## Advanced Discretization Techniques Homework 7

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## Exercise 15: Uzawa algorithm - a proof of convergence

a) The saddle point problem can be written in the following operator form:

$$Au + B^*p = f$$
$$Bu = g.$$

A is invertible, because it's positive definite (by assumption). Hence, we can multiply the first equation by  $BA^{-1}$  and substitute g for Bu to get that

$$Bu + BA^{-1}B^*p = BA^{-1}f$$
$$g + BA^{-1}B^*p = BA^{-1}f$$
$$Sp = BA^{-1}f - g.$$

b) Given a linear system Lx=r, the  $\omega$ -relaxated Richardson method is defined as the following iterative scheme:

$$x^{k+1} = x^k + \omega(r - Lx^k).$$

Uzawa's algorithm can be written in this form by substituting line 4 into line 6 (and eliminating  $u^{k+1}$  in the process):

$$\begin{split} p^{k+1} - p^k &= \omega(Bu^{k+1} - g) \\ &= \omega(B(A^{-1}f - A^{-1}B^*p^k) - g) \\ &= \omega(BA^{-1}f - g - BA^{-1}B^*p^k) \\ &= \omega(BA^{-1}f - g - Sp^k), \end{split}$$

As required, L = S and  $r = BA^{-1}f - q$ .

c) By the spectral theorem,  $A^{1/2}$  is a well-defined, real, s.p.d. operator. Then

$$\begin{split} \|v\|_A &= \langle Av, v \rangle_{H^1}^{1/2} = \left\langle A^{1/2}A^{1/2}v, v \right\rangle^{1/2} = \left\langle A^{1/2}v, A^{1/2}v \right\rangle^{1/2} = \left\|A^{1/2}v\right\|_1 \\ \|p\|_S &= \langle Sp, p \rangle_{L^2}^{1/2} = \left\langle BA^{-1}B^*p, p \right\rangle_{L^2}^{1/2} = \left\langle A^{-1/2}B^*p, A^{-1/2}B^*p \right\rangle_{H^1}^{1/2} = \left\|A^{-1/2}B^*p \right\|_1 \\ & \left\langle Bv, p \right\rangle_{L^2} = \left\langle BA^{-1/2}A^{1/2}v, p \right\rangle_{L^2} = \left\langle A^{1/2}v, A^{-1/2}B^*p \right\rangle_{H^1}. \end{split}$$

By the Cauchy-Schwarz inequality, it follows that

$$\sup_{v\in M_h}\frac{\left\langle Bv,p\right\rangle}{\left\|v\right\|_A}=\sup_{v\in M_h}\frac{\left\langle A^{1/2}v,A^{-1/2}B^*p\right\rangle}{\left\|A^{1/2}v\right\|_1}\leq \left\|A^{-1/2}B^*p\right\|_1=\left\|p\right\|_S,$$

and this inequality can be turned into an equality by choosing  $v \in M_h$  in the sup as  $A^{-1}B^*p$ , so that  $A^{1/2}v = A^{-1/2}B^*p$ .

d) In the Stokes case,

$$a(u,v) = \int_{\Omega} Du : Dv dx$$
  $b(v,q) = -\int_{\Omega} q \operatorname{div}(v) dx$ .

Let R(q) be the Rayleigh quotient associated with S:

$$R(q) = \frac{\langle Sq, q \rangle}{\langle q, q \rangle}.$$

Since S is s.p.d., it follows from the min-max theorem that

$$\lambda_{\min}(S) = \inf_{0 \neq q \in X_h} R(q)$$
 and  $\lambda_{\max}(S) = \sup_{0 \neq q \in X_h} R(q)$ .

If we now combine the result from point c) with the inf-sup condition, we get that

$$\lambda_{\min}(S) = \inf_{0 \neq q \in X_h} \frac{\langle Sq, q \rangle}{\langle q, q \rangle} = \inf_{0 \neq q \in X_h} \frac{\|q\|_S^2}{\|q\|_0^2} = \inf_{q} \sup_{v} \frac{\langle Bv, q \rangle^2}{\|v\|_A^2 \|q\|_0^2}$$
$$= \inf_{q} \sup_{v} \frac{\langle Bv, q \rangle^2}{a(v, v) \|q\|_0^2} = \inf_{q} \sup_{v} \frac{\langle Bv, q \rangle^2}{|v|_1^2 \|q\|_0^2} = \beta^2,$$

so the first half of the proof is complete. For the second half, we first need

to show that  $\|\text{div}(v)\|_{0}^{2} \leq \|v\|_{A}^{2}$ :

$$\begin{aligned} \|\operatorname{div}(v)\|_{0}^{2} &= \int_{\Omega} \left( \sum_{i=1}^{d} \partial_{i} v_{i}(x) \right)^{2} dx = \int_{\Omega} \sum_{i,j=1}^{d} \partial_{i} v_{i}(x) \partial_{j} v_{j}(x) dx \\ &= 0 + 0 + \int_{\Omega} \sum_{i,j=1}^{d} \partial_{j} v_{i}(x) \partial_{i} v_{j}(x) dx \\ &= \int_{\Omega} \sum_{i=1}^{d} (\partial_{i} v_{i}(x))^{2} dx + \int_{\Omega} \sum_{1 \leq i < j \leq d} 2 \partial_{j} v_{i}(x) \partial_{i} v_{j}(x) dx \\ &\leq \int_{\Omega} \sum_{i=1}^{d} (\partial_{i} v_{i}(x))^{2} dx + \int_{\Omega} \sum_{1 \leq i < j \leq d} (\partial_{j} v_{i}(x))^{2} + (\partial_{i} v_{j}(x))^{2} dx \\ &= \int_{\Omega} \sum_{i,j=1}^{d} (\partial_{i} v_{j}(x))^{2} dx = a(v,v) = \|v\|_{A}^{2}. \end{aligned}$$

We have used integration by parts twice (and, implicity, a density argument with  $C_0^{\infty}(\Omega)$  functions), symmetry of second derivatives and the inequality  $2ab \leq a^2 + b^2$ . We can now conclude the second part of the proof:

$$\lambda_{\max}(S) = \sup_{0 \neq q \in X_h} \frac{\langle Sq, q \rangle}{\langle q, q \rangle} = \sup_{q} \sup_{v} \frac{b(v, q)^2}{\|v\|_A^2 \|q\|_0^2}$$

$$= \sup_{q} \sup_{v} \frac{\left(\int_{\Omega} q \operatorname{div}(v) dx\right)^2}{\|v\|_A^2 \|q\|_0^2} \le \sup_{q} \sup_{v} \frac{\left(\int_{\Omega} q^2 dx\right) \left(\int_{\Omega} \operatorname{div}(v)^2 dx\right)}{\|v\|_A^2 \|q\|_0^2}$$

$$= \sup_{q} \sup_{v} \frac{\|q\|_0^2 \|\operatorname{div}(v)\|_0^2}{\|v\|_A^2 \|q\|_0^2} \le \sup_{0 \neq v \in M_h} \frac{\|v\|_A^2}{\|v\|_A^2} = 1.$$

e) By induction on the error estimate for Richardson's method, we get that

$$||p-p^k||_0 \le (\rho(I-S))^k ||p-p^0||_0$$
.

In point 4) we have shown that  $\sigma(S) \subseteq [\beta^2, 1]$ , so  $\sigma(I - S) \subseteq [0, 1 - \beta^2]$  and  $\rho(I - S) \le 1 - \beta^2$ . This is enough to prove the first error estimate for Uzawa's algorithm. To prove the second one, consider the first equation of the saddle point problem and line 4 in the algorithm:

$$Au + B^*p = f$$
  $Au^{k+1} + B^*p^k = f.$ 

Subtracting one equation from the other gives

$$A(u - u^{k+1}) + B^*(p - p^k) = 0.$$

from which we can deduce that

$$\begin{split} \left| u - u^{k+1} \right|_1^2 &= \left\| u - u^{k+1} \right\|_A^2 = \left\langle A(u - u^{k+1}), u - u^{k+1} \right\rangle_{H^1} \\ &= \left\langle -B^*(p - p^k), -A^{-1}B^*(p - p^k) \right\rangle_{H^1} \\ &= \left\langle S(p - p^k), p - p^k \right\rangle_{L^2} \leq \left\| S(p - p^k) \right\|_0 \left\| p - p^k \right\|_0^2 \\ &\leq \left\| S \right\|_2 \left\| p - p^k \right\|_0^2 \leq \rho(S) \left\| p - p^k \right\|_0^2 \leq (1 - \beta^2)^{2k} \left\| p - p^0 \right\|_0^2. \end{split}$$

Now we just have to take the square root of both sides.  $\square$ 

## Exercise 16: Voronoi diagrams

a) Let  $S_{ij} = \{x \in \mathbb{R}^2 \mid |x - a_i| < |x - a_j|\}$ , so that  $\tilde{\Omega}_i = \bigcap_{j \neq i} S_{ij}$ . Geometric intuition suggests that the sets  $S_{ij}$  are open half-planes, and that their boundaries  $\partial S_{ij}$  are perpendicular bisectors of the line segments  $a_i a_j$ . To show that this is really the case, consider the following:

$$x \in S_{ij} \iff |x - a_i| < |x - a_j| \iff |x - a_j|^2 - |x - a_i|^2 > 0$$

$$\iff \langle x - a_j, x - a_j \rangle + \langle x - a_i, a_i - x \rangle > 0$$

$$\iff \langle x - a_j, x - a_j \rangle + \langle x - a_i, a_i - x \rangle + \langle x - a_j, a_i - x \rangle + \langle x - a_i, x - a_j \rangle > 0$$

$$\iff \langle x - a_j, x - a_j \rangle + \langle x - a_j, a_i - x \rangle + \langle x - a_i, a_i - x \rangle + \langle x - a_i, x - a_j \rangle > 0$$

$$\iff \langle x - a_j, x - a_j + a_i - x \rangle + \langle x - a_i, a_i - x + x - a_j \rangle > 0$$

$$\iff \langle x - a_j, x - a_j + a_i - x \rangle + \langle x - a_i, a_i - x + x - a_j \rangle > 0$$

$$\iff \langle x - a_j, x - a_j, a_i - a_j \rangle > 0 \iff \langle x - \frac{a_i + a_j}{2}, a_i - a_j \rangle > 0.$$

We can now recognize the definition of open half-plane, the midpoint  $(a_i + a_j)/2$  and the direction  $a_i - a_j$  of the line segment  $a_i a_j$ . This proves that  $\tilde{\Omega}_i$  is convex, because we've expressed  $\tilde{\Omega}_i$  as the intersection of convex sets (the open semiplanes  $S_{ij}$ ). Moreover, the intersection of open half-planes is a (topologically) open polygonal region, so its boundary must be a polygonal chain (allowing half-lines as edges, if  $\tilde{\Omega}_i$  is unbounded).

b) Let  $n = \#(\partial B(p) \cap \mathcal{A})$ . To prove i), let p be a Voronoi vertex. This means that p is a vertex of the boundary of some Voronoi polygon  $\tilde{\Omega}_i$ , so there exist  $j, k \in \bar{\Lambda}$  such that i, j, k are all distinct and  $p \in \partial S_{ij} \cap \partial S_{ik}$ . The point p is therefore the circumcenter of the triangle  $a_i a_j a_k$ , since we have proved in point a) that  $\partial S_{ij}$  and  $\partial S_{ik}$  are the perpendicular bisectors of the sides  $a_i a_j$  and  $a_i a_k$ . As Euclid could confirm, this in turn implies that p has equal distance from all the vertices  $a_i, a_j, a_k$  of the triangle, so  $n \geq 3$  because we know that  $\{a_i, a_j, a_k\} \subseteq \partial B(p) \cap \mathcal{A}$ . To prove the converse, we can follow the same line of reasoning. Let  $n \geq 3$ . Then there exist distinct  $\{a_i, a_j, a_k\}$  in  $\partial B(p) \cap \mathcal{A}$ , and once again p is the circumcenter of the triangle  $a_i a_j a_k$ . This means that  $p \in \partial S_{ij} \cap \partial S_{ik}$ , so p is a Voronoi vertex.

To prove ii), let p be a point on the edge of a Voronoi polygon, say  $\Omega_i$ . We want to prove that n=2. On the one hand, we know that n can't be

greater than 2, otherwise p would be a vertex by i) (we implicitly assume that p is not on the boundary of the edge). On the other hand, we know that  $p \in \partial S_{ij}$  for some  $j \neq i$ , so p must be the midpoint of  $a_i a_j$ . This means that, if  $\partial B(p) \cap \mathcal{A}$  contains  $a_i$  (which it does, by the choice of i), then it must also contain  $a_j$ . So n can only be 2. To prove the converse, let  $p \in \mathbb{R}^2$  such that n = 2. For the sake of contradiction, suppose that p belongs to any of the open sets  $\tilde{\Omega}_i$ . Then  $|p - a_i| < |p - a_j|$  for every  $j \neq i$ , so  $\partial B(p)$  can only contain one point from  $\mathcal{A}$ , namely  $a_i$ . This contradicts the assumption n = 2, so p must be on the boundary of some Voronoi polygon. But p cannot be a vertex, otherwise we would have  $n \geq 3$  by point i). Therefore p can only be on an edge, as required.  $\square$