

Advanced Discretization Techniques

Homework 5

Bruno Degli Esposti, Xingyu Xu

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Exercise 11: A trace estimate using the Raviart-Thomas element RT_0

- a) For any $i \in \{1, 2, 3\}$ and any $x \in e_j \neq e_i$, we know that the vector $x - x_i$ is parallel to the side e_j , so

$$\frac{|e_i|}{2|K|}(x - x_i) \cdot \nu(x) = 0$$

by the definition of normal $\nu(x)$. Otherwise, if $x \in e_i$, we get that $(x - x_i) \cdot \nu(x) = h_i$, where h_i is the height of the triangle K with respect to the base e_i . It then follows by the formula for the area of a triangle that

$$\frac{|e_i|}{2|K|}(x - x_i) \cdot \nu(x) = \frac{1}{|K|} \frac{|e_i| h_i}{2} = 1,$$

as was required. This proves that $\tau_i(x) \cdot \nu(x) = \chi_{e_i}(x)$ for all $x \in \partial K$. Moving on to the second part of the proof, $\dim(\text{RT}_0(K)) = 1(1+2) = 3$, so we only need to prove that the functions τ_i are linearly independent. For this purpose, let $\alpha_1, \alpha_2, \alpha_3 \in \mathbb{R}$ be such that $\alpha_1 \tau_1(x) + \alpha_2 \tau_2(x) + \alpha_3 \tau_3(x) = 0$. If we now take the scalar product with respect to $\nu(x)$, we get that

$$\begin{aligned} 0 &= \alpha_1 \tau_1(x) \cdot \nu(x) + \alpha_2 \tau_2(x) \cdot \nu(x) + \alpha_3 \tau_3(x) \cdot \nu(x) \\ &= \alpha_1 \chi_{e_1}(x) + \alpha_2 \chi_{e_2}(x) + \alpha_3 \chi_{e_3}(x). \end{aligned}$$

By evaluating this identity in $x \in e_i$, we can conclude that $\alpha_i = 0$ for all $i \in \{1, 2, 3\}$. Hence $\{\tau_1, \tau_2, \tau_3\}$ forms a basis of $\text{RT}_0(K)$.

- b) We can get the required estimate by using the formula $\tau_i(x) \cdot \nu(x) = \chi_{e_i}(x)$ of point a), the divergence theorem and the Cauchy-Schwarz inequality:

$$\begin{aligned} \|u\|_{0,e_i}^2 &= \int_{e_i} u(x)^2 d\sigma = \int_{\partial K} u(x)^2 \chi_{e_i}(x) d\sigma \\ &= \int_{\partial K} u(x)^2 \tau_i(x) \cdot \nu(x) d\sigma = \int_K \nabla \cdot (u(x)^2 \tau_i(x)) dx \\ &= \int_K 2u(x) \nabla u(x) \cdot \tau_i(x) dx + \int_K u(x)^2 \nabla \cdot \tau_i(x) dx \\ &\leq 2\|u\|_{0,K} \|\nabla u\|_{0,K} \|\tau_i\|_{L^\infty} + \|\nabla \cdot \tau_i\|_{L^\infty(K)} \|u\|_{0,K}^2. \end{aligned}$$

c) The constant h is equal to the diameter of K . Therefore

$$\|\tau_i\|_{L^\infty(K)} = \operatorname{ess\,sup}_{x \in \partial K} \left\{ \frac{|e_i|}{2|K|} \|x - x_i\| \right\} \leq \frac{h}{2|K|} h \leq \frac{c}{2}.$$

Since K is a subset of \mathbb{R}^2 , we have that $\nabla \cdot x = 2$. Hence

$$\|\nabla \cdot \tau_i\|_{L^\infty(K)} = \operatorname{ess\,sup}_{x \in \partial K} \left\{ \frac{|e_i|}{2|K|} |\nabla \cdot (x - x_i)| \right\} = \frac{|e_i|}{2|K|} 2 \leq \frac{h}{|K|} \leq \frac{c}{h}.$$

d) By the inequalities we have proved in points b) and c), we have that

$$\|u\|_{0,e_i}^2 \leq \frac{c}{h} \|u\|_{0,K}^2 + c \|u\|_{0,K} \|\nabla u\|_{0,K}.$$

Then, since c and h are both positive constants,

$$\begin{aligned} \|u\|_{0,e_i}^2 &\leq \frac{c}{h} \|u\|_{0,K}^2 + 2c \|u\|_{0,K} \|\nabla u\|_{0,K} + ch \|\nabla u\|_{0,K}^2 \\ &= \left((c^{1/2} h^{-1/2} \|u\|_{0,K} + c^{1/2} h^{1/2} \|\nabla u\|_{0,K}) \right)^2. \end{aligned}$$

The result follows by taking the square root on both sides and making the choice $C = c^{1/2}$. \square

Exercise 12: Poisson's problem with \mathbf{RT}_0 - \mathcal{L}_0^0

Let $\lambda_1(x), \lambda_2(x), \lambda_3(x)$ be the barycentric coordinate maps for the triangle K , so that for each $x \in \mathbb{R}^2$ we have that

$$x = \sum_{i=1}^3 \lambda_i(x) x_i \quad \text{and} \quad \sum_{i=1}^3 \lambda_i(x) = 1.$$

We begin by proving the identity given as a hint. Let \hat{K} be the reference triangle in \mathbb{R}^2 , as defined in Chapter 2 of [K,A]. For any $i, j \in \{1, 2, 3\}$, let $F: \hat{K} \rightarrow K$ be an affine and bijective mapping such that $F(1, 0) = x_i$ and, if $j \neq i$, $F(0, 1) = x_j$. By the change of variables formula, it follows that

$$\int_K \lambda_i(\mathbf{x}) \lambda_j(\mathbf{x}) d\mathbf{x} = \int_{\hat{K}} \lambda_i(F(x, y)) \lambda_j(F(x, y)) |\det(dF(x, y))| dx dy.$$

By the choice of F , and the fact that $\lambda_i \circ F$ is still an affine map, it's easy to see that $\lambda_i(F(x, y)) = x$ and, if $j \neq i$, $\lambda_j(F(x, y)) = y$. Moreover, dF is a constant matrix such that $|\det(dF)| = 2|K|$. If $i = j$, we get that

$$\begin{aligned} \int_K \lambda_i(\mathbf{x}) \lambda_j(\mathbf{x}) d\mathbf{x} &= 2|K| \int_{\hat{K}} x^2 dx dy = 2|K| \int_0^1 \int_0^{1-x} x^2 dy dx \\ &= 2|K| \int_0^1 x^2 - x^3 dx = 2|K| \left(\frac{1}{3} - \frac{1}{4} \right) = \frac{|K|}{12} (1 + \delta_{ij}), \end{aligned}$$

as was required. If $i \neq j$, we still get that

$$\begin{aligned}
\int_K \lambda_i(\mathbf{x}) \lambda_j(\mathbf{x}) d\mathbf{x} &= 2|K| \int_{\tilde{K}} xy dx dy = 2|K| \int_0^1 \int_0^{1-x} xy dy dx \\
&= 2|K| \int_0^1 \frac{1}{2} x(1-x)^2 dx = |K| \int_0^1 x - 2x^2 + x^3 dx \\
&= |K| \left(\frac{1}{2} - \frac{2}{3} + \frac{1}{4} \right) = |K| \left(\frac{6-8+3}{12} \right) = \frac{|K|}{12} (1 + \delta_{ij}),
\end{aligned}$$

so the identity in the hint has been proved for all $i, j \in \{1, 2, 3\}$. Moving on to the central part of the proof,

$$\begin{aligned}
(\tau_{h,e_i}, \tau_{h,e_j})_K &= \int_K \langle \tau_{h,e_i}(x), \tau_{h,e_j}(x) \rangle dx \\
&= \int_K \sigma_i \sigma_j \frac{|e_i| |e_j|}{4|K|^2} \langle x - x_i, x - x_j \rangle dx.
\end{aligned}$$

Let c be the constant in the last integral. We can introduce barycentric coordinates to get that

$$\begin{aligned}
\int_K c \langle x - x_i, x - x_j \rangle dx &= c \int_K \left\langle \sum_{s=1}^3 \lambda_s(x)(x_s - x_i), \sum_{r=1}^3 \lambda_r(x)(x_r - x_j) \right\rangle dx \\
&= c \sum_{s,r=1}^3 \langle x_s - x_i, x_r - x_j \rangle \int_K \lambda_s(x) \lambda_r(x) dx \\
&= c \sum_{s,r=1}^3 \langle x_s - x_i, x_r - x_j \rangle \frac{|K|}{12} (1 + \delta_{sr}).
\end{aligned}$$

Let x_c be the barycenter of K . Then we can further simplify the sum:

$$\begin{aligned}
(\tau_{h,e_i}, \tau_{h,e_j})_K &= \frac{c|K|}{12} \left(\sum_{s,r=1}^3 \langle x_s - x_i, x_r - x_j \rangle + \sum_{s=1}^3 \langle x_s - x_i, x_s - x_j \rangle \right) \\
&= \frac{c|K|}{12} \left(\left\langle \sum_{s=1}^3 (x_s - x_i), \sum_{r=1}^3 (x_r - x_j) \right\rangle + \sum_{s=1}^3 \langle x_s - x_i, x_s - x_j \rangle \right) \\
&= \frac{c|K|}{12} \left(9 \langle x_c - x_i, x_c - x_j \rangle + \sum_{s=1}^3 \langle x_s - x_i, x_s - x_j \rangle \right) \\
&= \sigma_i \sigma_j \frac{|e_i| |e_j|}{48|K|} \left(9 \langle x_c - x_i, x_c - x_j \rangle + \sum_{s=1}^3 \langle x_s - x_i, x_s - x_j \rangle \right).
\end{aligned}$$

As for the last part of the proof, we compute that

$$\begin{aligned}
(v_{h,K}, \nabla \cdot \tau_{h,e_i})_K &= \int_K v_{h,K}(x) \nabla \cdot \tau_{h,e_i}(x) dx = \int_K \sigma_i \frac{|e_i|}{2|K|} \nabla \cdot (x - x_i) dx \\
&= \int_K \sigma_i \frac{|e_i|}{2|K|} 2 dx = \sigma_i \frac{|e_i|}{|K|} \int_K 1 dx = \sigma_i |e_i|. \quad \square
\end{aligned}$$