## 3D Scanning and Spatial Learning Volumetric Capture

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## Last week

- Optimization
  - Procrustes done Bad results, fast
  - Point Correspondences done Really good results, slow initialization
- Voxelgrid
  - CPU approach finished Proof of concept
  - One frame currently, no averaging
- Marching Cubes
  - CPU approach finished Proof of concept
  - Refinded triangle extraction per cube cell
- Graphical User Interface



## Next week

- Optimization
  - Point Correspondences: Fix Procrustes initialization
  - ICP for further alignment
- Voxelgrid
  - GPU approach Proof of concept
  - Weighted averaging of frames
- Marching Cubes
  - GPU approach Proof of concept

