

$$\textcircled{1} \quad C(s) = K$$

$$G(s) = \frac{5}{(s+2)(s+3)(s+4)}$$

$$G_{MF}(s) = \frac{5K}{s^3 + 9s^2 + 26s + 24 + 5K}$$

$$s^3: 1 \quad 26$$

$$s^2: 9 \quad 24+5K$$

$$s: \frac{9 \cdot 26 - 24 - 5K}{9} \quad 0$$

$$s^0: 24 + 5K \quad 0$$

$$\begin{cases} 24 + 5K > 0 \\ \frac{9 \cdot 26 - 24 - 5K}{9} > 0 \end{cases}$$

$$K > \frac{24}{5} = 4,8$$

$$SK < 234 - 24$$

$$K < 92$$

② $C(s) = \frac{K_p s + K_i}{s}$

$$D(s) = \frac{1}{s^2}$$

$$G(s) = \frac{1}{ms + b}$$

$$G_D(s) = \frac{G(s)}{1 + C(s)G(s)}$$

$$G_D(s) = \frac{s}{ms^2 + (b + K_p)s + K_i}$$

$$\frac{Y(s)}{D(s)} = \frac{s}{ms^2 + (b + K_p)s + K_i}$$

$$E(s) = Y(s)$$

$$e_{\infty} = \lim_{t \rightarrow \infty} y(t) = \lim_{s \rightarrow 0} s Y(s) =$$

$$\lim_{s \rightarrow 0} s \left(\frac{s}{ms^2 + bs + K_p} \right) \cdot \frac{1}{s^2} =$$

$$\lim_{s \rightarrow 0} \frac{1}{s(ms + b + K_p) + K_i} = \frac{1}{K_i}$$

③ $F(y, v, u) = K_F \frac{u^2}{(\overline{y_{max}} - y)^2}$

$$F(y, v, u) = K_F \frac{\left(\frac{m}{K_F} \delta\right) (\overline{y_{max}} - y_0)^2}{(\overline{y_{max}} - y_0)^2} +$$

$$2K_F \frac{\overline{mg}}{K_F} \frac{(\overline{y_{max}} - y_0)}{(\overline{y_{max}} - y_0)^2} \left(v - \sqrt{\frac{mg}{K_F}} (\overline{y_{max}} - y_0) \right) +$$

$$2K_F \frac{\frac{mg}{K_F}(\gamma_{max} - \gamma_0)^2}{(\gamma_{max} - \gamma_0)^\beta} (\gamma - \gamma_0)$$

$$F(\gamma, v, u) = mg + \frac{2\sqrt{K_F mg}}{(\gamma_{max} - \gamma_0)} \delta u + \frac{2mg\delta v}{(\gamma_{max} - \gamma_0)}$$

$$\dot{y} = v = v - v_0 = \delta v$$

$$m\ddot{v} = mg + \frac{2\sqrt{K_F mg}}{(\gamma_{max} - \gamma_0)} \delta u + \frac{2mg\delta y}{(\gamma_{max} - \gamma_0)} - bv - mg$$

$$A = \begin{bmatrix} 0 & 1 \\ \frac{2mg}{\gamma_{max} - \gamma_0} & -b \end{bmatrix} \quad B = \begin{bmatrix} 0 \\ \frac{2\sqrt{K_F mg}}{(\gamma_{max} - \gamma_0)} \end{bmatrix}$$

$$\textcircled{4} \quad G_F = \frac{600}{(s+10)(s+20)(s^2+2s+4)}$$

$$P_1 = -10$$

$$P_2 = -20$$

$$\textcircled{P_{3,4}} = \frac{-2 \pm 2\sqrt{3}}{2} = -1 \pm \sqrt{3};$$

↳ Polos dominantes

$$10 \geq s > -(-1)$$

$$20 \geq s > -(-1)$$

Logo:

$$G_{asym} \approx \lim_{s \rightarrow 0} G_F \cdot \frac{1}{s^2 + 2s + 4} = \frac{3}{4} \cdot \frac{1}{s^2 + 2s + 4}$$

$$\gamma(s) = \frac{3 \cdot 4^s}{s^2 + 2s + 4} R(s)$$

$$\lim_{s \rightarrow 0} G_F(s) = \frac{600}{10 \cdot 20 \cdot 4} : \frac{3}{4}$$

Degree unifario: 1

$$C_{ob} = \lim_{s \rightarrow 0} \frac{1}{1 + G_F(s)} = \frac{1}{1 + \frac{3}{4}} = \frac{4}{7}$$

$$2 \bar{\epsilon}_{Wn} = 2$$

$$w_n^2 = 4 \quad w_n = 2 \quad \bar{\epsilon} = \frac{1}{2}$$

$$t_r \left| \begin{array}{c} 90\% \\ 10\% \end{array} \right. = \frac{2,16 \cdot \frac{1}{2} + 0,6}{2} = \frac{1,68}{2} = 0,84$$

$$t_s \left| \begin{array}{c} 2\% \\ \bar{\epsilon}_{Wn} \end{array} \right. = \frac{3,9}{\bar{\epsilon}_{Wn}} = \frac{3,9}{1} = 3,9$$

(5)

$$R\dot{q} + Cq = v(t)$$

$$C(s) = \frac{K_p s + K_i}{s}$$

$$F(s) = \frac{K_i}{K_p s + K_i}$$

$$G(s) = \frac{1}{R_s + C}$$

$$G_F(s) = F(s) \left(\frac{C(s) G(s)}{1 + C(s) G(s)} \right)$$

$$G_F(s) = \frac{K_i}{K_p s + K_i} \left(\frac{K_p s + K_i}{R s^2 + (C + K_p)s + K_i} \right)$$

$$G_F(s) = \frac{K_i / R}{s^2 + \frac{(K_p + C)}{R} s + \frac{K_i}{R}}$$

$$\frac{K_i}{R} = \omega_n^2 \quad K_i = \omega_n^2 R$$

$$\left(\frac{K_p + C}{R} \right) = 2\epsilon \omega_n \quad K_p = 2\epsilon \omega_n R - C$$

$$M_p = e^{-\frac{\pi \epsilon}{\sqrt{1-\epsilon^2}}}$$

$$t_{100\%} = \frac{\pi - \arccos \epsilon}{\omega_n \sqrt{1-\epsilon^2}}$$