Grafos

Programação Dinâmica em DAGs

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* De fato, há uma relação direta entre uma DP e um DAG

 \star Uma DP induz um DAG cujos vértices são os estados e as arestas indicam as transições entre estados

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- \star Seja $p_u(x)$ o número de caminhos de u a x
- \star Há um único caminho de u a u: permanecer onde está
- \star Assim, $p_u(u)=1$ é o caso base

 \star Para os demais vértices $x \in V$, vale que

$$p_u(x) = \sum_{(v_i, x) \in E} p_u(v_i)$$

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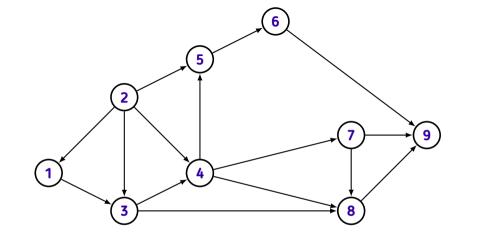
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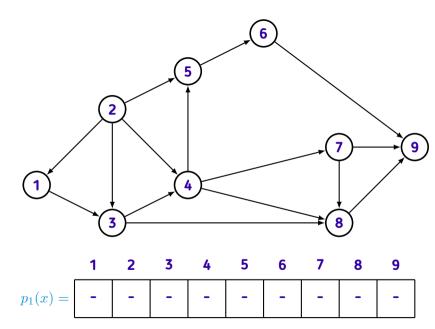
 \star O cálculo de $p_u(x)$ depende da ordem de processamento dos vértices

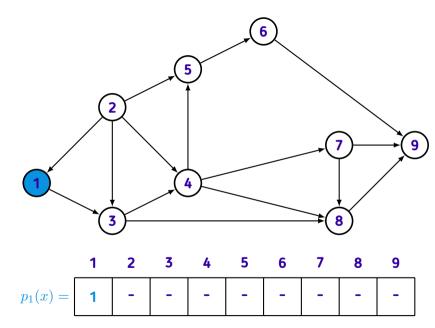
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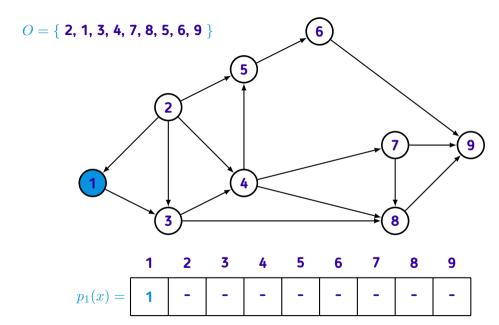
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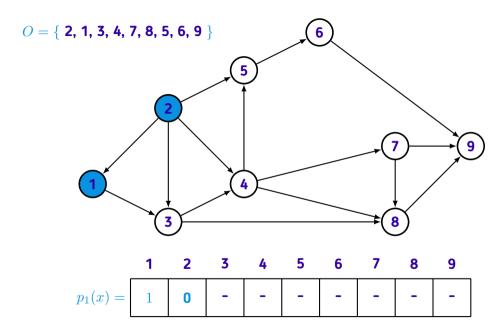
- \star O cálculo de $p_u(x)$ depende da ordem de processamento dos vértices
- \star Como G é um DAG, basta usar a ordenação topológica para computar $p_u(x)$

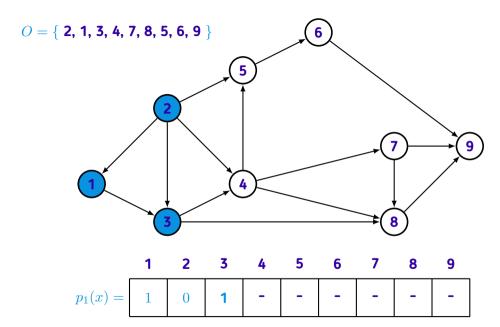


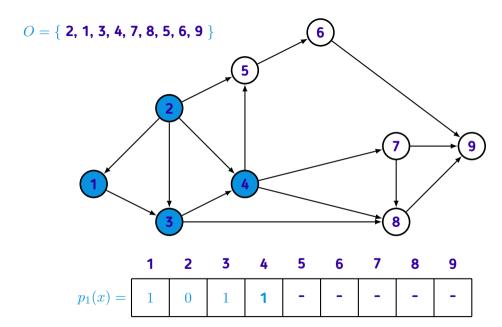


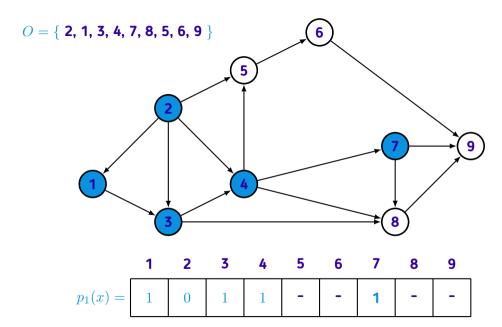


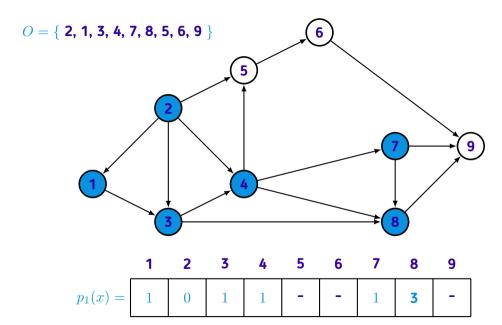


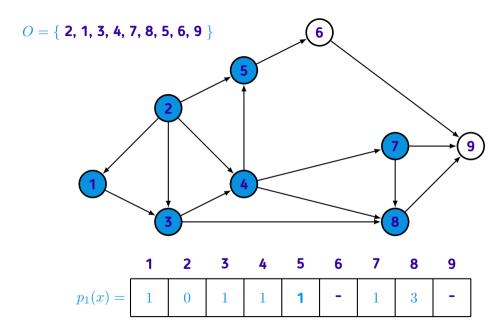


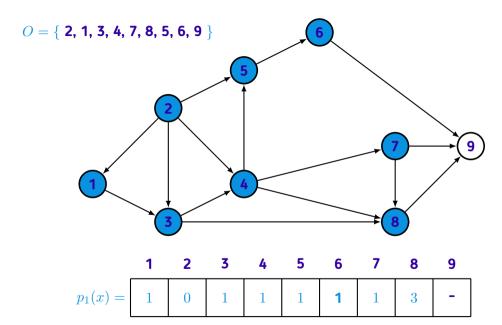


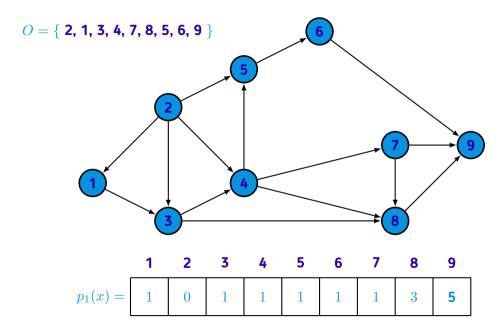


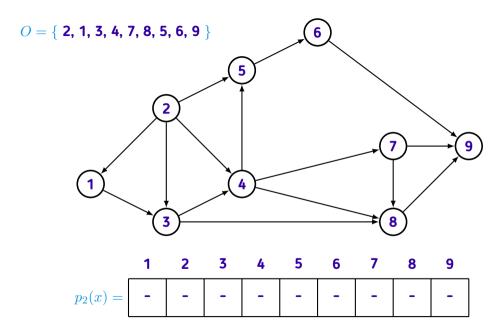


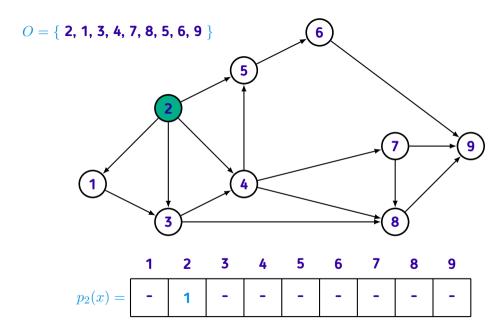


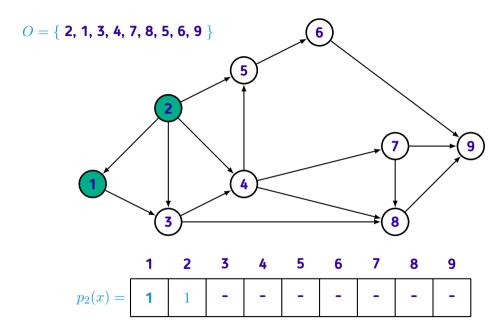


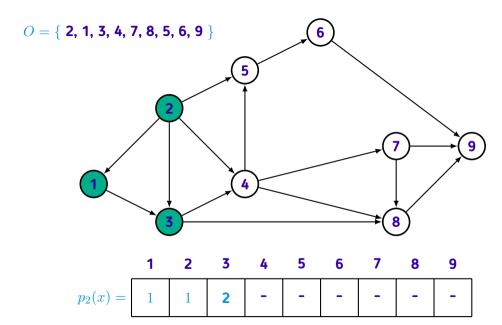


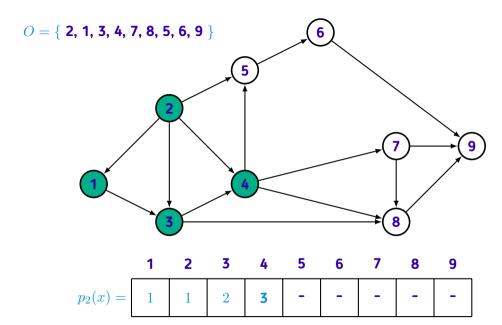


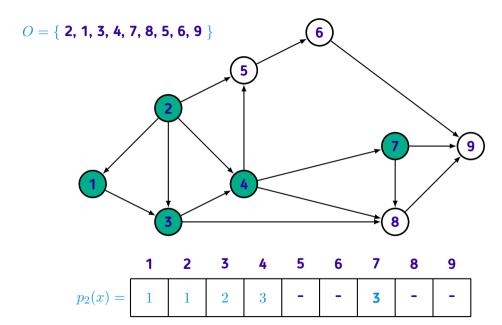


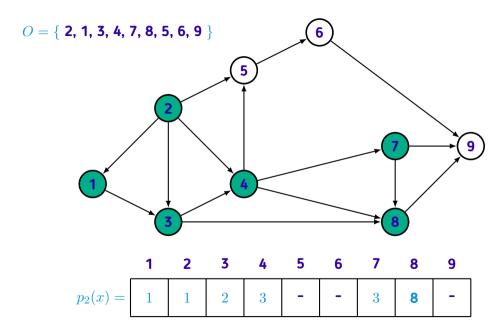


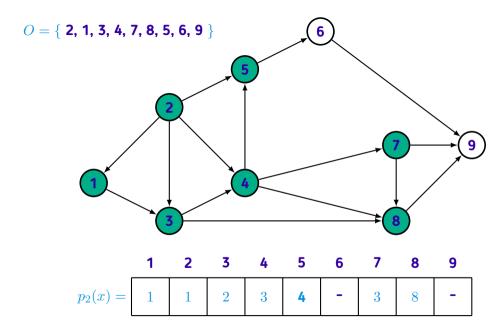


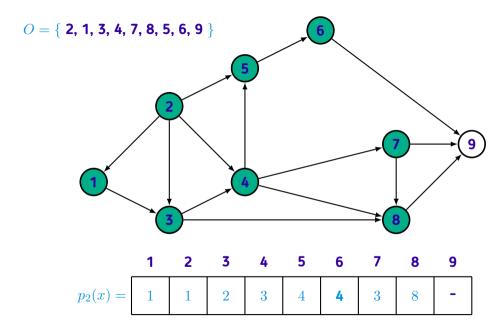


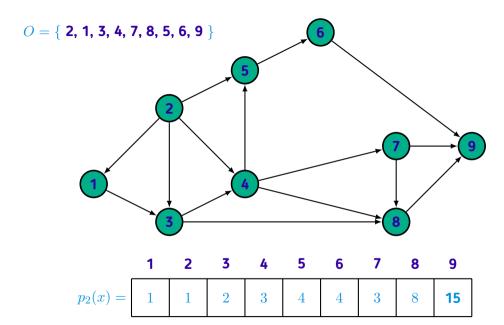












```
vector<int> paths(int u, int N)
{
    auto o = topological_sort(N);
    vector<int> ps(N + 1, 0);
    ps[u] = 1;
    for (auto x : o)
        for (auto v : in[x])
            ps[x] += ps[v];
    return ps;
```

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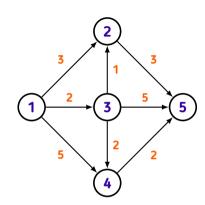
* Assim, pode-se usar DP neste grafo

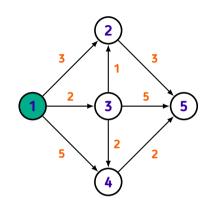
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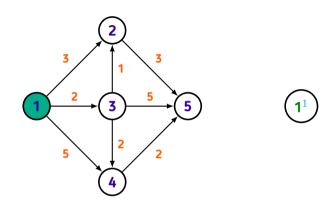
 \star Assim seria possível, por exemplo, computar o número de caminhos mínimos de u a v

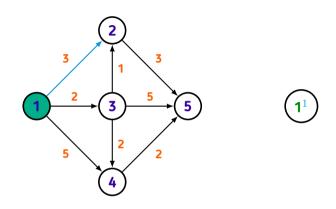
- \star O algoritmo de Dijkstra induz um DAG que indica, para cada vértice do grafo original, como atingir os demais vértices por caminhos mínimos
 - * Assim, pode-se usar DP neste grafo
- \star Assim seria possível, por exemplo, computar o número de caminhos mínimos de u a v
- \star O algoritmo seria o mesmo usado para computar o número de caminhos, com a ordenação O sendo substituída pela ordenação de Dijkstra

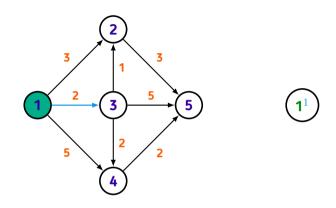




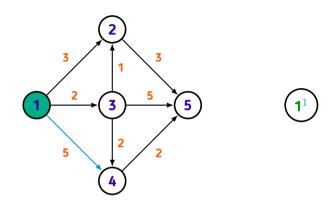
$$d_1(x) = \begin{array}{|c|c|c|c|c|c|c|c|} \hline & 1 & 2 & 3 & 4 & 5 \\ \hline & 0 & - & - & - & - \\ \hline \end{array}$$



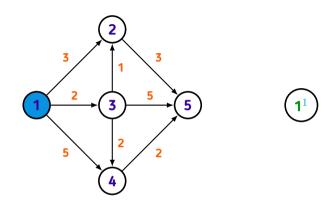




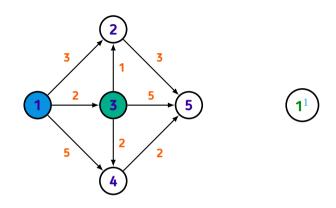
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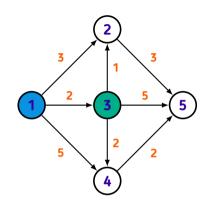
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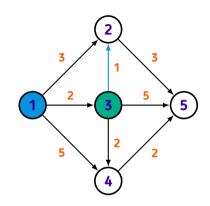
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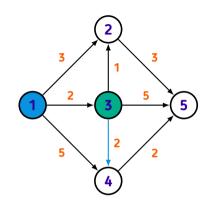
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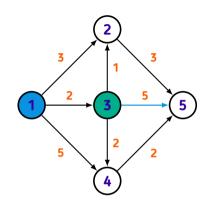
	1	2	3	4	5
$d_1(x) =$	0	3	2	5	-



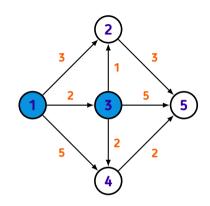
	1	2	3	4	5
$d_1(x) =$	0	3	2	5	1



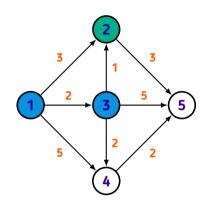
	1	2	3	4	5
$d_1(x) =$	0	3	2	4	-



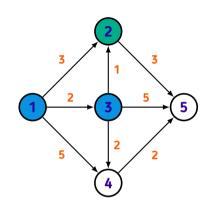
	1	2	3	4	5
$d_1(x) =$	0	3	2	4	7

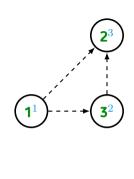


	1	2	3	4	5
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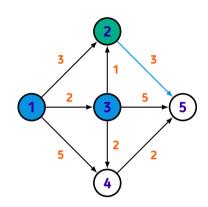


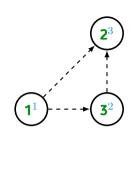
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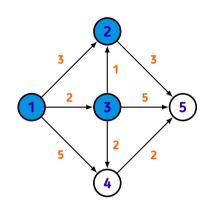


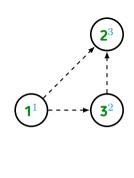
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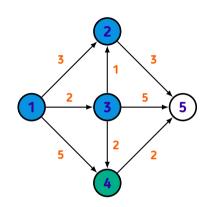


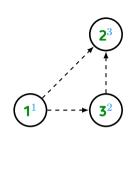
	1	2	3	4	5
$d_1(x) =$	0	3	2	4	6



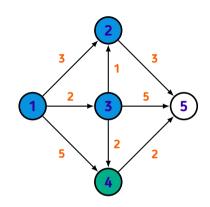


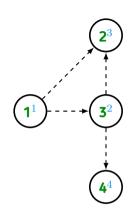
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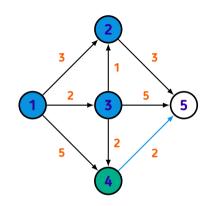


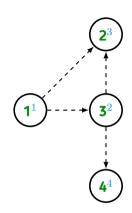
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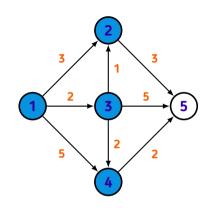


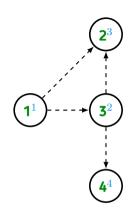
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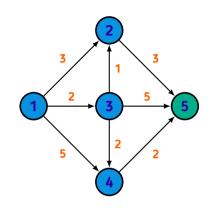


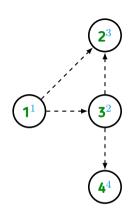
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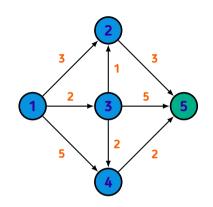


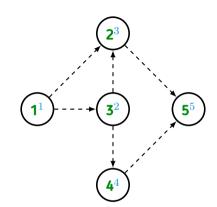
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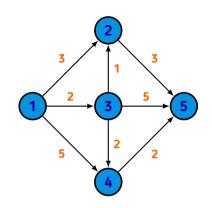


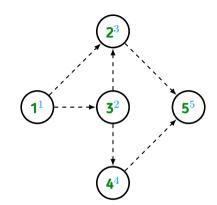
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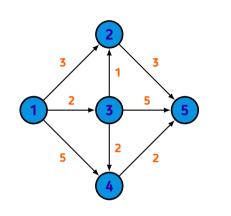


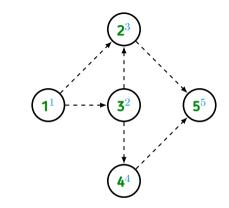
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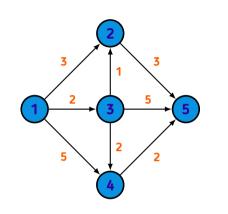


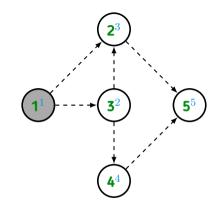
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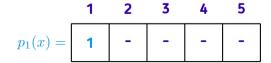


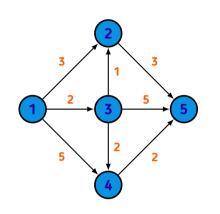
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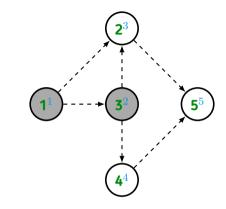




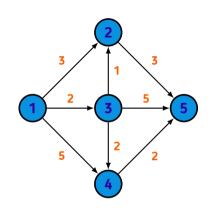
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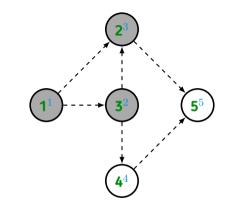




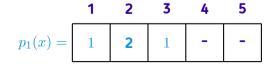


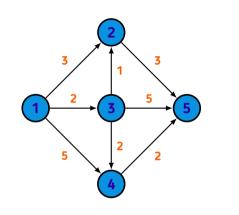
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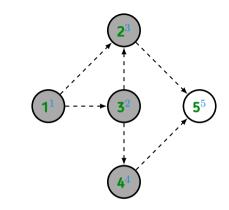




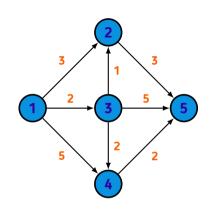
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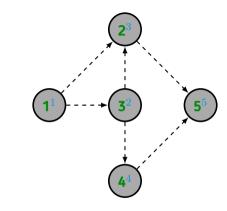






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```
vector<int> min_paths(int s, int N)
{
    vector<int> ps(N + 1, 0);
    ps[s] = 1;
    auto o = dijkstra_order(s, N);
    for (auto x : o)
        for (auto v : in[x])
           ps[x] += ps[v];
    return ps;
```

```
vector<int> dijkstra_order(int s, int N)
{
    vector<int> dist(N + 1, oo), order;
    dist[s] = 0:
    processed.reset();
    priority_queue<ii, vector<ii>, greater<ii>> pq;
    pq.emplace(0, s);
    while (not pq.empty())
        auto [d, u] = pq.top();
        pq.pop();
        if (processed[u])
            continue;
```

```
order.emplace_back(u);
    processed[u] = true;
    for (auto [v, w] : adj[u])
        if (dist[v] > d + w)
            dist[v] = d + w;
            pq.emplace(dist[v], v);
            in[v] = { u };
        } else if (dist[v] == d + w)
            in[v].emplace(u);
return order;
```

Problemas sugeridos

- 1. CSES 1202 Investigation
- 2. HackerEarth Counting on Tree
- 3. SPOJ DAGCNT2 Counting in a DAG
- 4. Timus 1018 Binary Apple Tree

Referências

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- 2. DUMOL, Tim. 101 Trainning Week 5 DP on Trees and DAGs.
- 3. HALIM, Felix; HALIM, Steve. Competitive Programming 3, 2010.
- 4. LAAKSONEN, Antti. Competitive Programmer's Handbook, 2018.