

1 Context-dependent consequences of lagged effects in
2 demographic models

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Abstract

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14 Text of 150 words max summarizing this amazing paper.

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Introduction

Current environmental conditions can have large and immediate effects on the growth, survival, or reproduction of long-lived organisms. There is also mounting evidence, however, for intervals that range from months to years between environmental conditions and the resulting changes in demographic vital rates. These *Lagged Effects*, also known as *Delayed Life-history Events* (i.e., DLHEs) (Beckerman et al. 2002), can simultaneously affect an entire cohort (e.g., juveniles hatching during a period of scarcity will all have delayed maturation and lower lifetime fecundity) or only a subset of the population (e.g., cold temperatures in one year lead to reduced flowering by potentially reproductive individuals in the next). In addition, the temporal delay between an environmental event and changes in demographic vital rates depends on both the intensity of the event and its timing relative to the underlying physiological processes (Criley and Lekawatana 1994; Evers et al. 2021). A drought during the early stages of gestation or floral bud formation, for example, might have a much larger impact on the number of fruits or offspring produced than one at a later stage of the reproductive process. The delay or intensity of lagged effects can also be location- or habitat-specific, with individuals in some sites or habitats buffered against, or able to recover more quickly from, the delayed effects of environmental variation.

Because Lagged Effects are often directly linked to reproduction and survival, it has been argued they could have major but underappreciated consequences for population dynamics (Beckerman et al. 2002). While recent studies suggest this could indeed be the case (Williams et al. 2015; e.g., Molowny-Horas et al. 2017; Tenhumberg et al. 2018), broader efforts to test this hypothesis have faced a number of obstacles (Metcalf et al. 2015). Empirical tests of putative lagged effects are rare because these are challenging to design, implement, and maintain (Kuss et al. 2008). While one could conceivably use observational data to detect lagged effects, doing so requires long-term data on both the putative lagged effect (e.g., reduced probability of flowering) and its potential

environmental drivers (e.g., drought during early floral development), and such coupled data sets are rare (sensu Evers et al. 2021). In addition, the methods for both identifying lagged effects and modeling their demographic impacts can be challenging to implement. For example, many of the potentially applicable statistical methods have stringent assumptions and data requirements rarely met by ecological data (Metcalf et al. 2015), while the including complex biological processes in demographic models can render them less tractable or amenable to analysis using currently available tools. Addressing these challenges is a major undertaking; the value of doing so will depend on the effort required vs. the potential consequences of failing to consider lagged effects — consequences that range from overestimating projections of population growth rate (i.e., λ) in a conservation setting to drawing invalid conclusions regarding support for the predictions of ecological or evolutionary theory.

Integral Projection Models (i.e., IPMs) are an important and widely used tool for studying demography and population dynamics (Ellner and Rees 2006; Rees and Ellner 2009; Rees et al. 2014). Their flexibility, in concert with a rapidly growing suite of software, data, and other resources (Salguero-Gómez et al. 2015; Ellner et al. 2016; Levin et al. 2021), have facilitated their use to study a wide range of topics in ecology, evolution, and conservation (Morris and Doak 2002; Crone et al. 2011; Ellner et al. 2016). Mathematical and statistical advances (e.g., Williams et al. 2012; Brooks et al. 2019) have rapidly expanded the scope of questions and biological processes that can be investigated with these models (e.g., Metcalf et al. 2015; Ellner et al. 2016; Rees and Ellner 2016). Here we investigate how including lagged effects in Integral Projection Models influences projections of λ and population structure.

We have previously shown that the effects of precipitation extremes on the demographic vital rates of an Amazonian understory herb (*Heliconia acuminata*, Heliconiaceae) can be delayed up to 36 months (Scott et al. 2022), with the presence and duration of these lagged effects varying by vital rate and habitat. We parameterized three

classes of Integral Projection Models — a deterministic IPM, a stochastic IPM, and a stochastic IPM with lagged effects of precipitation on vital rates — for populations in two habitat types (i.e., continuous forest vs. forest fragments). Based on previous studies (Bruna and Kress 2002; Bruna 2003; Bruna and Oli 2005) and demographic theory (Tuljapurkar 1990; Caswell 2001) we predicted that: (i) projections of λ from deterministic models would be higher than those of stochastic models, and that (ii) λ is lower for Forest Fragment than Continuous Forest populations regardless of model, but the difference between the two habitats is greatest for the IPM with lagged effects.

Methods

Study System and Demographic Data

Heliconia acuminata (Heliconiaceae) is a perennial, self-incompatible monocot that is distributed throughout much of the Amazon basin (Kress 1990). While some *Heliconia* species grow in large aggregations on roadsides, gaps, and in other disturbed habitats, others, including *H. acuminata*, grow primarily in the forest understory (Kress 1983; Ribeiro et al. 2010). Understory *Heliconia* species produce fewer flowers and are pollinated by traplining hummingbirds (Stouffer and Bierregaard 1996; Bruna et al. 2004). The models and analyses here are based on 11 years (1998-2009) of demographic data collected on >8500 *H. acuminata* found at Brazil's Biological Dynamics of Forest Fragments Project (BDFFP), located ~70 km north of Manaus, Brazil. The BDFFP reserves include both continuous forest and forest fragments that range in size from 1-100 ha. These fragment reserves were originally isolated in the early 1980's by the creation of cattle pastures, with the secondary growth surrounding them periodically cleared to ensure their continued isolation. The habitat in all sites is non-flooded lowland rain forest with rugged topography. A complete summary of the BDFFP and its history can be found in Bierregaard et al. (2001).

A complete description of our demographic methods, data, and analyses to date can be found in Bruna et al. (2023). Briefly, in 1997–1998 a series of 5000 m² plots were established in the BDFFP reserves: N=6 in Continuous Forest and N=4 in 1-ha Forest Fragments (i.e., CF and FF, respectively). All of the *Heliconia acuminata* in these plots were marked and measured; the plots were censused annually, at which time a team recorded the size of surviving individuals, marked and measured new seedlings, and identified any previously marked plants that died. Each plot was also surveyed 4–5 times during the flowering season to identify reproductive plants. These surveys were complemented by data on the number of fruits per flowering plant (Bruna 2021) and seeds per fruit (Bruna 2014) that were collected outside of the demographic plots to avoid altering within-plot recruitment. We also conducted experiments to quantify the probability of seed germination and seedling establishment in both forest fragments and continuous forest (Bruna 1999, 2002).

The rainy season in our sites is typically from late December through late May. *Heliconia acuminata* in our site begin flowering early in the rainy season and most reproductive plants produce a single inflorescence (range = 1–7) with 20–25 flowers (Bruna and Kress 2002). Fruits mature April–May and have 1–3 seeds per fruit ($\bar{x} = 2$) that are dispersed by a thrush and several species of manakin (Uriarte et al. 2011). Dispersed seeds germinate approximately 6 months after dispersal at the onset of the subsequent rainy season, with rates of germination and seedling establishment higher in continuous forest than forest fragments (Bruna 1999, 2002). On average, plots in CF also had more than twice as many plants as the plots in 1-ha fragments (CF median = 788, range = (201–1549); 1-ha median = 339, range = (297–400)).

Construction of Integral Projection Models

We projected the growth rate and structure of *Heliconia acuminata* with three classes of IPMs: Deterministic, Stochastic, and Stochastic with Lagged Environmental Effects. Each

of these IPMs required different functional forms of the underlying vital rate functions used to describe the *H. acuminata* life cycle (Figure 1). All models were density-independent, with the deterministic model serving as the foundation for the more complex models. Our modeling workflows were managed using the **targets** R package (Landau 2021); in addition to ensuring reproducibility this allowed us to track computational time spent processing and analyzing each class of IPM.

(1) Deterministic IPM: In this model the size and structure of a population in year $t + 1$ is determined by the survival and growth of plants alive in year t (Equation 1) plus the number of new seedlings that entered the population (Equation 2).

$$n(z', t + 1) = R(z')n_s(t) + \int_L^U P(z', z)n(z, t) dz \quad (1)$$

$$n_s(t + 1) = \int_L^U F(z)n(z, t) dz \quad (2)$$

Equation 1 has two components. The first is the sub-kernel $P(z', z)$, which describes the size-dependent survival and growth/regression of mature plants (Equation 3):

$$P(z', z) = s(z)G(z', z) \quad (3)$$

The second is sub-kernel $R(z')$, which describes the survival of seedlings established in year t and their size when entering the mature plant population in year $t + 1$ (Equation 4):

$$R(z') = s_s G_s(z') \quad (4)$$

Note that in Equation 4 both the probability that new seedlings survive their first year, s_s , and their size at the end of this year, $G(z', z)$, are size-independent. IPMs can include transitions between individuals from a discrete state to a continuous one (i.e., from ‘seedling’ to ‘mature plant of size z' ,’ Ellner et al. 2016); we treat seedlings as a distinct

and discrete category because they have lower survival and growth in their first year than comparably sized plants (Bruna 2003; Scott et al. 2022).

The number of new seedlings entering the population in year $t + 1$ is a function of the number of mature plants in year t and a sub-kernel describing the size-dependent fecundity of these individuals (Equation 5):

$$F(z) = p_f(z)f(z)g \quad (5)$$

Both the probability that a mature plant will flower, $p_f(z)$, and the number of seeds a flowering plant will produce, $f(z)$, are size-dependent. All seeds germinate and establish as seedlings with probability g .

We used the annual census data (Bruna 2003) to fit the deterministic vital rate functions for growth, survival, and flowering in each habitat type (i.e., Fragments, Continuous Forest; the data from all plots within a habitat class were pooled to create a single ‘summary population’ for the CF and FF habitats (Bruna 2003). For established plants these were modeled as a smooth function of size in the previous census with generalized additive models (GAMs) fit with the `mgcv` package (Wood 2011) for the R statistical programming language (R Core Team 2020). For consistency, seedling survival and growth were also modeled using GAMs, but without size in the previous census as a predictor (i.e. ‘intercept-only’ models). For growth models a scaled t family distribution provided a better fit to the data than a Gaussian fit, as the residuals with a simple Gaussian model were Leptokurtic. To model size-specific fecundity we used the data on fruits per flowering plant (Bruna 2021), seeds per fruit (Bruna 2014), and the experimentally-derived estimates of seed germination and seedling establishment (Bruna 1999, 2002).

(2) Stochastic IPMs: To include temporal stochasticity in our IPMs we included a random effect of year. This was done using a factor–smooth interaction that allowed the

functional form of the relationship between plant size and vital rates to vary among transition years (Figure 1). We generated kernels for every transition year using the long-term survey data (Bruna et al. 2023) and random smooths for year. We then randomly selected one of these sets of kernels to use in each iteration of the IPM. This procedure is equivalent to ‘*kernel resampling*’ (*sensu* Metcalf et al. 2015) or matrix selection for matrix population models (Caswell 2001).

(3) Stochastic IPMs with lagged effects of precipitation on vital rates: We explicit modeled the lagged effects of precipitation extremes on vital rates using the procedure described in Scott et al. (2022). Briefly, we first calculated the Standardized Precipitation Evapotranspiration Index (i.e., SPEI) for our study site using a published gridded dataset based on ground measurements (Xavier et al. 2016). After we fit vital rate models using the long-term survey data (Figure 1), we modeled delayed effects of SPEI with Distributed Lag Non-linear Models (i.e., DLNMs) with a maximum lag of 36 months (Scott et al. 2022). To iterate these parameter-resampled IPMs (*sensu* Metcalf et al. 2015) we first created a random sequence of SPEI values by sampling years of the observed (monthly) SPEI data. For every year we then calculated a lag of 36 months from the month in which that year’s census was completed. These values were then used to predict the fitted values from vital rate models, which generated different kernels for each iteration of the IPM. The kernels of successive iterations are not entirely independent — the SPEI values used to calculate vital rates include values used in the previous two iterations — but they are ergodic.

All IPMs were constructed and iterated using the `ipmr` package (Levin et al. 2021) for the R statistical programming language (R Core Team 2020). The IPMs used 100 meshpoints and the midpoint rule for calculating kernels. For each type of IPM we iterated the model for 1000 time steps, but discarded the first 100 time steps to omit transient effects. Stochastic growth rates (λ_s) were calculated as the average $\ln(\lambda)$ from each time step (Caswell 2001) and then back-transformed to allow for direct comparison with

projections of λ from deterministic models. The initial starting vector primarily influences a population's transient dynamics; we therefore used the distribution of established plant sizes and proportion of seedlings in the full demographic data set as the initial population vector for all models.

Finally, We estimated the 95% confidence intervals for each IPMs projections of λ . To do so we first created 500 populations for each habitat type by sampling individual plants with replacement (i.e., bootstrapping) until the population size of each matched that of the initial population vector. We then re-fit the vital rate models for growth, survival, and flowering for each of these bootstrapped population and constructed new IPMs for each population as above (the models for germination and establishment rate, fruits per flowering plant, and seeds per fruit were not refit because these were estimated using different data sets). The projections of λ for the new populations were then used to estimate the upper and lower 95% bias-corrected percentile intervals (Caswell 2001; Manly 2018).

Statistical analyses

Comparison of λ in Continuous Forest and Forest Fragments. To determine if the deterministic projections of λ for Continuous Forest and Forest Fragment populations were significantly different we used the randomization test procedure described by Caswell (2001). Briefly, we randomly assigned plants with their demographic history among two populations, R_1 and R_2 , that were equal in size to the original CF and FF populations. We then calculated λ^{R_1} , λ^{R_2} , and the absolute value of the difference between the two (i.e., θ). This was repeated $N = 1000$ times, after which we determined the proportion of simulations in which θ was greater than the observed difference between λ^{CF} and λ^{FF} (i.e., $P[\theta \geq \theta_{obs}]$).

We used a Generalized Linear Model to compare the projections of λ from the two stochastic IPMs. We modelled the lambda as a function of IPM type (kernel-resampling vs

parameter-resampling) and Habitat (continuous forest vs. fragments), and the interaction of IPM type and Habitat. Because the response variable (λ) was continuous we used the Gaussian distribution with the identity link function in our model. We verified the model assumptions by plotting residuals versus fitted values.

Population Structure. Finally, we compared the structure of populations through the first 250 time steps in each habitat by each of the stochastic IPMs (i.e, kernel- vs. parameter-resampling). At each time step, we assigned the individuals to one of four stage classes based on plant size, probability of survival, and probability of reproduction (see Table Table 3). We then calculated the proportion of the population that was in each stage class in each habitat for each IPM type. Comparing the means and variances of these proportions will allow us to determine (1) if the two IPMs project different population structures over time, (2) if the population structure for a given IPM is consistent across habitat type. Because Shapiro-Wilk tests indicated that the distributions of proportions were not normally distributed, we used the non-parametric Ansari-Bradley Test to compare the distribution of proportions in each habitat x stage combination. These analyses were conducted using the R packages `rstatix` and `vartest`, respectively (Kassambara 2023; Cosar and Dag 2024).

Results & Discussion

All IPMs projected higher population growth rates for *Heliconia acuminata* populations in Continuous Forest than for those in Forest Fragments (Table 2, Table 6). The differences between λ^{CF} and λ^{FF} , which ranged from 1.19-2%, were significant for both deterministic ($P[\theta \geq \theta_{obs}] = 0$, $N = 1000$ randomization) and stochastic IPMs (Table 6). There were also significant effects of IPM Type, Habitat, and their interaction on λ (Table 6). Because stochasticity is predicted to reduce population growth rates (Tuljapurkar et al. 2003; Doak et al. 2005; Metcalf et al. 2015), we were surprised to find that deterministic λ was nearly

identical to the average λ from kernel-resampled IPMs (Figure 3). However, we did see reductions in population growth rate when including lagged effects in IPMs: on average the projections of λ from these models were 1.5-2% lower, with 70-76% of the values below deterministic λ (Figure 3). The IPMs with lagged effects also appear to be more accurate — the underlying vital rate models for IPMs with lagged effects all had the best fit to the survey data (dAIC = 0, Table 1).

Including lagged effects in IPMs also resulted in significantly less predictable projections of population structure, both within (Figure 2 a) and across habitats (Figure 2 b, Table 4). This variability is particularly notable in forest fragments (Figure 4, Table 5), where we have previously shown lagged effects have very large impacts on growth and survival (Scott et al. 2022). The deterministic IPM for Continuous Forest projected slightly more of the smallest and largest plants than the one for Forest Fragments. In other words, populations in forest fragments had proportionately less recruitment and fewer individuals growing into the larger, reproductive size classes (Bruna and Oli 2005). This shift towards intermediately sized, pre-reproductive plants in forest fragments is even more dramatic when using the parameter-resampled stochastic IPM (Figure 2 b).

What are the implications of these results for the use of IPMs to study plant demography? First, they suggest that failing to include lagged effects in models could significantly underestimate the growth rate of populations. While relative differences in projections of λ may be sufficient for some tests of theory, the actual value of projections may be critical in conservation or management settings. For example, they could be used to identify which populations face the greatest risk of extinction (e.g., $\lambda = 0.99$ vs. $\lambda = 1.01$) or — because even small differences in λ can have major short-term consequences for population dynamics (e.g., $\lambda = 1.01$ vs. $\lambda = 1.02$) - be used to choose among management strategies. Moreover, including lagged effects in models could be especially critical for studies assessing the effects of climate change, given many DLHE are climate driven. That said, there is a cost to including lagged effects in demographic models, even when doing so

is conceptually appropriate or if the outcome is potentially more accurate. While Deterministic and Kernel-resampled Stochastic IPMs took only ~ 0.02 and ~ 0.07 min to iterate (respectively), the Stochastic IPMs with using parameter-resampled kernels and lagged effects took ~ 87.12 min. This is largely due to the required computational resources and algorithms (i.e., `predict()`), which are much slower for Generalized Additive Models with 2D smooths because of the much higher number of knots than for the GAMs used in Deterministic and Kernel-resampled IPMs. Advances in computational power and access to high-performance computing resources could lower this cost.

That said, computational power cannot compensate for limited data. Detecting lagged effects and evaluating their consequences requires long-term demographic data — data that are only available for a relatively small number of species, few of which are in the tropics. The increasing evidence that lagged effects are ubiquitous, and that they can have major demographic impacts, underscores the need to support the collection of such long-term data, the complementary development of experimental and statistical approaches to disentangling lagged effects, and community driven efforts to identify priority or model systems for in-depth investigation.

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CRediT Statement

ERS contributed to the conceptualization, methodology, formal analysis, and led the writing of the original draft. EMB contributed to the conceptualization, methodology, writing, and, acquired funding.

Data Availability Statement

Data and R code used in this study are archived with Zenodo at *(doi and url to be added on acceptance)*.

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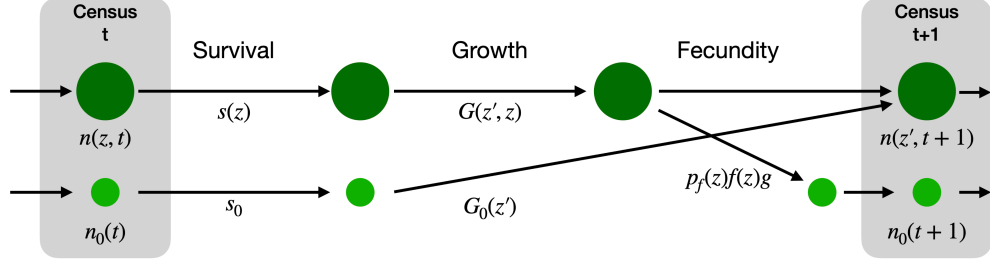
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Description	Deterministic	Stochastic, kernel-resampled	Stochastic, parameter-resampled
Survival	$s(z)$	$s_y(z)$	$s(z; \theta_{0-36})$
Growth	$G(z'; z)$	$G_y(z'; z)$	$G(z', z; \theta_{0-36})$
Flowering	$p_f(z)$	$p_{f_y}(z)$	$p_f(z; \theta_{0-36})$
Size-specific fecundity	$f(z)$	$f(z)$	$f(z)$
Germination & establishment	g	g	g
Seedling survival	s_0	s_{0_y}	$s_0(\theta_{0-36})$
Seedling growth	$G_0(z')$	$G_{0_y}(z')$	$G_0(z'; \theta_{0-36})$

fig. 1. Life cycle diagram of *Heliconia acuminata*. Each transition is associated with an equation for a vital rate function. The functions shown on the diagram correspond to those used to construct a general, density-independent, deterministic IPM. The table below shows the equivalent equations for stochastic, kernel-resampled IPMs and stochastic, parameter-resampled IPMs.

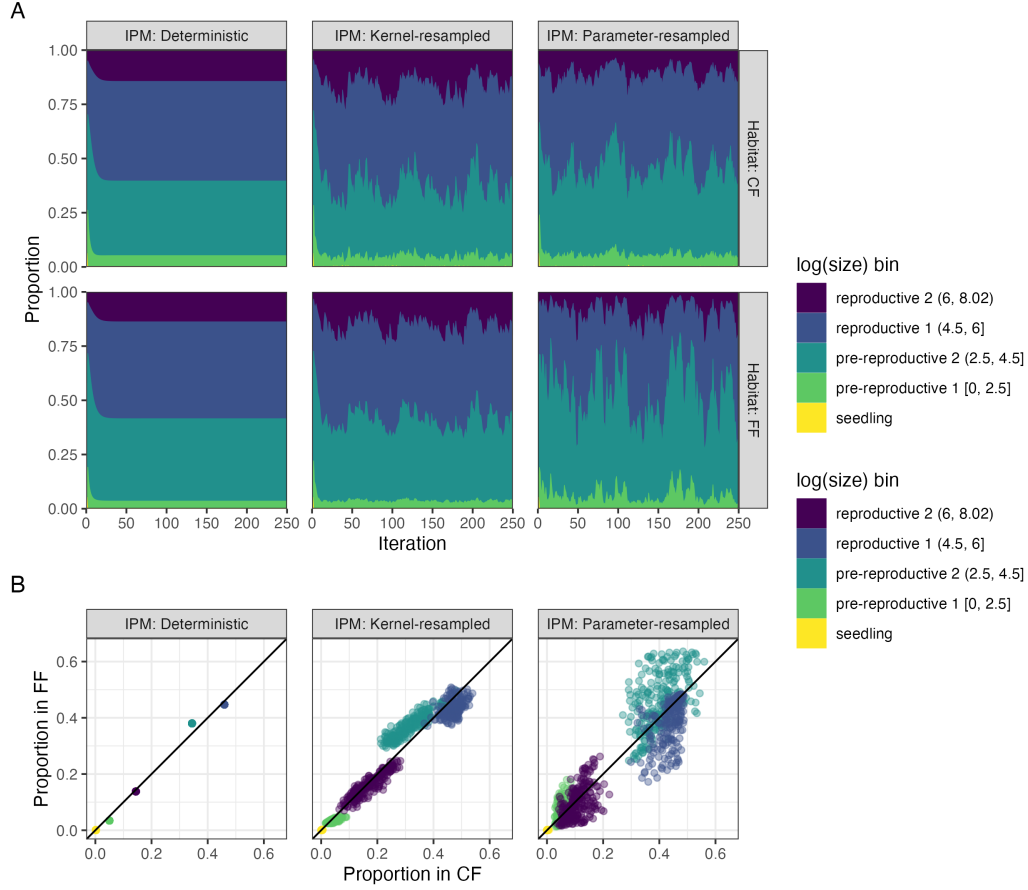


fig. 2. **(A)** The change over time in the the proportion of *Heliconia acuminata* populations in different size/stage classes when simulating population dyammics in Continuous Forest (CF) or Forest Fragment (FF) with three different Integral Projection Models. Results are shown for the first 250 iterations of populations; for the criteria used to define the size categories see Table 3. **(B)** The relative proportion of the population in each size class (FF vs. CF) for 250 iterations of each IPM model. Note that this excludes transient dynamics (iterations 1-30). Values on the 1-1 line indicate an iteration where CF and FF have the same proportion of the population in a given size class.

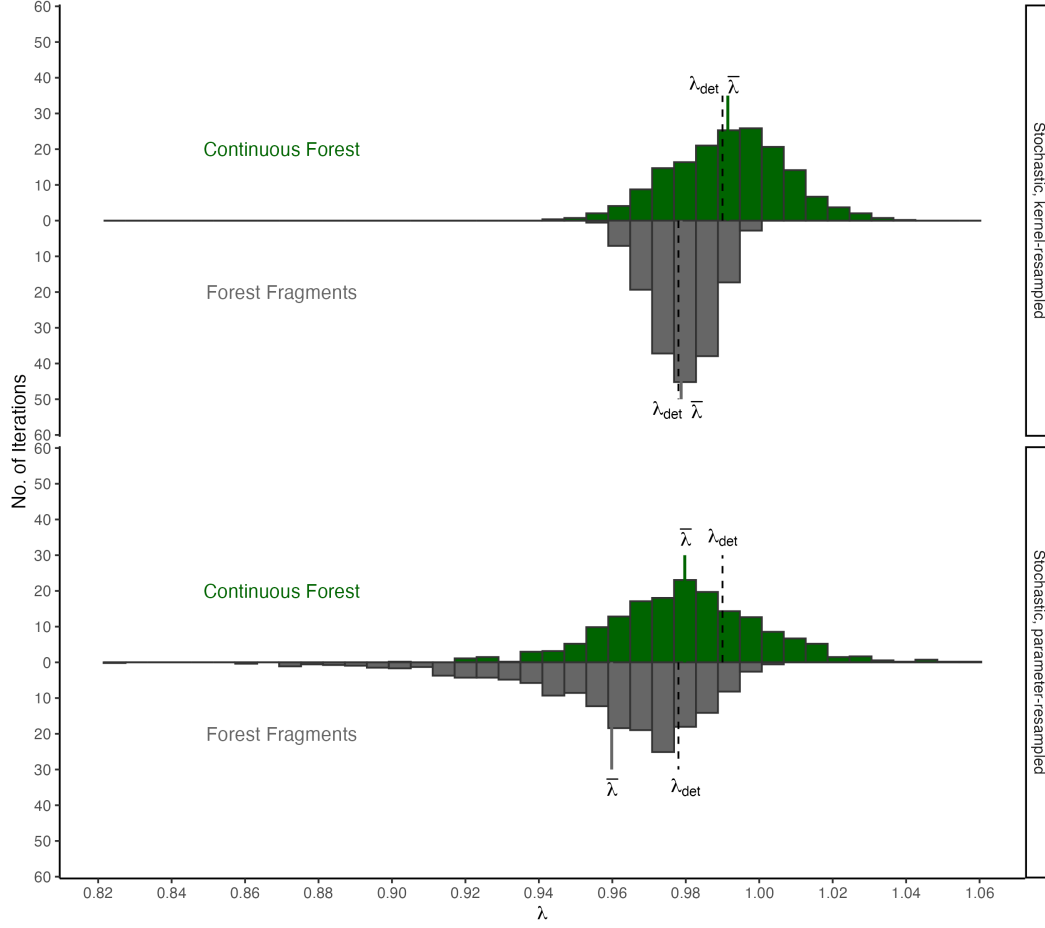


fig. 3. Distribution of 900 values of λ projected with (A) Stochastic, kernel-resampled IPMs and (B) Stochastic, parameter-resampled IPMs. IPMs were used to project λ for both Continuous Forest (above, in green) and Forest Fragments (below, in gray). The solid line indicates the mean value of λ , the dashed line indicates the value of λ in that habitat projected with Deterministic IPMs.

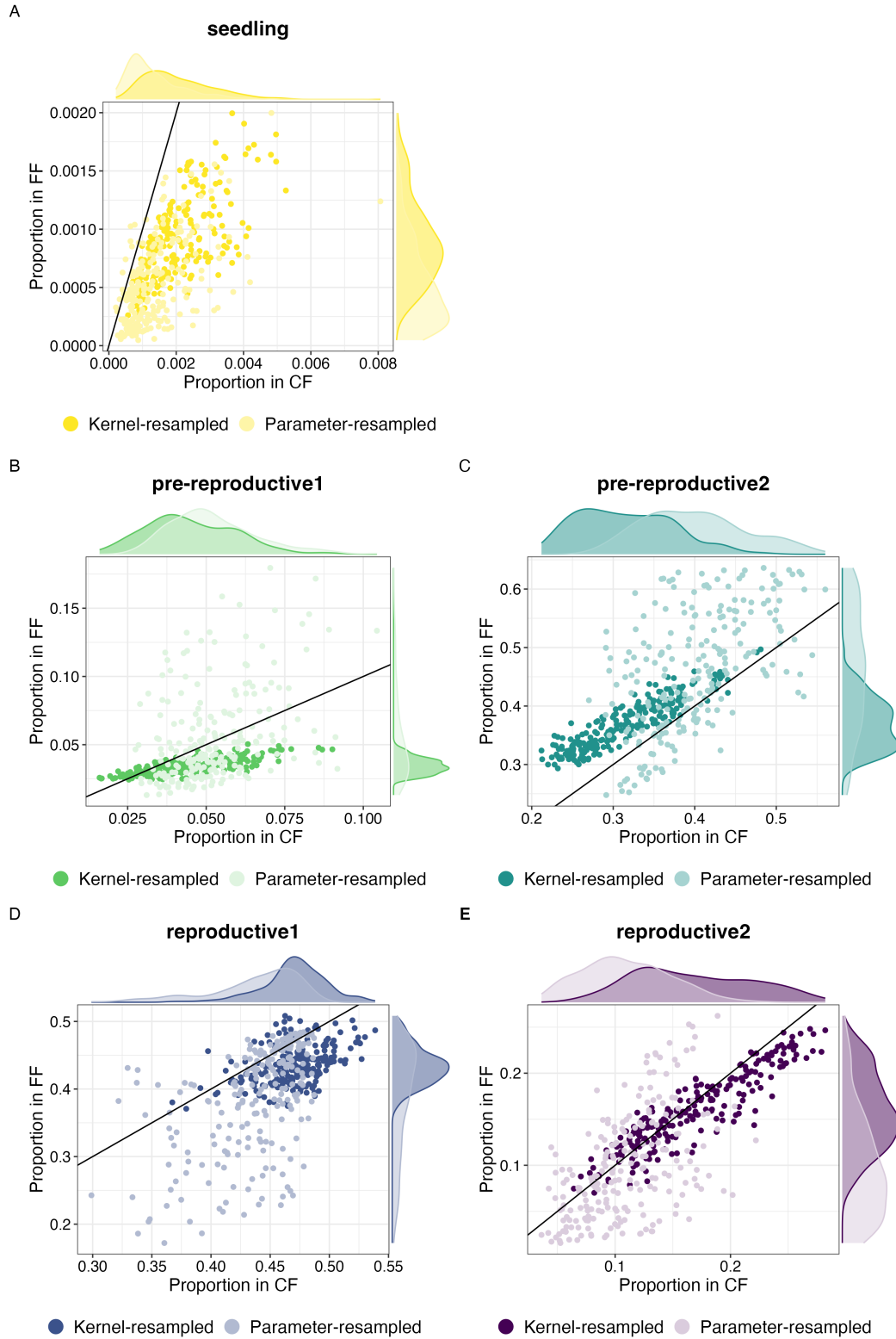


fig. 4. The relative proportion of the population in each size class (FF vs. CF) for each of 250 iterations of the kernel-resampled (dark shading) and parameter-resampled IPM models (light shading). Values on the 1-1 line indicate an iteration where CF and FF have the same proportion of the population in a given size class; the marginal plots indicate the distribution of these relative proportions for each class of IPM in each habitat. Note that both the scatterplots and marginal plots exclude transient dynamics (iterations 1-30).

Table 1: Comparison of vital rate models used to build IPM. The ‘Effect of Environment’ column describes how environmental effects were included in models. Those with ‘none’ were used to build deterministic IPMs; those with a random effect of year were used to build stochastic, kernel-resampled IPMs; and those with a distributed lag non-linear model (DLNM) were used to build stochastic, parameter-resampled IPMs. ‘edf’ is the estimated degrees of freedom of the penalized GAM. Δ AIC is calculated within each habitat and vital rate combination. Δ AIC within 2 indicates models are equivalent.

Habitat	Vital Rate	Effect of Environment	edf	ΔAIC
Continuous Forest	Survival	Random effect of year	43.26	0.00
		DLNM	19.72	78.92
		None	4.98	260.01
	Growth	Random effect of year	78.43	0.00
		DLNM	23.87	158.46
		None	7.81	1896.03
	Flowering	DLNM	19.59	0.00
		Random effect of year	17.19	1.63
		None	7.47	381.86
	Seedling survival	None	1.00	0.00
		Random effect of year	1.82	1.39
		DLNM	4.01	1.53
	Seedling growth	Random effect of year	9.47	0.00
		DLNM	8.95	2.90
		None	1.00	172.33
Forest Fragments	Survival	DLNM	14.95	0.00
		Random effect of year	19.21	35.68
		None	4.33	51.25
	Growth	DLNM	25.18	0.00
		Random effect of year	37.84	199.98
		None	5.60	382.76
	Flowering	DLNM	20.61	0.00
		Random effect of year	13.81	27.40
		None	5.01	101.70
	Seedling survival	DLNM	5.57	0.00
		Random effect of year	5.09	5.72
		None	1.00	6.49
	Seedling growth	Random effect of year	6.25	0.00
		DLNM	8.18	2.29
		None	1.00	5.74

Table 2: Population growth rates for continuous forest (CF) and forest fragments (FF) under different kinds of IPMs with bootstrapped, bias-corrected, 95% confidence intervals.

IPM	Habitat	λ	(Lower, Upper 95% CI)
Deterministic			
	FF	0.9778	(0.9736, 0.9823)
	CF	0.9897	(0.9877, 0.9920)
Stochastic, kernel resampled			
	FF	0.9787	(0.9735, 0.9835)
	CF	0.9913	(0.9892, 0.9939)
Stochastic, parameter-resampled			
	FF	0.9595	(0.9459, 0.9689)
	CF	0.9795	(0.9752, 0.9867)

Table 3: Size and stage categories used for comparing *Heliconia acuminata* population structure. Note that seedlings are a discrete size class not based on size (see *Methods* for additional details).

Category	Log(size)	Avg. prob. survival	Prob. flowering
Seedlings	-	-	-
Pre-reproductive 1	0-2.5	≤ 0.9	≈ 0
Pre-reproductive 2	2.5-4.5	≥ 0.8	≈ 0
Reproductive 1	4.5-6	≥ 0.95	≤ 0.25
Reproductive 2	≥ 6	≥ 0.95	≥ 0.2

Table 4: Results of statistical tests comparing the variance in the proportion of each habitat's population projected to be in each stage class by kernel-resampled vs. parameter resampled IPMs ($N = 220$ projections per stage class). The variances for each habitat x stage class x IPM combination can be found in Table 5. Comparisons where the p-value of the test was < 0.05 are indicated with an asterisk.

Stage	Habitat	Statistic	df	p value
Seedling				
	CF	4.59	1	0.032*
	FF	11.51	1	0.001*
Pre-reproductive 1				
	CF	8.73	1	0.003*
	FF	96.13	1	$< 0.0001^*$
Pre-reproductive 2				
	CF	0.99	1	0.319
	FF	39.67	1	$< 0.0001^*$
Reproductive 1				
	CF	0.57	1	0.452
	FF	61.58	1	$< 0.0001^*$
Reproductive 2				
	CF	0.11	1	0.745
	FF	18.78	1	$< 0.0001^*$

Table 5: Summary statistics (median, mean, and variance) describing the proportion of populations projected to be in each of five life-history stages by kernel- and parameter-resampled IPMs (N = 220 projections for each IPM class x habitat combination.)

Stage	IPM	Median		Mean		Variance	
		CF	FF	CF	FF	CF	FF
Seedling							
	Kernel-resampled	0.0018	0.0009	0.0020	0.0020	0.000001	0.000000
	Parameter-resampled	0.0011	0.0004	0.0014	0.0014	0.000001	0.000000
Pre-reproductive 1							
	Kernel-resampled	0.0426	0.0340	0.0450	0.0450	0.000203	0.000034
	Parameter-resampled	0.0499	0.0438	0.0522	0.0522	0.000192	0.001167
Pre-reproductive 2							
	Kernel-resampled	0.3097	0.3677	0.3147	0.3147	0.003354	0.001884
	Parameter-resampled	0.3975	0.4613	0.4002	0.4002	0.003934	0.010380
Reproductive 1							
	Kernel-resampled	0.4725	0.4332	0.4704	0.4704	0.000736	0.000822
	Parameter-resampled	0.4464	0.4049	0.4371	0.4371	0.001481	0.006388
Reproductive 2							
	Kernel-resampled	0.1630	0.1554	0.1679	0.1679	0.002630	0.001745
	Parameter-resampled	0.1062	0.0882	0.1092	0.1092	0.001427	0.003213

Table 6: Estimated parameters, standard errors, t-values and P-values for the GLM of the effect of Habitat and IPM Type on projections of lambda.

Term	Estimate	SE	z value	P value
(Intercept)	0.98	0	1568.20	0
$Habitat_{FF}$	-0.02	0	-22.52	0
IPM_{Stoch}	0.01	0	13.27	0
$Habitat_{FF} : IPM_{Stoch}$	0.01	0	5.76	0