

# Parkinson UPDRS Prediction with K-Nearest Neighbour

Barişcan Tunali  
Big Data Masters Student  
Istanbul Bahcesehir University,  
bariscantunali@outlook.com

## ABSTRACT

In this paper, I will explain my study on Parkinson classification using K-NN.

Tracking Parkinson's disease (PD) symptom progression often uses the Unified Parkinson's Disease Rating Scale (UPDRS), which requires the patient's presence in clinic<sup>[1]</sup>.

Our problem is predicting continious value (total UPDRS) from continious variables which will be explained later. UPDRS score was calculated by patient metrics. Main dataset has no test set so I need to extract our test set myself.

I applied 3 different distance measures which were euclidean, manhattan, minkowski(order of two) to compare results and take K as 5 since dataset is very small.

## Categories and Subject Descriptors

[Computing methodologies]: Machine learning—*Machine learning algorithms; Ensemble methods*

## Keywords

K Nearest Neighbour, K-NN,KNN, Data Mining, Classification, Prediction, Parkinson, UPDRS

## 1. INTRODUCTION

Neurological disorders affect people profoundly and claim lives at an epidemic rate worldwide. Parkinson's disease (PD) is the second most common neurodegenerative disorder after Alzheimer's [2], and it is estimated that more than one million people in North America alone are affected [3]

Tricky part of dataset is also its time series. I treated data every row is like other patient. Becasue with time this illness also proceeds. I treated time as another property.

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The paper is organized as follows: In Section 2, we briefly describe the dataset and data preparation. Next, in Section 3, we

explain our classification approach in detail. Experimental results and comparisons with other algorithms are provided in Section 4. Finally, Section 5 concludes the paper.

## 2. DATASET AND FEATURES

Parkinson dataset consists of 5875 values, I had 21 attributes, one of them was total UPDRS.

My attributes are : [FixedAcidity], [VolatileAcidity], [CitricAcid], [ResidualSugar], [Chlorides], [FreeSulfurDioxide], [TotalSulfurDioxide], [Density], [PH], [Sulphates], [Alcohol], [Quality]

Attribute name: max value – min value – different values

age : 85 - 36

test\_time : 215.49 - 4.2625 - 23

motor\_UPDRS : 39.511 - 5.0377 - 2442

total\_UPDRS : 54.992 - 7 - 1080

Jitter\_Pct : 0.09999 - 0.00083 - 1305

Jitter\_Abs : 0.00044559 - 2.25E-06 - 4105

Jitter\_RAP : 0.05754 - 0.00033 - 853

Jitter\_PPQ5 : 0.06956 - 0.00043 - 840

Jitter\_DDP : 0.17263 - 0.00098 - 1703

Shimmer : 0.26863 - 0.00306 - 3581

Shimmer\_dB : 2.107 - 0.026 - 852

Shimmer\_APQ3 : 0.16267 - 0.00161 - 2664

Shimmer\_APQ5 : 0.16702 - 0.00194 - 2850

Shimmer\_APQ11 : 0.27546 - 0.00249 - 3283

Shimmer\_DDA : 0.48802 - 0.00484 - 4223

NHR : 0.74826 - 0.000286 - 5532

HNR : 37.875 - 1.659 - 4780

RPDE : 0.96608 - 0.15102 - 5430

DFA : 0.8656 - 0.51404 - 5282

PPE : 0.73173 - 0.73173 - 4777

Except age and test time all of the attributes were continious so I standardized them with mean stardardization ( $(x - \bar{x}) / \text{Xstddev}$ ).

In order to make my program more flexible I created a class and handled all data operations, test train seperations, standardizations etc. On presentation layer you only create class and call Initialize() function. After that you only access necessary train and test sets and send them to appropriate classification algorithms.

```
ParkinsonTrainSet = dprp.ParkinsonTrainSet;  
ParkinsonTestSet = dprp.ParkinsonTestSet;
```

```
KNN KNNRParkinson = new KNN(ParkinsonTrainSet);
KNNRParkinson.GetIndividualScore(ParkinsonTestSet);
```

Data preparation class structure as below :

```
public void Initialize()
{
    ExtractData();
    TransformData();
    NormalizeData(ParkinsonOriginalSetTransformed);
    SeperateTestData(ParkinsonOriginalSetTransformed);
}
```

*ExcractData()* : Dataset was in .csv format so I made a reader function that reads file, creates class, converts string values to appropriate type and bind them into class. Appends this class object into Parkinsons List.

*TransformData()* : Gets list of different data classes and converts them to common Parkinson.cs class.

*NormalizeData()* : Calculates standart deviations, means and standardizes each column except quality score.

*SeperateTestData()* : Gets normalized data and randomly separates %20 of data as test and %80 as train.

### 3. METHOD

I implemented K-NN with 5 neighbours.

My K-NN class has 5 functions :

```
public double[] GetIndividualScore(Parkinson _Parkinson)
public List<double[]> GetIndividualScore(List<Parkinson>
_Parkinson)
private double Euclidean(double x, double y)
private double Manhattan(double x, double y)
private double Minkowski(double x, double y, double order)
```

As we can see in implementations we have batch versions of each function. Distance functions doesn't calculate cumulative root, so we do it on caller side after summing each attributes distances. They are only mini calculation functions for clean code. There is example euclidean distance function call below, we have also similar Manhattan and Minkowski calls.

Example call for euclidean distance :

```
CumulativeEuclideanDistance = Math.Sqrt(
Euclidean(x.age, _Parkinson.age) +
Euclidean(x.test_time, _Parkinson.test_time) +
Euclidean(x.Jitter_Pct, _Parkinson.Jitter_Pct) +
Euclidean(x.Jitter_Abs, _Parkinson.Jitter_Abs) +
Euclidean(x.Jitter_RAP, _Parkinson.Jitter_RAP) +
Euclidean(x.Jitter_PPQ5, _Parkinson.Jitter_PPQ5) +
Euclidean(x.Jitter_DDP, _Parkinson.Jitter_DDP) +
Euclidean(x.Shimmer, _Parkinson.Shimmer) +
Euclidean(x.Shimmer_dB, _Parkinson.Shimmer_dB) +
Euclidean(x.Shimmer_APQ3, _Parkinson.Shimmer_APQ3) +
Euclidean(x.Shimmer_APQ5, _Parkinson.Shimmer_APQ5) +
Euclidean(x.Shimmer_APQ11, _Parkinson.Shimmer_APQ11) +
Euclidean(x.Shimmer_DDA, _Parkinson.Shimmer_DDA) +
Euclidean(x.NHR, _Parkinson.NHR) +
Euclidean(x.HNR, _Parkinson.HNR) +
Euclidean(x.RPDE, _Parkinson.RPDE) +
Euclidean(x.DFA, _Parkinson.DFA) +
Euclidean(x.PPE, _Parkinson.PPE));
```

```
x.temp1 = CumulativeEuclideanDistance;
```

I didn't use any c# library or dll to implement knn itself but I used lambda expressions to avoid code complexity. After calculating these distance measures I used these expressions to sort and take 5 nearest neighbours and get average :

```
double[] finalScores = new double[4];
finalScores[0] = _Parkinsons.OrderBy(x => x.temp1).Take(5).ToList().Average(z =>
zy.total_UPDRS);
finalScores[1] = _Parkinsons.OrderBy(x => x.temp2).Take(5).ToList().Average(z =>
zy.total_UPDRS);
finalScores[2] = _Parkinsons.OrderBy(x => x.temp3).Take(5).ToList().Average(z =>
zy.total_UPDRS);
finalScores[3] = (int)_Parkinson.total_UPDRS;
```

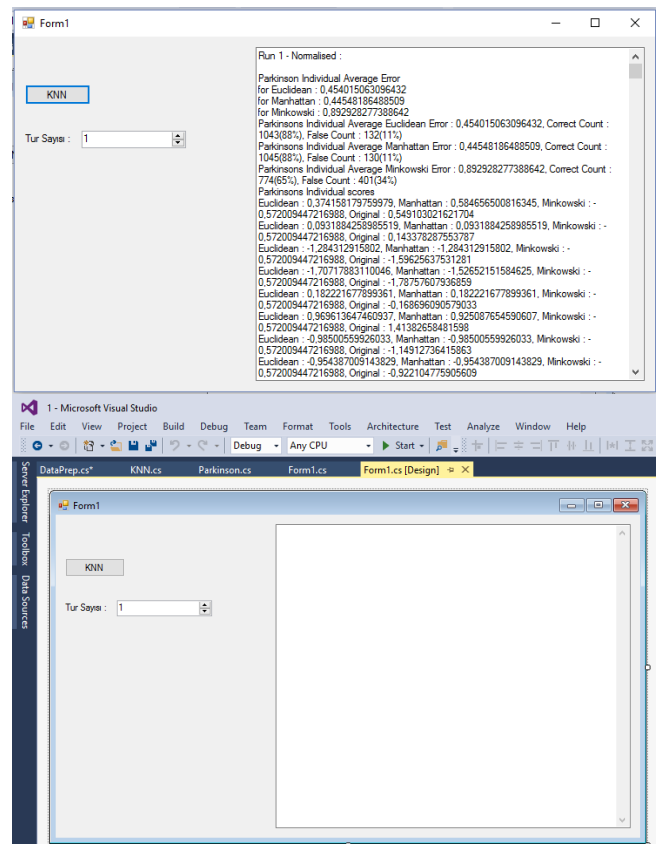
I kept these scores on wine class to calculate error and compare results.

## 4. EXPERIMENTS

I implemented 10 run loop, which creates new class, new train and test sets. On presentation layer I only call knn class and print out results into a file. On results I counted correct predictions, I decided that if  $|\text{Abs}(\text{prediction} - \text{real score})| \leq 1$  then I took it as correct prediction else false prediction.

Also in order to see difference between normalized and unnormalized results I call same function with no normalization.

If necessary you can change the experiment count from GUI as shown below. It writes data into txt file also. But shows in the gui as well:



## 5. CONCLUSIONS

Here are 2 run results for knn :

#### Run 1 - Normalised :

##### Parkinson Average Error

Euclidean Error : 0,456349628096565,  
Correct Count : 1040(88%),  
False Count : 135(11%)

Manhattan Error : 0,445386029940336,  
Correct Count : 1058(90%),  
False Count : 117(9%)

Minkowski Error : 0,859582537094246,  
Correct Count : 781(66%),  
False Count : 394(33%)

#### Run 1 - No Normalisation :

##### Parkinson Average Error

Average Euclidean Error : 0,227171508917367,  
Correct Count : 2299(97%),  
False Count : 51(2%)

Manhattan Error : 0,205369305889588,  
Correct Count : 2307(98%),  
False Count : 43(1%)

Minkowski Error : 1,08376043070654,  
Correct Count : 1195(50%),  
False Count : 1155(49%)

#### Run 2 - Normalised :

##### Parkinson Average Error

Euclidean Error : 0,439425687625529,  
Correct Count : 1052(89%),  
False Count : 123(10%)

Manhattan Error : 0,426017156962146,  
Correct Count : 1064(90%),  
False Count : 111(9%)

Minkowski Error : 0,822458203607021,  
Correct Count : 759(64%),  
False Count : 416(35%)

#### Run 2 - No Normalisation :

##### Parkinson Average Error

Euclidean Error : 0,224787383895685,  
Correct Count : 2304(98%),  
False Count : 46(1%)

Manhattan Error : 0,201287239606582,  
Correct Count : 2322(98%),  
False Count : 28(1%)

Minkowski Error : 0,863552714962304,  
Correct Count : 1214(51%),  
False Count : 1136(48%)

Results are interesting with normalisation and without normalisation. Normalizing process decreases prediction rate about %10 percent. But Minkowski measure gives always bad results compared to Manhattan and Euclidean. But normalisation increases prediction rate on Minkowski

There is a trade off between these algorithms. KNN's runtime is very high, it compares test wine with every wine in train set and then sorts them so run time is about  $O(n + O_{\text{sort}}(n))$  so on real time applications or even nightly jobs its cost is very high on large datasets. And average error  $((\text{prediction} - \text{actual}) / \text{count})$  is about 0.2 for unnormalised data, 0.4 for normalised data. Minkowski about 0.8 for both

#### References

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- [2] A.E. Lang, A.M. Lozano. Parkinson's disease – First of two parts, *New England Journal Medicine*, 339, 1044-1053, 1998
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