Exercise1: Inter-Process Communication in Distributed Computing

Objective:

- To understand and implement inter-process communication using Java sockets.
- To explore and implement Remote Method Invocation (RMI) for distributed computing.

Task 1: Build a Simple Client-Server Application

Description: Create a simple client-server application where the server provides a service and the client communicates with it.

Task 2: Enhanced Communication with Data Transfer

Description: Modify the client-server application to send and receive user-defined objects using ObjectInputStream and ObjectOutputStream.

Part 2: Remote Method Invocation (RMI)

Task 1: Create an RMI Service

Description: Develop an RMI-based distributed application where the server provides a remote service, and the client invokes this service.

Solution:

Part 1: Inter-Process Communication using Python Sockets

Task 1: Simple Client-Server Application

Server Code (Python):

```
import socket

def simple_server():
    server_socket = socket.socket(socket.AF_INET, socket.SOCK_STREAM)
    server_socket.bind(('localhost', 5000))
    server_socket.listen(1)

    print("Server is listening on port 5000...")

    connection, address = server_socket.accept()
    print(f"Connection from {address} has been established.")

    client_message = connection.recv(1024).decode('utf-8')
    print(f"Client says: {client_message}")

    server_message = "Hello from the server!"
    connection.sendall(server_message.encode('utf-8'))

    connection.close()
    server_socket.close()
```

```
if __name__ == "__main__":
    simple_server()
```

Client Code (Python):

```
import socket

def simple_client():
    client_socket = socket.socket(socket.AF_INET, socket.SOCK_STREAM)
    client_socket.connect(('localhost', 5000))

    client_message = "Hello from the client!"
    client_socket.sendall(client_message.encode('utf-8'))

    server_message = client_socket.recv(1024).decode('utf-8')
    print(f"Server says: {server_message}")

    client_socket.close()

if __name__ == "__main__":
    simple_client()
```

Task 2: Enhanced Communication with Data Transfer (Sending and Receiving Objects)

In this task, we modify the client-server application to send and receive custom objects using Python's pickle module, which allows serialization of objects.

Server Code (Python with Object Transfer):

```
import socket
import pickle
class CustomObject:
   def __init__(self, name, value):
       self.name = name
        self.value = value
def enhanced server():
    server_socket = socket.socket(socket.AF_INET, socket.SOCK_STREAM)
    server_socket.bind(('localhost', 5000))
    server_socket.listen(1)
   print("Server is listening on port 5000...")
    connection, address = server_socket.accept()
    print(f"Connection from {address} has been established.")
    # Receive object
    data = connection.recv(4096)
    received_object = pickle.loads(data)
```

```
print(f"Received object: Name = {received_object.name}, Value =
{received_object.value}")

# Send response object
response_object = CustomObject("ResponseObject", 123)
connection.sendall(pickle.dumps(response_object))

connection.close()
server_socket.close()

if __name__ == "__main__":
enhanced_server()
```

Client Code (Python with Object Transfer):

```
import socket
import pickle
class CustomObject:
   def __init__(self, name, value):
       self.name = name
       self.value = value
def enhanced client():
    client_socket = socket.socket(socket.AF_INET, socket.SOCK_STREAM)
    client_socket.connect(('localhost', 5000))
   # Create and send custom object
    client_object = CustomObject("ClientObject", 42)
    client_socket.sendall(pickle.dumps(client_object))
   # Receive response object
    data = client socket.recv(4096)
    response_object = pickle.loads(data)
   print(f"Server response: Name = {response_object.name}, Value =
{response_object.value}")
    client_socket.close()
if name == " main ":
    enhanced_client()
```

Part 2: Remote Method Invocation (RMI)

Although Python doesn't have a native RMI system like Java, the equivalent would be using **XML-RPC** or **Pyro4** to implement remote method invocation. Below is an example using **Pyro4**.

First, you need to install Pyro4:

pip install Pyro4

Task 1: Create an RMI Service

RMI Server Code (Python using Pyro4):

```
import Pyro4
# Create a class for the remote service
@Pyro4.expose
class RemoteService:
   def say_hello(self, name):
        return f"Hello, {name}! This is the RMI server."
def start_server():
   # Start the Pyro4 Daemon
   daemon = Pyro4.Daemon() # Pyro4 daemon
   ns = Pyro4.locateNS() # Locate the name server
   uri = daemon.register(RemoteService) # Register the service
   ns.register("example.rmi", uri) # Register the service with a name in the
name server
    print(f"RMI Server started with URI: {uri}")
    daemon.requestLoop() # Start the event loop for listening
if __name__ == "__main <u>":</u>
    start_server()
```

RMI Client Code (Python using Pyro4):

```
import Pyro4

def rmi_client():
    # Locate the RMI server by the name 'example.rmi'
    remote_service = Pyro4.Proxy("PYRONAME:example.rmi")

# Call the remote method
    response = remote_service.say_hello("Client")
    print(f"Server says: {response}")

if __name__ == "__main__":
    rmi_client()
```

Running the Pyro4-based RMI Application:

1. Start the name server by running:

python -m Pyro4.naming

- 2. Run the server code (RMI Server), which will register the service and wait for requests.
- 3. Run the client code (RMI Client), which will connect to the server and invoke the remote method.

Exercise 3: Message Passing and Distributed Mutual Exclusion

Objective:

To understand and implement message passing between distributed processes.

To implement a distributed mutual exclusion algorithm to manage resource access in a distributed system.

Part 1: Message Passing

Task 1: Implement a Simple Message Passing System

Description: Create a message passing system where multiple processes communicate with each other using Java sockets. Each process will send and receive messages.

Part 2: Distributed Mutual Exclusion

Task 1: Implement Distributed Mutual Exclusion Using Ricart-Agrawala Algorithm

Description: Implement a distributed mutual exclusion algorithm (Ricart-Agrawala) to ensure that only one process at a time can access a critical section.

Solution:

Part 1 - Message Passing

Server Code

```
import socket
import threading
import sys
clients=[]
def handle_clients(client_socket,client_address):
    print(f"Client {client_address} has connected to the server")
    clients.append(client_socket)
   while True:
        try:
         message=client socket.recv(1024).decode()
         if message:
            broadcast(client_socket,message)
        except:
           break
    print("Disconnected from connection")
    clients.remove(client_socket)
    client_socket.close()
```

```
def broadcast(client_socket,message):
  for client in clients:
      try:
        if client!=client socket:
            client.send(message.encode('utf-8'))
      except:
         clients.remove(client)
         client.close()
server_socket=socket.socket(socket.AF_INET6,socket.SOCK_STREAM)
host="localhost"
port=5002
server_socket.bind((host,port))
server_socket.listen()
while True:
   client_socket,addr=server_socket.accept()
   thread=threading.Thread(target=handle_clients,args=(client_socket,addr))
  thread.start()
```

Client:

```
import threading
import socket
import sys
lock=threading.Lock()
def receive_messages(client_socket):
   while True:
        try:
                message=client_socket.recv(1024).decode()
                if message:
                    with lock:
                        sys.stdout.write("\r\033[K")
                        print(f"Message from Server:{message}")
                        print("YOU:",end='',flush=True)
        except:
            client_socket.close()
            break
client_socket=socket.socket(socket.AF_INET6,socket.SOCK_STREAM)
host="localhost"
```

```
port=5002
client_socket.connect((host,port))
thread=threading.Thread(target=receive_messages,args=(client_socket,))
thread.start()
while True:
   try:
       message=input("YOU:")
        if message.lower()=="exit":
            client_socket.send("Client is exiting".encode('utf-8'))
            client socket.close()
            break
        else:
            client socket.send(message.encode('utf-8'))
    except:
        client_socket.close()
        break
```

Part 2: Distributed Mutual Exclusion

```
import threading
import time
import random
from queue import PriorityQueue
class RicartAgrawala:
   def _init_(self, pid, total_processes):
        self.pid = pid
        self.processes = total_processes
        self.lock = threading.Lock()
        self.reply count = 0
        self.requesting CS = False
        self.timestamp = 0
        self.request_queue = PriorityQueue()
    def request_cs(self):
        self.requesting_CS = True
        self.timestamp += 1
        print(f"Process {self.pid} requests to enter the CS")
        for i in range(self.processes):
            if self.pid != i:
                self.send message(i)
        while self.reply_count < self.processes - 1:</pre>
            time.sleep(1)
        self.enter cs()
    def send_message(self, target_pid):
        print(f"Process {self.pid} sends message to {target_pid} at timestamp
{self.timestamp}")
```

```
processes[target_pid].receive_message(self)
   def receive_message(self, sender):
        with self.lock:
            self.timestamp = max(self.timestamp, sender.timestamp) + 1
            print(f"Process {self.pid} received message from {sender.pid}")
            if not self.requesting_CS or (sender.timestamp, sender.pid) <</pre>
(self.timestamp, self.pid):
                self.send reply(sender)
            else:
                self.request_queue.put((sender.timestamp, sender))
    def send_reply(self, recipient):
        print(f"Process {self.pid} replies to {recipient.pid}")
        recipient.receive_reply(self)
    def receive_reply(self, _):
        self.reply count += 1
    def enter_cs(self):
        print(f"Process {self.pid} enters the CS at timestamp
{self.timestamp}")
        time.sleep(random.uniform(0.5, 1.5))
        self.exit_cs()
    def exit_cs(self):
        self.reply count = 0
        self.requesting CS = False
        print(f"Process {self.pid} exits the CS at timestamp
{self.timestamp}")
        while not self.request queue.empty():
            _, process = self.request_queue.get()
            self.send_reply(process)
def process_action(process):
   process.request_cs()
    time.sleep(random.uniform(0.5, 1.5))
if _name_ == "_main_":
    num_processes = 5
    processes = [RicartAgrawala(i, num processes) for i in
range(num processes)]
    threads = [threading.Thread(target=process_action, args=(p,)) for p in
processes]
   for thread in threads:
        thread.start()
    for thread in threads:
        thread.join()
```

Exercise 4: Clock and Time Synchronization in Distributed Computing

Objective:

To understand and implement logical clocks and vector clocks in distributed systems.

To explore how clock synchronization helps maintain consistent order of events in distributed systems.

Part 1: Logical Clocks

Task 1: Implement Logical Clocks Using Lamport's Logical Clock

Description: Implement a simple distributed system with multiple processes that use Lamport's Logical Clock to order events. Each process will increment its logical clock and send time-stamped messages to other processes.

Part 2: Vector Clocks

Task 1: Implement Vector Clocks

Description: Implement vector clocks to handle more complex scenarios where multiple processes can be in concurrent states. Vector clocks help in determining the partial ordering of events and detecting causality.

Solution:

Part 1: Logical Clocks

```
import threading
import time
import random

class LogicalClock:
    def __init__(self, pid):
        self.pid = pid  # Process ID
        self.clock = 0  # Logical clock value
        self.lock = threading.Lock()  # Lock for thread safety

def increment_clock(self):
    """ Increment the clock for this process. """
        self.clock += 1

def send_message(self, receiver):
    """ Send a message to another process with the current logical clock. """
    with self.lock:
        self.increment_clock()
```

```
print(f"Process {self.pid} sending message with timestamp {self.clock} to
Process {receiver.pid}")
        receiver.receive_message(self.clock)
   def receive_message(self, received_time):
        """ Update the logical clock on receiving a message. """
       with self.lock:
            self.clock = max(self.clock, received_time) + 1
            print(f"Process {self.pid} received message with timestamp
{received_time}. Updated clock to {self.clock}")
   def perform_event(self):
       """ Simulate an internal event that increments the logical clock. """
       with self.lock:
           self.increment clock()
            print(f"Process {self.pid} performs an internal event. Updated clock to
{self.clock}")
   def run(self, peers):
       """ Simulate sending and receiving messages between processes. """
       for _ in range(5):
           # Perform an internal event
           self.perform_event()
           time.sleep(random.random()) # Random sleep to simulate concurrency
           receiver = random.choice(peers) # Randomly pick a process to send a
message to
           if receiver != self: # Don't send to itself
                self.send message(receiver)
            time.sleep(random.random()) # Random sleep to simulate concurrency
# Simulating logical clock across multiple processes using threading
def start_simulation():
   num_processes = 3
   processes = [LogicalClock(i) for i in range(1, num_processes + 1)]
   threads = []
    for process in processes:
       thread = threading.Thread(target=process.run, args=(processes,))
       threads.append(thread)
       thread.start()
   # Wait for all threads to complete
    for thread in threads:
        thread.join()
```

```
start_simulation()
```

Part 2 - Vector Clocks

```
import threading
import time
import random
class VectorClock:
   def __init__(self, pid, num processes):
        self.pid = pid # Process ID
       self.clock = [0] * num_processes # Vector clock
        self.num_processes = num_processes
        self.lock = threading.Lock() # Lock for thread safety
   def increment_clock(self):
        """ Increment the clock for this process. """
       self.clock[self.pid] += 1
   def send_message(self, receiver, message):
        """ Send a message to another process with the current vector clock. """
       with self.lock:
           self.increment_clock()
           print(f"Process {self.pid} sending message '{message}' with clock {self.clock} to
Process {receiver.pid}")
        receiver.receive_message(message, self.clock.copy())
   def receive_message(self, message, sender_clock):
        """ Update the vector clock on receiving a message. """
       with self.lock:
           # Element-wise max between the current clock and the received clock
           for i in range(self.num_processes):
                self.clock[i] = max(self.clock[i], sender_clock[i])
           self.increment_clock() # Increment own clock after receiving the message
           print(f"Process {self.pid} received message '{message}' with sender's clock
{sender_clock}. Updated clock to {self.clock}")
   def perform_event(self):
       with self.lock:
           self.increment clock()
           print(f"Process {self.pid} performs an internal event. Updated clock to
{self.clock}")
   def run(self, peers):
        """ Simulate sending and receiving messages between processes. """
        for _ in range(5):
```

```
self.perform_event()
           time.sleep(random.random()) # Random sleep to simulate concurrency
           receiver = random.choice(peers) # Randomly pick a process to send a message to
           if receiver != self: # Don't send to itself
                self.send_message(receiver, f"Message from Process {self.pid}")
           time.sleep(random.random()) # Random sleep to simulate concurrency
# Simulating vector clock across multiple processes using threading
def start_simulation():
   num_processes = 3
   processes = [VectorClock(i, num_processes) for i in range(num_processes)]
   threads = []
   for process in processes:
       thread = threading.Thread(target=process.run, args=(processes,))
       threads.append(thread)
       thread.start()
   for thread in threads:
       thread.join()
start_simulation()
```