if F(i,1)==1
        q3=q3+1;%number of B
    end

end

j=(k3-q)/(q3-1)%Expected duration of the period between two outages.

j =

    3.1392
```

Published with MATLAB® R2018b

3. Conclusions

In the "Outdoor Link" part, the system is memoryless, since the probabilities of getting a Good (G), Moderate (M) or Bad (B) state are constant, hence independent of the previous states.

On the other hand, in the "Indoor Link" part, the probability of getting a state is dependent of the previous state, which indicates that the system is with memory. For example, probabilities of entering a Bad (B) state changes with previous state: $P_{BB}=0.6$, $P_{GB}=0.1$, $P_{MB}=0.1$.

Increasing the memory of a system (in this case, entering the Indoor Link situation from Outdoor Link situation) lowers the variance of the outage duration.

The system with increased memory is better, since its variance is lower, it is more stable.