

HW3

November 8, 2016

A. Boosting

1. I use 10-fold cross validation to test the average error, the result is shown in Fig 1. k is selected 3 as maximum.

Next, I set $T^* = 400$ and plot the error on the test data, shown in Fig 2.

Obviously, AdaBoost outperforms SVM (5% vs 15% error), which shows weak learner can be trained robust.

2. First, we don't care about what values α_t and Z_t are. In each iteration, we still choose $h_t \in \mathbb{H}$ with the smallest error $1_{y_i h_t(x_i) < 0}$. So the algorithm structure is the same, the only difference is the exact values.

The normalized factor

$$\begin{aligned}
 Z_t &= \sum_{i=1}^m D_t(i) e^{-\alpha_t y_i h_t(x_i)} \\
 &= \sum_{i: y_i h_t(x_i)=1} D_t(i) e^{-\alpha} + \sum_{i: y_i h_t(x_i)=0} D_t(i) + \sum_{i: y_i h_t(x_i)=-1} D_t(i) e^{\alpha_t} \\
 &= \epsilon_t^1 e^{-\alpha_t} + \epsilon_t^0 + \epsilon_t^{-1} e^{\alpha_t} \\
 (\text{choose } \alpha_t \text{ s.t. } \min Z_t) \text{ we get } \alpha_t &= \frac{1}{2} \ln \frac{\epsilon_t^1}{\epsilon_t^{-1}} \\
 &= 2\sqrt{\epsilon_t^1 \epsilon_t^{-1}} + \epsilon_t^0
 \end{aligned}$$

- (a) The objective function is

$$F(\alpha) = \frac{1}{m} \sum_{i=1}^m e^{-y_i \sum_{s=1}^n \alpha_s h_s(x_i)}.$$

And let e_t be the t th unit vector in \mathbb{R}^n . We need to find the greatest gradient each iteration. Like the original AdaBoost,

$$F(\alpha_{t-1} + \eta e_t) = \frac{1}{m} \sum_{i=1}^m e^{-y_i \sum_{s=1}^n \alpha_s h_s(x_i) - y_i \eta h_t(x_i)}.$$

Then

$$\begin{aligned}
 F'(\alpha_{t-1}, e_t) &= \frac{1}{m} \sum_{i=1}^m -y_i h_t(x_i) e^{-y_i \sum_{s=1}^n \alpha_s h_s(x_i)} \\
 &= -\frac{1}{m} \sum_{i=1}^m y_i h_t(x_i) m D_t(i) \prod_{s=1}^{t-1} Z_s \\
 &= -\left[\sum_{i: y_i h_t(x_i)=1} D_t(i) + 0 - \sum_{i: y_i h_t(x_i)=-1} D_t(i) \right] \prod_{s=1}^{t-1} Z_s \\
 &= (\epsilon_t^{-1} - \epsilon_t^1) \prod_{s=1}^{t-1} Z_s
 \end{aligned}$$

As we find the direction with greatest gradient, and ϵ_t^{-1} is the error rate, we will pick h_t with the smallest ϵ_t^{-1} .

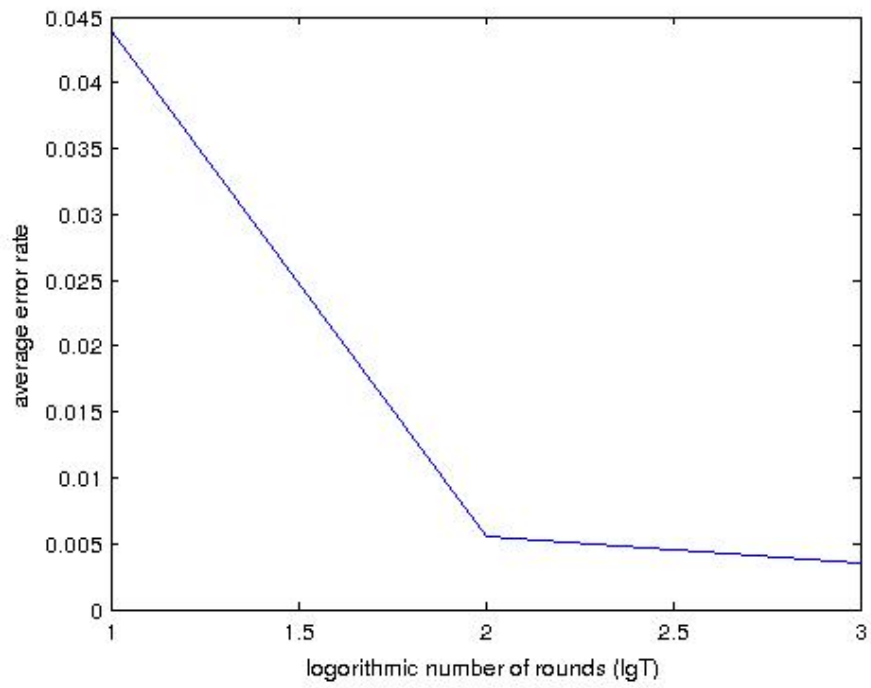


Figure 1: Average cross validation error versus $\lg(T)$.

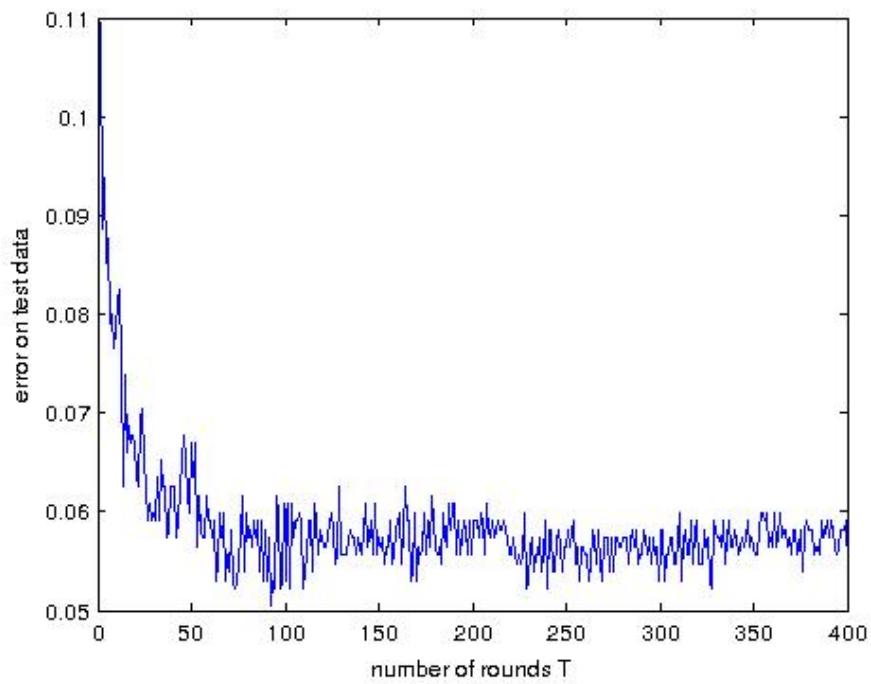


Figure 2: Test error on the test data.

For the step size η ,

$$\begin{aligned}
\frac{dF(\alpha_{t-1} + \eta \mathbf{e}_t)}{d\eta} = 0 &\Leftrightarrow - \sum_{i=1}^m y_i h_t(x_i) e^{-y_i \sum_{s=1}^{t-1} \alpha_s h_s(x_i)} e^{-\eta y_i h_t(x_i)} = 0 \\
&\Leftrightarrow \sum_{i=1}^m y_i h_t(x_i) D_t(i) m \prod_{s=1}^{t-1} Z_s e^{-\eta y_i h_t(x_i)} = 0 \\
&\Leftrightarrow \sum_{i=1}^m y_i h_t(x_i) D_t(i) e^{-\eta y_i h_t(x_i)} = 0 \\
&\Leftrightarrow \epsilon_t^1 e^{-\eta} - \epsilon_t^{-1} e^{\eta} = 0 \\
&\Leftrightarrow \eta = \frac{1}{2} \ln \frac{\epsilon_t^1}{\epsilon_t^{-1}}
\end{aligned}$$

which is the same as α_t as discussed previously.

(b) Edge can still be defined as

$$\gamma_t(D) = \frac{1}{2} \sum_{i=1}^m y_i h_t(x_i) D(i) = \frac{1}{2} (\epsilon_t^1 - \epsilon_t^{-1}).$$

Then the weak learning assumption would be: $\exists \gamma > 0$ s.t. $\forall D$ and $\forall h_t$, $\gamma_t(D) > \gamma$ holds. i.e. the best edge $\gamma^* > 0$

(c)

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1:  $H \in \{-1, 0, 1\}^X$ 
2: function ADABOOST3( $S = (x_1, y_1), \dots, (x_m, y_m)$ )
3:   for  $i \leftarrow 1$  to  $m$  do
4:      $D_1(i) = \frac{1}{m}$ 
5:   end for
6:   for  $t \leftarrow 1$  to  $T$  do
7:      $h_t \leftarrow$  base classifier in  $H$  with small error  $\epsilon_t^{-1}$ 
8:      $\alpha_t \leftarrow \frac{1}{2} \ln \frac{\epsilon_t^1}{\epsilon_t^{-1}}$ 
9:      $Z_t = 2\sqrt{\epsilon_t^1 \epsilon_t^{-1}} + \epsilon_t^0$ 
10:    for  $i \leftarrow 1$  to  $m$  do
11:       $D_{t+1}(i) = \frac{D_t(i) e^{-\alpha_t y_i h_t(x_i)}}{Z_t}$ 
12:    end for
13:     $f_t = \sum_{i=1}^t \alpha_s h_s$ 
14:  end for
15:  return  $f_T$ 
16: end function

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(d)

$$\begin{aligned}
\hat{R}(h) &= \frac{1}{m} \sum_{i=1}^m 1_{y_i f(x_i) < 0} \\
&\leq \frac{1}{m} \sum_{i=1}^m e^{-y_i f(x_i)} \\
&\leq \frac{1}{m} \sum_{i=1}^m D_{T+1}(i) m \prod_{t=1}^T Z_t \\
&= \prod_{t=1}^T Z_t \\
&= \prod_{t=1}^T \left[2\sqrt{\epsilon_t^1 \epsilon_t^{-1}} + \epsilon_t^0 \right]
\end{aligned}$$