## How to use SimpleMio DSL

The user can write a program, that contains multiple events and each event has the following syntax:

## **ConditionalSensor -> Actions**

**ConditionalSensor** are composed by sensor separated by conditional operators, such as, "or", "and", "(" something here ")" and "not".

"or" and "and" are <u>followed with two ConditionalSensors</u>, one in each side. "not" is <u>followed</u> <u>by just one conditional sensor</u>, after the "not". "(" ")", the parenthesis <u>contains a</u> <u>ConditionalSensor</u>, inside the parenthesis.

Each **sensor** is composed by a **sensorName** (<u>obstacle</u>, <u>sound</u>, <u>line</u>, <u>button</u> or <u>motor</u>), a **sensorSpecifier** (<u>front</u>, <u>back</u>, <u>left</u>, <u>right</u>, <u>up</u>, <u>down</u>, or <u>center</u>) and optionally the user can set the **strength** of the sensor by adding a value after the "<u>@</u>" symbol, the **strength** has to be a <u>value</u> between 0 and 10.

Actions are composed by actions separated by a comma ","

Each **action** is composed by an **actionName** (<u>move</u>, <u>led</u> or <u>turn</u>), an **actionSpecifier** (<u>left</u>, <u>right</u>, <u>forward</u>, <u>backward</u>, <u>stop</u>, <u>red</u>, <u>green</u> or <u>blue</u>) and optionally the user can set the **strength** of the action by adding a value after the "<u>@</u>" symbol, the **strength** has to be a <u>value between 0</u> and 10.

Also, each action or sensor is allowed to be followed by:

- move can be followed by <u>forwards</u>, <u>backwards</u> or <u>stop</u>.
- **led** can be followed by <u>red</u>, <u>blue</u> or <u>green</u>.
- **turn** can be followed by <u>right</u> or left.
- **obstacle** can be followed by <u>front</u>, <u>back</u>, <u>left</u> or <u>right</u> (activates the sensors on the front, sides or on the back of the thymio).
- line can be followed by left or right (activates the sensors under the thymio).
- button can be followed by <u>left</u>, <u>right</u>, <u>up</u>, <u>down</u> and <u>center</u>.
- sound and motor don't have any specifier.
- The sensor motor doesn't support intensity.
- Overlapping actions is not allowed, like, more than 1 action led or more than 1 action turn or move in total.

## Examples of programs

```
not obstacle front -> move forward @7
obstacle front or obstacle right-> turn right
```

```
sound -> led red @10
button center and not obstacle back @6 -> move backward @2
```