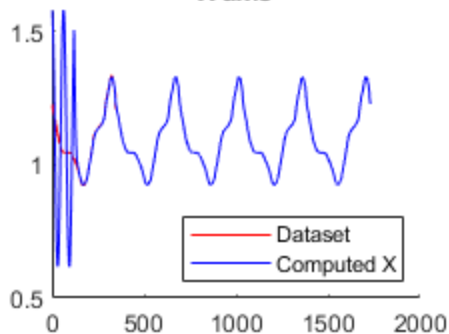
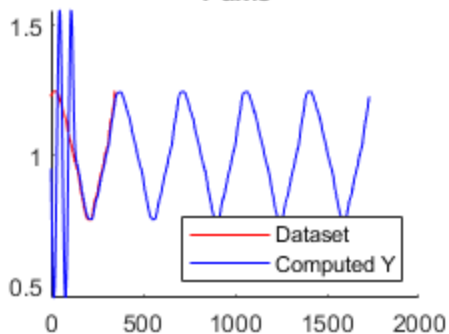


X axis**Y axis****Robot movement**