



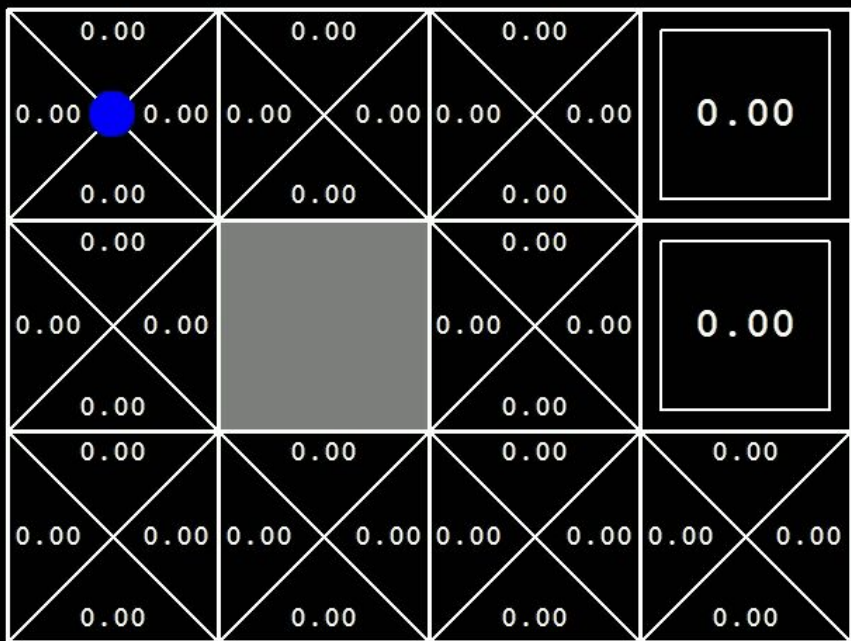
Q-Learning

Como aprender quais ações tomar



GRUPO
TURING

Objetivo



CURRENT Q-VALUES

Queremos estimar o valor q de cada ação, para poder escolher as melhores.

Para isto, precisamos explorar as ações do ambiente em cada estado para descobrir suas recompensas médias.

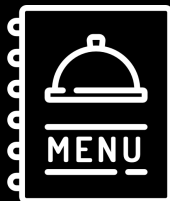
Dilema

Exploração

Aproveitar ações conhecidas

Maior recompensa com o conhecimento que já possui

Não garante que se trata das melhores escolhas



Exploração

Tomar novas ações para explorar estados diferentes

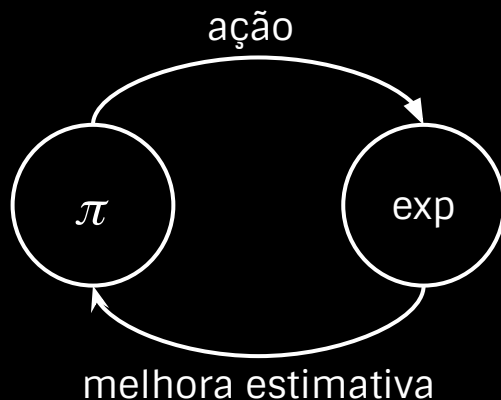
Pode levar a caminhos melhores

Menores recompensas a curto prazo

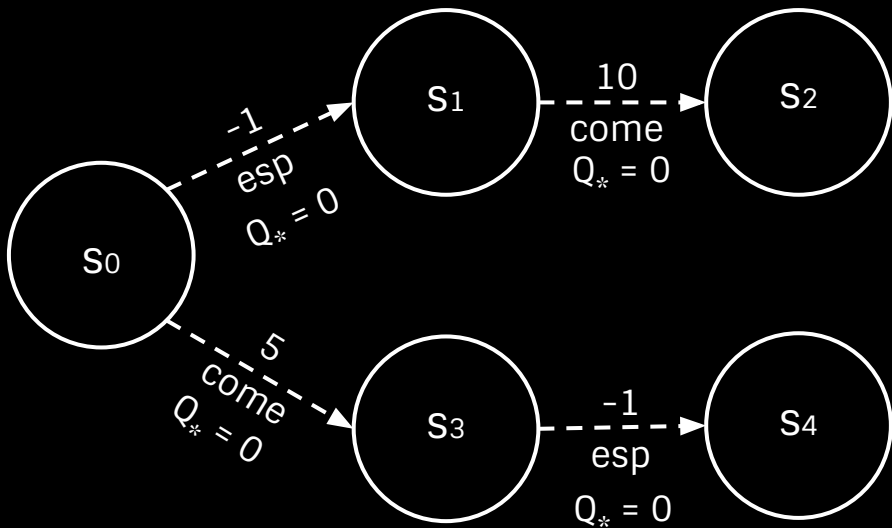
Objetivo: buscar equilíbrio entre exploração e exploração

Q-Learning

$$Q_*(s, a) \leftarrow (1 - \alpha) \cdot Q_*(s, a) + \alpha \cdot Q_*^{\text{nov}}(s, a)$$

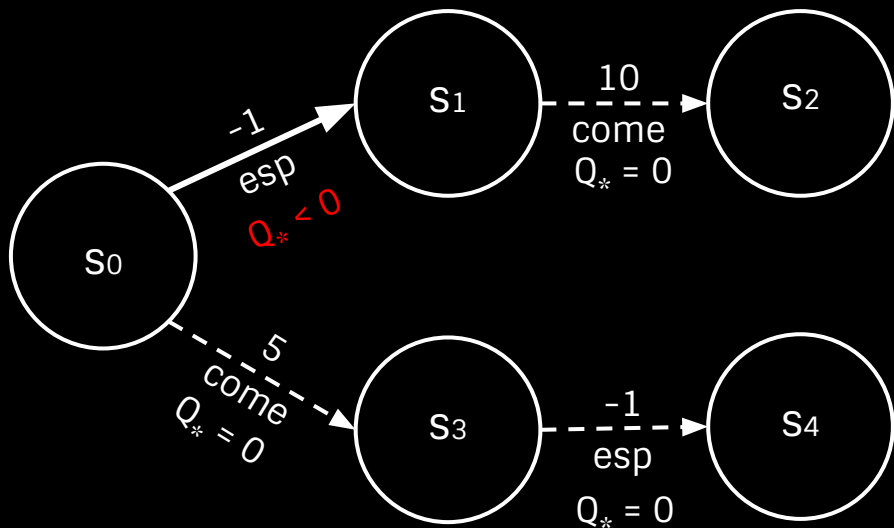


Exemplo



$$Q_*(s, a) \leftarrow (1 - \alpha) \cdot Q_*(s, a) + \alpha \cdot Q_*^{\text{nov}}(s, a)$$

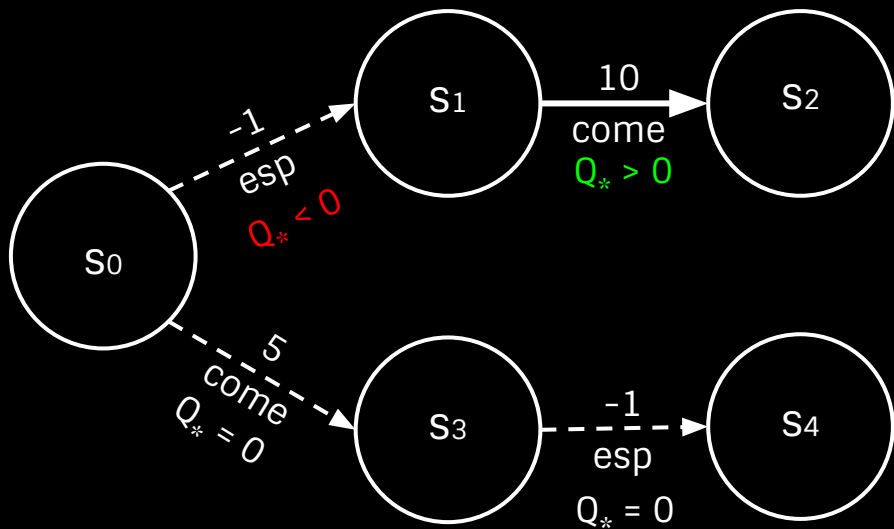
Exemplo



$$Q_*(s, a) \leftarrow (1 - \alpha) \cdot Q_*(s, a) + \alpha \cdot Q_*^{\text{nov}}(s, a)$$



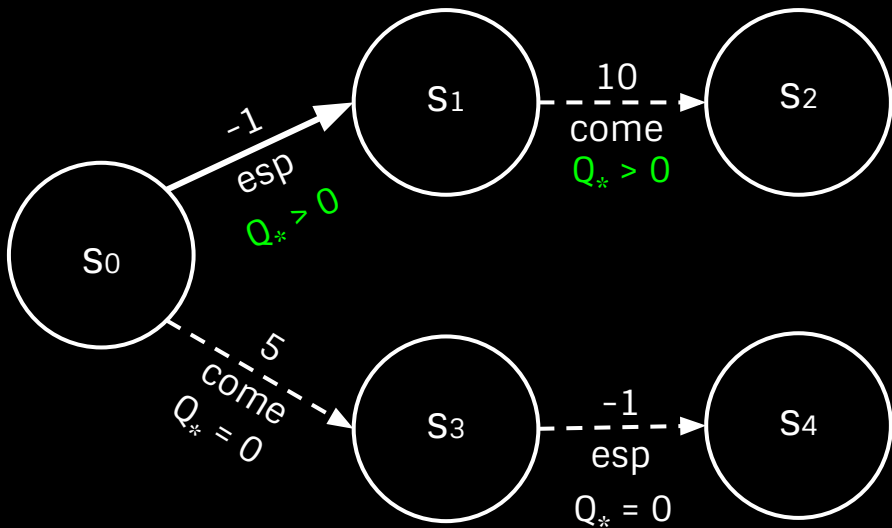
Exemplo



$$Q_*(s, a) \leftarrow (1 - \alpha) \cdot Q_*(s, a) + \alpha \cdot Q_*^{\text{nov}}(s, a)$$



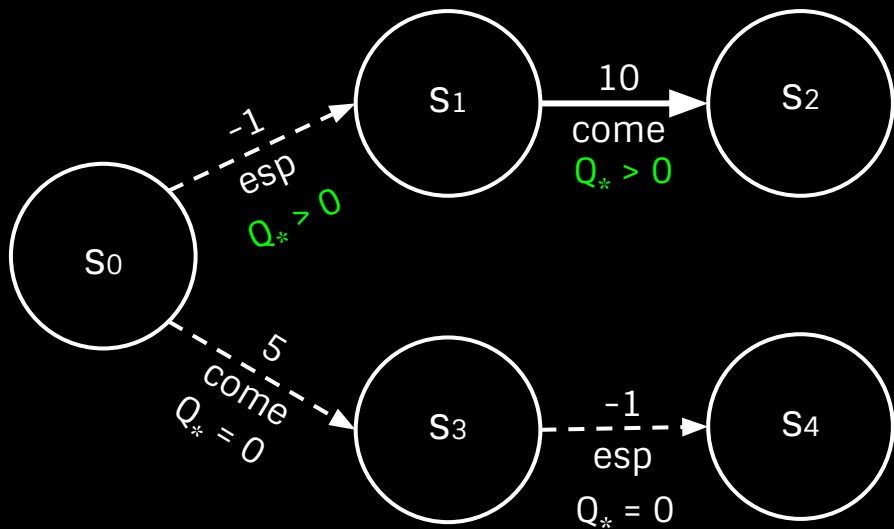
Exemplo



$$Q_*(s, a) \leftarrow (1 - \alpha) \cdot Q_*(s, a) + \alpha \cdot Q_*^{\text{nov}}(s, a)$$



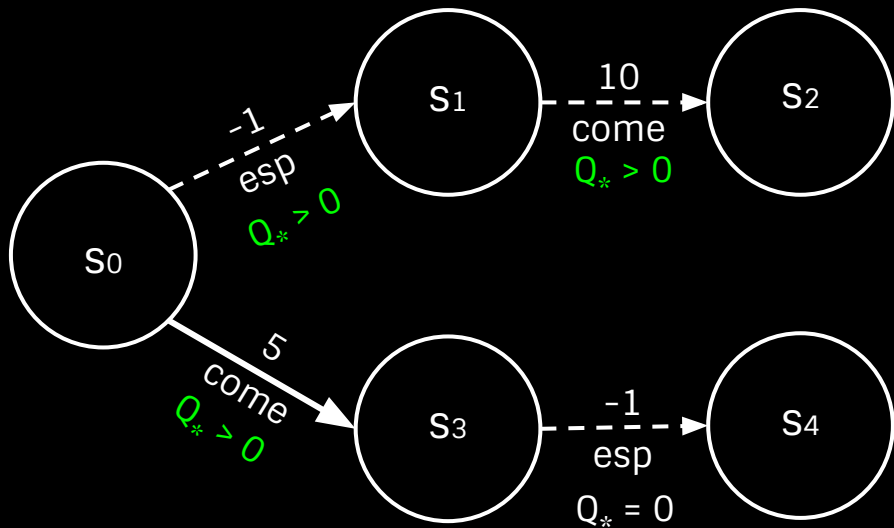
Exemplo



$$Q_*(s, a) \leftarrow (1 - \alpha) \cdot Q_*(s, a) + \alpha \cdot Q_*^{\text{nov}}(s, a)$$



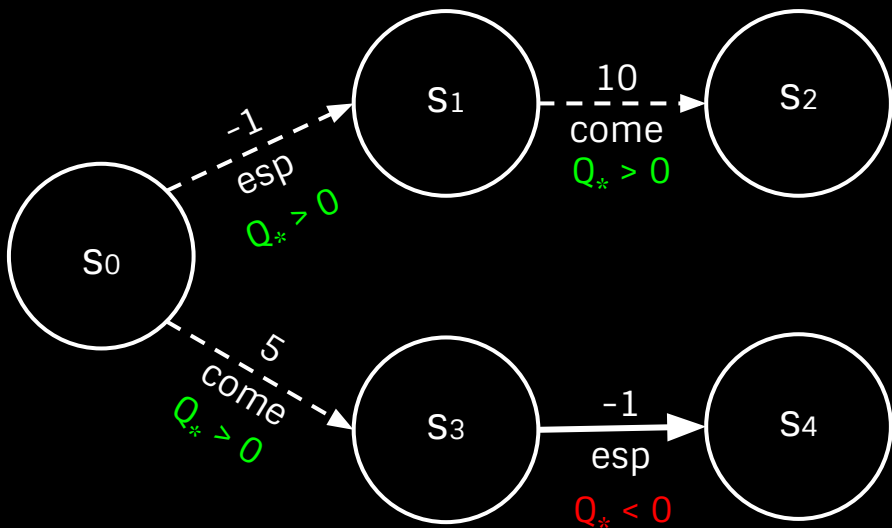
Exemplo



$$Q_*(s, a) \leftarrow (1 - \alpha) \cdot Q_*(s, a) + \alpha \cdot Q_*^{\text{nov}}(s, a)$$



Exemplo



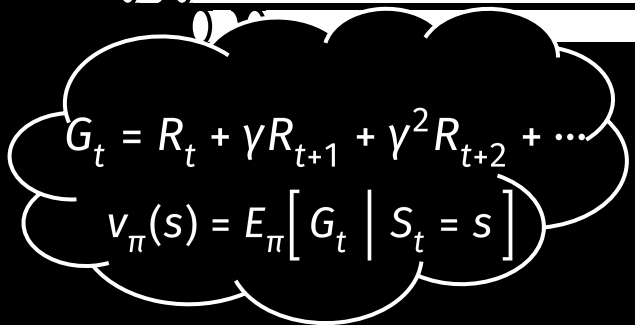
$$Q_*(s, a) \leftarrow (1 - \alpha) \cdot Q_*(s, a) + \alpha \cdot Q_*^{\text{nov}}(s, a)$$



Como estimar os valores Q?

GRUPO
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Equação de Bellman


$$G_t = R_t + \gamma R_{t+1} + \gamma^2 R_{t+2} + \dots$$

$$v_{\pi}(s) = E_{\pi} [G_t \mid S_t = s]$$

$$q_{*}(s, a) = E_{\pi^{*}} [G_t \mid S_t = s, A_t = a]$$

$$= E_{\pi^{*}} [R_t + \gamma R_{t+1} + \gamma^2 R_{t+2} + \dots \mid S_t = s, A_t = a]$$
 Retorno no instante t

$$= E_{\pi^{*}} [R_t + \gamma (R_{t+1} + \gamma R_{t+2} + \dots) \mid S_t = s, A_t = a]$$
 Isolando o γ

$$= E_{\pi^{*}} [R_t + \gamma G_{t+1} \mid S_t = s, A_t = a]$$
 Retorno no instante t+1

$$= E_{\pi^{*}} [R_t + \gamma v_{*}(S_{t+1}) \mid S_t = s, A_t = a]$$
 Tomando o valor médio de G_{t+1}

$$= E_{\pi^{*}} [R_t + \gamma \max_{a'} q_{*}(S_{t+1}, a') \mid S_t = s, A_t = a]$$
 Como o agente sempre toma a melhor ação

Bootstrapping

Como calcular essa média?

$$q_*(s, a) = E_{\pi^*} \left[R_t + \gamma \max_{a'} q_*(S_{t+1}, a') \mid S_t = s, A_t = a \right]$$

Uma estimativa bem grosseira:
podemos considerar apenas um episódio

$$Q_{\text{bootstrap}}(s, a) = \underbrace{r}_{\text{recompensa}} + \underbrace{\gamma}_{\text{fator de desconto}} \cdot \underbrace{\max_{a'} Q_*(s', a')}_{\text{estimativa do valor futuro \u00f3timo}}$$

Aplicação das conclusões: Q-learning

GRUPO
TURING

Q-Learning

Bootstrap gera estimativas ruins,
que variam muito

$$Q_{\text{bootstrap}}(s, a) = \underbrace{r}_{\text{recompensa}} + \underbrace{\gamma}_{\text{fator de desconto}} \cdot \underbrace{\max_{a'} Q_*(s', a')}_{\text{estimativa do valor futuro \u00f3timo}}$$

Podemos “estabilizar” esses valores usando uma m\u00e9dia ponderada:

$$Q_*(s, a) \leftarrow (1 - \alpha) \cdot Q_*(s, a) + \alpha \cdot Q_{\text{bootstrap}}(s, a)$$

$$Q_*(s, a) \leftarrow (1 - \alpha) \cdot \underbrace{Q_*(s, a)}_{\text{valor antigo}} + \underbrace{\alpha}_{\text{taxa de aprendizado}} \cdot \underbrace{\left(r + \gamma \max_{a'} Q_*(s', a') \right)}_{Q_{\text{bootstrap}}(s, a)}$$

Q-Learning

$$Q_*(s, a) \leftarrow (1 - \alpha) \cdot Q_*(s, a) + \alpha \cdot Q_{\text{bootstrap}}(s, a)$$

$$Q_*(s, a) \leftarrow \underbrace{(1 - \alpha) \cdot Q_*(s, a)}_{\text{valor antigo}} + \underbrace{\alpha}_{\text{taxa de aprendizado}} \cdot \underbrace{\left(r + \gamma \max_{a'} Q_*(s', a') \right)}_{Q_{\text{bootstrap}}(s, a)}$$

média ponderada

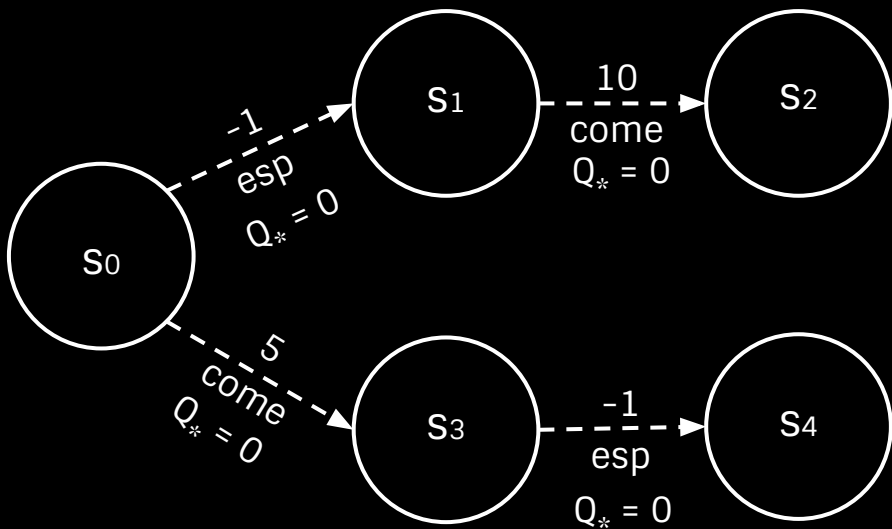
$$Q_*(s, a) \leftarrow \underbrace{Q_*(s, a)}_{\text{valor antigo}} + \underbrace{\alpha}_{\text{taxa de aprendizado}} \cdot \overbrace{\left(\underbrace{r + \gamma \max_{a'} Q_*(s', a')}_{Q_{\text{bootstrap}}(s, a)} - Q_*(s, a) \right)}^{\text{erro}}$$

minimização do erro

Exemplo

$$\alpha = 0.5$$

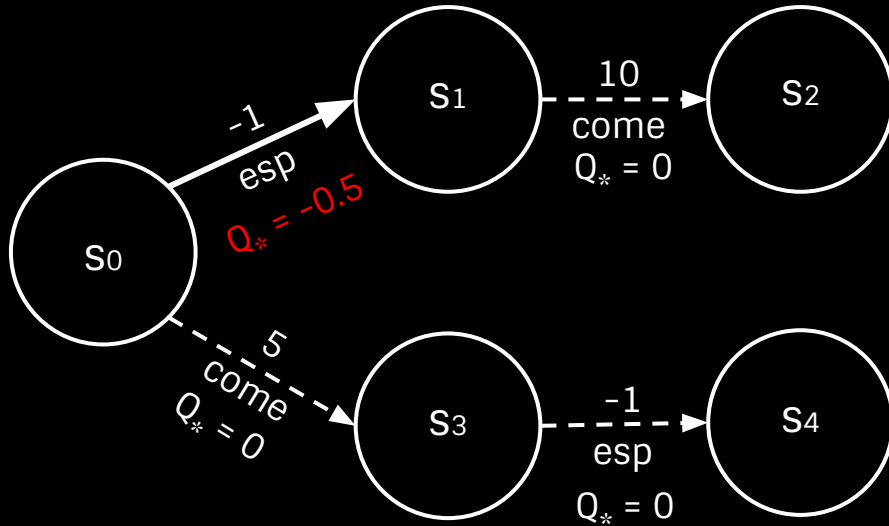
$$\gamma = 0.9$$



Exemplo (ep. 1)

$$\alpha = 0.5$$

$$\gamma = 0.9$$



$$Q_{boot}(s_0, esp) = r + \gamma \max_{a'} Q_*(s_1, a') = -1 + 0.9 \cdot 0 = -1$$

$$Q_*(s_0, esp) \leftarrow (1 - \alpha) \cdot Q_*(s_0, esp) + \alpha \cdot Q_{boot}(s_0, esp)$$

$$Q_*(s_0, esp) \leftarrow 0.5 \cdot 0 + 0.5 \cdot (-1)$$

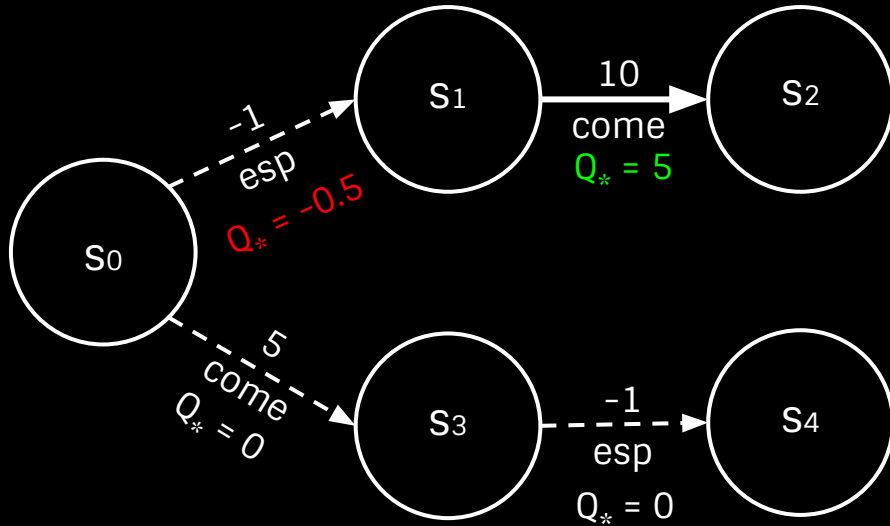
$$Q_*(s_0, esp) \leftarrow -0.5$$



Exemplo (ep. 1)

$$\alpha = 0.5$$

$$\gamma = 0.9$$



$$Q_{\text{boot}}(s_0, \text{esp}) = r + \gamma \max_{a'} Q_*(s_1, a') = -1 + 0.9 \cdot 0 = -1$$

$$Q_*(s_0, \text{esp}) \leftarrow (1 - \alpha) \cdot Q_*(s_0, \text{esp}) + \alpha \cdot Q_{\text{boot}}(s_0, \text{esp})$$

$$Q_*(s_0, \text{esp}) \leftarrow 0.5 \cdot 0 + 0.5 \cdot (-1)$$

$$Q_*(s_0, \text{esp}) \leftarrow -0.5$$

$$Q_{\text{boot}}(s_1, \text{come}) = r + \gamma \max_{a'} Q_*(s_2, a') = 10 + 0.9 \cdot 0 = 10$$

$$Q_*(s_1, \text{come}) \leftarrow (1 - \alpha) \cdot Q_*(s_1, \text{come}) + \alpha \cdot Q_{\text{boot}}(s_1, \text{come})$$

$$Q_*(s_1, \text{come}) \leftarrow 0.5 \cdot 0 + 0.5 \cdot 10$$

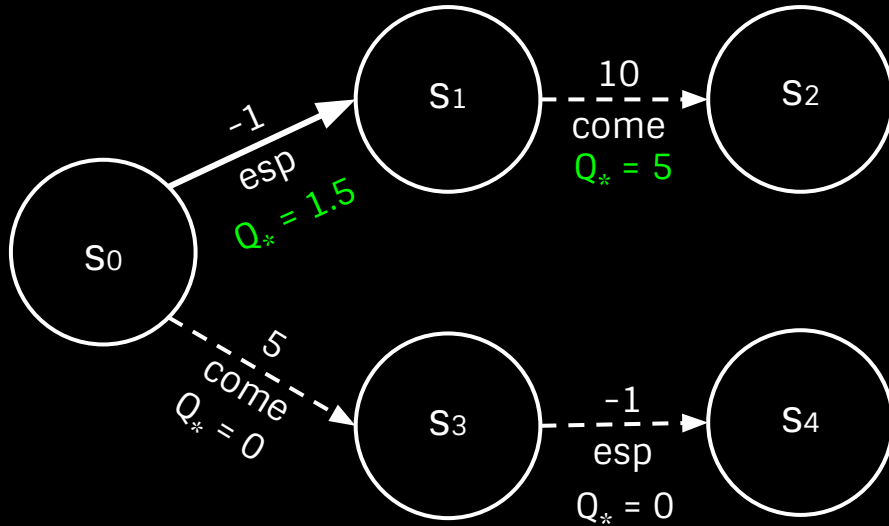
$$Q_*(s_1, \text{come}) \leftarrow 5$$



Exemplo (ep. 2)

$$\alpha = 0.5$$

$$\gamma = 0.9$$



$$Q_{\text{boot}}(s_0, \text{esp}) = r + \gamma \max_{a'} Q_*(s_1, a') = -1 + 0.9 \cdot 5 = 3.5$$

$$Q_*(s_0, \text{esp}) \leftarrow (1 - \alpha) \cdot Q_*(s_0, \text{esp}) + \alpha \cdot Q_{\text{boot}}(s_0, \text{esp})$$

$$Q_*(s_0, \text{esp}) \leftarrow 0.5 \cdot (-0.5) + 0.5 \cdot 3.5$$

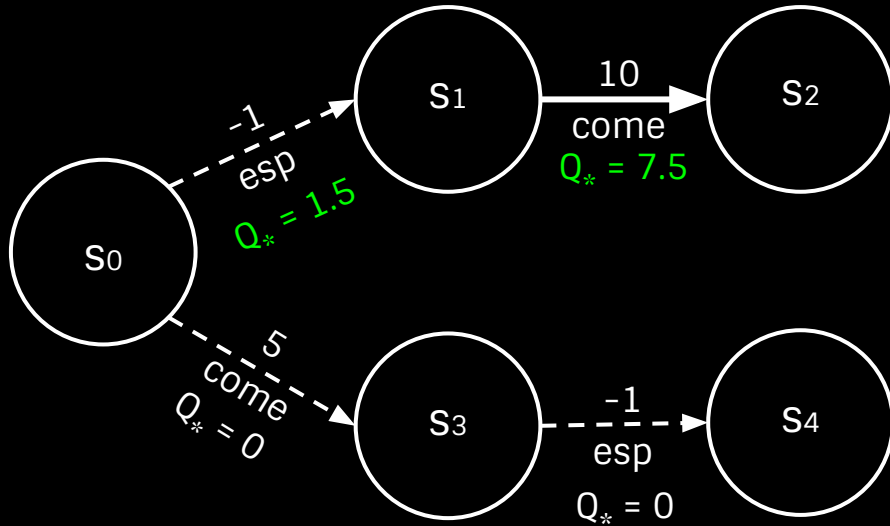
$$Q_*(s_0, \text{esp}) \leftarrow 1.5$$



Exemplo (ep. 2)

$$\alpha = 0.5$$

$$\gamma = 0.9$$



$$Q_{\text{boot}}(s_0, \text{esp}) = r + \gamma \max_{a'} Q_*(s_1, a') = -1 + 0.9 \cdot 5 = 3.5$$

$$Q_*(s_0, \text{esp}) \leftarrow (1 - \alpha) \cdot Q_*(s_0, \text{esp}) + \alpha \cdot Q_{\text{boot}}(s_0, \text{esp})$$

$$Q_*(s_0, \text{esp}) \leftarrow 0.5 \cdot (-0.5) + 0.5 \cdot 3.5$$

$$Q_*(s_0, \text{esp}) \leftarrow 1.5$$

$$Q_{\text{boot}}(s_1, \text{come}) = r + \gamma \max_{a'} Q_*(s_2, a') = 10 + 0.9 \cdot 0 = 10$$

$$Q_*(s_1, \text{come}) \leftarrow (1 - \alpha) \cdot Q_*(s_1, \text{come}) + \alpha \cdot Q_{\text{boot}}(s_1, \text{come})$$

$$Q_*(s_1, \text{come}) \leftarrow 0.5 \cdot 5 + 0.5 \cdot 10$$

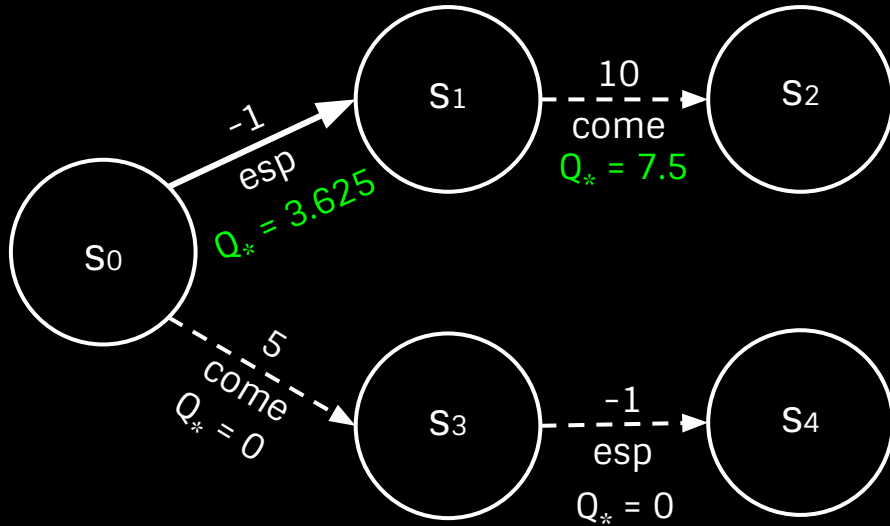
$$Q_*(s_1, \text{come}) \leftarrow 7.5$$



Exemplo (ep. 3)

$$\alpha = 0.5$$

$$\gamma = 0.9$$



$$Q_{boot}(s_0, esp) = r + \gamma \max_{a'} Q_*(s_1, a') = -1 + 0.9 \cdot 7.5 = 5.75$$

$$Q_*(s_0, esp) \leftarrow (1 - \alpha) \cdot Q_*(s_0, esp) + \alpha \cdot Q_{boot}(s_0, esp)$$

$$Q_*(s_0, esp) \leftarrow 0.5 \cdot 1.5 + 0.5 \cdot 5.75$$

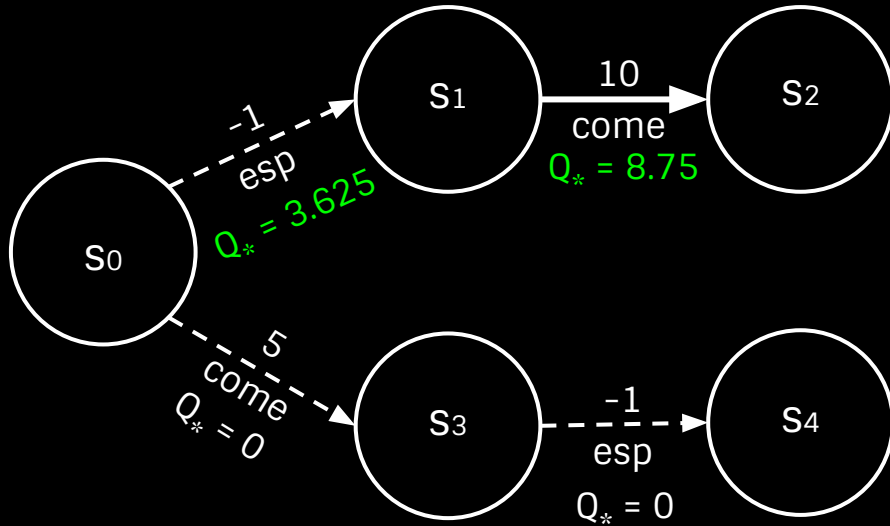
$$Q_*(s_0, esp) \leftarrow 3.625$$



Exemplo (ep. 3)

$$\alpha = 0.5$$

$$\gamma = 0.9$$



$$Q_{\text{boot}}(s_0, \text{esp}) = r + \gamma \max_{a'} Q_*(s_1, a') = -1 + 0.9 \cdot 7.5 = 5.75$$

$$Q_*(s_0, \text{esp}) \leftarrow (1 - \alpha) \cdot Q_*(s_0, \text{esp}) + \alpha \cdot Q_{\text{boot}}(s_0, \text{esp})$$

$$Q_*(s_0, \text{esp}) \leftarrow 0.5 \cdot 1.5 + 0.5 \cdot 5.75$$

$$Q_*(s_0, \text{esp}) \leftarrow 3.625$$

$$Q_{\text{boot}}(s_1, \text{come}) = r + \gamma \max_{a'} Q_*(s_2, a') = 10 + 0.9 \cdot 0 = 10$$

$$Q_*(s_1, \text{come}) \leftarrow (1 - \alpha) \cdot Q_*(s_1, \text{come}) + \alpha \cdot Q_{\text{boot}}(s_1, \text{come})$$

$$Q_*(s_1, \text{come}) \leftarrow 0.5 \cdot 7.5 + 0.5 \cdot 10$$

$$Q_*(s_1, \text{come}) \leftarrow 8.75$$



Q-Learning Tabular

Q-learning funciona armazenando as estimativas dos Q-valores numa tabela.

As estimativas da tabela são atualizadas através da já mencionada equação de Bellman.

Q	a0	a1	a2
s0	1	15	2
s1	24	5	16
s2	10	62	-7
s3	10	15	35

Algoritmo de Q-Learning



Parâmetros: parâmetros $\alpha, \gamma \in (0, 1]$, ε pequeno > 0 .

Inicialize $Q(s, a)$, arbitrariamente, para todo s, a , exceto quando $Q(\text{terminal}, \cdot) = 0$

Loop para cada episódio:

 Inicialize S

 Loop para cada instante do episódio:

 Escolha A usando uma política derivada de Q (e.g, ε -gulosa)

 Tome a ação A , observe R, S'

$Q(S, A) \leftarrow Q(S, A) + \alpha [R + \gamma \max_{a'} Q(S', a') - Q(S, A)]$

$S \leftarrow S'$

 até que S seja o estado terminal



Recursos



Turing Talks: textos desde o básico de RL até algoritmos mais avançados

Curso:

- Reinforcement Learning (Coursera)

Livro:

- Reinforcement Learning: An Introduction (Sutton, Barto)

