

Regression: N : data-size D : dim (features) θ : Model para. with offset w_0

\rightarrow relates x_n to y_n . **Regression Function:** $y_n \approx f(x_n) = w^T x_n \rightarrow$ 2 goals: Prediction / Interpretation

Linear Regression: Univariate: $y_n \approx f(x_n) := w_0 + w_1 x_n$

Multivariate: $y_n \approx f(x_n) := w_0 + w_1 x_{n1} + \dots + w_d x_{nd} = w_0 + x_n^T w := x_n^T w$

Note: If $D > N$, we say the model is overparametrized \rightarrow Solution: Regularization

Cost Function: $\hat{f}(w) = \frac{1}{N} \sum_{n=1}^N \text{loss}(e_n)$, $e_n = y_n - f_w(x_n)$ | 2 desirable properties:

- 1) symmetric around 0
- 2) Penalize large and huge mistakes the same (outliers robust)

MSE (w): $\frac{1}{N} \sum_{n=1}^N (y_n - f_w(x_n))^2$ **MAE (w):** $\frac{1}{N} \sum_{n=1}^N |y_n - f_w(x_n)|$ more robust to outliers than MSE

Convexity: A function $h(u)$ with $u \in \mathbb{R}^d$ is convex if for any $u, v \in \mathbb{R}^d$ and any $0 < t < 1$: $h(tu + (1-t)v) \leq t h(u) + (1-t)h(v)$ desirable computational property

A strict convex function has a unique global min. For convex functions, every local min is a global min

Sum of Convex Functions are Convex $f: \mathbb{R}^d \rightarrow \mathbb{R}$ convex iff ∇f is PSD

Local opt: $L(w) \leq L(w^*)$, $\forall w$ with $\|w - w^*\| < \epsilon$ | Global: $L(w^*) \leq L(w)$, $\forall w \in \mathbb{R}^D$

Solving Lin Reg With MSE analytically: 2 steps for global opt. \rightarrow Show convexity $\rightarrow \nabla \hat{f}(w) = 0$

Normal eq.: $\hat{f}(w) = \frac{1}{N} \sum_{n=1}^N (y_n - x_n^T w)^2 = \frac{1}{N} e^T e$ with $e = Y - Xw$

Cost Fct is convex b/c it's combination of convex facts | Cost: $\Theta(D^2 \cdot N)$

2) $\nabla \hat{f}(w) = -\frac{1}{N} X^T e = 0 \Rightarrow x^T x w = x^T y \Rightarrow w^* = (X^T X)^{-1} X^T y$ iff Gram matrix $X^T X \in \mathbb{R}^{D \times D}$ is invertible. (if $\text{rank}(X) = D$) Prediction on unseen data: $\rightarrow y_m = x_m^T w^* = x_m^T (X^T X)^{-1} X^T y$. • If $D > N$: $\text{rank}(X) < D \leq N$ • If $D \leq N$, but some col. x_i are (nearly) collinear: ill-cond. \Rightarrow Solution: (linear Solver); $X^T X w = X^T y$

Underfitting: Can't find fit, too limited. **Overttting:** Fits noise too, too rich

Augmented models: $y_n \approx w_0 + w_1 x_{n1} + w_2 x_{n2}^2 + \dots + w_M x_M^n = \phi(x_n)^T w$

Avoid overfit: Increase N , keep D fixed (odd data, same model complexity)

NLL: Gaussian RV in \mathbb{R}^D : $N(y | \mu, \Sigma) = (\det(\Sigma)^{1/2})^{-1} \exp[-0.5(y - \mu)^T \Sigma^{-1} (y - \mu)]$ (2 PBF)

Note: 2 Rv indep. in \mathbb{R}^D : $P(y | \mu, \sigma^2) = N(y | \mu, \sigma^2) = (2\pi\sigma^2)^{-D/2} \exp[-(y - \mu)^2 / 2\sigma^2]$ When $\text{PCF} = 100\%$

Probabilistic Model for LS: assume data $y_n = x_n^T w + \epsilon_n$ with $\epsilon_n \sim N(0, \sigma^2)$

Likelihood: $p(y | X, w) = \prod_{n=1}^N p(y_n | x_n, w) = \prod_{n=1}^N N(y_n | x_n^T w, \sigma^2)$ **Goal:** to max it, and it's equivalent as Min JSE

$\log L(w) = \log p(y | X, w) = -\frac{1}{2\sigma^2} \sum_{n=1}^N (y_n - x_n^T w)^2 + \text{const.}$

$\Rightarrow \arg \min L_{\text{MLE}}(w) = \arg \max_w L_{\text{LL}}(w)$ **MLE can also be interpreted as finding the model under which the observed data is most likely to have been generated from (probabilistically)**

Properties:

- MLE is a sample approximation to the expected log-likelihood: $\hat{f}_{\text{ML}}(w) \approx E_{y \sim p(y)} [\log p(y | X, w)]$
- MLE is consistent, i.e., it will give us the correct model assuming that we have a sufficient amount of data.
- MLE \rightarrow Norm. MLE is efficient, i.e. it achieves the Cramer-Rao lower bound

Replace Gaussian with Laplace: $P(y_n | x_n, w) = (2\pi)^{-1} \exp[-\frac{1}{2} |y_n - x_n^T w|]$

Generalization: Data Model: unknown distrib D with range $X \times Y$

Data: $S = \{(x_n, y_n)\}_{n=1}^N \sim D$; learning algo: $A(s) = f_s$ (output) (s : input)

Expect. error: $L_b(f) = E_{(x,y) \sim D} [P(y \neq f(x))]$ But b is unknown Empirical error: $L_{\text{EM}}(f) = \frac{1}{N} \sum_{n=1}^N I(y_n \neq f(x_n))$

Ls(f) = $\frac{1}{N} \sum_{n=1}^N l(y_n, f(x_n))$ Training error: $L_s(f) = \frac{1}{N} \sum_{n=1}^N l(y_n, f_s(x_n))$ But could diverge from L_b b/c of overfitting

Split data (test error): $L_{\text{test}}(f_{\text{train}}) = \frac{1}{N_{\text{test}}} \sum_{n \in \text{test}} l(y_n, f_{\text{train}}(x_n)) \approx L_b(f_{\text{train}})$

Generalization error: $P[L_b(f) - L_{\text{test}}(f)] \leq \sqrt{\frac{(b-a)^2 \ln(2/\delta)}{2N_{\text{test}}}}$ Error decreases as $(b-a)^2 / (N_{\text{test}})^2$ $\#$ of test points

Hoeffding's: $P[\frac{1}{N} \sum_{n=1}^N \alpha_n - E(\alpha) \geq \epsilon] \leq 2e^{-2N\epsilon^2/(b-a)^2}$ \rightarrow with $\alpha = l(y_n, f(x_n))$

$\Rightarrow S = 2e^{-2N\epsilon^2/(b-a)^2} \rightarrow \epsilon = \sqrt{2N\epsilon^2/(b-a)^2}$

Model Selection: Split data, train K times for each value, compute error. Bound: $P[\max_k L_b(f_k) - L_{\text{test}}(f_k)] \leq \sqrt{\frac{(b-a)^2 \ln(2K/\delta)}{2N_{\text{test}}}} \leq \delta$ same Θ

Let $K = \arg \min_k L_{\text{test}}(f_k) \Rightarrow P[L_b(f_k) \geq L_b(f_K) + 2\sqrt{\frac{(b-a)^2 \ln(2K/\delta)}{2N_{\text{test}}}}] \leq \delta$ and $K = \arg \min_k L_{\text{test}}(f_k)$

K-fold Cross-Validation: 1. Randomly partition data into K groups. 2. Train K times, leaving 1 group for test and $K-1$ for train. 3. Average K results. \rightarrow unbiased estimate of the gen. error and its var.

Logistic reg: model probas $\hat{o}_i(\beta) = (1 + e^{-\beta})^{-1}$, $1 - \hat{o}_i(\beta) = (1 + e^{-\beta})^{-1}$, Robust to outliers and unbalanced data

$\hat{o}'(\beta) = \sigma(\beta)(1 - \hat{o}(\beta))$, $\hat{f}(x) = \sigma(x^T w)$, $P(w) = 1 - P(\hat{f}(x))$; if $P(\hat{f}(x)) \geq \frac{1}{2} \rightarrow$ class 1

NLL: assume $X \perp\!\!\!\perp w$: $L(w) \propto \prod_{n=1}^N \hat{o}_n(\beta_n) [1 - \hat{o}_n(\beta_n)]^{1-y_n}$ **LL:** $w_* = \arg \min L(w) \rightarrow$

$\hat{o}_n(\beta_n) = \frac{1}{1 + e^{-\beta_n}} = y_n x_n^T w + \log(1 + e^{x_n^T w}) \rightarrow$ Note: if $\hat{o}_n(\beta_n) < 0.5$: $y_n(x_n^T w) = -y_n(g(x) + \log(1 + \exp(g(x))))$ if $\hat{o}_n(\beta_n) > 0.5$: $y_n(x_n^T w) = 1 - \hat{o}_n(\beta_n)$

$\log(1 + \exp(-y_n g(x))) \rightarrow \nabla L(w) = \frac{1}{N} \sum_{n=1}^N (\hat{o}_n(x_n^T w) - y_n) x_n = \frac{1}{N} X^T (\hat{o}(x^T w) - y) \rightarrow$ No CS solution but convex! | **GD:** slow $\Theta(N)$ SGD: fast but converges slow

Newton's: $L(w) \sim L(w_0) + \nabla L(w_0)^T (w - w_0) + \frac{1}{2} (w - w_0)^T \nabla^2 L(w_0)(w - w_0) \rightarrow$

$w_{t+1} = w_t - \gamma_t \nabla^2 L(w_t)^{-1} \nabla L(w_t) \rightarrow$ intensive! Regularized: issue is data in separable. $\Rightarrow \frac{1}{N} \sum_{n=1}^N -y_n x_n^T w + \log(1 + e^{x_n^T w}) + \frac{1}{2} \|w\|^2$

Optimization: $w^* = \underset{w}{\operatorname{argmin}} \hat{f}(w)$ s.t. $w \in \mathbb{R}^D$ \rightarrow very sensitive to ill-conditioning \rightarrow Solution: normalize

Smooth: 1) GridSearch: $G(\theta)$ the lowest loss over all W . Brute-force | Exponential complexity | No guarantee to find an optimum

2) Gradient descent: A gradient (at a point) is the slope of the tangent to the function (at that point). It points to the direction of largest increase of the function.

Vector: $\nabla \hat{f}(w) := \left[\frac{\partial \hat{f}(w)}{\partial w_1}, \dots, \frac{\partial \hat{f}(w)}{\partial w_D} \right]^T \in \mathbb{R}^D$ | update rule: $w^{(t+1)} := w^{(t)} - \gamma \nabla \hat{f}(w^{(t)})$ \rightarrow γ is the step-size or lr. Smaller $\gamma = \frac{\epsilon}{\eta}$ \rightarrow smaller and smaller..

Example: GD for 1-param and MSE: $w_0^{(t+1)} := (1 - \gamma) w_0^{(t)} + \gamma \bar{y}$ (Converges for $\gamma \in (0, 1)$)

GD for linear MSE: $y = \begin{bmatrix} y_1 \\ \vdots \\ y_N \end{bmatrix}$, $X = \begin{bmatrix} x_{11} & \dots & x_{1N} \\ \vdots & \ddots & \vdots \\ x_{N1} & \dots & x_{NN} \end{bmatrix}$, $e = Y - Xw \rightarrow \hat{f}(w) = \frac{1}{N} \sum_{n=1}^N (y_n - x_n^T w)^2 = \frac{1}{N} e^T e$

Loss of 1 data point $\rightarrow \nabla \hat{f}(w) = -\frac{1}{N} X^T e$ Cost of GD per step: $\Theta(N)$

SGD: 1) Take 1 random n 2) $w^{(t+1)} := w^{(t)} - \gamma \nabla \hat{f}_{\text{nn}}(w^{(t)})$ Cheap and unbiased estimate of the gradient: $E[\nabla \hat{f}_{\text{nn}}(w)] = \nabla \hat{f}(w)$ \rightarrow $\nabla \hat{f}_{\text{nn}}(w) = \nabla \hat{f}(w)$ stable Cost of SGD per step $\Theta(1)$

Mini-batch SGD: $w^{(t+1)} := w^{(t)} - \gamma g$ with $g = \frac{1}{|\mathcal{B}|} \sum_{n \in \mathcal{B}} \nabla \hat{f}_{\text{nn}}(w^{(t)})$, where \mathcal{B} is a subset. $\rightarrow \mathcal{B} = \mathcal{N}$: classic GD $\rightarrow g$ easily parallelized

4.1) SGD with momentum: $w^{(t+1)} := w^{(t)} - \gamma m^{(t+1)}$ with $m^{(t+1)} := \beta_1 m^{(t)} + (1 - \beta_1) g$ faster forgetting of older weights

4.2) ADAM: $w_i^{(t+1)} := w_i^{(t)} - \frac{\gamma}{\sqrt{v_i^{(t+1)}}} m_i^{(t+1)}$ with $m_i^{(t+1)} := \beta_1 m_i^{(t)} + (1 - \beta_1) g$ is a momentum variant of Adagrad coordinate-wise adjusted learning rate strong performance in practice, e.g. for self-attention networks

4.3) Sign-SGD: $w_i^{(t+1)} := w_i^{(t)} - \gamma \text{sign}(g_i)$ only use the sign (one bit) of each gradient entry \rightarrow communication efficient for distributed training (but convergence issue)

Non-smooth: if \hat{f} convex and differentiable: Vector where function is above a subgradient

1) Subgradient D: Vector $g \in \mathbb{R}^D$ such that $L(u) \geq \hat{f}(w) + g^T(u - w) \forall u$ Trick: if $\hat{f}(w) = h(\hat{f}(w))$ with h non-diff. and g diff., \rightarrow subgrad of \hat{f} at w is $g \in \partial h(\hat{f}(w)) \cdot \nabla \hat{f}(w)$ set of subgrads

2) S(S)GD: $g = \text{subgradient}$ to $\hat{f}_n(w)$

Conclusion: W local min if $\nabla \hat{f}(w) = 0$ (critical point) and $\nabla^2 \hat{f}(w) \succ 0$ (positive definite)

Regularization: Penalize complex models via: $\min_w \hat{f}(w) + \Omega(w)$ where $\Omega(w)$ is the regularizer $\lambda \rightarrow$ λ (noisy) \rightarrow λ (overfitting) \rightarrow λ (underfitting)

L2: $\Omega(w) = \lambda \|w\|_2^2 = \lambda \sum_i w_i^2$ **Ridge:** $L_2 + \text{MSE} : \min_w \frac{1}{N} \sum_{n=1}^N (y_n - x_n^T w)^2 + \lambda \|w\|_2^2$ \rightarrow always invertible thanks to $X = 2N\lambda$ $X^T X + \lambda I$ is the EV so EV are at least λ Closed-form sol: $w_{\text{ridge}} = (X^T X + \lambda I)^{-1} X^T y$ \rightarrow fiddly ill-conditioning.

L1: $\Omega(w) = \lambda \|w\|_1 = \lambda \sum_i |w_i|$ **Lasso:** $L_1 + \text{MSE} : \min_w \frac{1}{N} \sum_{n=1}^N (y_n - x_n^T w)^2 + \lambda \|w\|_1$ More powerful. Makes w sparse \rightarrow few non-0 components

Note: $\{w : \|y - Xw\|^2 = \alpha\}$ is an ellipsoid. These are likely to touch a corner of the L_1 -ball \rightarrow sparsity.

Notes: gradient of $\|w\|_1^2 = 2w$ Subgradient $\|w\|_1 = (\text{sign}(w_1), \dots, \text{sign}(w_d))$

Bias-Variance: $f = f(x) + \epsilon$. Expected error: $E_{y \sim p(y)} [(y - f(x))^2] \rightarrow$ True at every point: $L(f) = E_{y \sim p(y)} [(f(x) + \epsilon - f(x))^2]$

$E_{S \sim \mathcal{D}} [L(f_S)] = E_{S \sim \mathcal{D}, \epsilon \sim \mathcal{D}_S} [(f(x) + \epsilon - f_S(x))^2] = \text{Var}_{\epsilon \sim \mathcal{D}_S} [\epsilon] + (f(x) - E_{S \sim \mathcal{D}} [f_S(x)])^2 + E_{S \sim \mathcal{D}} [(f_S(x) - E_{S \sim \mathcal{D}} [f_S(x)])^2]$ (can't go below) noise var

Classification: unlike reg. $y \in \{C_1, \dots, C_K\}$ Binary \rightarrow classifier divides space into classes

KNN: Pros: $\frac{1}{N}$ no opt., easy, good for low dim? Cons: slow, bad for high dim, distance? \rightarrow Max-Margin: HP which max margin Nonlinear classif: feature aug. or kernels Binary classif goal: $\min L(f) = E_{\text{D}} [I(y \neq f(x))] = P_b(y \neq f(x))$

Bayes classif: $f^* = \arg \min_f L(f) \rightarrow f^*(x) = \arg \max_y P(y = y | x = x)$ unlabeled loc. not known

2 classes of classif algo \rightarrow Non-param: (local Avg (KNN)) 2) Param: min ER Problem: Not convex. Replace f and t by convex fact.

ERM: min ER instead True Risk: $\min_{f: X \rightarrow Y} L_{\text{train}}(f) := \frac{1}{N} \sum_{n=1}^N I(f(x_n) \neq y_n) = \frac{1}{N} \sum_{n=1}^N I(y_n f(x_n) \neq 0)$

Kernel: Ridge: $\min_w \frac{1}{N} \sum_{n=1}^N (y_n - w^T x_n)^2 + \frac{\lambda}{2} \|w\|^2 \rightarrow$ 2 Solutions $w_n = \frac{1}{N} (X^T X + \lambda I)^{-1} X^T y$, $w_n = \frac{1}{N} X^T (\frac{1}{N} X X^T + \lambda I)^{-1} y = X^T \alpha_n$ $| w_n \in \text{span}(x_1, \dots, x_N)$ Kernel $O(D^3 + Nd^2)$

Representer theorem: $w_n \in \arg \min_w \frac{1}{N} \sum_{n=1}^N (y_n - w^T x_n)^2 + \frac{\lambda}{2} \|w\|^2$ for ANY loss and min (better than LS) $\rightarrow w_n = X^T \alpha_n$ \rightarrow soln. in α

For ridge ($\ell = \|y - Xw\|^2$): alt formula $\alpha_n = \arg \min_{\alpha} \frac{1}{2} \alpha^T (\frac{1}{N} X X^T + \lambda I_N) \alpha - \frac{1}{N} y^T \alpha$ Kernel matrix: $K = X X^T = \begin{bmatrix} x_1^T x_1 & x_1^T x_2 & \dots & x_1^T x_N \\ x_2^T x_1 & x_2^T x_2 & \dots & x_2^T x_N \\ \vdots & \vdots & \ddots & \vdots \\ x_N^T x_1 & x_N^T x_2 & \dots & x_N^T x_N \end{bmatrix} = (x_i^T x_j)_{i,j \in \mathcal{D}}$

With feature map $R^d \rightarrow R^D$: $K = \Phi(\alpha)^T = (\Phi(x_i)^T \Phi(x_j))_{i,j \in \mathcal{D}}$, $\Phi: R^d \rightarrow R^D$. Problem: if $d \gg d$, $\Phi(x)$ expensive!

Kernel Trick: $K(x, x') = \phi(x)^T \phi(x')$ $K(x, x')$ is in the original space! enable computation of classifiers in high-dimensional space without performing computations in this high-dimensional space.

Prediction: $y = \phi(x)^T w_n$ is expensive, so use Rep. theorem: $\phi(x)^T w_n = \phi(x)^T \phi(x')^T \alpha_n = \sum_{n=1}^N K(x, x') \alpha_n$ (\neq feature space)

Kernels: $\text{Gram} = K(x, x') = x^T x'$ $\text{Quadr} = K(x, x') = (x_1^T x_1 + x_1^T x_2 + x_2^T x_2)^2$ $\text{Poly} = K(x, x') = \text{exp}(-\gamma \|x - x'\|^2)$ $\text{RBF} = K(x, x') = \text{exp}(-\gamma \|x - x'\|^2)$ $\bullet K(x, x') = \Phi(x) \Phi(x')$

Create kernels: 1) lin. Comb: $K(x, x') = \alpha_1 K_1(x, x') + \alpha_2 K_2(x, x')$ products: $K(x, x') = K_1(x, x') K_2(x, x')$ $\bullet K(x, x') = \mathcal{E} \otimes K(x, x')$

Mercer condition: given K , ensures ϕ iff: Kernel for is symmetric $K(x, x') = K(x', x)$ Kernel matrix psd $K = (K(x_i, x_j))_{i,j=1}^N \geq 0 \forall N \geq 0, \forall x_i, x_j$

SVM: Hard-SVM: Max-margin separating HP: $\max_{w, b} \frac{1}{N} \sum_{n=1}^N y_n w_n$ such that $\forall n, y_n w_n \geq 0$ Margin correctly classified Equiv to: $\max_{M, b} M$ such that $\forall n, y_n w_n \geq M$ $W = \frac{1}{N} \sum_{n=1}^N y_n x_n^T w$ \rightarrow use slack variable: $y_n x_n^T w \geq 1 - \xi_n$

$\Rightarrow \min_{w, b} \frac{1}{2} \|w\|^2$ such that $\forall n, y_n w_n \geq 1$ soft-SVM: Not linearly separable! \rightarrow use slack variable: $y_n x_n^T w \geq 1 - \xi_n$

$\rightarrow \min_{w, b} \frac{1}{2} \|w\|^2 + \frac{1}{N} \sum_{n=1}^N \xi_n$ s.t. $\forall n, y_n w_n \geq 1 - \xi_n$ and $\xi_n \geq 0$ equiv to: $\min_{w, b} \frac{1}{2} \|w\|^2 + \frac{1}{N} \sum_{n=1}^N [1 - y_n w_n]_+$ with ridge λ because if $y_n w_n \geq 1$, then $\xi_n = 0$ if $y_n w_n < 1$, $\xi_n = 1 - y_n w_n$

Margin-based losses ($\ell = y - x^T w$) MSE(η) = $(1 - \eta)^2$ Hinge(η) = $[1 - \eta]_+$ Logistic(η) = $\frac{\log(1 + \exp(-\eta))}{\log(2)}$ all upper bound for ℓ -loss all

Opt: Convex duality: How to get w for soft-SVM \rightarrow Find $G(w, \kappa)$ so $\min_w L(w) = \min_w \max_{\kappa} G(w, \kappa) \geq \max_{\kappa} \min_w G(w, \kappa)$

1) $[1 - y_n w_n]_+ = \max_{\alpha_n \in \{0, 1\}} (1 - y_n w_n) \rightarrow \min_w L(w) = \min_w \max_{\alpha \in \{0, 1\}} \sum_{n=1}^N (\alpha_n [1 - y_n w_n]_+ + \frac{\lambda}{2} \|w\|^2)$ Primal: $\min_w L(w) = \min_w \max_{\kappa} G(w, \kappa) \geq \max_{\kappa} \min_w G(w, \kappa)$ Dual: $\max_{\kappa} G(w, \kappa) = \max_{\kappa} \min_w G(w, \kappa)$

2) Min: $\nabla_w G(w, \kappa) = -\frac{1}{N} \sum_{n=1}^N \alpha_n y_n x_n + \lambda w = 0 \rightarrow w(\alpha) = \frac{1}{N \alpha} \sum_{n=1}^N \alpha_n y_n x_n = \frac{1}{N \alpha} X^T Y \alpha$ Kernel of data

3) Max: $\min_w L(w) = \min_{w \in \text{affine}} \frac{1}{N} \alpha^T X X^T Y \alpha \rightarrow$ $\alpha \gg 0$ are SV!

Ethics: We want knowledge, not stereotypes. ML can't distinguish data. Might discriminate minorities. Three fairness criterias: can't satisfy them all. Independence: R independent of $A \rightarrow$ equal acceptance rate Separation: R independent of A , conditional on $Y \rightarrow$ equal error rate Sufficiency: Y independent of A conditional on $R \rightarrow$ calibration by group

NN: $f_{\text{NN}}: \mathcal{X} \rightarrow \mathcal{Y}$ $x \mapsto$ the k elements of S_{train} closest to x . **Slow: O(N)**

For reg: $f_{\text{train},x} = \frac{1}{k} \sum_{i=1}^k g_i$ (avg of points around) For classif: $f_{\text{train},x} = \text{majority sign: } g_i \in S_{\text{train}}$

Small K: low bias, high var. Use odd K. When $K=N$: cfr predict: on.

Curse of D: When dimension d gets large (with fixed N), hard to find a neighboring point $x + y = [0, r]^d \times [0, r]^d$

Bayes classifier: min L on all classif: $f_*(x) = 1_{f(x) \geq 1/2}$ $\eta(x) = P(Y=1 | X=x)$

Bayes Risk: $L(f_*) = P(f_*(X) \neq Y) = E_{X \sim P_X} [\min\{\eta(X), 1 - \eta(X)\}]$

Bound for t-NN: $E_{S_{\text{train}}} [L(f_{\text{train}})] \leq 2L(f_*) + 4C\sqrt{dN^{-1/d}}$ Lipschitz

If $N \rightarrow \infty$, bound is $2L(f_*)$. But we need $N \propto d$ to have constant error. Curse of D!

CNN: Conv: filter f, size K, stride S. $x_{n,m}^{(1)} = \sum_{k,l} f_{k,l} \cdot x_{n+S+k, m+S+l}^{(0)}$ \Rightarrow same filter used \rightarrow weight sharing. Value depends on close values. \Rightarrow 0 and valid padding. Can also use multiple filters. $\text{Wout} = \frac{W \times H \times C \times K \times S^2}{S^2 + 1}$

Conv (layer) has multiple filters. HP: size, padding, stride

Pooling: Max or Avg \rightarrow reduce spatial dim. HP: size, type, stride

ReLU after each Conv layer to make it non-linear.

Back propa: 1) Backpropa: indep 2) sum grad of edges with same weights

ResNet: Add x to standard Network f(x) \rightarrow skip-connection $f(x) + x$

Data augmentation: transform $x: \mathbb{R}^d \rightarrow \mathbb{R}^d$ (same label) by rotation

Weight decay: $\min L + \frac{\lambda}{2} \sum \|W^{(l)}\|_F^2$ No need for bias.

Dropout: Subnetwork by keeping with proba $p^{(l)}$ each node. But use whole net work when testing!

Adversarial ML: Standard vs Adv risk: $R(f) = E_D [1_{f(X) \neq Y}]$ $R_s(f) = E_D [\max_{\tilde{x}: \|x - \tilde{x}\| \leq \epsilon} 1_{f(\tilde{x}) \neq Y}]$

Generating adv example: given input (x, y) and $f: x \rightarrow \mathbb{R}^{1,1,3}$. Find \hat{x} s.t. a) $\|\hat{x} - x\| \leq \epsilon$ b) the model f makes a mistake $\max_{\tilde{x}: \|\hat{x} - \tilde{x}\| \leq \epsilon} 1_{f(\tilde{x}) \neq y}$

Issues: 1) f is not continuous 2) NN pred output $\mathbb{R}^{1,1,3}$. **Solutions:** 1) use $\text{ReLU}(x) = \max(0, x)$ 2) smooth f. 2) consider output before classif ($f(x) = \text{Sign}(g(x))$). $P(y|x) = \text{ReLU}(g(x)) / \max(g(x), 0)$

White-box: Solve $\max_{\|\hat{x} - x\| \leq \epsilon} \ell(y(\hat{x}))$ $\nabla_{\hat{x}} \ell(y(\hat{x})) \nabla_x g(x) (\alpha - y \nabla_x g(x))$ since classification loss are decreasing

L2: $\hat{x} = x - ey \cdot \frac{\nabla_x g(x)}{\|\nabla_x g(x)\|_2}$ **Loss:** $\hat{x} = x - ey \cdot \text{sign}(\nabla_x g(x)) \Rightarrow$ PGD: multiple steps! don't know g(x)

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LLM: **LM**: distribution over text: $p(\text{I saw a cat on a mat}) = p(x_1, \dots, x_t)$ **Next-tokenpred:** $P(x_1 | x_0, \dots, x_{t-1}), P(x_2 | x_0, \dots, x_{t-1}) \dots P(x_t) \Rightarrow p(\text{mat} | \text{I saw a cat on a}) = 0.002$

Tokenizer: indep from model **AR inference:** 1) Tokenize 2) forward 3) proba for next token \hookrightarrow sample 5) tokens 6) repeat 2) **Data pre-training:** A lot of low quality to learn. **Post-training:** small or high quality to make model useable. **Distributed learning:** LLM need multiple GPUs to run in parallel **3) Post-training:** 2S vs FS (in-context): if we give examples to GPT, it will perform better. Also if we give examples of reasoning (CoT). **Supervised finetuning:** Have labelers show desired output

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