

Advanced Discretization Techniques

Homework 2

Bruno Degli Esposti

October 29th - November 5th, 2019

Exercise 5: A different kind of element

- a) Let $\{e_1, \dots, e_d\}$ be the canonical basis of \mathbb{R}^d . We will first prove the statement for the case $T = \hat{T}$, where \hat{T} is the convex hull of the points $\{0, e_1, \dots, e_d\}$. The volume of \hat{T} is $1/d!$. The functions

$$v \mapsto \int_T v(y) dy \quad \text{and} \quad v \mapsto \frac{1}{d!} v\left(\frac{1}{d+1}, \dots, \frac{1}{d+1}\right)$$

belong to \mathbb{P}_1^* , so in order to show that they are equal it suffices to check that they agree on a basis of \mathbb{P}_1 . In this proof, we will choose the monomial basis. The case $v(y) = 1$ is trivial. If $v(y) = y_1$, then

$$\int_T v(y) dy = \int_T y_1 dy_1 \dots dy_d = \int_0^1 \left(\int_{L(y_1)} y_1 dy_2 \dots dy_d \right) dy_1 = \int_0^1 y_1 |L(y_1)| dy_1$$

by Fubini's theorem, where

$$L(y_1) = \{y_1\} \times \{(y_2, \dots, y_d) \in \mathbb{R}_+^{d-1} \mid y_2 + \dots + y_d \leq 1 - y_1\}.$$

Now,

$$|L(y_1)| = |(1 - y_1)L(0)| = (1 - y_1)^{d-1} |L(0)| = \frac{(1 - y_1)^{d-1}}{(d-1)!},$$

hence

$$\begin{aligned} \int_0^1 y_1 |L(y_1)| dy_1 &= \frac{1}{(d-1)!} \int_0^1 y_1 (1 - y_1)^{d-1} dy_1 \\ &= 0 - \frac{1}{(d-1)!} \int_0^1 -\frac{(1 - y_1)^d}{d} dy_1 = \frac{1}{(d-1)!} \left[-\frac{(1 - y_1)^{d+1}}{d(d+1)} \right]_0^1 \\ &= \frac{1}{(d+1)!} = \frac{1}{d!} v\left(\frac{1}{d+1}, \dots, \frac{1}{d+1}\right), \end{aligned}$$

as was requested. The cases $v(y) = y_2, \dots, v(y) = y_d$ can be proven in the same way. Now we prove the theorem for a generic T . Let $m: \hat{T} \mapsto T$ be

the affine mapping sending \hat{T} to T . Then

$$\begin{aligned} \int_T v(y) dy &= \int_{\hat{T}} v(m(y)) |\det(J_m)| dy = |\det(J_m)| \int_{\hat{T}} v(m(y)) dy \\ &= d! |T| \frac{1}{d!} v\left(m\left(\frac{1}{d+1}, \dots, \frac{1}{d+1}\right)\right) = |T| v\left(\frac{1}{d+1} \sum_{i=0}^d x_i\right) \end{aligned}$$

- b) The only nontrivial condition to check is that the functions $\{\sigma_0, \dots, \sigma_d\}$ are linearly independent. Let $a_0, \dots, a_d \in \mathbb{R}$ be such that

$$a_0 \sigma_0 + \dots + a_d \sigma_d = 0.$$

We want to show that all a_i are 0. As per the hint, we can evaluate the linear combination in $\theta_i(y) = 1 - d\lambda_i(y) \in \mathbb{P}_1$:

$$\begin{aligned} 0 &= \sum_{j=0}^d a_j \sigma_j(\theta_i) = \sum_{j=0}^d \frac{a_j}{|e_j|} \int_{e_j} \theta_i(y) dy \stackrel{a)}{=} \sum_{j=0}^d \frac{a_j}{|e_j|} |e_j| \theta_i\left(\frac{1}{d} \sum_{k=0, k \neq j}^d x_k\right) \\ &= \sum_{j=0}^d a_j \left(1 - d\lambda_i\left(\frac{1}{d} \sum_{k=0, k \neq j}^d x_k\right)\right) = \sum_{j=0}^d a_j \delta_{ij} = a_i \end{aligned}$$

for all $i = 0, \dots, d$, as required for linear independence.

- c) Let p_1 and p_2 be the restrictions of v_h to T_1 and T_2 , two elements sharing the face e . Let e_c be the centroid of e . Since v_h is piecewise affine, the size of the jump discontinuity $\llbracket v_h \rrbracket$ across e is given by $p_1 - p_2$, and v_h is continuous in e_c if and only if $p_1(e_c) = p_2(e_c)$. Let's prove this equality:

$$\begin{aligned} 0 &= \int_e \llbracket v_h \rrbracket dy = \int_e p_1(y) - p_2(y) dy \\ \int_e p_1(y) dy &= \int_e p_2(y) dy \stackrel{a)}{\Rightarrow} |e| p_1(e_c) = |e| p_2(e_c) \Rightarrow p_1(e_c) = p_2(e_c). \quad \square \end{aligned}$$

Exercise 6: A different kind of elliptic equation

- a) We multiply the equation by a test function $\varphi \in X = H_0^2(\Omega)$, then integrate over Ω , integrate by parts twice and use the fact that both φ and $\nabla \varphi$ vanish on the boundary of the domain:

$$\begin{aligned} \int_{\Omega} \Delta^2 u \varphi dx &= \int_{\Omega} f \varphi dx \\ \int_{\partial\Omega} (\nabla(\Delta u) \cdot \mathbf{n}) \varphi d\sigma - \int_{\Omega} \nabla(\Delta u) \cdot \nabla \varphi dx &= \int_{\Omega} f \varphi dx \\ - \int_{\partial\Omega} \Delta u (\nabla \varphi \cdot \mathbf{n}) d\sigma + \int_{\Omega} \Delta u \Delta \varphi dx &= \int_{\Omega} f \varphi dx \\ \int_{\Omega} \Delta u \Delta \varphi dx &= \int_{\Omega} f \varphi dx. \end{aligned}$$

Let

$$a(u, \varphi) = \int_{\Omega} \Delta u \Delta \varphi \, dx, \quad f(\varphi) = \int_{\Omega} f \varphi \, dx.$$

Then the weak form of the equation is $a(u, \varphi) = f(\varphi)$. In the continuous setting, the problem is:

Find $u \in X$ such that $a(u, \varphi) = f(\varphi)$ holds for every $\varphi \in X$.

The system is not overconstrained because the weak gradient of every function in H_0^2 vanishes on the boundary (has trace 0), so the boundary condition $Du = 0$ is quite natural. Otherwise, by just asking for $u = 0$ we would have to work in $H_0^1(\Omega) \cap H^2(\Omega)$, but then we can't integrate by parts a second time without introducing an unwanted extra term.

- b) The first half of the proof boils down to Schwarz's theorem and integration by parts. Indeed, for each $\varphi \in C_0^\infty(\Omega)$, we have that

$$\begin{aligned} \int_{\Omega} (\Delta \varphi(x))^2 \, dx &= \int_{\Omega} \left(\sum_{i=1}^d \partial_{x_i x_i} \varphi(x) \right)^2 \, dx = \int_{\Omega} \sum_{i,j=1,\dots,d} \partial_{x_i x_i} \varphi(x) \partial_{x_j x_j} \varphi(x) \, dx \\ &= \int_{\Omega} \sum_{i,j=1,\dots,d} \partial_{x_i} \varphi(x) \partial_{x_j x_j x_i} \varphi(x) \, dx = \int_{\Omega} \sum_{i,j=1,\dots,d} \partial_{x_i} \varphi(x) \partial_{x_i x_j x_j} \varphi(x) \, dx \\ &= \int_{\Omega} \sum_{i,j=1,\dots,d} \partial_{x_i x_j} \varphi(x) \partial_{x_i x_j} \varphi(x) \, dx = \int_{\Omega} \sum_{|\alpha|=2} (\partial_{x^\alpha} \varphi(x))^2 \, dx = |\varphi|_2^2. \end{aligned}$$

The second half of the proof follows by the density of $\varphi \in C_0^\infty(\Omega)$ in $H_0^2(\Omega)$ and the continuity of the two functionals, which is readily checked:

$$\begin{aligned} \int_{\Omega} (\Delta \varphi(x))^2 \, dx &= \int_{\Omega} \left(\sum_{i=1}^d \partial_{x_i x_i} \varphi(x) \right)^2 \, dx \\ &\leq d \int_{\Omega} \sum_{i=1}^d (\partial_{x_i x_i} \varphi(x))^2 \, dx \leq d |\varphi|_2^2 \leq d \|\varphi\|_2^2. \end{aligned}$$

The first inequality is just the usual AM-QM inequality.

- c) We derive the following inequality, which will be useful in point d):

$$\exists C > 0 \text{ such that } |u|_2^2 \geq C \|u\|_2^2 \text{ for each } u \in H_0^2(\Omega).$$

The proof relies on the fact that weak derivatives of functions in $H_0^2(\Omega)$ belong to $H_0^1(\Omega)$, so the basic version of Poincaré's inequality still applies to them: there exist constants $c, c_1, \dots, c_d > 0$ such that

$$\|u\|_{L^2}^2 \leq c |u|_1^2 \text{ and } \|\partial_{x_i} u\|_{L^2}^2 \leq c_i |\partial_{x_i} u|_1^2 \text{ for each } i = 1, \dots, d.$$

From now on, it's just algebra:

$$\begin{aligned} \|u\|_{L^2}^2 &\leq c |u|_1^2 = c \|\nabla u\|_{L^2}^2 = c \sum_{i=1}^d \|\partial_{x_i} u\|_{L^2}^2 \leq c \sum_{i=1}^d c_i |\partial_{x_i} u|_1^2 \\ &= c \sum_{i=1}^d c_i \|\nabla \partial_{x_i} u\|_{L^2}^2 \leq c' \sum_{i,j=1}^d \|\partial_{x_i x_j} u\|_{L^2}^2 = c' |u|_2^2. \end{aligned}$$

Comparing the first, second and last terms we get that

$$\|u\|_2^2 = \|u\|_{L^2}^2 + |u|_1^2 + |u|_2^2 \leq \left(c' + \frac{c'}{c} + 1\right) |u|_2^2 = c'' |u|_2^2,$$

so we can just choose $C = 1/c''$.

- d) Existence and uniqueness of a weak solution $u \in X$ is given by the Lax-Milgram theorem applied to the equation $a(u, v) = f(v)$. Let's check that the hypothesis are satisfied. The continuity of f is given by $f \in X^*$. The continuity of $a(\cdot, \cdot)$ follows from the Cauchy-Schwarz inequality and point b):

$$\begin{aligned} a(u, v) &= \int_{\Omega} \Delta u \Delta v \, dx \leq \left(\int_{\Omega} (\Delta u)^2 \, dx \right)^{1/2} \left(\int_{\Omega} (\Delta v)^2 \, dx \right)^{1/2} \\ &= |u|_2 |v|_2 \leq \|u\|_2 \|v\|_2. \end{aligned}$$

The coercivity of $a(\cdot, \cdot)$ follows from points b) and c):

$$a(u, u) = \int_{\Omega} (\Delta u)^2 \, dx = |u|_2^2 \geq C \|u\|_2^2. \quad \square$$