

### 2.3. Characterising Implicitly Bayesian Prediction Rules

In the case of assumed *i.i.d.* data, De Finetti’s theorem gives a simple condition for a prediction rule to be implicitly Bayesian. As mentioned before, a prediction rule implies a unique joint distribution over the sequence of random variables  $(X_1, X_2, \dots)$ . By a version of the De Finetti’s theorem, under some mild assumptions, a prediction rule is implicitly Bayesian if and only if the joint distribution it implies over  $(X_1, X_2, \dots)$  is *exchangeable* (Hewitt and Savage, 1955):

**Definition 1 (Exchangeable Sequence of Random Variables)** *A finite sequence of  $n$  random variables  $(X_1, \dots, X_n)$  is said to be exchangeable if for any permutation  $\pi : \{1, \dots, n\} \rightarrow \{1, \dots, n\}$  the joint distribution of  $(X_1, \dots, X_n)$  is the same as the joint distribution of  $(X_{\pi(1)}, \dots, X_{\pi(n)})$ .*

*An infinite sequence of random variables  $(X_1, X_2, \dots)$  is said to be exchangeable if, for any  $n$ , the finite sequence  $(X_1, \dots, X_n)$  is exchangeable.*

By De Finetti’s theorem (see Appendix ?? for a more thorough explanation), we know that a sequence of random variables  $(X_1, X_2, \dots)$  is exchangeable if and only if there exists a (unique) prior probability  $\pi$  on the space  $\mathcal{P}$  of probability measures on  $\mathcal{X}$  such that:

$$P[X_1 \in A_1, \dots, X_n \in A_n] = \int_{\mathcal{P}} \prod_{i=1}^n p(A_i) d\pi(p) \quad \forall A_1, \dots, A_n \forall n \in \mathbb{N},$$

where  $p \in \mathcal{P}$  is a probability measure on  $\mathcal{X}$ . In other words, only if there exists a likelihood/prior construction that defines the same joint distribution as the prediction rule. Hence, exchangeability is the defining characteristic of implicitly Bayesian prediction rules on *i.i.d.* data. This suggests one direct way of checking whether a prediction rule is implicitly Bayesian: check whether the joint distribution on  $(X_1, X_2, \dots)$  implied by the prediction rule is exchangeable.

**Conditionally Identically Distributed** Another desirable coherence property that we might expect of a prediction rule is that the future observations are identically distributed given the past. For example, under the *i.i.d.* assumption, if we were to observe  $(x_1, \dots, x_n)$ , the prediction for the next observation  $X_{n+1}$  *surely* shouldn’t be different from the prediction for the observation after that. After all, we know they are identically distributed, we just don’t know what the distribution is; it’d be irrational to make different predictions for  $X_{n+1}, X_{n+2}$  given the same data.

This property can be formalised as follows:

**Definition 2 (Conditionally Identically Distributed)** *We say that a sequence of random variables  $(X_1, X_2, \dots)$  is conditionally identically distributed (c.i.d.) if for any  $n$ :*

$$P[X_{n+1} \in \cdot | X_1 = x_1, \dots, X_n = x_n] = P[X_{n+k} \in \cdot | X_1 = x_1, \dots, X_n = x_n] \quad \forall k > n$$

*holds almost surely.*

A prediction rule is then *c.i.d.* if the joint distribution it implies over  $(X_1, X_2, \dots)$  is *c.i.d.*. Conditionally Identically Distributed sequences have been introduced in (Kallenberg, 1988) and studied and applied in a range of works (Berti et al., 2004, 2013; Fong et al., 2021a).

## Appendix A. De Finetti's theorem

Consider a probability space  $(\Omega, \mathcal{F}_\Omega, P)$  and a sequence of random variables  $(X_1, X_2, \dots)$ ,  $X_i : \Omega \rightarrow \mathcal{X}$ , where  $X_i$  takes values in some measurable space  $(\mathcal{X}, \mathcal{F})$ . Then, by a version of the De Finetti's theorem given by [Hewitt and Savage \(1955\)](#), under fairly general conditions, if  $(X_1, X_2, \dots)$  is exchangeable as per Definition 1, then the distribution of  $(X_1, X_2, \dots)$  can be represented as a mixture of *i.i.d.* distributions.

Concretely, consider the set  $\mathcal{P}$  of probability measures  $p \in \mathcal{P}$  on  $(\mathcal{X}, \mathcal{F})$ , and the smallest  $\sigma$ -algebra  $\mathcal{S}$  that makes  $p \mapsto p(A)$  measurable for all  $A \in \mathcal{F}$ . For  $p \in \mathcal{P}$ , denote by  $p^\infty$  the product probability measure  $\otimes_{i=1}^\infty p$  on the product space  $(\prod_{i=1}^\infty \mathcal{X}, \otimes_{i=1}^\infty \mathcal{F})$ . Then, if  $(X_1, X_2, \dots)$  is exchangeable, there exists a unique probability measure  $\pi$  on  $(\mathcal{P}, \mathcal{S})$  such that the joint distribution of  $(X_1, X_2, \dots)$  can be represented as:

$$P[(X_1, X_2, \dots) \in A] = \int_{\mathcal{P}} p^\infty(A) d\pi(p) \quad \forall A \in \otimes_{i=1}^\infty \mathcal{F}, \quad (7)$$

The only condition is that  $\mathcal{X}$  must be a Hausdorff space with  $\mathcal{F}$  being the  $\sigma$ -algebra of all Baire sets in  $\mathcal{X}$ . The practically relevant aspect of that condition is that it is satisfied in the typically considered settings of  $\mathcal{X}$  being  $\mathbb{R}$  or  $\mathbb{R}^d$  with the usual Borel  $\sigma$ -algebra.

The above formulation is slightly different than the one given in Section 2.3. Namely, the proposition in (7) was instead replaced with: there exists a unique probability measure  $\pi$  on  $(\mathcal{P}, \mathcal{S})$  such that:

$$P[X_1 \in A_1, \dots, X_n \in A_n] = \int_{\mathcal{P}} \prod_{i=1}^n p(A_i) d\pi(p) \quad \forall A_1, \dots, A_n \in \mathcal{F}, \forall n \in \mathbb{N}, \quad (8)$$

which we think is a little bit more approachable. The propositions in (7) and (8) are equivalent. Clearly, (7) implies (8); if the equality holds for all sets  $A$  in the infinite product  $\sigma$ -algebra  $\otimes_{i=1}^\infty \mathcal{F}$ , then it will hold for rectangles  $A = (A_1, \dots, A_n, \mathcal{X}, \mathcal{X}, \dots) \in \otimes_{i=1}^\infty \mathcal{F}$ , and so:

$$\begin{aligned} P[X_1 \in A_1, \dots, X_n \in A_n] &= P[(X_1, X_2, \dots) \in A] \quad B = (A_1, \dots, A_n, \mathcal{X}, \mathcal{X}, \dots) \\ &= \int_{\mathcal{P}} p^\infty(B) d\pi(p) \\ &= \int_{\mathcal{P}} \prod_{i=1}^n p(A_i) \prod_{i=n+1}^\infty \overbrace{p(\mathcal{X})}^1 d\pi(p) \quad \triangle \text{Definition of product measure} \\ &= \int_{\mathcal{P}} \prod_{i=1}^n p(A_i) d\pi(p) \end{aligned}$$

To go the other way around from (8) to (7), assume that there exists a unique measure  $\pi$  such that (8) holds. We can extend the statement to ‘infinite rectangle’ sets of the form  $B = (A_1, A_2, \dots)$ ,  $A_i \in \mathcal{F} \forall i \in \mathbb{N}$  by noting that since  $(A_1, \dots, A_n, \mathcal{X}, \mathcal{X}, \dots) \downarrow B$ , we have

that  $P[X_1 \in A_1, \dots, X_n \in A_n] \downarrow P[(X_1, X_2, \dots) \in B]$ . Hence:

$$\begin{aligned}
 P[(X_1, X_2, \dots) \in B] &= \lim_{n \rightarrow \infty} P[X_1 \in A_1, \dots, X_n \in A_n] \\
 &= \lim_{n \rightarrow \infty} \int_{\mathcal{P}} \prod_{i=1}^n p(A_i) d\pi(p) \\
 &= \int_{\mathcal{P}} \lim_{n \rightarrow \infty} \prod_{i=1}^n p(A_i) d\pi(p) \quad \triangle \text{Dominated Convergence Theorem} \\
 &= \int_{\mathcal{P}} p^\infty(B) d\pi(p)
 \end{aligned}$$

Now, since  $P[(X_1, X_2, \dots) \in \cdot]$  and  $\int_{\mathcal{P}} p^\infty(\cdot) d\pi(p)$  are two measures on  $(\prod_{i=1}^\infty \mathcal{X}, \otimes_{i=1}^\infty \mathcal{F})$  that agree on the  $\pi$ -system of rectangles that generates the product  $\sigma$ -algebra, they must agree on the entire  $\sigma$ -algebra.

It is worth noting that exchangeability of the entire infinite sequence  $(X_1, X_2, \dots)$  is required for the result to hold. One might hope that if a finite sequence  $(X_1, \dots, X_n)$  is exchangeable for some  $n$ , then the joint distribution of these  $n$  random variables might also be a mixture distribution. This is not always the case ([Kerns and Székely, 2006](#)).