

Mat and Image, Video



Image Reading

```
//image reading
Mat img = imread("ss.jpg"); //imread("ss.jpg",0); -> grayscale
namedWindow("img", 0); //make window
imshow("img", img); //show
waitKey(0);
```

Video Reading

```
//video reading
//VideoCapture cap(0); // open the default camera
VideoCapture cap("rhinos.avi"); // open the video file
if (!cap.isOpened()) // check if we succeeded
    return -1;

namedWindow("video", 1);
for (;;)
{
    Mat frame;
    cap >> frame; // get a new frame from camera
    imshow("video", frame);
    if (waitKey(30) >= 0)
        break;
}
// the camera will be deinitialized automatically in VideoCapture destructor
return 0;
```

Image reading:

http://study.marearts.com/2016/06/opencv-matcopyto-clone-roi-example-code.html

KeyCode:

<u>http://study.marearts.com/2016/11/keycode-and-ascii-</u> code.html

Video reading:

http://study.marearts.com/2013/09/opencv-video-file-load-and-display.html

Mat and Image

Image related functions Mat img = imread(tr(imq.cols)





```
Mat img = imread("ss.jpg");
Rect r(img.cols / 4, img.rows / 4, img.cols / 4 * 2, img.rows / 4 * 2);
//clone #1
Mat img2 = img.clone();
bitwise_not(img2, img2);
//clone #2
Mat img5 = img(r).clone();
//copyTo #1
Mat cimg;
img.copyTo(cimg);
//copyTo #2
Mat cimg2;
img(r).copyTo(cimg2);
Mat cimg3(Size(img.cols * 2, img.rows), img.type());
cimg3.setTo(255);
img.copyTo(cimg3(Range::all(), Range(0, img.cols)));
img2.copyTo(cimg3(Range::all(), Range(img2.cols, img2.cols * 2)));
Mat roi(img, r);
bitwise_not(roi, roi);
```









- Image Reading And Pixel Access in Mat
 - o 1. using 'at'
 - Safety but most slow
 - 2. using 'ptr'
 - Faster than 'at'
 - 3. using 'data'
 - Fastest but unsafety

http://study.marearts.com/2014/04/opencv-study-mat-point-access-method.html http://study.marearts.com/2016/06/opencv-pixel-access-at-ptr-data.html

^{*} Refer at, ptr, data, iteration example code to

at case

```
//using at
for (int i = img.rows / 10*3; i < img.rows / 10*4; ++i)
{
    for (int j = 0; j < img.cols; ++j)
    {
        //Vec3b means 'uchar 3ch'
        unsigned char b = img.at < cv::Vec3b>(i, j)[0];
        unsigned char g = img.at < cv::Vec3b>(i, j)[1];
        unsigned char r = img.at < cv::Vec3b>(i, j)[2];

        //printf("%d %d %d\n", b, g, r);

        img.at < cv::Vec3b>(i, j)[0] = unsigned char(255 - b); //b
        img.at < cv::Vec3b>(i, j)[1] = unsigned char(255 - g); //g
        img.at < cv::Vec3b>(i, j)[2] = unsigned char(255 - r); //r
    }
}
```



ptr case

```
//using ptr
for (int i = img.rows / 10 * 6; i < img.rows / 10 * 7; i++) {
    cv::Vec3b* ptr = img.ptr< cv::Vec3b>(i);
    for (int j = 0; j < img.cols; j++) {
        cv::Vec3b bgr = ptr[j];
        unsigned char b = (bgr[0]);
        unsigned char g = (ptr[j][1]); //note!!
        unsigned char r = (bgr[2]);
        ptr[j] = cv::Vec3b(255 - b, 255 - g, 255 - r);
    }
}</pre>
```

data case

```
//using data
for (int i = img.rows / 10 * 8; i < img.rows / 10 * 9; i++) {
    for (int j = 0; j < img.cols; j++) {
        unsigned char r, g, b;
        b = img.data[i * img.step + j * img.elemSize() + 0];
        g = img.data[i * img.step + j * img.elemSize() + 1];
        r = img.data[i * img.step + j * img.elemSize() + 2];

    img.data[i * img.step + j * img.elemSize() + 0] = unsigned char(255 - b);
    img.data[i * img.step + j * img.elemSize() + 1] = unsigned char(255 - g);
    img.data[i * img.step + j * img.elemSize() + 2] = unsigned char(255 - r);
}
</pre>
```



STL iteration case

```
//using iteration
cv::MatIterator_< cv::Vec3b> itd = img.begin< cv::Vec3b>(), itd_end = img.end< cv::Vec3b>();
for (int i = 0; itd != itd_end; ++itd, ++i) {
    cv::Vec3b bgr = (*itd);

    (*itd)[0] = 255 - bgr[0];
    (*itd)[1] = 255 - bgr[1];
    (*itd)[2] = 255 - bgr[2];
}
```

Input & output

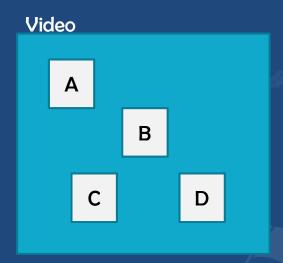








- Assignment #1
 - Make color invert in each region in video image
 - A : use 'at' operator
 - A : use 'ptr' operator
 - A : use 'iterator' operator
 - A : use 'data' operator
 - * Region's position and scale is free.



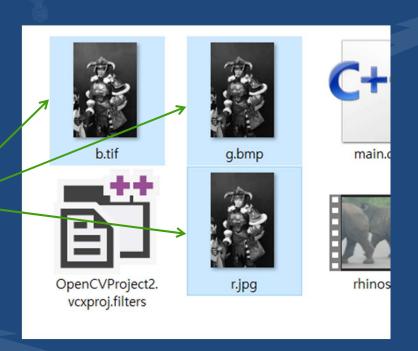
Mat and Image, video write

Image write

```
Mat img = imread("ss.jpg");
vector< Mat> rgbMat(3);
cv::split(img, rgbMat);

namedWindow("img", 0); //make window
imshow("img", rgbMat[2]); //show
waitKey(0);

imwrite("r.jpg", rgbMat[2]);
imwrite("g.bmp", rgbMat[1]);
imwrite("b.tif", rgbMat[0]);
```



Mat and Image, video write

video write

```
VideoCapture capture("rhinos.avi");
Mat frame:
//Set properties
int askFileTypeBox = 0; //-1 is show box of codec
int Color = 1;
Size S = Size((int)capture.get(CV CAP PROP FRAME WIDTH), (int)capture.get(CV CAP PROP FRAME HEIGHT));
//make output video file
VideoWriter outVideo;
outVideo.open(".\\overline{\text{"outVideo.avi"}}, askFileTypeBox, capture.get(CV_CAP_PROP_FPS), S, Color);
//check
if (!capture.isOpened())
                                                                                        g.bmp
    printf("AVI file can not open.\n");
    return 0;
//create window
namedWindow("w");
                                                                                      outVideo.avi
```

http://study.marearts.com/2013/09/opencv-video-writer-example-source-code.htm







- We learned that in previous lesson
 - Mat creation and simple matrix operation
 - Let's look in more detail

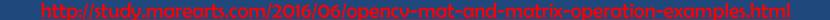
```
Mat m = Mat::ones(3, 3, CV_64F);
m = m * 3;
cout << m << endl;

double dm[3][3] = { { 1, 2, 1 }, { 0, 1, 1 }, { 1, 0, 0 } };
Mat m2 = Mat(3, 3, CV_64F, dm);
cout << m2 << endl;
cout << m+m2 << endl;
cout << m-m2 << endl;
cout << m*m2 << endl;
cout << m*m2 << endl;
cout << m/m2 << endl;
cout << m2.inv() << endl;
cout << m2.t() << endl;</pre>
```

```
int main(int, char)
   //Declaration and at the same time created
   Mat mtx(3, 3, CV 32F); // make a 3x3 floating-point matrix
   Mat cmtx(10, 1, CV_64FC2); // make a 10x1 2-channel floating-point
   // matrix (10-element complex vector)
   Mat img(Size(5, 3), CV_8UC3); // make a 3-channel (color) image
   // of 1920 columns and 1080 rows.
   //Created after the declaration
   Mat mtx2;
   mt \times 2 = Mat(3, 3, CV_32F);
   Mat cmtx2;
   cmt \times 2 = Mat(10, 1, CV 64FC1);
   //Create a point
   Mat* mtx3 = new Mat(3, 3, CV_32F);
   delete mtx3;
   //value set and print
   mtx.setTo(10);
   cout << mtx << endl;
   cmtx2.setTo(11);
   cout << cmtx2 << endl;
   return 0;
```

Matrix operations

```
//Matrix - matrix operations :
Mat Mc;
cv::add(Ma, Mb, Mc); // Ma+Mb -> Mc
cout << Ma+Mb << endl;
cout << Mc << endl;
cv::subtract(Ma, Mb, Mc); // Ma-Mb -> Mc
cout << Ma - Mb << endl;
cout << Mc << endl;
Mc = Ma*Mb; //Ma*Mb;
cout << Mc << endl;</pre>
```



Elementwise matrix operations

```
//Elementwise matrix operations :
cv::multiply(Ma, Mb, Mc); // Ma.*Mb -> Mc
cout << Mc << endl;
Mc = Ma.mul(Mb);
cout << Mc << endl;
cv::divide(Ma, Mb, Mc); // Ma./Mb -> Mc
cout << Mc << endl;
Mc = Ma + 10; //Ma + 10 = Mc
cout << Mc << endl;</pre>
```

Vector products

```
//Vector products :
double va[] = { 1, 2, 3 };
double vb[] = { 0, 0, 1 };
double vc[3];

Mat Va(3, 1, CV_64FC1, va);
Mat Vb(3, 1, CV_64FC1, vb);
Mat Vc(3, 1, CV_64FC1, vc);

double res = Va.dot(Vb); // dot product: Va . Vb -> res
Vc = Va.cross(Vb); // cross product: Va x Vb -> Vc
cout << res << " " << Vc << end];
```

Single matrix operations

Inhomogeneous linear system solver

```
//Inhomogeneous linear system solver :
double dm2[3][3] = { { 1, 2, 3 }, { 4, 5, 6 }, { 7, 8, 9 } };
Mat A(3, 3, CV_64FC1, dm2);
Mat x(3, 1, CV_64FC1);
double vvb[] = { 14, 32, 52 };
Mat b(3, 1, CV_64FC1, vvb);
cv::solve(A, b, x, DECOMP_SVD); //// solve (Ax=b) for x
cout << x << endl;
```

Eigen analysis

```
//Eigen analysis(of a symmetric matrix) :
float f11[] = { 1, 0.446, -0.56, 0.446, 1, -0.239, -0.56, 0.239, 1 };
Mat data(3, 3, CV_32F, f11);
Mat value, vector;
eigen(data, value, vector);
cout << "Eigenvalues" << value << endl;
cout << "Eigenvectors" << endl;
cout << vector << endl;</pre>
```



SVD example

```
//Singular value decomposition :
Mat w, u, v;
SVDecomp(data, w, u, v); // A = U W V^T
//The flags cause U and V to be returned transposed(does not work well without the transpose flags),
cout << w << endl;
cout << u << endl;
cout << v << endl;
```

Mat and gpuMat

imshow("r", r); //show

imshow("g", g); //show

imshow("b", b); //show

waitKey(0);

namedWindow("g", 0); //make window

namedWindow("b", 0); //make window

Cuda example

```
//#include "opencv2/cuda.hpp"
//#include "opencv2#cudaarithm.hpp"

cuda::GpuMat gpulmg;
Mat img = imread("ss.jpg");

gpulmg.upload(img); //upload
vector< cuda::GpuMat> rgbGpuMat(3);
cuda::split(gpulmg, rgbGpuMat); //cuda processing

Mat r, g, b;
rgbGpuMat[0].download(b); //download
rgbGpuMat[1].download(g);
rgbGpuMat[2].download(r);

namedWindow("r", 0); //make window
```



Mat and gpuMat





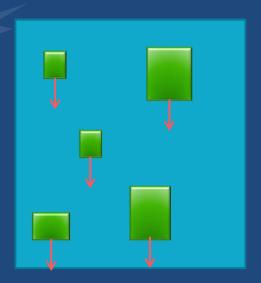
- Assignment #2
 - To use over 20 functions related to the GpuMat
 - Create example code

Bonus Assignment #1





- The bomb removing game
 - Square box comes down slowly from top to bottom.
 - Square box size and position is random.
 - When a user clicks on a box, box is eliminated.
 - And score is increase.
 - But if the box is touching the floor loses the score.



Thank you.

- See you later
 - Do not forget your assignment!!
 - o I will miss you very much!!



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