

# Grafos

*Algoritmo de Dijkstra*

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**Faculdade UnB Gama**

**Proponente**

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**Edsger Wybe Dijkstra**  
**(1956)**

## **Características do algoritmo de Dijkstra**

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- ★ Complexidade:  $O(E + V \log V)$



# Pseudocódigo

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2. Enquanto  $U \neq \emptyset$ :
  - (a) Seja  $u \in U$  o vértice mais próximo de  $s$  em  $U$
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  - (c) Remova  $u$  de  $U$

# Pseudocódigo

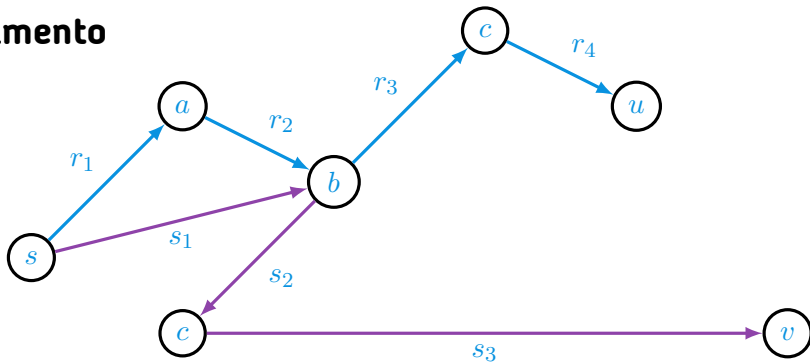
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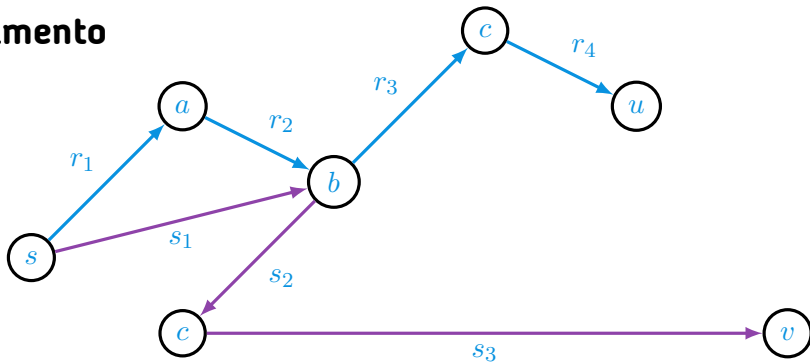
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3. Retorne  $d$

# Relaxamento

## Relaxamento



## Relaxamento

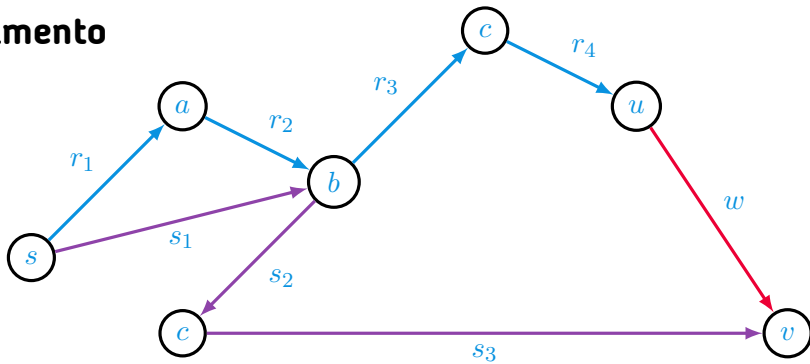


$$\text{dist}(s, u) = \sum_{i=1}^4 r_i$$

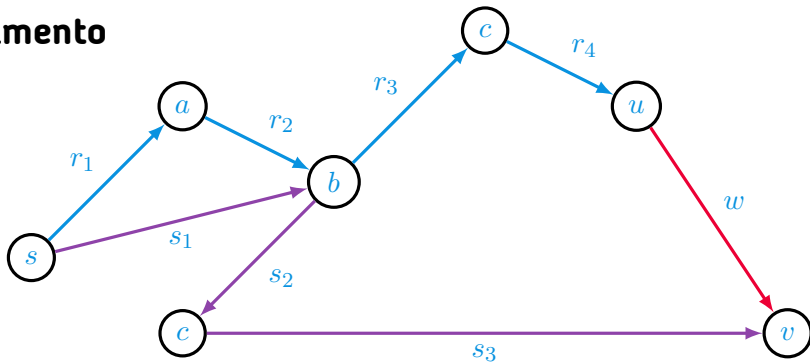
$$\text{dist}(s, v) = \sum_{j=1}^3 s_j$$



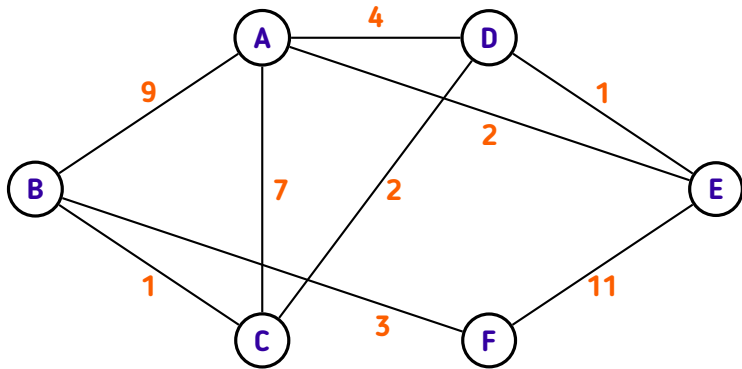
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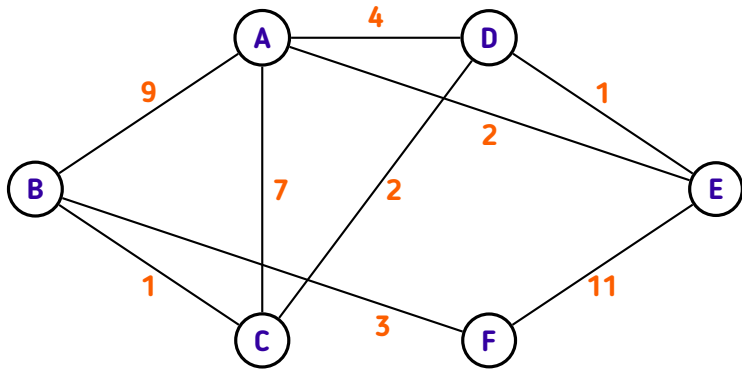


## Relaxamento



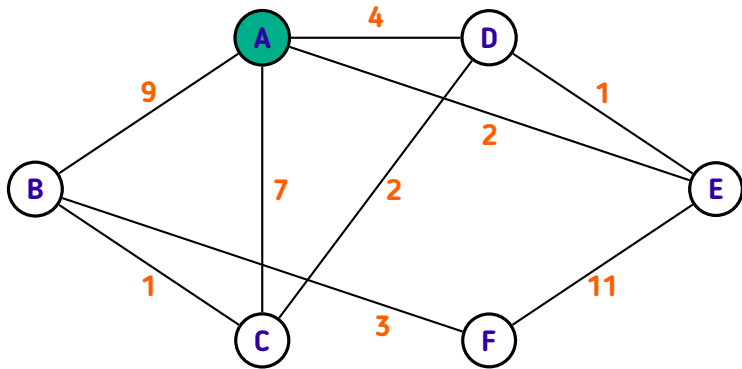
**Se**  $\text{dist}(s, u) + w < \text{dist}(s, v)$ , **faça**  $\text{dist}(s, v) = \text{dist}(s, u) + w$





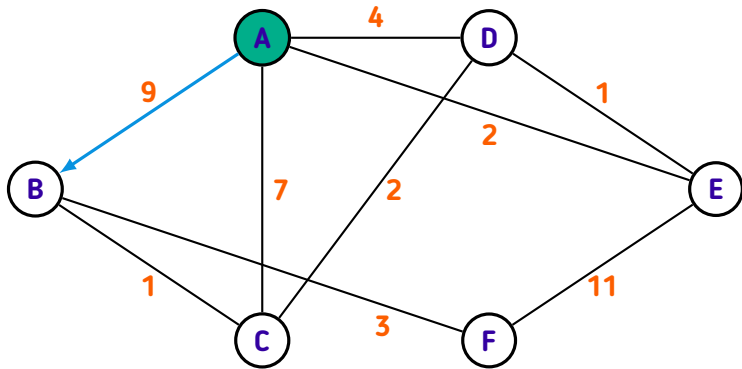
|                              | A | B        | C        | D        | E        | F        |
|------------------------------|---|----------|----------|----------|----------|----------|
| $\text{dist}(u, \mathbf{A})$ | 0 | $\infty$ | $\infty$ | $\infty$ | $\infty$ | $\infty$ |

$$U = \{ \mathbf{A}, \mathbf{B}, \mathbf{C}, \mathbf{D}, \mathbf{E}, \mathbf{F} \}$$



|                              | A | B        | C        | D        | E        | F        |
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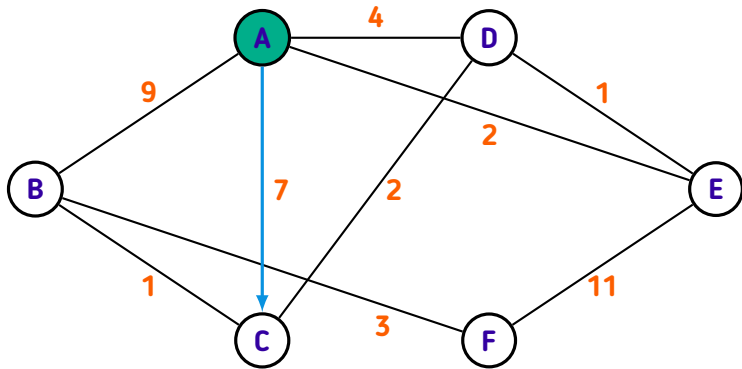
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$\text{dist}(u, \mathbf{A})$

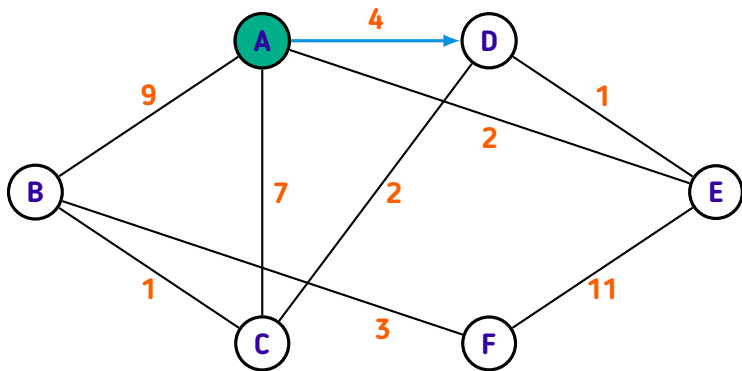
| A | B | C        | D        | E        | F        |
|---|---|----------|----------|----------|----------|
| 0 | 9 | $\infty$ | $\infty$ | $\infty$ | $\infty$ |

$$U = \{ \mathbf{B}, \mathbf{C}, \mathbf{D}, \mathbf{E}, \mathbf{F} \}$$



|                              | A | B | C | D        | E        | F        |
|------------------------------|---|---|---|----------|----------|----------|
| $\text{dist}(u, \mathbf{A})$ | 0 | 9 | 7 | $\infty$ | $\infty$ | $\infty$ |

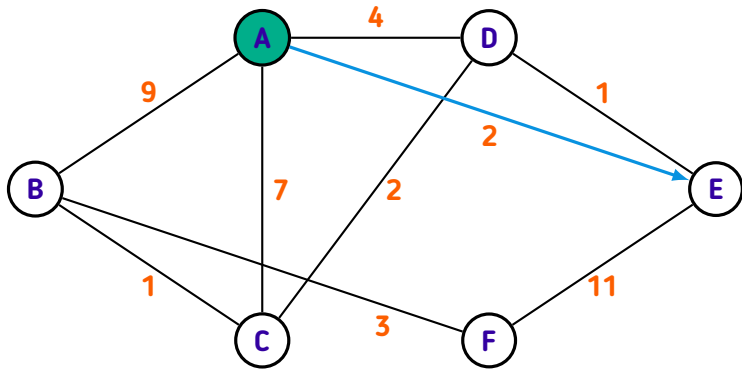
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|                              | A | B | C | D | E        | F        |
|------------------------------|---|---|---|---|----------|----------|
| $\text{dist}(u, \mathbf{A})$ | 0 | 9 | 7 | 4 | $\infty$ | $\infty$ |

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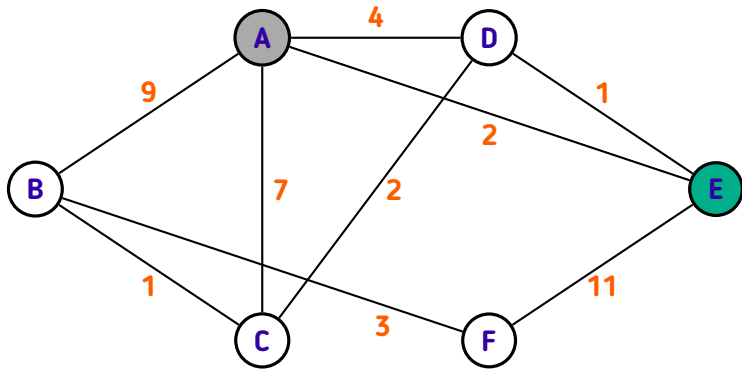




$\text{dist}(u, \mathbf{A})$

| A | B | C | D | E | F        |
|---|---|---|---|---|----------|
| 0 | 9 | 7 | 4 | 2 | $\infty$ |

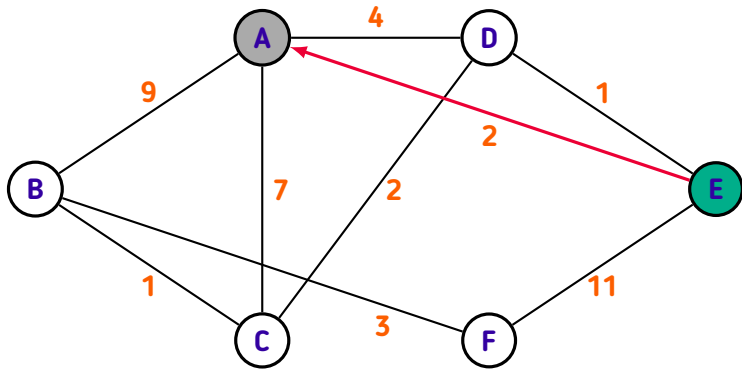
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| A | B | C | D | E | F        |
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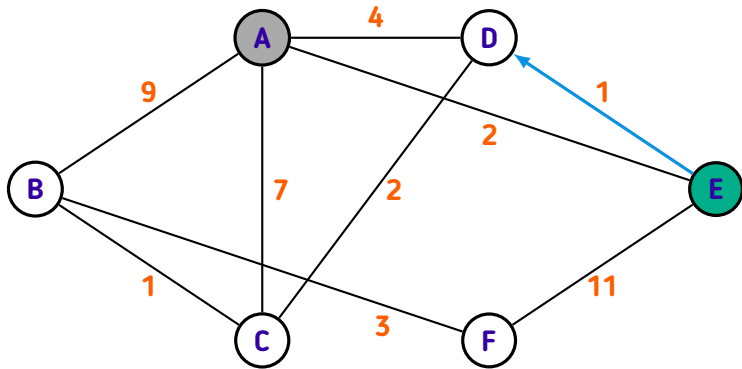
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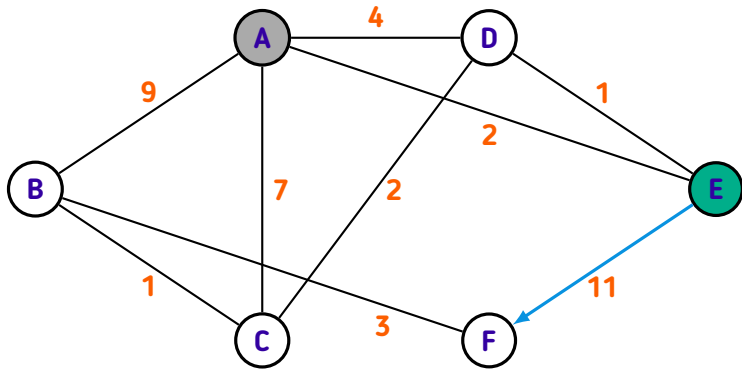
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|---|---|---|---|---|----------|
| 0 | 9 | 7 | 4 | 2 | $\infty$ |

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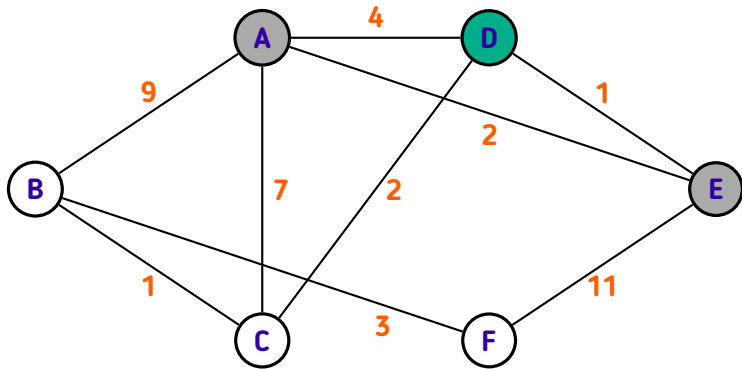
|                              | A | B | C | D | E | F        |
|------------------------------|---|---|---|---|---|----------|
| $\text{dist}(u, \mathbf{A})$ | 0 | 9 | 7 | 3 | 2 | $\infty$ |

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|                              | A | B | C | D | E | F         |
|------------------------------|---|---|---|---|---|-----------|
| $\text{dist}(u, \mathbf{A})$ | 0 | 9 | 7 | 3 | 2 | <b>13</b> |

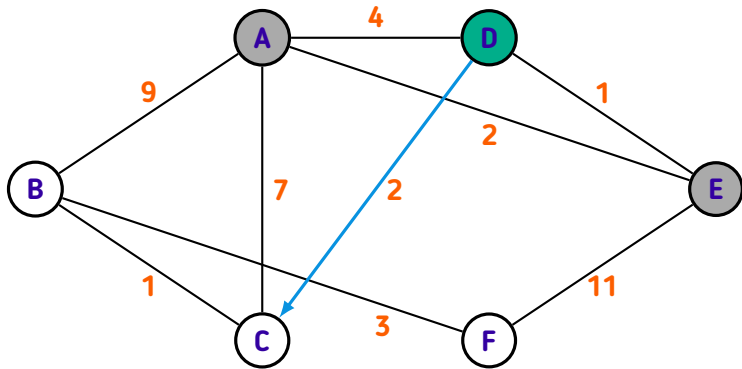
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$\text{dist}(u, \mathbf{A})$

| A | B | C | D | E | F  |
|---|---|---|---|---|----|
| 0 | 9 | 7 | 3 | 2 | 13 |

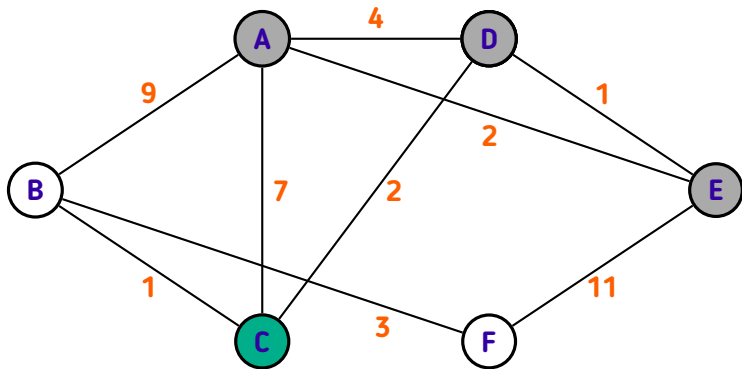
$$U = \{ \mathbf{B}, \mathbf{C}, \mathbf{F} \}$$



$\text{dist}(u, \mathbf{A})$

| A | B | C | D | E | F  |
|---|---|---|---|---|----|
| 0 | 9 | 5 | 3 | 2 | 13 |

$$U = \{ \mathbf{B}, \mathbf{C}, \mathbf{F} \}$$

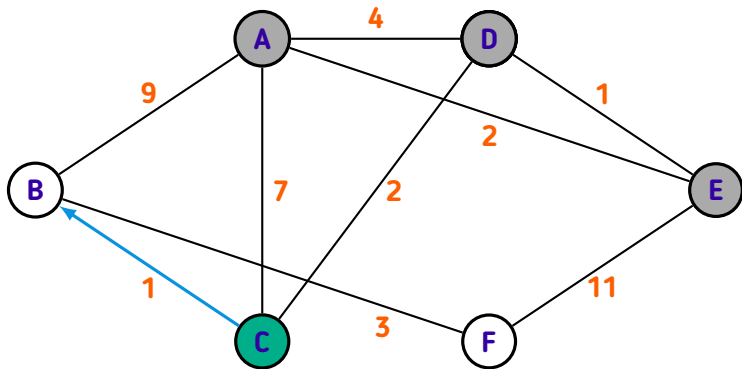


$\text{dist}(u, \mathbf{A})$

| A | B | C | D | E | F  |
|---|---|---|---|---|----|
| 0 | 9 | 5 | 3 | 2 | 13 |

$$U = \{ \mathbf{B}, \mathbf{F} \}$$

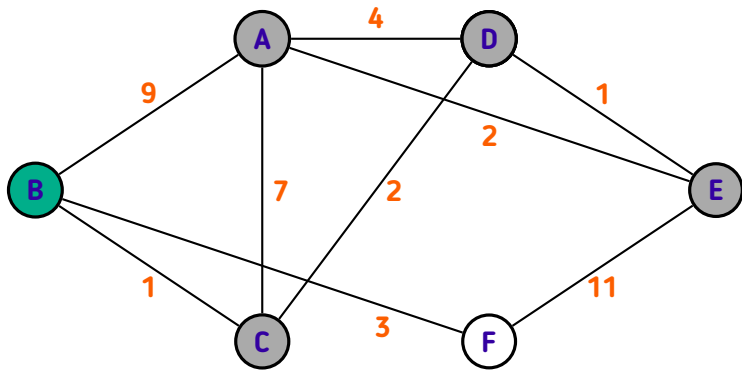




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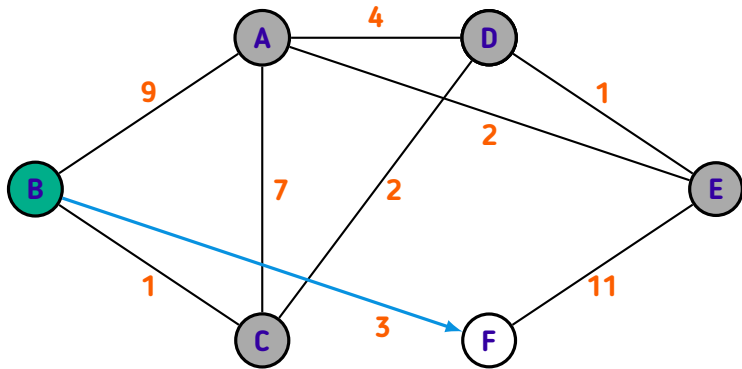
| A | B | C | D | E | F  |
|---|---|---|---|---|----|
| 0 | 6 | 5 | 3 | 2 | 13 |

$$U = \{ \mathbf{B}, \mathbf{F} \}$$



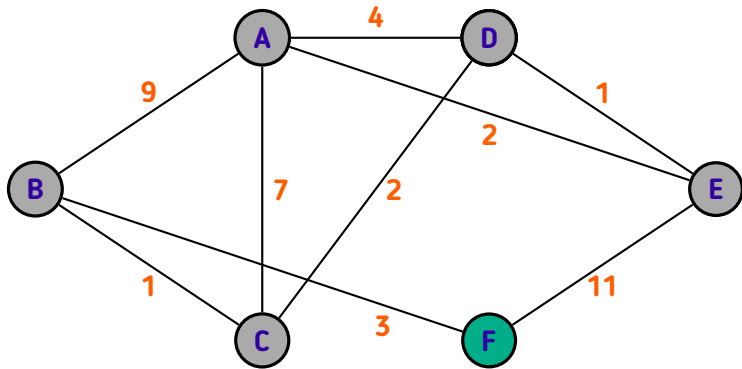
|                              | A | B | C | D | E | F  |
|------------------------------|---|---|---|---|---|----|
| $\text{dist}(u, \mathbf{A})$ | 0 | 6 | 5 | 3 | 2 | 13 |

$$U = \{ \mathbf{F} \}$$



|                              | A | B | C | D | E | F        |
|------------------------------|---|---|---|---|---|----------|
| $\text{dist}(u, \mathbf{A})$ | 0 | 6 | 5 | 3 | 2 | <b>9</b> |

$$U = \{ \mathbf{F} \}$$

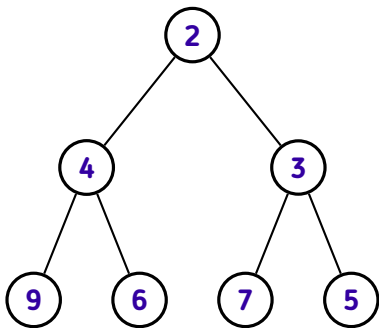


|                              | A | B | C | D | E | F |
|------------------------------|---|---|---|---|---|---|
| $\text{dist}(u, \mathbf{A})$ | 0 | 6 | 5 | 3 | 2 | 9 |

$U = \emptyset$

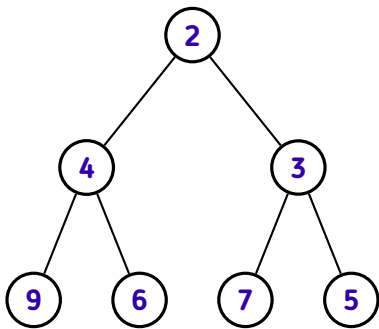
**Identificação eficiente do vértice  $u$  mais próximo de  $s$**

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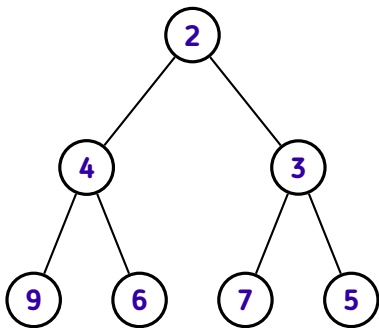
*min heap*

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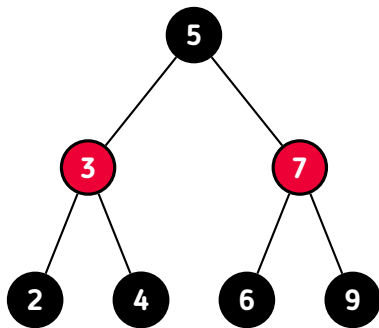


*min heap*  
(priority\_queue)

Identificação eficiente do vértice  $u$  mais próximo de  $s$



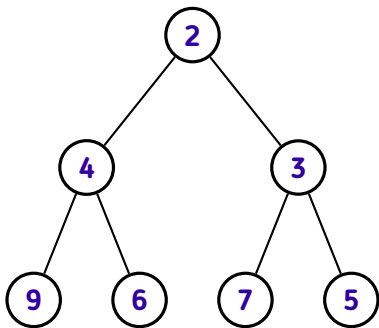
*min heap*  
(priority\_queue)



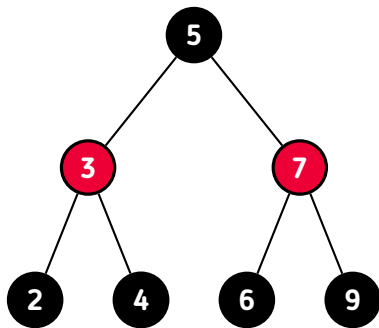
*red-black tree*



Identificação eficiente do vértice  $u$  mais próximo de  $s$



*min heap*  
(priority\_queue)



*red-black tree*  
(set)

```
vector<int> dijkstra(int s, int N)
{
    const int oo { 1000000010 };

    vector<int> dist(N + 1, oo);
    dist[s] = 0;

    set<ii> U;
    U.emplace(0, s);

    while (not U.empty())
    {
        auto [d, u] = *U.begin();
        U.erase(U.begin());
    }
}
```

```
    for (auto [v, w] : adj[u])
    {
        if (dist[v] > d + w)
        {
            if (U.count(ii(dist[v], v)))
                U.erase(ii(dist[v], v));

            dist[v] = d + w;
            U.emplace(dist[v], v);
        }
    }

    return dist;
}
```

## **Identificação do caminho mínimo**

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- ★ No início do algoritmo,  $\text{pred}[s] = s$  e  $\text{pred}[u] = \text{undef}$ , se  $u \neq s$

## Identificação do caminho mínimo

★ Se  $(u, v)$  atualizar  $d[v]$ , faça  $\text{pred}[v] = u$



## Identificação do caminho mínimo

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★ A sequência

$$p = \{(s, \text{pred}^{k-1}[u]), \dots, (\text{pred}[\text{pred}[u]], \text{pred}[u]), (\text{pred}[u], u)\}$$

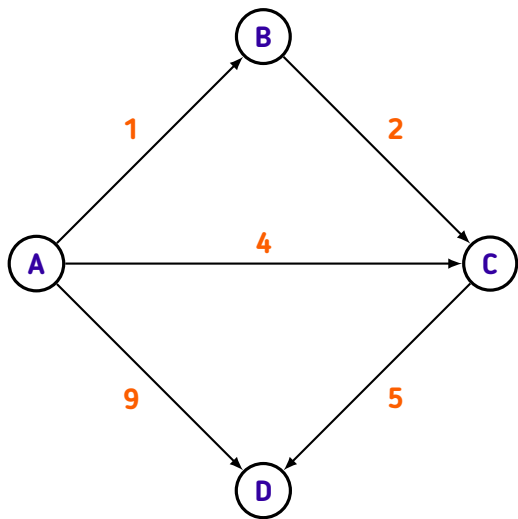
## Identificação do caminho mínimo

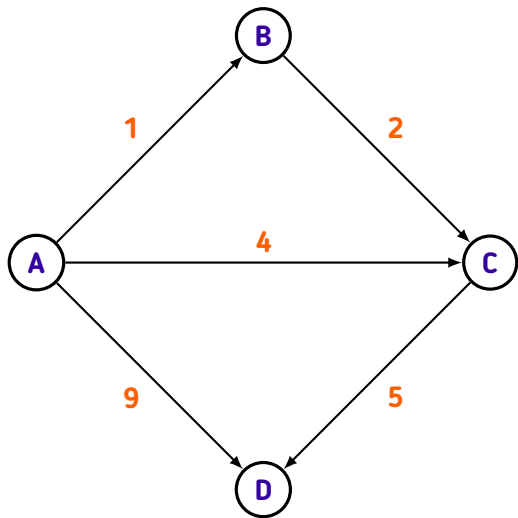
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$$p = \{(s, \text{pred}^{k-1}[u]), \dots, (\text{pred}[\text{pred}[u]], \text{pred}[u]), (\text{pred}[u], u)\}$$

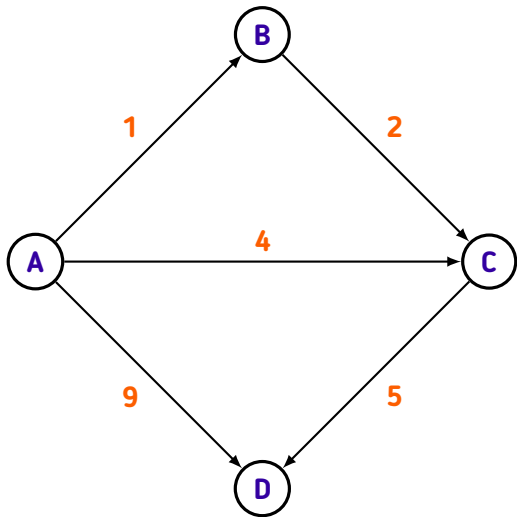
é um caminho mínimo de  $s$  a  $u$  composto de  $k$  arestas e tamanho  $d[u]$





$\text{dist}(u, \mathbf{A})$

| A | B        | C        | D        |
|---|----------|----------|----------|
| 0 | $\infty$ | $\infty$ | $\infty$ |

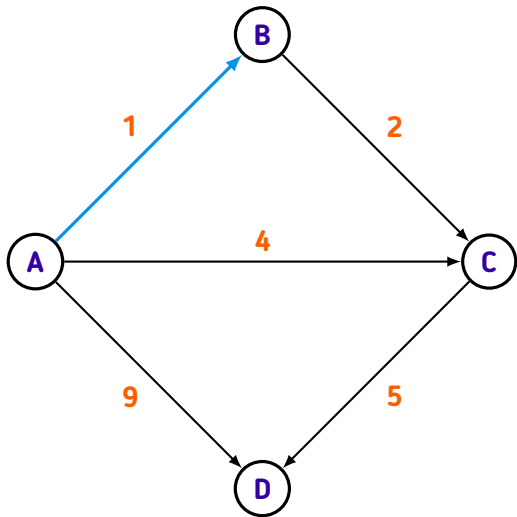


$\text{dist}(u, \mathbf{A})$

| A | B        | C        | D        |
|---|----------|----------|----------|
| 0 | $\infty$ | $\infty$ | $\infty$ |

$\text{pred}(u)$

| A | B | C | D |
|---|---|---|---|
| A | - | - | - |

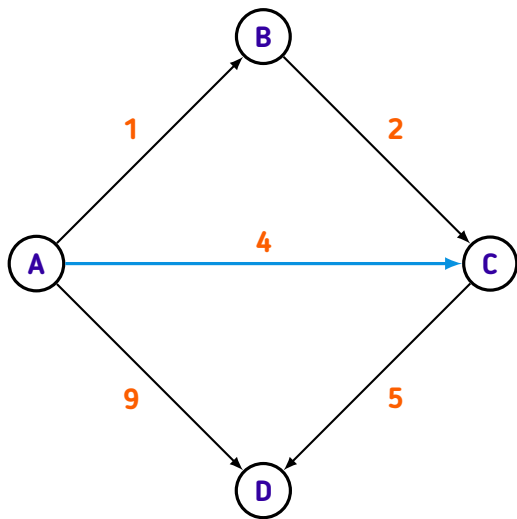


$\text{dist}(u, \mathbf{A})$

| A | B | C        | D        |
|---|---|----------|----------|
| 0 | 1 | $\infty$ | $\infty$ |

$\text{pred}(u)$

| A | B | C | D |
|---|---|---|---|
| A | A | - | - |

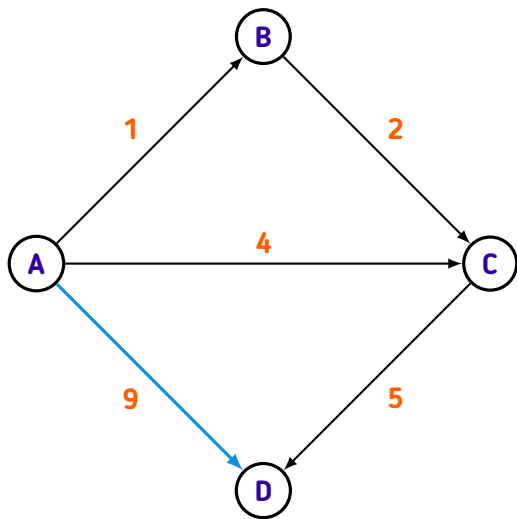


$\text{dist}(u, \mathbf{A})$

| A | B | C | D        |
|---|---|---|----------|
| 0 | 1 | 4 | $\infty$ |

$\text{pred}(u)$

| A | B | C | D |
|---|---|---|---|
| A | A | A | - |



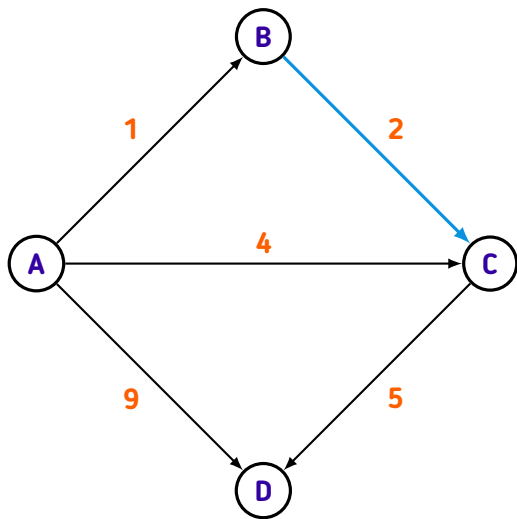
$\text{dist}(u, \mathbf{A})$

| A | B | C | D |
|---|---|---|---|
| 0 | 1 | 4 | 9 |

$\text{pred}(u)$

| A | B | C | D |
|---|---|---|---|
| A | A | A | A |



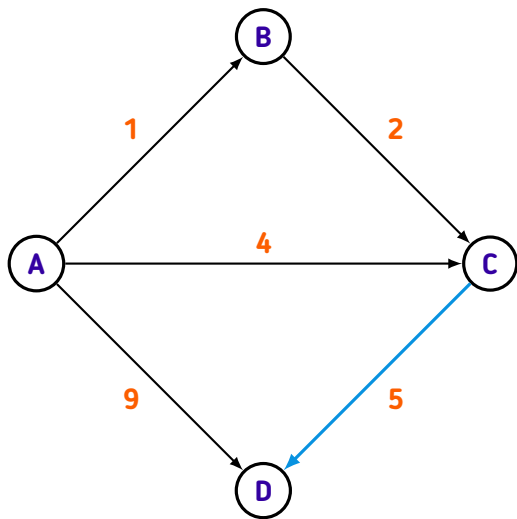


$\text{dist}(u, \mathbf{A})$

| A | B | C | D |
|---|---|---|---|
| 0 | 1 | 3 | 9 |

$\text{pred}(u)$

| A | B | C | D |
|---|---|---|---|
| A | A | B | A |

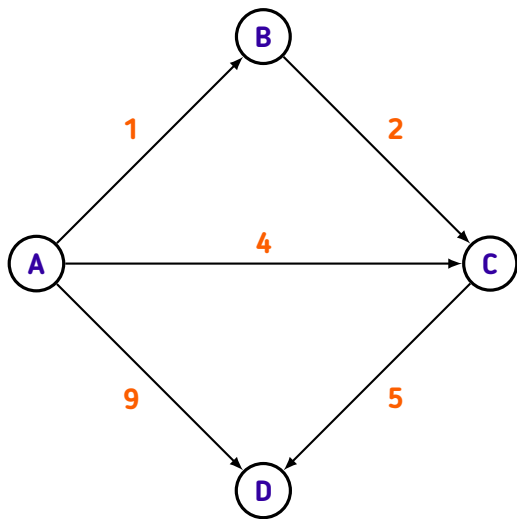


$\text{dist}(u, \mathbf{A})$

| A | B | C | D |
|---|---|---|---|
| 0 | 1 | 3 | 8 |

$\text{pred}(u)$

| A | B | C | D |
|---|---|---|---|
| A | A | B | C |

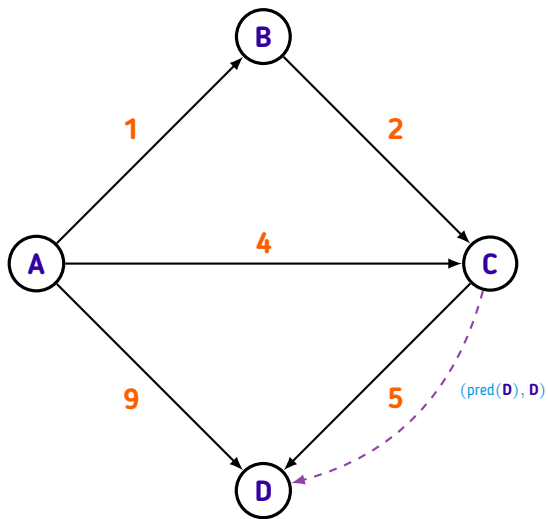


$\text{dist}(u, \mathbf{A})$

| A | B | C | D |
|---|---|---|---|
| 0 | 1 | 3 | 8 |

$\text{pred}(u)$

| A | B | C | D |
|---|---|---|---|
| A | A | B | C |

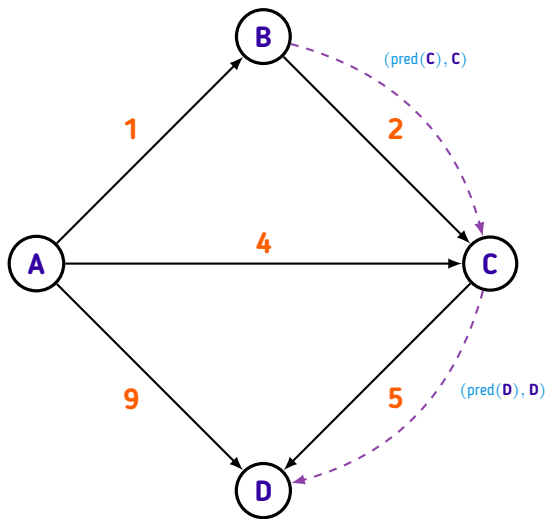


$\text{dist}(u, \mathbf{A})$

| A | B | C | D |
|---|---|---|---|
| 0 | 1 | 3 | 8 |

$\text{pred}(u)$

| A | B | C | D |
|---|---|---|---|
| A | A | B | C |

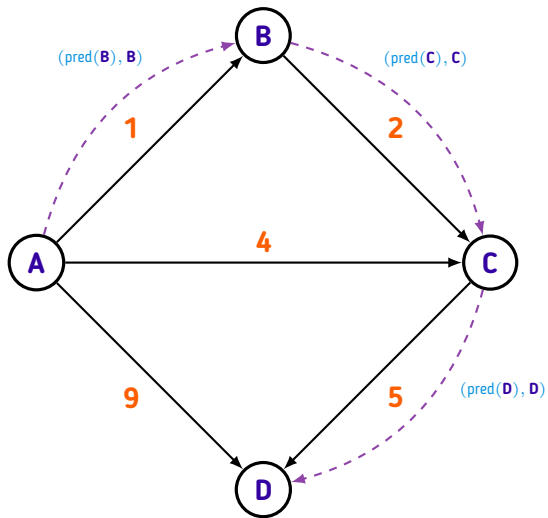


$\text{dist}(u, \text{A})$

| A | B | C | D |
|---|---|---|---|
| 0 | 1 | 3 | 8 |

$\text{pred}(u)$

| A | B | C | D |
|---|---|---|---|
| A | A | B | C |



$\text{dist}(u, \mathbf{A})$

| A | B | C | D |
|---|---|---|---|
| 0 | 1 | 3 | 8 |

$\text{pred}(u)$

| A | B | C | D |
|---|---|---|---|
| A | A | B | C |

```
pair<vector<int>, vector<int>> dijkstra(int s, int N)
{
    vector<int> dist(N + 1, oo), pred(N + 1, oo);
    dist[s] = 0;
    pred[s] = s;

    processed.reset();

    priority_queue<ii, vector<ii>, greater<ii>> pq;
    pq.emplace(0, s);

    while (not pq.empty())
    {
        auto [d, u] = pq.top();
        pq.pop();
```

```
    if (processed[u])
        continue;

    processed[u] = true;

    for (auto [v, w] : adj[u])
    {
        if (dist[v] > d + w) {
            dist[v] = d + w;
            pred[v] = u;
            pq.emplace(dist[v], v);
        }
    }
}

return { dist, pred };
}
```



```
vector<ii> path(int s, int u, const vector<int>& pred)
{
    vector<ii> p;
    int v = u;

    do {
        p.push_back(ii(pred[v], v));
        v = pred[v];
    } while (v != s);

    reverse(p.begin(), p.end());

    return p;
}
```

## Problemas sugeridos

1. [AtCoder Beginner Contest 143 – Problem E: Travel by Car](#)
2. [Codeforces Alpha Round #20 – Problem C: Dijkstra?](#)
3. [OJ 1112 – Mice and Maze](#)
4. [OJ 10986 – Sending email](#)

## Referências

1. HALIM, Felix; HALIM, Steve. *Competitive Programming 3*, 2010.
2. LAAKSONEN, Antti. *Competitive Programmer's Handbook*, 2018.
3. SKIENA, Steven; REVILLA, Miguel. *Programming Challenges*, 2003.
4. Wikipédia, *Dijkstra's algorithm*. Acesso em 13/07/2021.
5. Wikipédia, *Edsger W. Dijkstra*. Acesso em 13/07/2021.