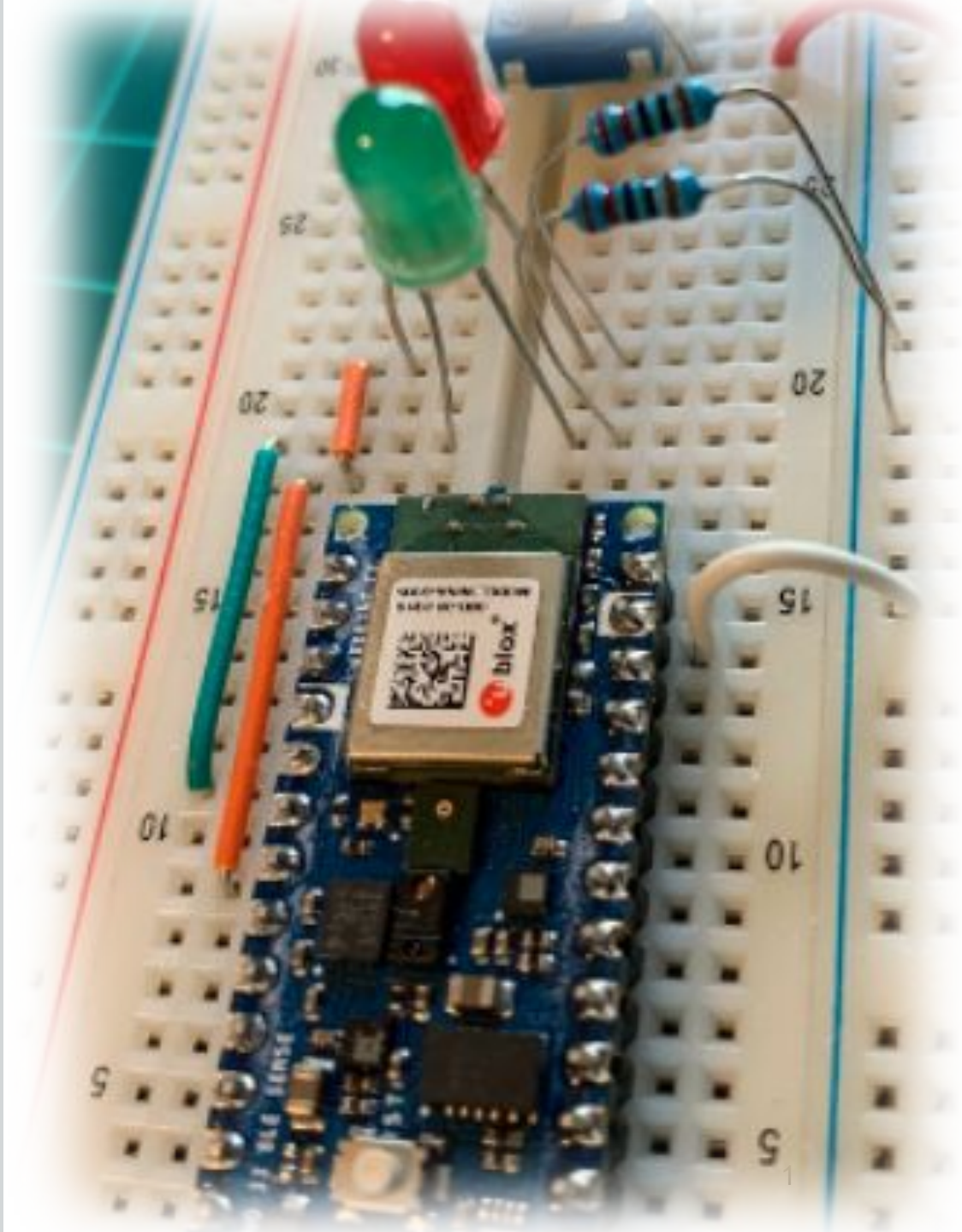
IESTI01 – TinyML

Embedded Machine Learning

26.a Person Detection (VWW) Application



Prof. Marcelo Rovai
UNIFEI

Person Detection:
Application Architecture

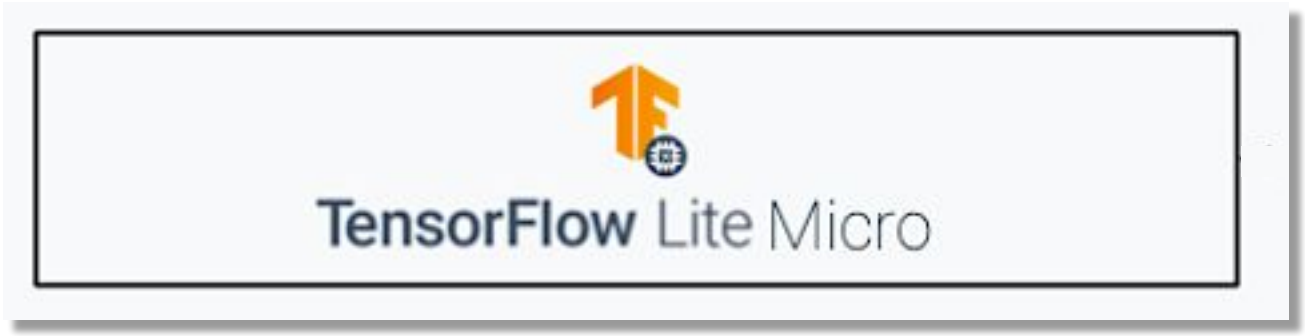
✔

X

Person Detection using Transfer Learning Model

Code Walkthrough!

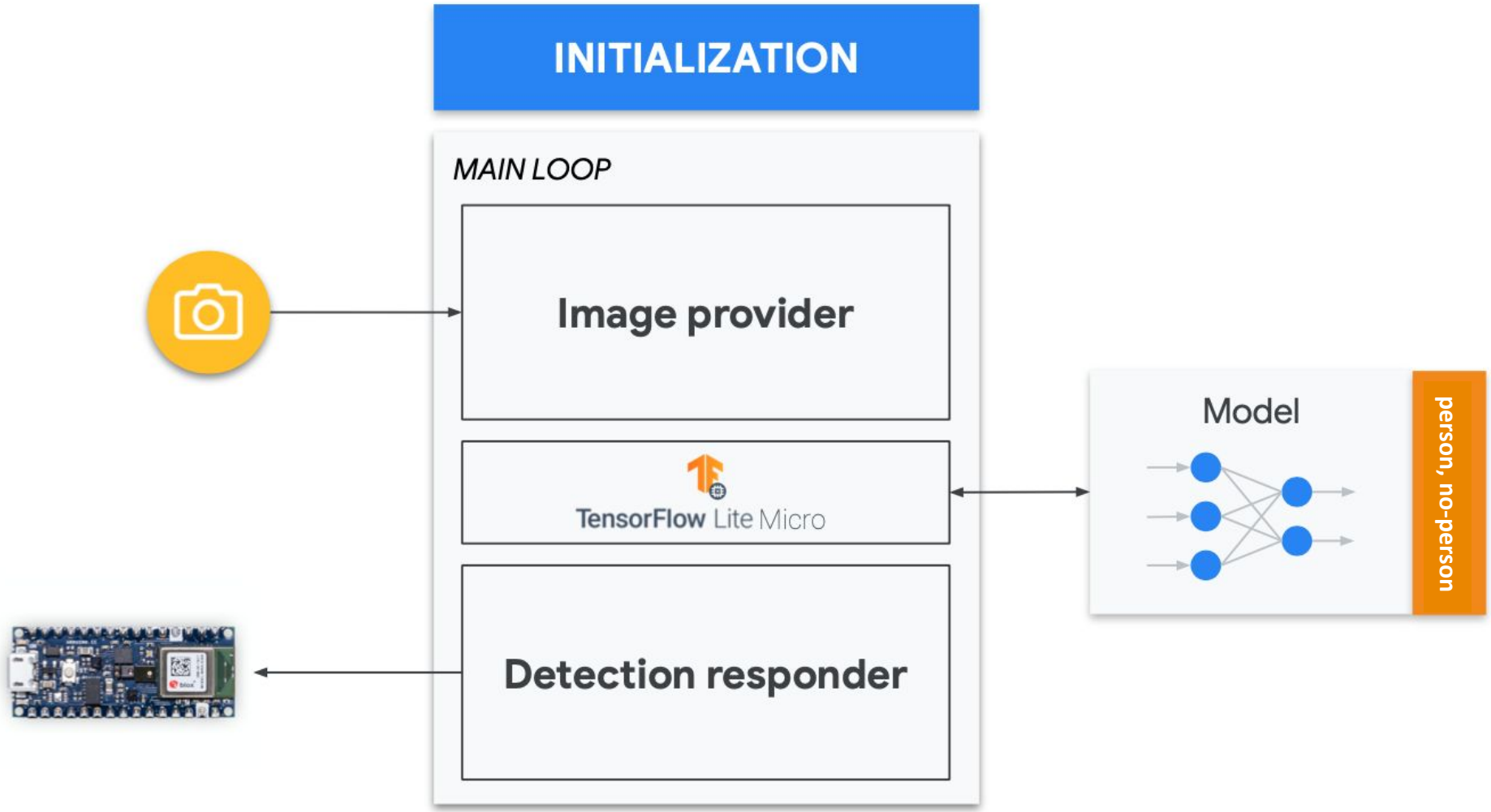
person_detection.ino (Arduino IDE TFLite Example)



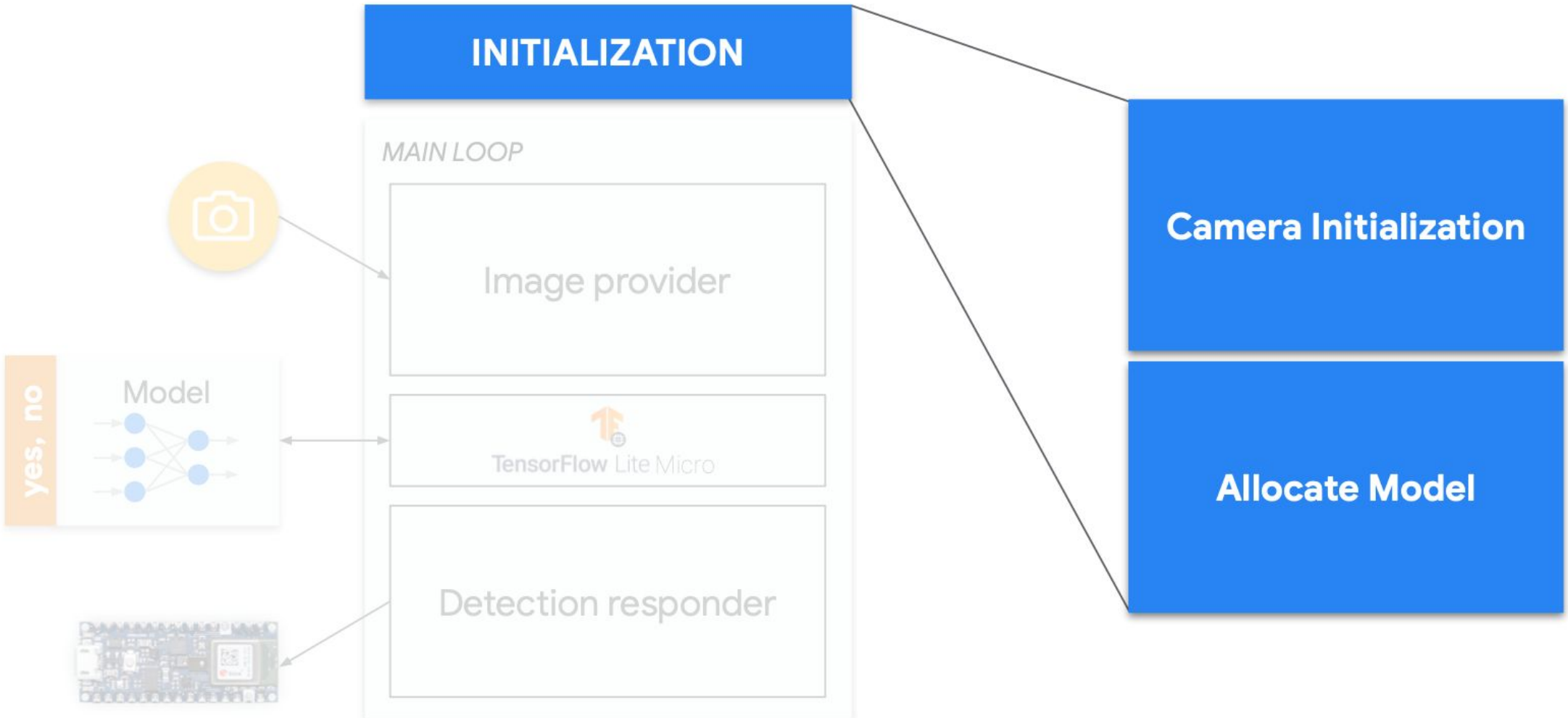
TensorFlow Lite Micro - Paper

MLSys 2021: TensorFlow Lite Micro TFLM

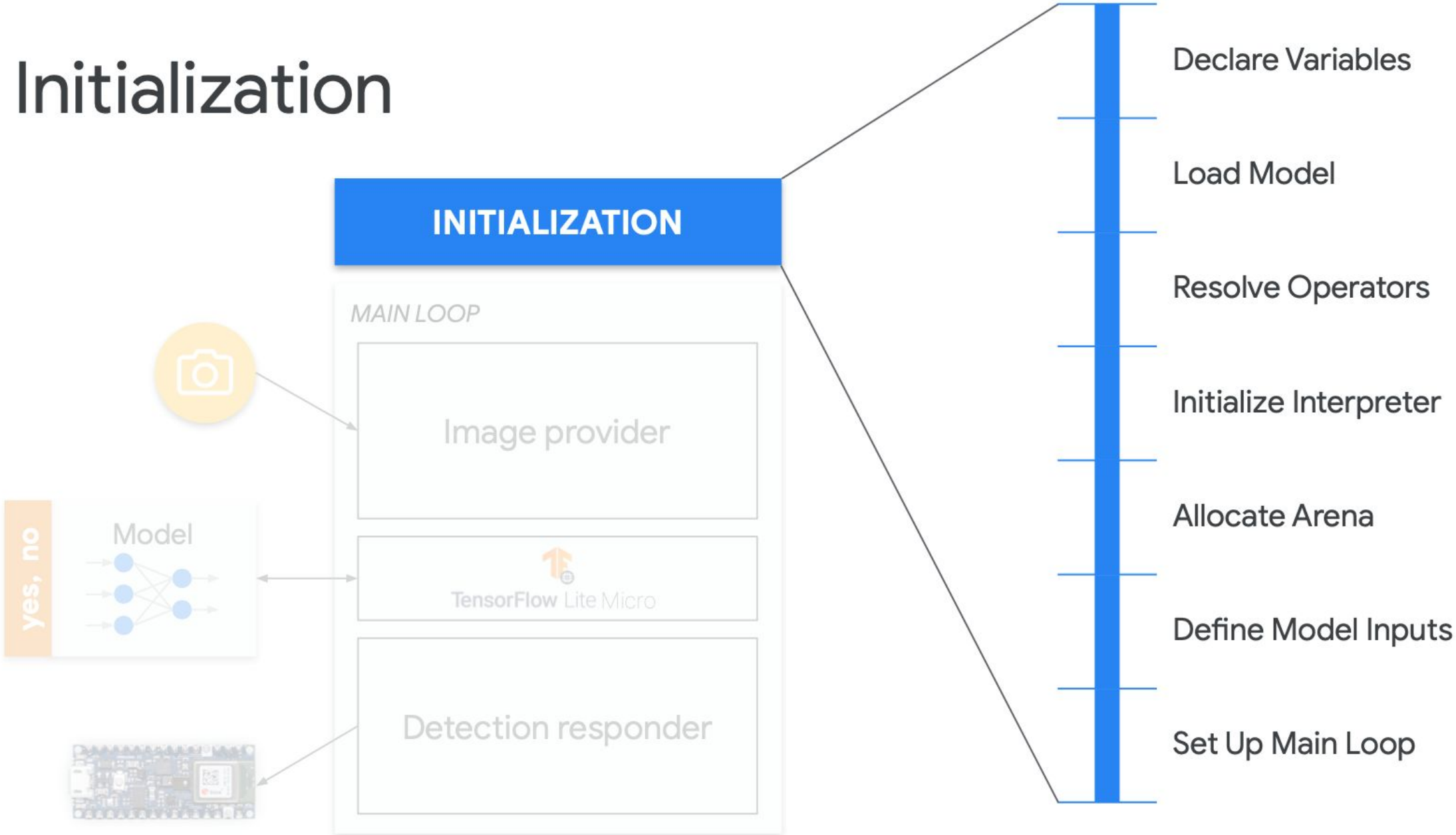
Person Detection **Components**



Initialization



Initialization

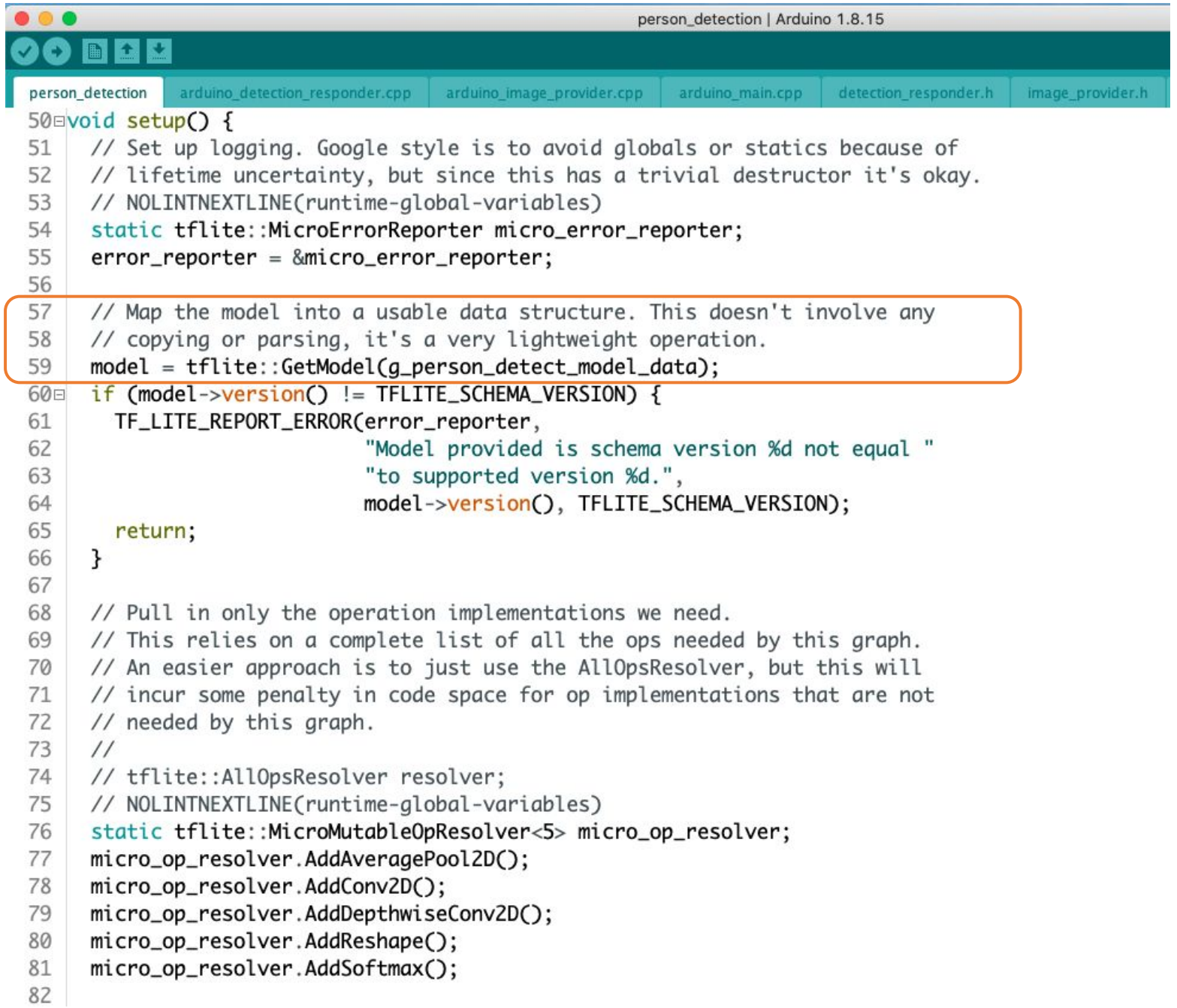


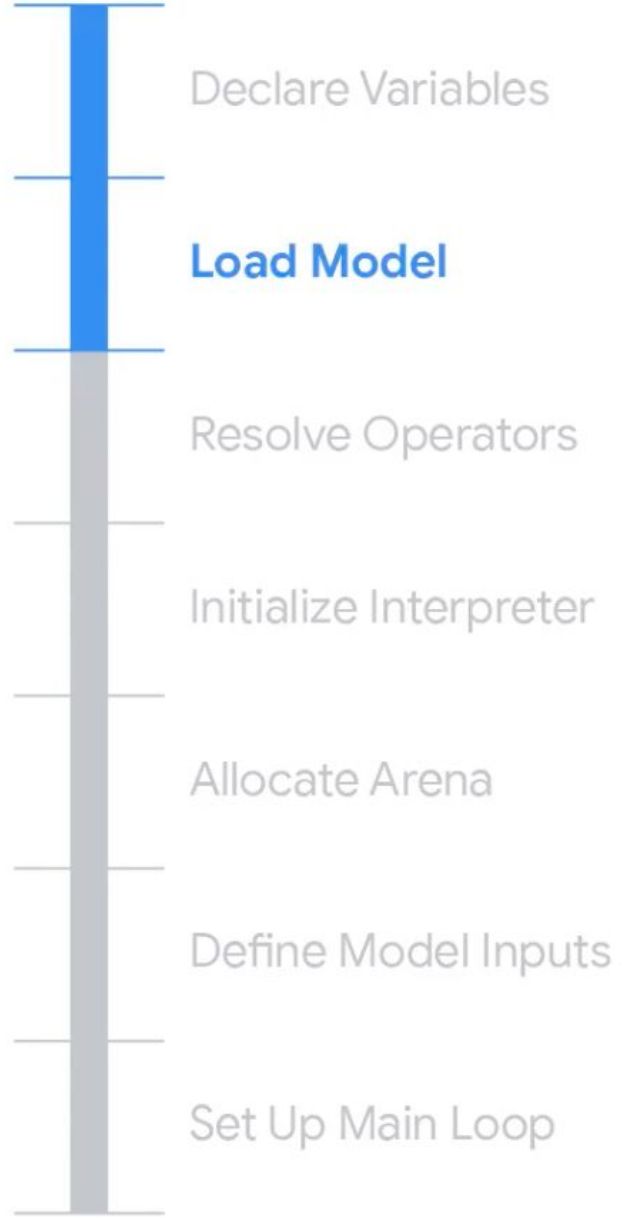
person_detection | Arduino 1.8.15

person_detection | arduino_detection_responder.cpp | arduino_image_provider.cpp | arduino_main.cpp | detection_responder.h | image_provider.h

```
15
16 #include <TensorFlowLite.h>
17
18 #include "main_functions.h"
19
20 #include "detection_responder.h"
21 #include "image_provider.h"
22 #include "model_settings.h"
23 #include "person_detect_model_data.h"
24 #include "tensorflow/lite/micro/micro_error_reporter.h"
25 #include "tensorflow/lite/micro/micro_interpreter.h"
26 #include "tensorflow/lite/micro/micro_mutable_op_resolver.h"
27 #include "tensorflow/lite/schema/schema_generated.h"
28 #include "tensorflow/lite/version.h"
29
30 // Globals, used for compatibility with Arduino-style sketches.
31 namespace {
32 tflite::ErrorReporter* error_reporter = nullptr;
33 const tflite::Model* model = nullptr;
34 tflite::MicroInterpreter* interpreter = nullptr;
35 TfLiteTensor* input = nullptr;
36
37 // In order to use optimized tensorflow lite kernels, a signed int8_t quantized
38 // model is preferred over the legacy unsigned model format. This means that
39 // throughout this project, input images must be converted from unisgned to
40 // signed format. The easiest and quickest way to convert from unsigned to
41 // signed 8-bit integers is to subtract 128 from the unsigned value to get a
42 // signed value.
43
44 // An area of memory to use for input, output, and intermediate arrays.
45 constexpr int kTensorArenaSize = 136 * 1024;
46 static uint8_t tensor_arena[kTensorArenaSize];
47 } // namespace
48
```

- **Declare Variables**
- Load Model
- Resolve Operators
- Initialize Interpreter
- Allocate Arena
- Define Model Inputs
- Set Up Main Loop


person_detection | Arduino 1.8.15
person_detection
arduino_detection_responder.cpp
arduino_image_provider.cpp
arduino_main.cpp
detection_responder.h
image_provider.h
50 void setup() {
51 // Set up logging. Google style is to avoid globals or statics because of
52 // lifetime uncertainty, but since this has a trivial destructor it's okay.
53 // NOLINTNEXTLINE(runtime-global-variables)
54 static tflite::MicroErrorReporter micro_error_reporter;
55 error_reporter = &micro_error_reporter;
56
57 // Map the model into a usable data structure. This doesn't involve any
58 // copying or parsing, it's a very lightweight operation.
59 model = tflite::GetModel(g_person_detect_model_data);
60 if (model->version() != TFLITE_SCHEMA_VERSION) {
61 TF_LITE_REPORT_ERROR(error_reporter,
62 "Model provided is schema version %d not equal "
63 "to supported version %d.",
64 model->version(), TFLITE_SCHEMA_VERSION);
65 return;
66 }
67
68 // Pull in only the operation implementations we need.
69 // This relies on a complete list of all the ops needed by this graph.
70 // An easier approach is to just use the AllOpsResolver, but this will
71 // incur some penalty in code space for op implementations that are not
72 // needed by this graph.
73 //
74 // tflite::AllOpsResolver resolver;
75 // NOLINTNEXTLINE(runtime-global-variables)
76 static tflite::MicroMutableOpResolver<5> micro_op_resolver;
77 micro_op_resolver.AddAveragePool2D();
78 micro_op_resolver.AddConv2D();
79 micro_op_resolver.AddDepthwiseConv2D();
80 micro_op_resolver.AddReshape();
81 micro_op_resolver.AddSoftmax();
82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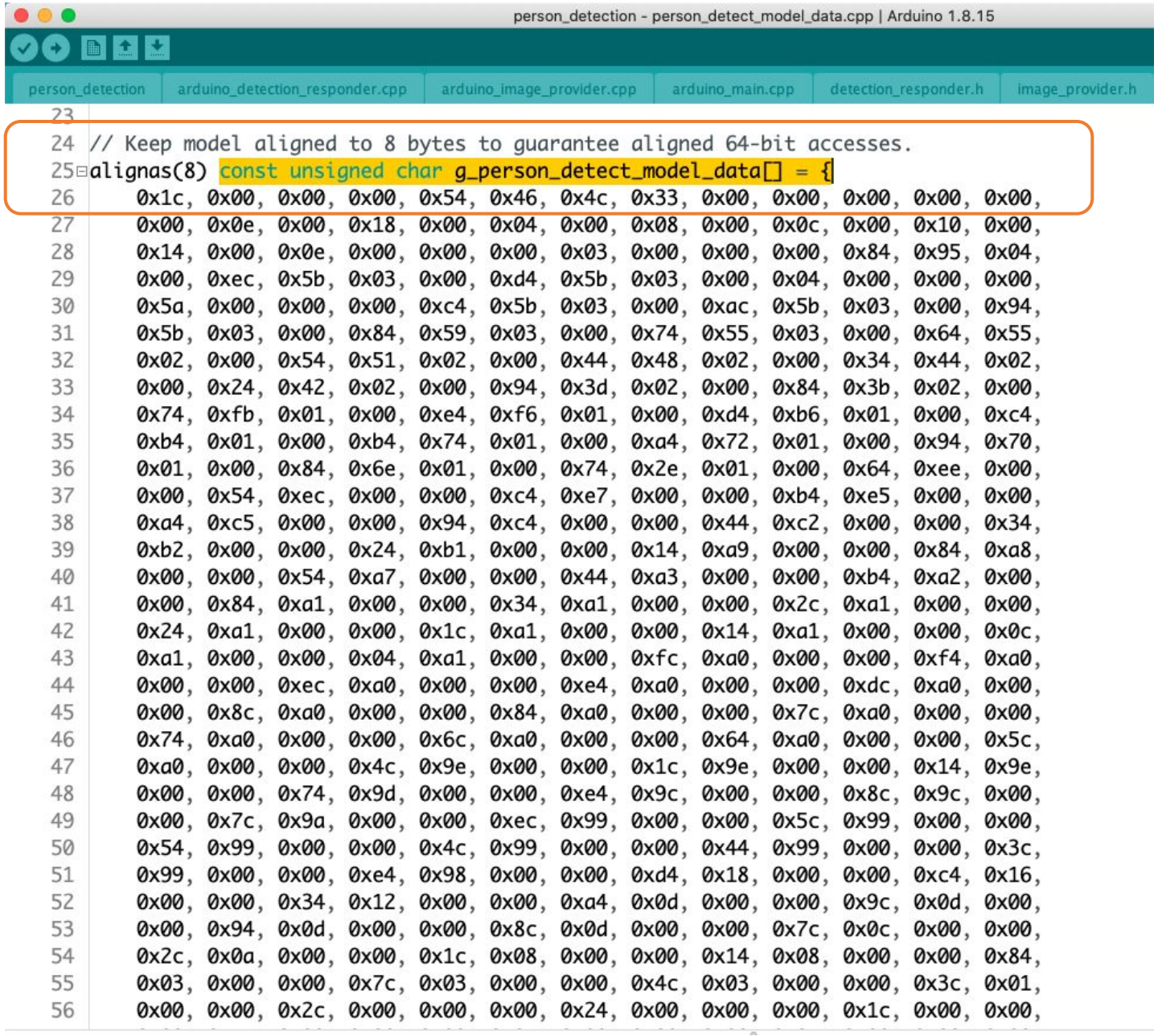
person_detection - person_detect_model_data.cpp | Arduino 1.8.15
person_detection
arduino_detection_responder.cpp
arduino_image_provider.cpp
arduino_main.cpp
detection_responder.h
image_provider.h
// Keep model aligned to 8 bytes to guarantee aligned 64-bit accesses.
alignas(8) const unsigned char g_person_detect_model_data[] = {
0x1c, 0x00, 0x00, 0x00, 0x54, 0x46, 0x4c, 0x33, 0x00, 0x00, 0x00, 0x00, 0x00,
0x00, 0x0e, 0x00, 0x18, 0x00, 0x04, 0x00, 0x08, 0x00, 0x0c, 0x00, 0x10, 0x00,
0x14, 0x00, 0x0e, 0x00, 0x00, 0x00, 0x03, 0x00, 0x00, 0x00, 0x84, 0x95, 0x04,
0x00, 0xec, 0x5b, 0x03, 0x00, 0xd4, 0x5b, 0x03, 0x00, 0x04, 0x00, 0x00, 0x00,
0x5a, 0x00, 0x00, 0x00, 0xc4, 0x5b, 0x03, 0x00, 0xac, 0x5b, 0x03, 0x00, 0x94,
0x5b, 0x03, 0x00, 0x84, 0x59, 0x03, 0x00, 0x74, 0x55, 0x03, 0x00, 0x64, 0x55,
0x02, 0x00, 0x54, 0x51, 0x02, 0x00, 0x44, 0x48, 0x02, 0x00, 0x34, 0x44, 0x02,
0x00, 0x24, 0x42, 0x02, 0x00, 0x94, 0x3d, 0x02, 0x00, 0x84, 0x3b, 0x02, 0x00,
0x74, 0xfb, 0x01, 0x00, 0xe4, 0xf6, 0x01, 0x00, 0xd4, 0xb6, 0x01, 0x00, 0xc4,
0xb4, 0x01, 0x00, 0xb4, 0x74, 0x01, 0x00, 0xa4, 0x72, 0x01, 0x00, 0x94, 0x70,
0x01, 0x00, 0x84, 0x6e, 0x01, 0x00, 0x74, 0x2e, 0x01, 0x00, 0x64, 0xee, 0x00,
0x00, 0x54, 0xec, 0x00, 0x00, 0xc4, 0xe7, 0x00, 0x00, 0xb4, 0xe5, 0x00, 0x00,
0xa4, 0xc5, 0x00, 0x00, 0x94, 0xc4, 0x00, 0x00, 0x44, 0xc2, 0x00, 0x00, 0x34,
0xb2, 0x00, 0x00, 0x24, 0xb1, 0x00, 0x00, 0x14, 0xa9, 0x00, 0x00, 0x84, 0xa8,
0x00, 0x00, 0x54, 0xa7, 0x00, 0x00, 0x44, 0xa3, 0x00, 0x00, 0xb4, 0xa2, 0x00,
0x00, 0x84, 0xa1, 0x00, 0x00, 0x34, 0xa1, 0x00, 0x00, 0x2c, 0xa1, 0x00, 0x00,
0x24, 0xa1, 0x00, 0x00, 0x1c, 0xa1, 0x00, 0x00, 0x14, 0xa1, 0x00, 0x00, 0x0c,
0xa1, 0x00, 0x00, 0x04, 0xa1, 0x00, 0x00, 0xfc, 0xa0, 0x00, 0x00, 0xf4, 0xa0,
0x00, 0x00, 0xec, 0xa0, 0x00, 0x00, 0xe4, 0xa0, 0x00, 0x00, 0xdc, 0xa0, 0x00,
0x00, 0x8c, 0xa0, 0x00, 0x00, 0x84, 0xa0, 0x00, 0x00, 0x7c, 0xa0, 0x00, 0x00,
0x74, 0xa0, 0x00, 0x00, 0x6c, 0xa0, 0x00, 0x00, 0x64, 0xa0, 0x00, 0x00, 0x5c,
0xa0, 0x00, 0x00, 0x4c, 0x9e, 0x00, 0x00, 0x1c, 0x9e, 0x00, 0x00, 0x14, 0x9e,
0x00, 0x00, 0x74, 0x9d, 0x00, 0x00, 0xe4, 0x9c, 0x00, 0x00, 0x8c, 0x9c, 0x00,
0x00, 0x7c, 0x9a, 0x00, 0x00, 0xec, 0x99, 0x00, 0x00, 0x5c, 0x99, 0x00, 0x00,
0x54, 0x99, 0x00, 0x00, 0x4c, 0x99, 0x00, 0x00, 0x44, 0x99, 0x00, 0x00, 0x3c,
0x99, 0x00, 0x00, 0xe4, 0x98, 0x00, 0x00, 0xd4, 0x18, 0x00, 0x00, 0xc4, 0x16,
0x00, 0x00, 0x34, 0x12, 0x00, 0x00, 0xa4, 0x0d, 0x00, 0x00, 0x9c, 0x0d, 0x00,
0x00, 0x94, 0x0d, 0x00, 0x00, 0x8c, 0x0d, 0x00, 0x00, 0x7c, 0x0c, 0x00, 0x00,
0x2c, 0x0a, 0x00, 0x00, 0x1c, 0x08, 0x00, 0x00, 0x14, 0x08, 0x00, 0x00, 0x84,
0x03, 0x00, 0x00, 0x7c, 0x03, 0x00, 0x00, 0x4c, 0x03, 0x00, 0x00, 0x3c, 0x01,
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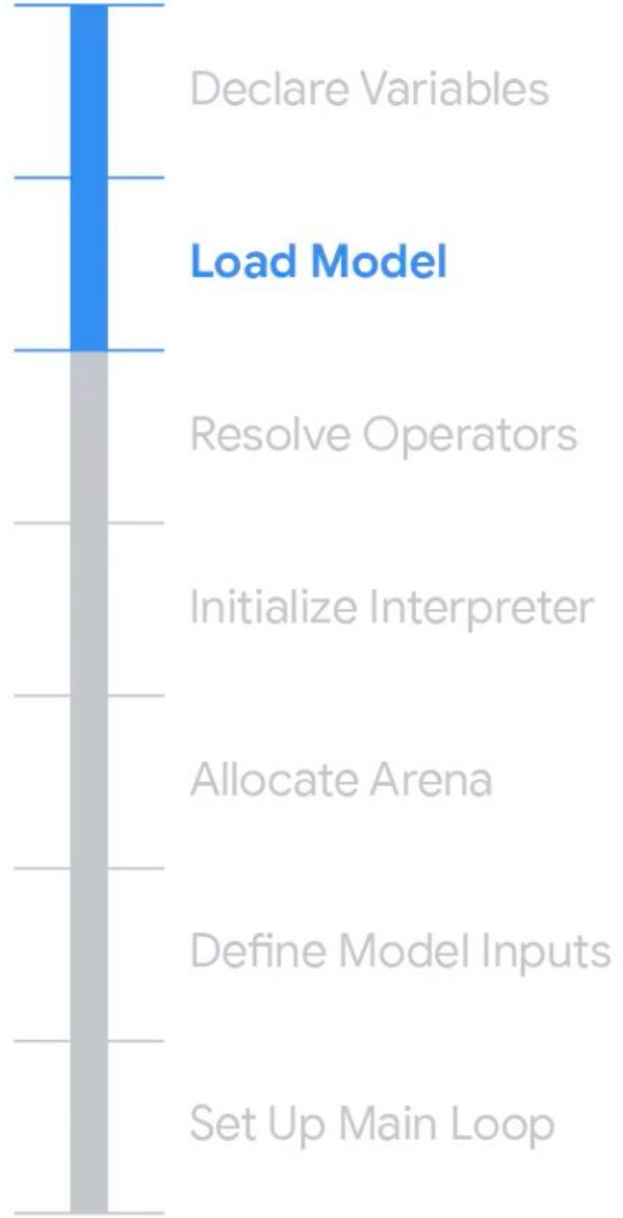
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83  // Build an interpreter to run the model with.
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85  static tflite::MicroInterpreter static_interpreter(
86      model, micro_op_resolver, tensor_arena, kTensorArenaSize, error_reporter);
87  interpreter = &static_interpreter;
88
89  // Allocate memory from the tensor_arena for the model's tensors.
90  TfLiteStatus allocate_status = interpreter->AllocateTensors();
91  if (allocate_status != kTfLiteOk) {
92    TF_LITE_REPORT_ERROR(error_reporter, "AllocateTensors() failed");
93    return;
94  }
95
96  // Get information about the memory area to use for the model's input.
97  input = interpreter->input(0);
98 }
99
```

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Initialization

Camera Initialization

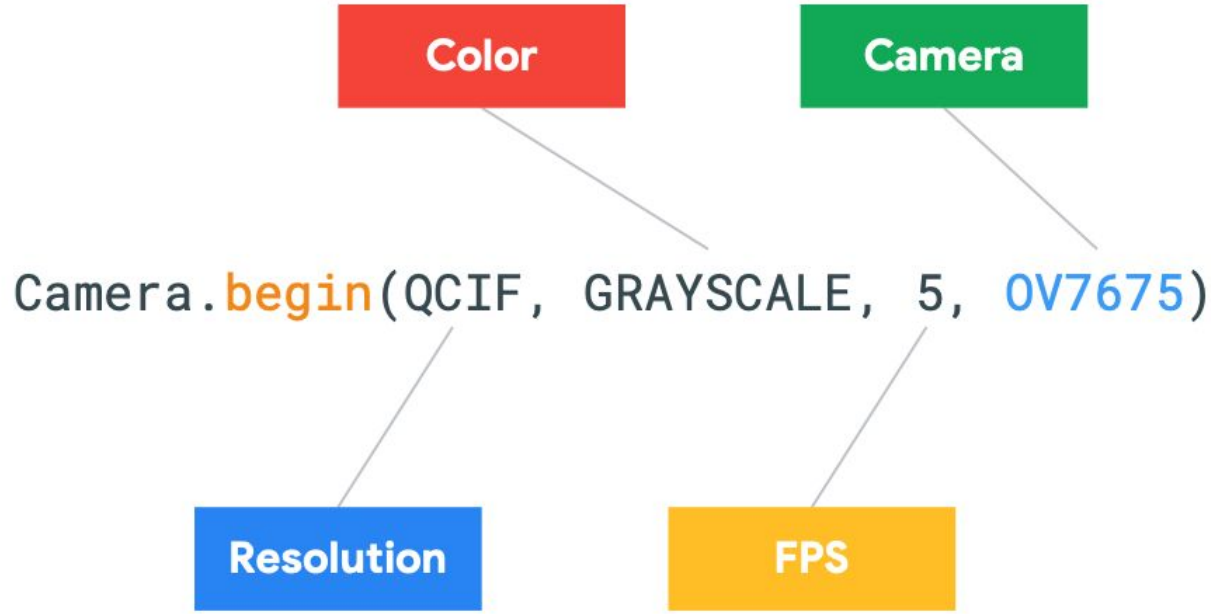
Allocate Model

```
// Initialize camera if necessary
if (!g_is_camera_initialized) {
  if (!Camera.begin(QCIF, GRAYSCALE, 5, OV7675)) {
    TF_LITE_REPORT_ERROR(error_reporter, "Failed to
                                  initialize
                                camera!");
    return kTfLiteError;
  }
  g_is_camera_initialized = true;
}
```

Initialization

Camera Initialization

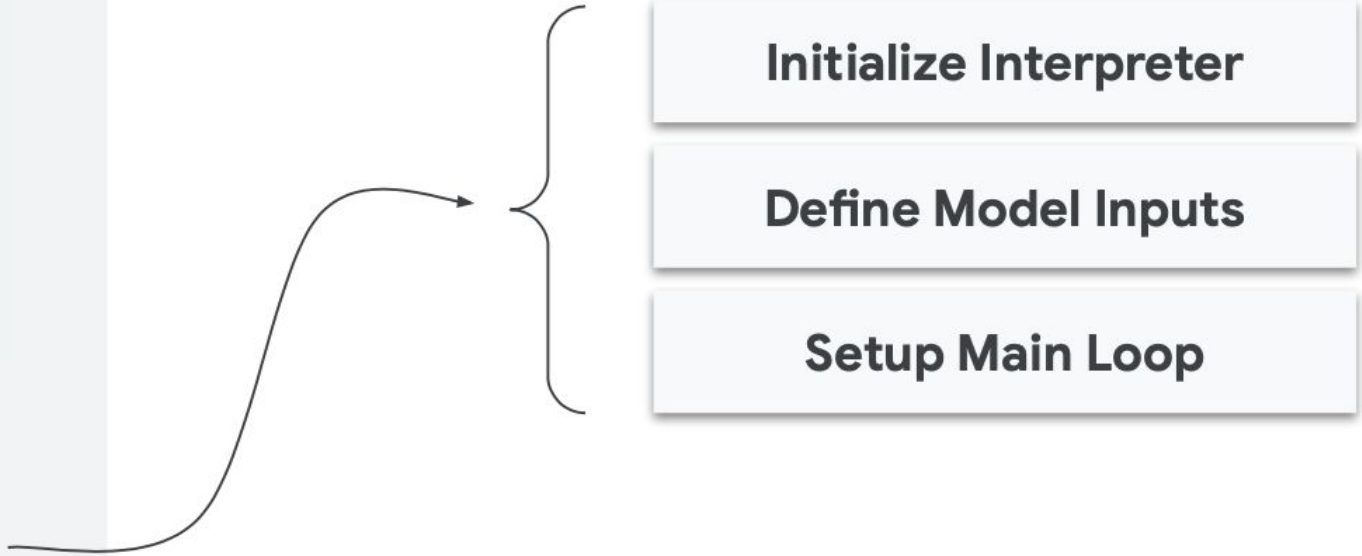
Allocate Model



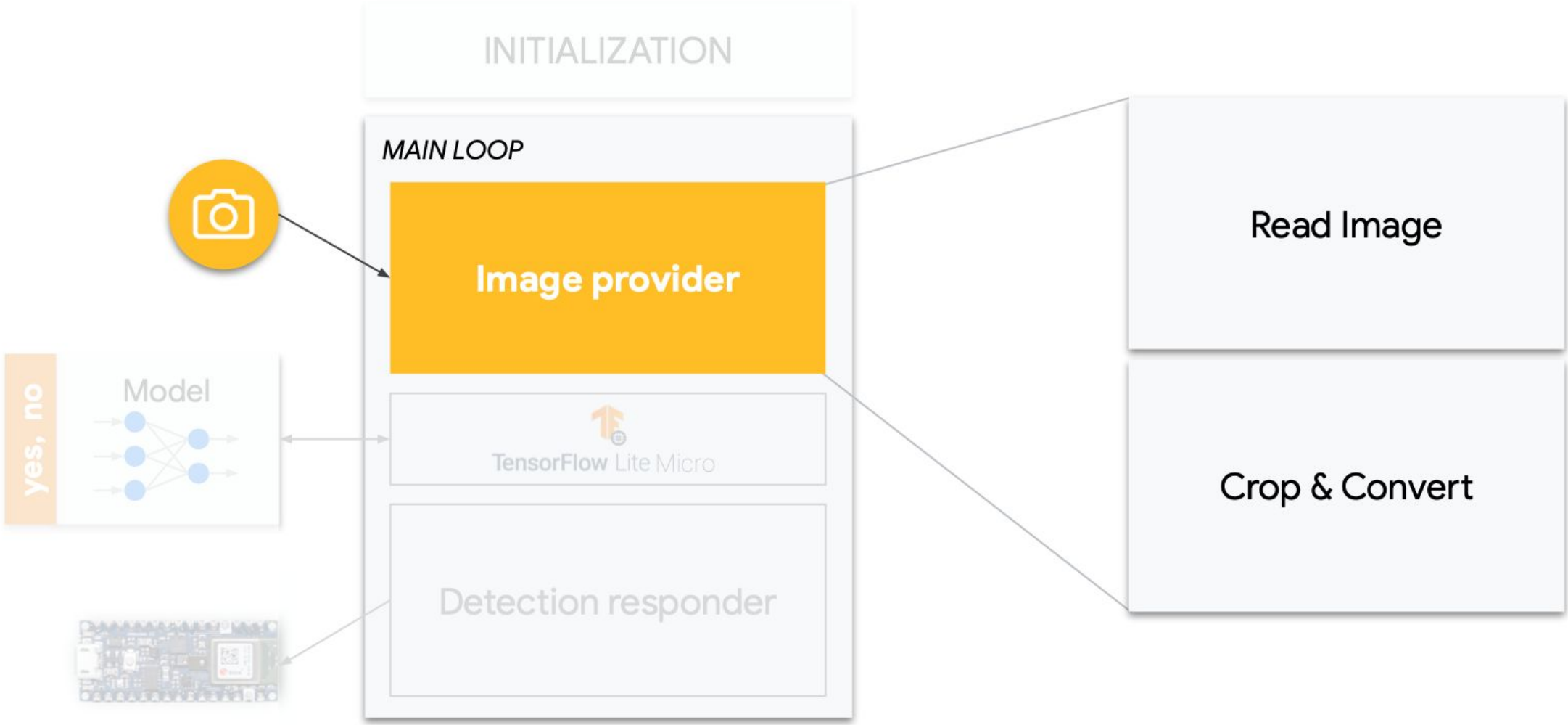
Initialization

Camera Initialization

Allocate Model



Pre-processing



Pre-processing

Read Image

Crop & Convert

```
// Get an image from the camera module
TfLiteStatus GetImage(tflite::ErrorReporter* error_reporter,
          int image_width, int image_height, int channels,
          int8_t* image_data)
```

Pre-processing

Read Image

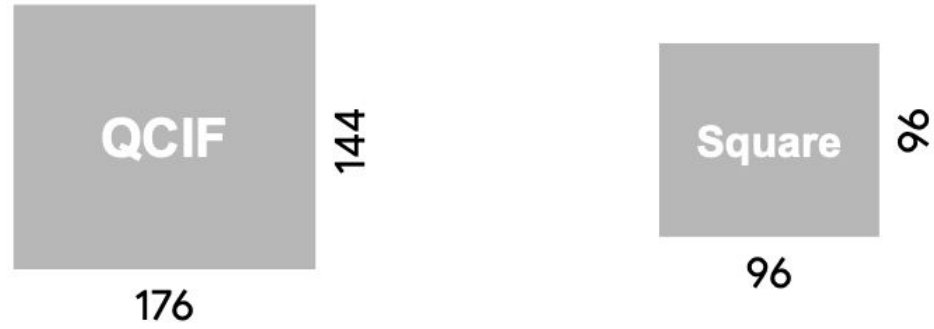
Crop & Convert

```
// Read camera data
Camera.readFrame(data);
```

Pre-processing

Read Image

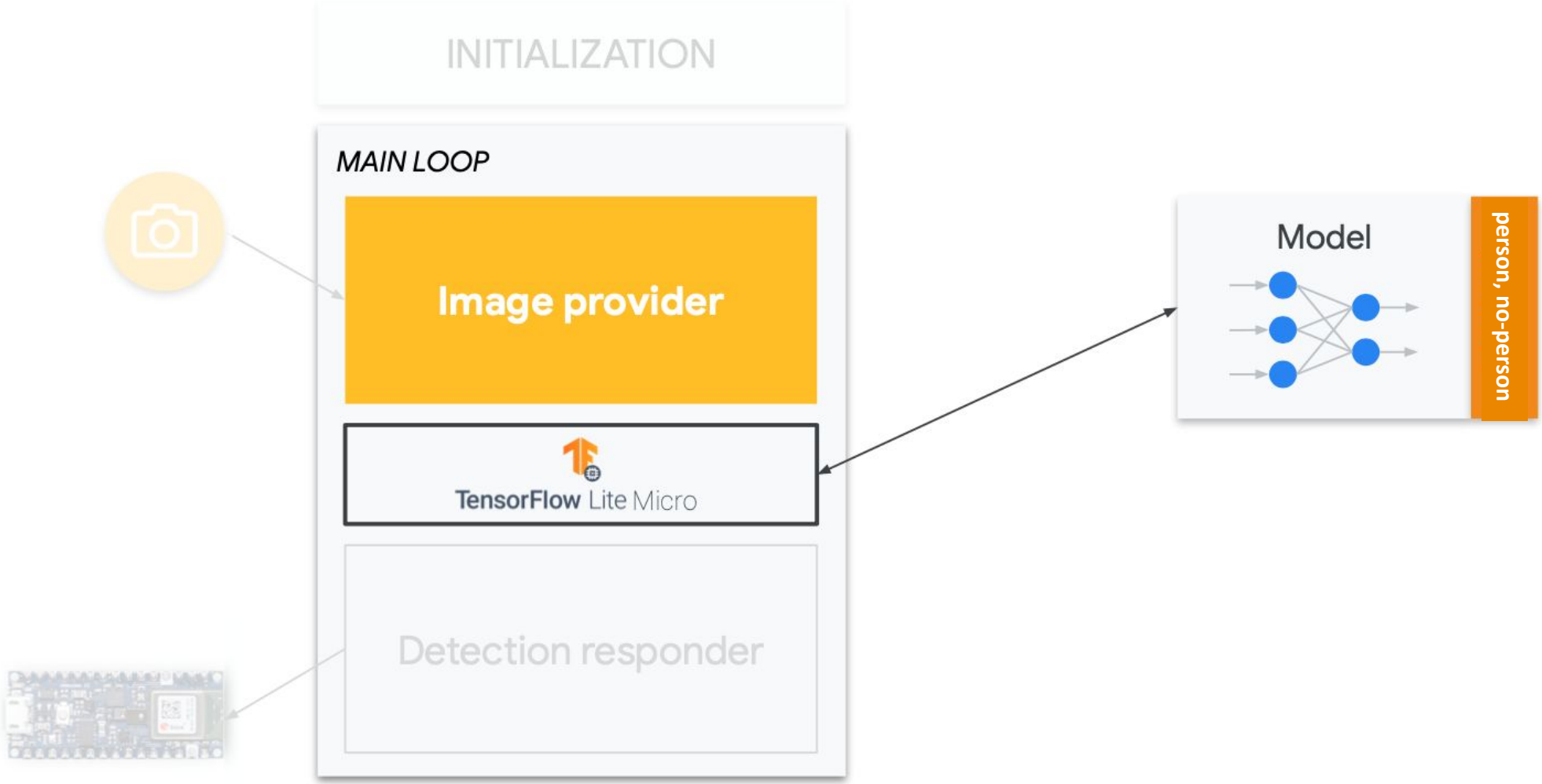
Crop & Convert




```
int min_x = (176 - 96) / 2;
int min_y = (144 - 96) / 2;
int index = 0;

// Crop 96x96 image. This lowers FOV, ideally we should downsample
for (int y = min_y; y < min_y + 96; y++) {
  for (int x = min_x; x < min_x + 96; x++) {
    image_data[index++] = static_cast<int8_t>(data[(y * 176) + x] - 128);
    // convert TF input image to signed 8-bit
  }
}
```

Interpreter + Model



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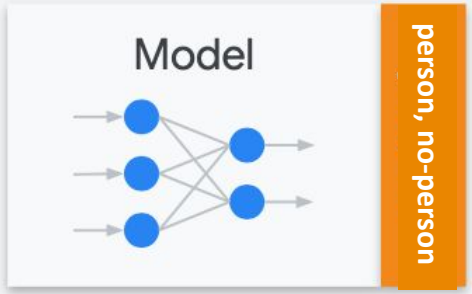
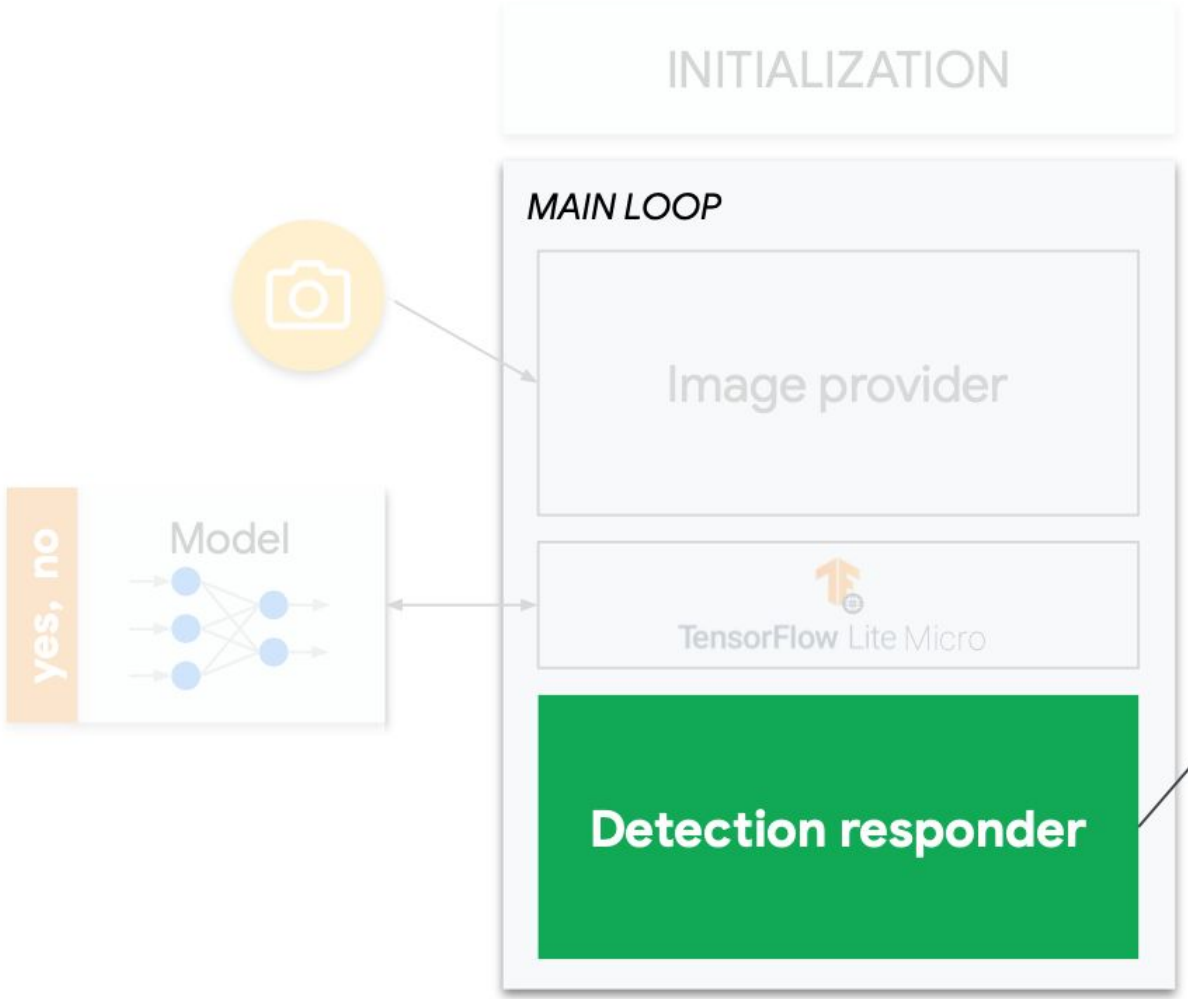



```
kTfLiteOk != vww_interpreter->Invoke()
```

Post-processing




```
113  TfLiteTensor* output = interpreter->output(0);
114
115  // Process the inference results.
116  int8_t person_score = output->data.uint8[kPersonIndex];
117  int8_t no_person_score = output->data.uint8[kNotAPersonIndex];
118  RespondToDetection(error_reporter, person_score, no_person_score);
```

Detection responder

```
if (person_score > no_person_score) {
  digitalWrite(LEDG, LOW);
  digitalWrite(LEDR, HIGH);
} else {
  digitalWrite(LEDG, HIGH);
  digitalWrite(LEDR, LOW);
}
```

Reading Material

Main references

- Harvard School of Engineering and Applied Sciences - CS249r: Tiny Machine Learning
- Professional Certificate in Tiny Machine Learning (TinyML) – edX/Harvard
- Introduction to Embedded Machine Learning (Coursera)
- Text Book: "TinyML" by Pete Warden, Daniel Situnayake

I want to thank Shawn Hymel and Edge Impulse, Pete Warden and Laurence Moroney from Google, and especially Harvard professor Vijay Janapa Reddi, Ph.D. student Brian Plancher and their staff for preparing the excellent material on TinyML that is the basis of this course at UNIFEI.

The IESTI01 course is part of the TinyML4D, an initiative to make TinyML education available to everyone globally.

Thanks

And stay safe!

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