



UNIVERSITEIT VAN PRETORIA
UNIVERSITY OF PRETORIA
YUNIBESITHI YA PRETORIA

Denkieleers • Leading Minds • Dikgopolo tš'a Dihalefi

PROCESS DYNAMICS – CPN321

SEMESTER TEST 2

Chemical Engineering
Engineering and the Built Environment

Examiner: Carl Sandrock

Date: 2017-10-09

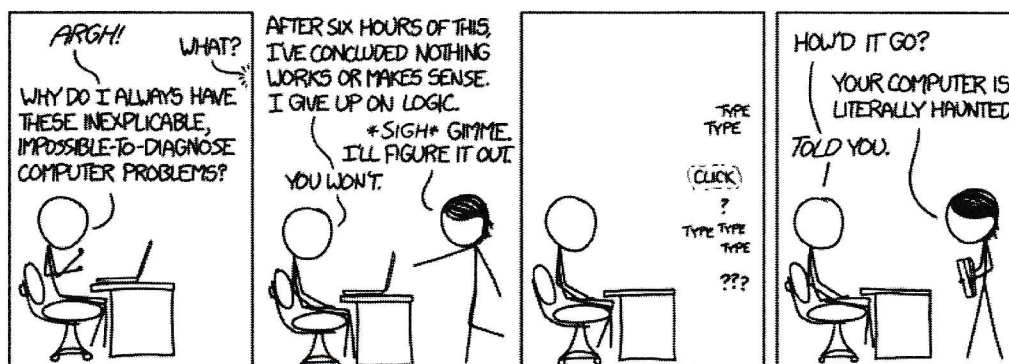
Duration: 90 minutes

Total: 90

Total Pages: 6

Instructions – Read carefully

- Answer all the questions.
- This is a closed book test. All the information you may use is contained in the paper.
- You may use the computer
- Make sure that you motivate all your answers and write legibly.



xkcd.com

1 Second order dynamics

Consider the following differential equation. u' and x' are deviation variables of u and x respectively. a , b and c are all positive.

$$a \frac{dx}{dt^2} + b \frac{dx'}{dt} + cx'(t) = u'(t) \quad (1)$$

1. Find the transfer function between u and x . 5
2. Find the gain, time constant and damping coefficient of the system in terms of a , b and c . 10
3. When u is moved suddenly from 2,3 kg/h to 4,0 kg/h, x moves from 12,1 °C and eventually ends up around 15,8 °C. What is the gain of the process? 5
4. Plant personnel describe the step response as having a slight overshoot and a rise time of 10 minutes. Draw a sketch showing the response and indicate the rise time, overshoot and time constant. What does this information tell you about the damping coefficient of the system? 10

Total for question 1: 30

2 Complex system dynamics

Due to limitations in software used on site, you have decided to approximate a model of a piece of equipment as a second order plus dead time system as follows:

$$\frac{(s - 1)}{(3s + 1)^3(s + 2)} \approx \frac{Ke^{-\theta s}}{(\tau_1 s + 1)(\tau_2 s + 1)} \quad (2)$$

1. Find K , τ_1 and τ_2 using Skogestad's half rule 20
2. Sketch a qualitative response of the original system to a step input. Indicate key features of the response on the graph. Mention the gain, poles and zeros. 10
3. An engineer on site criticizes your approximation by saying "Your approximation no longer exhibits inverse response". Is she right? Is this a serious problem? 5
4. Explain why Skogestad's half rule could not be used for the system in equation 1 with reference to the nature of the poles. 5

Total for question 2: 40

3 Multivariable system representations

Consider the following state space description of a system:

$$\frac{dx}{dt} = Ax + Bu \quad (3)$$

$$y = Cx + Du \quad (4)$$

with

$$A = \begin{bmatrix} -1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -\frac{1}{2} \end{bmatrix} \quad B = \begin{bmatrix} 2 & 0 \\ 0 & 2 \\ 0 & 1 \end{bmatrix} \quad C = \begin{bmatrix} 1 & \frac{3}{2} & 0 \\ \frac{1}{2} & 0 & 1 \end{bmatrix} \quad D = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

1. How many inputs, states and outputs does this model have? Motivate your answer. 5
2. Obtain a transfer function matrix for this model. Derive any equations that you use in the process and write each matrix element as a simplified rational function of s . 10
3. Determine whether the system is stable without referring to the transfer function model. Show your working. 5

Total for question 3: 20

Full Marks 90