

AI Scientist for Large-Scale Biomedical Research

Eli Conlin¹, Prem Rajendran¹, Brooklyn Varela²

College of Arts and Sciences, Boston University, MA¹, College of Engineering, Boston University, MA²

Introduction

Our project builds a prototype neuro-symbolic AI Scientist for the biomedical domain. Rather than treating a large language model as a stand-alone chatbot, we decompose the research workflow into coordinated agents that read papers, extract candidate mechanisms, and design experiments. A separate reasoning layer then checks these ideas against the iKraph biomedical knowledge graph and simple simulation tools, so the system outputs hypotheses with explicit evidence paths and concrete experiment blueprints; moving from free-form text to something closer to a reproducible research plan.

Motivation

Modern LLMs can write, summarize, and reason over scientific text, but they still struggle with turning scientific ideas into complete, correct, and executable experiments. They hallucinate steps, violate physical constraints, omit crucial parameters, and cannot reliably validate their own work. At the same time, scientific research produces vast amounts of literature, making it increasingly difficult for humans to synthesize knowledge and design experiments efficiently.

Our project explores whether an “AI Scientist” can close this gap by integrating three capabilities:

1. reading and reasoning over existing scientific knowledge,
2. generating structured experimental protocols, and
3. validating those protocols through simulation and physical rules.

Research Objectives

Our work aims to address the following research questions:

- *RQ₁*: How does grounding AI-generated biomedical hypotheses in the iKraph knowledge graph affect the plausibility, safety, and novelty of proposed experiments compared to an ungrounded LLM baseline?
- *RQ₂*: Can robotic simulation serve as an intermediate layer toward autonomous experiment execution?

Knowledge Graph

Our AI Scientist is grounded in iKraph, a large-scale biomedical knowledge graph built from all PubMed abstracts and enriched with relations from more than 40 public databases and genomics sources, covering diseases, genes, drugs, pathways, and other key entities. iKraph thus serves as the symbolic constraint layer in our neuro-symbolic loop, filtering out biologically implausible or unsupported ideas before they proceed to simulation while providing structured, citable evidence for those that survive; we also log successful experiments into a project-specific subgraph, giving the agent an explicit, query-able memory of past findings. We query iKraph through a Neo4j graph database using Cypher, enabling the agent to run targeted analyses such as the example shown below.

Example iKraph Cypher Query

```
MATCH (s:Entity)-[r:Positive_Correlation]-(t:Entity)
WHERE
(
    toLower(s.`official name`) = 'adenosine triphosphate' OR
    toLower(s.`common name`) = 'atp' OR
    toLower(s.`official name`) = 'atp'
)
AND (
    toLower(t.`official name`) CONTAINS 'acetate kinase' OR
    toLower(t.`common name`) CONTAINS 'acetate kinase'
)
OPTIONAL MATCH
--> (s)-[ms:MENTIONED_IN]-->(p:PubMed)<-[mt:MENTIONED_IN]-(t)
RETURN DISTINCT
    s.id,
    coalesce(s.`official name`, s.`common name`),
    s.type,
    t.id,
    coalesce(t.`official name`, t.`common name`),
    t.type,
    type(r),
    toFloat(coalesce(r.prob, ms.prob, mt.prob)),
    p.pmid,
    CASE WHEN p.pmid IS NULL
        THEN NULL
        ELSE 'https://pubmed.ncbi.nlm.nih.gov/' + p.pmid
    END,
    p.date,
    --> publication_date,
    p.sentence,
    AS source_id,
    AS source_name,
    AS source_type,
    AS target_id,
    AS target_name,
    AS target_type,
    AS probability,
    AS pmid,
    AS url,
    AS sentence
ORDER BY probability DESC, pmid;
```

source_id,source_name,source_type,target_id,target_name,target_type,relationship_type,probability,pmid,url,publication_date,sentence

92 ATP Chemical 1767 Acetate Kinase Gene Positive_Correlation 0.9999_10816048 https://pubmed.ncbi.nlm.nih.gov/2000018
92 ATP Chemical 1767 Acetate Kinase Gene Positive_Correlation 0.9999_11716215 https://pubmed.ncbi.nlm.nih.gov/2011122
92 ATP Chemical 1767 Acetate Kinase Gene Positive_Correlation 0.9999_12450851 https://pubmed.ncbi.nlm.nih.gov/2021127
92 ATP Chemical 1767 Acetate Kinase Gene Positive_Correlation 0.9999_15516572 https://pubmed.ncbi.nlm.nih.gov/2041102
92 ATP Chemical 1767 Acetate Kinase Gene Positive_Correlation 0.9999_25978901 https://pubmed.ncbi.nlm.nih.gov/2015015
92 ATP Chemical 1767 Acetate Kinase Gene Positive_Correlation 0.9999_3107866 https://pubmed.ncbi.nlm.nih.gov/2019040
92 ATP Chemical 1767 Acetate Kinase Gene Positive_Correlation 0.9999_9484901 https://pubmed.ncbi.nlm.nih.gov/19980304

Figure 1: Result of the Cypher query exported as a csv file

Experimental Agent

The Experimental Planning Agent converts a mechanistic hypothesis about *E. coli* metabolism into a full fluorescence-plate experiment that discriminates between GIVEN causal confounds under fixed well/probe budgets. It behaves as a compiler: hypothesis → workspace → experiment plan.

2. Knowledge Graph Reporter Selection. KGraph paths from interventions to targets identify measurable entities. The agent selects a minimal reporter set maximizing path coverage and confound discrimination. Example: ATP optimization emphasized reporters tied to acetate overflow, NADH balance, and ATP maintenance—entities appearing across competing causal explanations.

3. Confound-Driven Experiment Design. Using the selected reporters, the agent builds experiments explicitly designed to separate GIVEN confounds:

- *Time series* for direct vs mediated vs compensatory dynamics.
- *CRISPR/a dose-responses* for linear vs ultrasensitive effects.
- *Multi-node perturbations* (intervention + mediator/compensator KO).
- *State-variation* to expose state-dependent artifacts.

Each design includes expected patterns under competing mechanisms.

4. Well Allocation & Plate Layout. Experiment families are ranked by *discriminative power per well*. The agent fits the highest-value sets within the max-wells budget, trimming timepoints or doses when necessary. It outputs precise 96/384-well layouts annotated with intervention, reporter, timepoint, replicate, and confound tested.

5. Metabolic Validation After design, the agent attempts COBRApy simulations to validate its effects

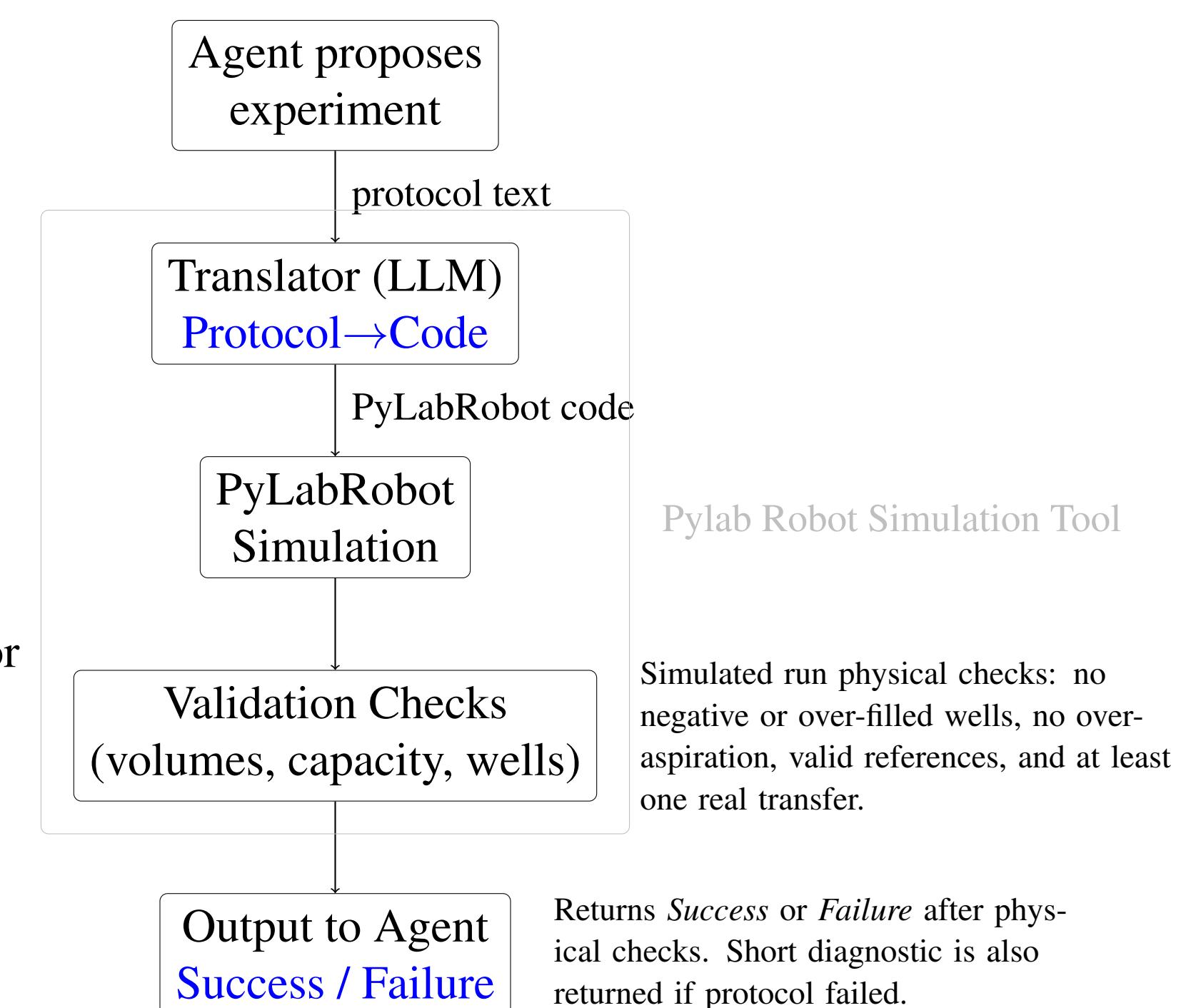
6. Output. The final JSON includes KGraph path summaries, reporter scoring, experiment families, prioritized selection, plate layout, budget summary, and (if available) metabolic validation results.

Demonstrated Behavior. In the ATP-growth run, the agent produced a complete experiment workspace, generated multi-KO designs with confound rationales, and maintained a coherent experimental plan—showing a functioning system rather than a hypothetical pipeline.

Robotic Validation with PyLabRobot

This robotics simulation acts as an external validation layer. After the agent proposes an experiment and the knowledge graph checks feasibility, the robotic layer verifies whether it can be executed as a real liquid-handling protocol. This forces the AI scientist to ground its ideas in experiments it can actually run.

Robotic Simulation Workflow



Natural Language to PyLabRobot Code

Example Translation

Input prompt

“Transfer 100 μ L of buffer from A1 of the reservoir to B2 of the plate. Then mix the contents of well B2 three times with 50 μ L.”

Generated PyLabRobot code

```
# Transfer 100  $\mu$ L from A1 + B2
await lh.pick_up_tips(tip_rack["A1"])
await lh.aspirate([reservoir["A1"][0]], vols=[100.0])
await lh.dispense([plate["B2"][0]], vols=[100.0])
await lh.return_tips()

# Mix B2 three times with 50  $\mu$ L
for _ in range(3):
    await lh.pick_up_tips(tip_rack["A1"])
    await lh.aspirate([plate["B2"][0]], vols=[50.0])
    await lh.dispense([plate["B2"][0]], vols=[50.0])
    await lh.return_tips()
```

Conclusion

The integrated system demonstrated a full causal-to-execution pipeline: iKraph extracted mechanistic paths and confound structure; the Experimental Agent converted them into a budget-aware fluorescence experiments, and the PyLabRobot translator supplied the automation bridge for robotic execution.