

Kernel PCA and related methods

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Lecture 9

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- Classical linear PCA analysis
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Classical PCA formulation (1)

- Given data $\{x_k\}_{k=1}^N$ with $x_k \in \mathbb{R}^n$ (zero mean)
- Find projected variables $w^T x_k$ with maximal variance

$$\max_w \text{Var}(w^T x) = \text{Cov}(w^T x, w^T x) \simeq \frac{1}{N} \sum_{k=1}^N (w^T x_k)^2 = w^T C w$$

where $C = (1/N) \sum_{k=1}^N x_k x_k^T$. Take constraint $w^T w = 1$.

- Constrained optimization: Lagrangian $\mathcal{L}(w; \lambda) = \frac{1}{2} w^T C w - \lambda(w^T w - 1)$ with Lagrange multiplier λ .
- Eigenvalue problem

$$Cw = \lambda w$$

with $C = C^T \succeq 0$, obtained from $\partial \mathcal{L} / \partial w = 0$, $\partial \mathcal{L} / \partial \lambda = 0$.

Classical PCA formulation (2)

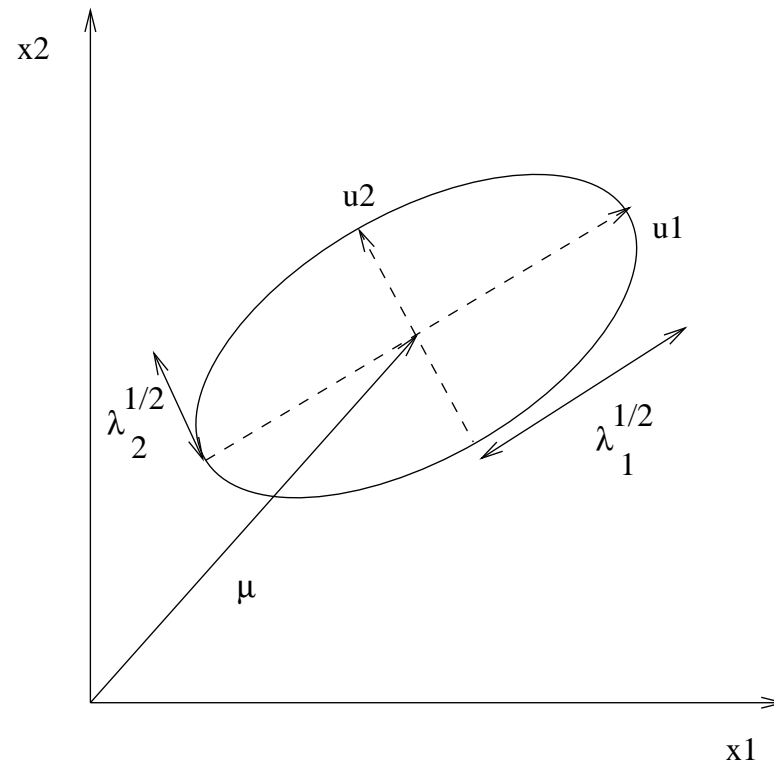


Illustration of an eigenvalue decomposition

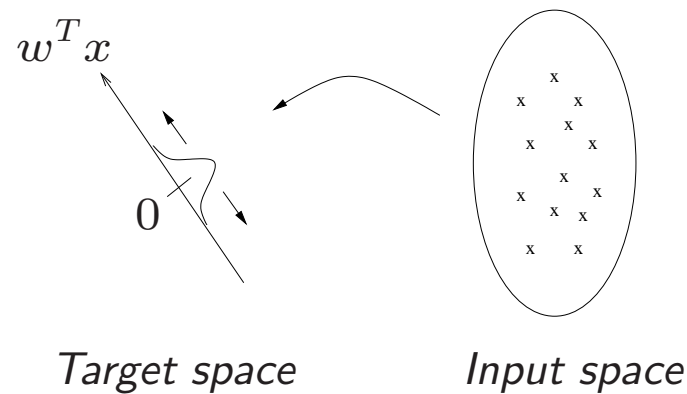
$$Cu = \lambda u$$

PCA analysis as a one-class modelling problem (1)

- One-class with target value zero:

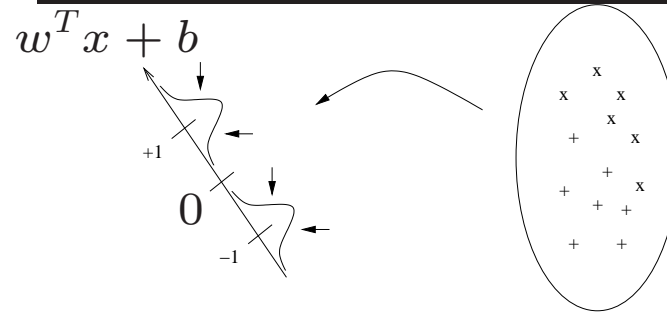
$$\max_w \sum_{k=1}^N (0 - w^T x_k)^2$$

- Score variables: $z = w^T x$
- Illustration:



PCA analysis as a one-class modelling problem (2)

LS-SVM interpretation to FDA

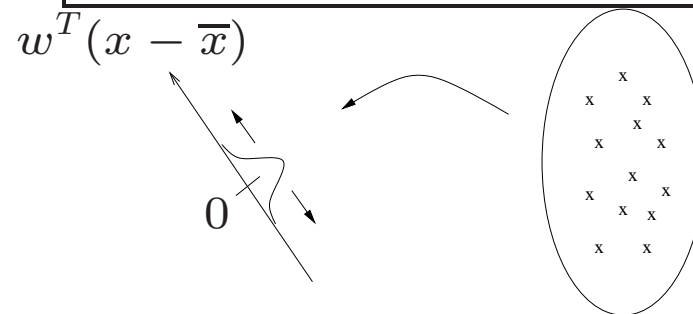


Target space

Input space

Minimize within class scatter

LS-SVM interpretation to PCA



Target space

Input space

Find direction with maximal variance

LS-SVM formulation to linear PCA (1)

- Primal problem:

$$\boxed{\text{P}} : \max_{w, e} J_P(w, e) = \gamma \frac{1}{2} \sum_{k=1}^N e_k^2 - \frac{1}{2} w^T w$$

subject to $e_k = w^T x_k, \quad k = 1, \dots, N$

- Lagrangian $\mathcal{L}(w, e; \alpha) = \gamma \frac{1}{2} \sum_{k=1}^N e_k^2 - \frac{1}{2} w^T w - \sum_{k=1}^N \alpha_k (e_k - w^T x_k)$
- Conditions for optimality

$$\left\{ \begin{array}{ll} \frac{\partial \mathcal{L}}{\partial w} = 0 & \rightarrow w = \sum_{k=1}^N \alpha_k x_k \\ \frac{\partial \mathcal{L}}{\partial e_k} = 0 & \rightarrow \alpha_k = \gamma e_k, \quad k = 1, \dots, N \\ \frac{\partial \mathcal{L}}{\partial \alpha_k} = 0 & \rightarrow e_k - w^T x_k = 0, \quad k = 1, \dots, N \end{array} \right.$$

LS-SVM formulation to linear PCA (2)

- Elimination of variables e, w gives

$$\frac{1}{\gamma}\alpha_k - \sum_{l=1}^N \alpha_l x_l^T x_k = 0, \quad k = 1, \dots, N$$

- After defining $\lambda = 1/\gamma$ one obtains the eigenvalue problem

D : solve in α :

$$\begin{bmatrix} x_1^T x_1 & \dots & x_1^T x_N \\ \vdots & & \vdots \\ x_N^T x_1 & \dots & x_N^T x_N \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_N \end{bmatrix} = \lambda \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_N \end{bmatrix}$$

as the dual problem (quantization in terms of $\lambda = 1/\gamma$).

LS-SVM formulation to linear PCA (3)

- Score variables become

$$z(x) = w^T x = \sum_{l=1}^N \alpha_l x_l^T x$$

- Optimal solution corresponding to largest eigenvalue

$$\sum_{k=1}^N (w^T x_k)^2 = \sum_{k=1}^N e_k^2 = \sum_{k=1}^N \frac{1}{\gamma^2} \alpha_k^2 = \lambda_{max}^2$$

where $\sum_{k=1}^N \alpha_k^2 = 1$ for the normalized eigenvector.

- Many data: better solve primal problem
Many inputs: better solve dual problem

Formulation with bias term (1)

- Usually: apply PCA analysis to *centered data* and consider

$$\max_w \sum_{k=1}^N [w^T (x_k - \hat{\mu}_x)]^2 \text{ where } \hat{\mu}_x = \frac{1}{N} \sum_{k=1}^N x_k.$$

- Bias term formulation: score variables $z(x) = w^T x + b$ and objective

$$\max_{w,b} \sum_{k=1}^N [0 - (w^T x_k + b)]^2$$

- Primal optimization problem

$$\boxed{\text{P}} : \max_{w,b,e} J_P(w, e) = \gamma \frac{1}{2} \sum_{k=1}^N e_k^2 - \frac{1}{2} w^T w$$

subject to $e_k = w^T x_k + b, \quad k = 1, \dots, N$

Formulation with bias term (2)

- Conditions for optimality

$$\left\{ \begin{array}{ll} \frac{\partial \mathcal{L}}{\partial w} = 0 & \rightarrow w = \sum_{k=1}^N \alpha_k x_k \\ \frac{\partial \mathcal{L}}{\partial e_k} = 0 & \rightarrow \alpha_k = \gamma e_k, \quad k = 1, \dots, N \\ \frac{\partial \mathcal{L}}{\partial b} = 0 & \rightarrow \sum_{k=1}^N \alpha_k = 0 \\ \frac{\partial \mathcal{L}}{\partial \alpha_k} = 0 & \rightarrow e_k - w^T x_k - b = 0, \quad k = 1, \dots, N \end{array} \right.$$

- Applying $\sum_{k=1}^N \alpha_k = 0$ yields

$$b = -\frac{1}{N} \sum_{k=1}^N \sum_{l=1}^N \alpha_l x_l^T x_k.$$

Formulation with bias term (3)

- By defining $\lambda = 1/\gamma$ one obtains the dual problem

D

: solve in α :

$$\begin{bmatrix} (x_1 - \hat{\mu}_x)^T(x_1 - \hat{\mu}_x) & \dots & (x_1 - \hat{\mu}_x)^T(x_N - \hat{\mu}_x) \\ \vdots & & \vdots \\ (x_N - \hat{\mu}_x)^T(x_1 - \hat{\mu}_x) & \dots & (x_N - \hat{\mu}_x)^T(x_N - \hat{\mu}_x) \end{bmatrix} \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_N \end{bmatrix} = \lambda \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_N \end{bmatrix}$$

which is an eigenvalue decomposition of the centered Gram matrix

$$\Omega_c \alpha = \lambda \alpha$$

with $\Omega_c = M_c \Omega M_c$ where $M_c = I - 1_v 1_v^T / N$, $1_v = [1; 1; \dots; 1]$ and $\Omega_{kl} = x_k^T x_l$ for $k, l = 1, \dots, N$.

- Score variables: $z(x) = w^T x + b = \sum_{l=1}^N \alpha_l x_l^T x + b$.

Reconstruction problem for linear PCA (1)

- Reconstruction error:

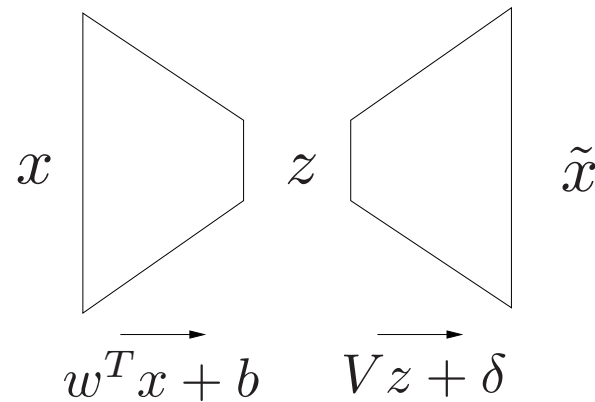
$$\min \sum_{k=1}^N \|x_k - \tilde{x}_k\|_2^2$$

where \tilde{x}_k are variables reconstructed from the score variables, with

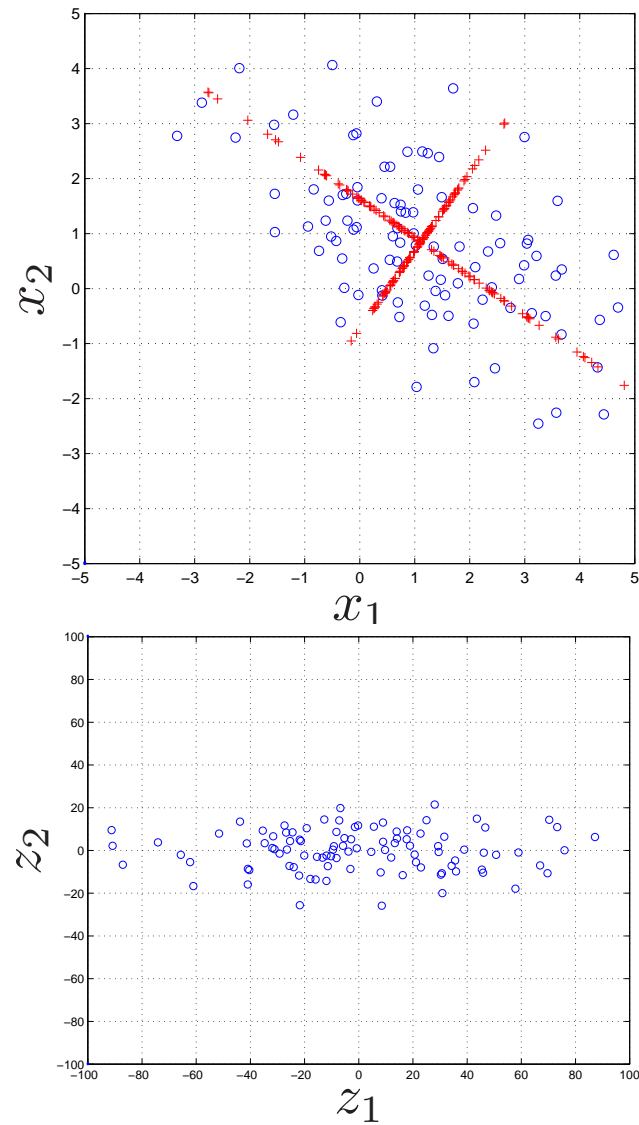
$$\tilde{x} = Vz + \delta$$

Hence $\min_{V, \delta} \sum_{k=1}^N \|x_k - (Vz_k + \delta)\|_2^2$.

- Information bottleneck:



Reconstruction problem for linear PCA (2)



LS-SVM approach to kernel PCA (1)

- Create nonlinear version of the method by
 - Mapping input space to a high dimensional feature space
 - Applying the kernel trick

(kernel PCA - Schölkopf *et al.*; LS-SVM approach - Suykens *et al.*, 2002)

- Primal optimization problem:

$$\boxed{\text{P}} : \max_{w, e} J_P(w, e) = \gamma \frac{1}{2} \sum_{k=1}^N e_k^2 - \frac{1}{2} w^T w$$

subject to $e_k = w^T (\varphi(x_k) - \hat{\mu}_\varphi), \quad k = 1, \dots, N.$

- Lagrangian

$$\mathcal{L}(w, e; \alpha) = \gamma \frac{1}{2} \sum_{k=1}^N e_k^2 - \frac{1}{2} w^T w - \sum_{k=1}^N \alpha_k (e_k - w^T (\varphi(x_k) - \hat{\mu}_\varphi))$$

LS-SVM approach to kernel PCA (2)

- Conditions for optimality

$$\left\{ \begin{array}{ll} \frac{\partial \mathcal{L}}{\partial w} = 0 & \rightarrow w = \sum_{k=1}^N \alpha_k (\varphi(x_k) - \hat{\mu}_\varphi) \\ \frac{\partial \mathcal{L}}{\partial e_k} = 0 & \rightarrow \alpha_k = \gamma e_k, \quad k = 1, \dots, N \\ \frac{\partial \mathcal{L}}{\partial \alpha_k} = 0 & \rightarrow e_k - w^T (\varphi(x_k) - \hat{\mu}_\varphi) = 0, \quad k = 1, \dots, N. \end{array} \right.$$

- By elimination of the variables e, w and defining $\lambda = 1/\gamma$ one obtains

$$\boxed{\text{D}} : \text{ solve in } \alpha : \quad \Omega_c \alpha = \lambda \alpha$$

with

$$\Omega_c = \begin{bmatrix} (\varphi(x_1) - \hat{\mu}_\varphi)^T (\varphi(x_1) - \hat{\mu}_\varphi) & \dots & (\varphi(x_1) - \hat{\mu}_\varphi)^T (\varphi(x_N) - \hat{\mu}_\varphi) \\ \vdots & & \vdots \\ (\varphi(x_N) - \hat{\mu}_\varphi)^T (\varphi(x_1) - \hat{\mu}_\varphi) & \dots & (\varphi(x_N) - \hat{\mu}_\varphi)^T (\varphi(x_N) - \hat{\mu}_\varphi) \end{bmatrix}$$

LS-SVM approach to kernel PCA (3)

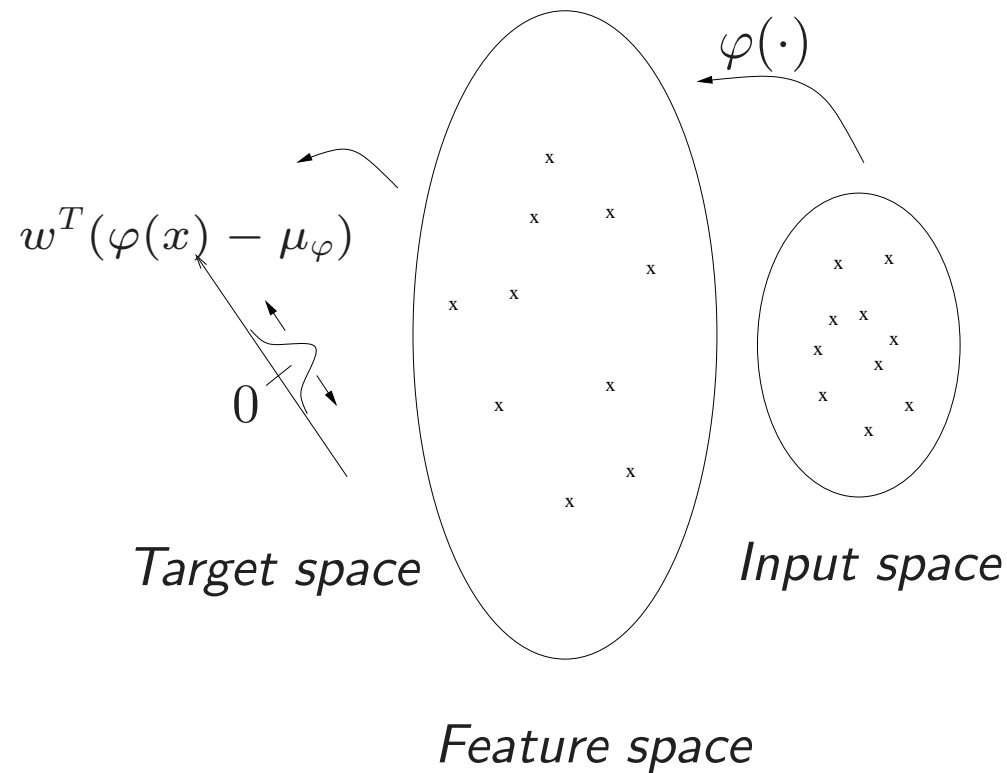
- Elements of the centered kernel matrix

$$\Omega_{c,kl} = (\varphi(x_k) - \hat{\mu}_\varphi)^T (\varphi(x_l) - \hat{\mu}_\varphi), \quad k, l = 1, \dots, N$$

- Score variables

$$\begin{aligned} z(x) &= w^T (\varphi(x) - \hat{\mu}_\varphi) \\ &= \sum_{l=1}^N \alpha_l (\varphi(x_l) - \hat{\mu}_\varphi)^T (\varphi(x) - \hat{\mu}_\varphi) \\ &= \sum_{l=1}^N \alpha_l \left(K(x_l, x) - \frac{1}{N} \sum_{r=1}^N K(x_r, x) - \frac{1}{N} \sum_{r=1}^N K(x_r, x_l) + \right. \\ &\quad \left. \frac{1}{N^2} \sum_{r=1}^N \sum_{s=1}^N K(x_r, x_s) \right). \end{aligned}$$

LS-SVM approach to kernel PCA (4)



Find direction with maximal variance

Example: denoising by kernel PCA (1)

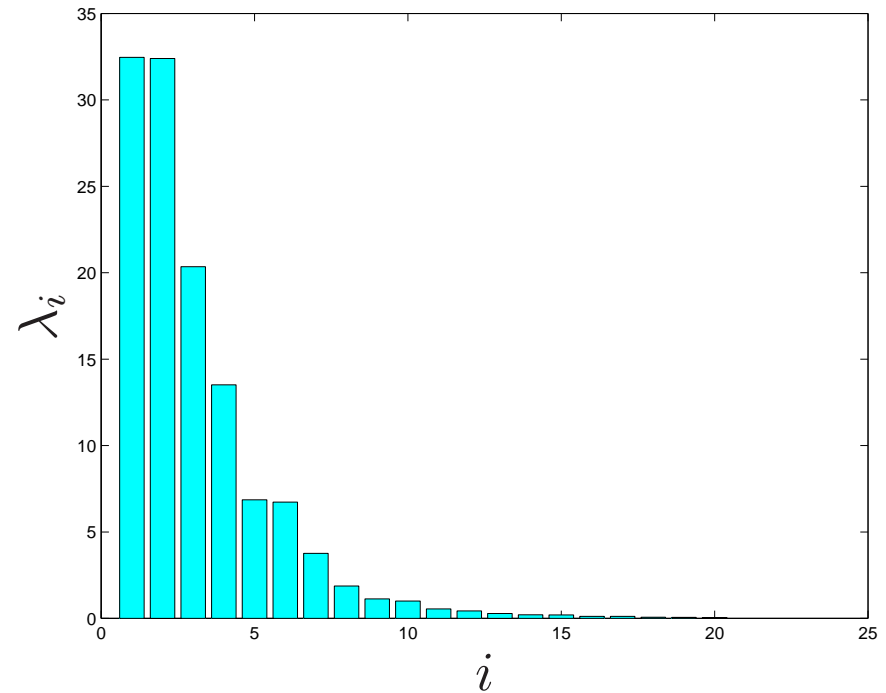
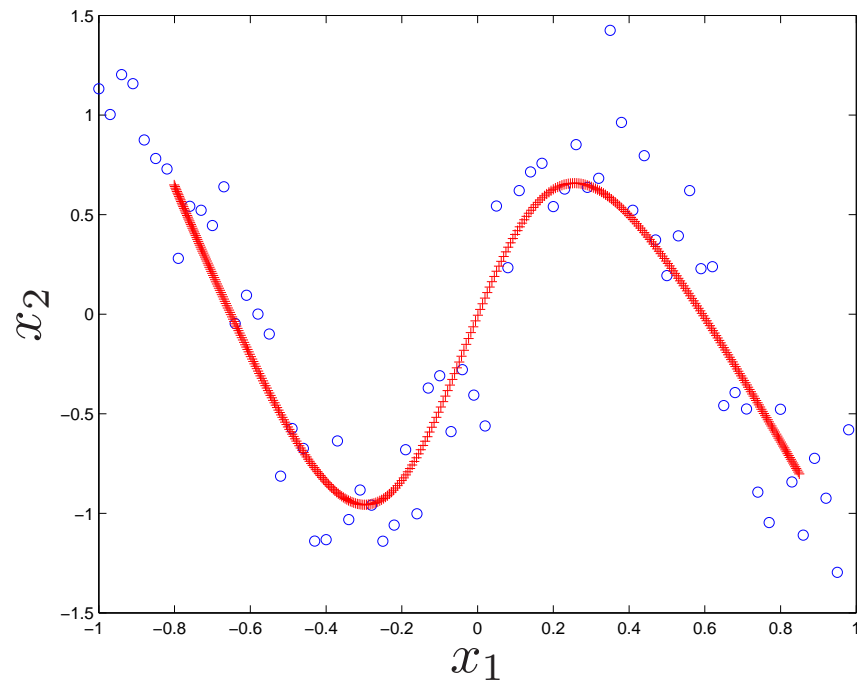
- For the nonlinear PCA case the number of score variables n_s can be larger than the dimension of the input space n . One selects then as few score variables as possible and minimize the reconstruction error. In this form of nonlinear PCA the mappings are nonlinear.
- The mapping from the score variables to the reconstructed input variables is done as

$$\tilde{x} = h(z)$$

such that one minimizes the reconstruction error

$$\min \sum_{k=1}^N \|x_k - h(z_k)\|_2^2$$

Example: denoising by kernel PCA (2)



Example: Denoising a noisy sine function. For the nonlinear mapping h an MLP with one hidden layer has been taken which was trained by Bayesian learning.

Example: denoising by kernel PCA (3)

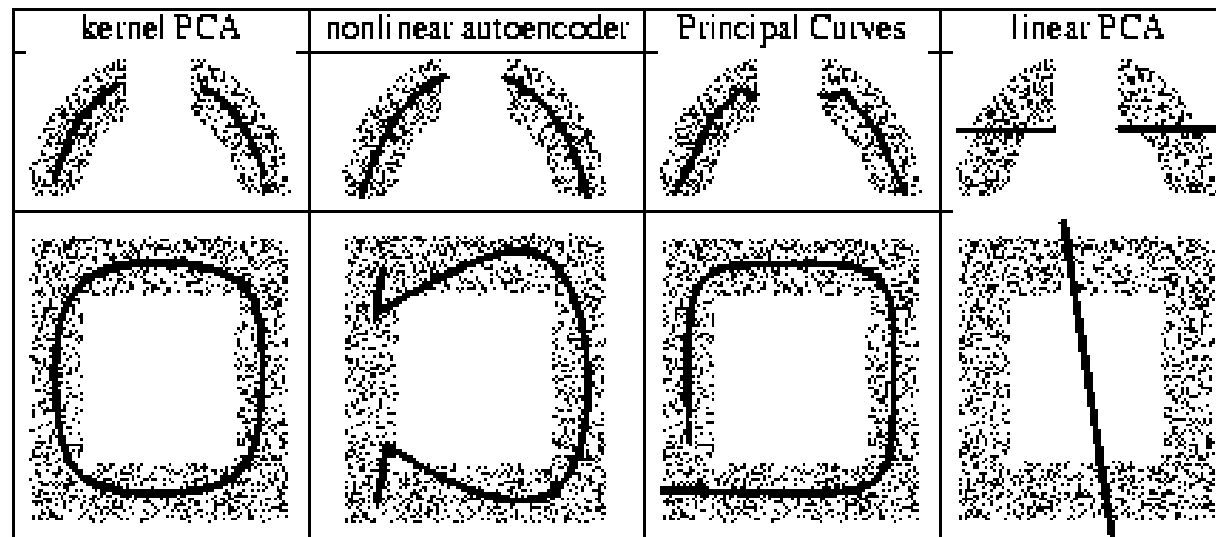


Figure 1: De-noising in 2-d (see text). Depicted are the data set (small points) and its de-noised version (big points, joining up to solid lines). For linear PCA, we used one component for reconstruction, as using two components, reconstruction is perfect and thus does not de-noise. Note that all algorithms except for our approach have problems in capturing the circular structure in the bottom example.

Schölkopf B., Mika S., Burges C., Knirsch P., Müller K.-R., Rätsch G., Smola A., Input space vs. feature space in kernel-based methods, IEEE Transactions on Neural Networks, 10(5), 1000-1017, 1999.

Example: denoising by kernel PCA (4)

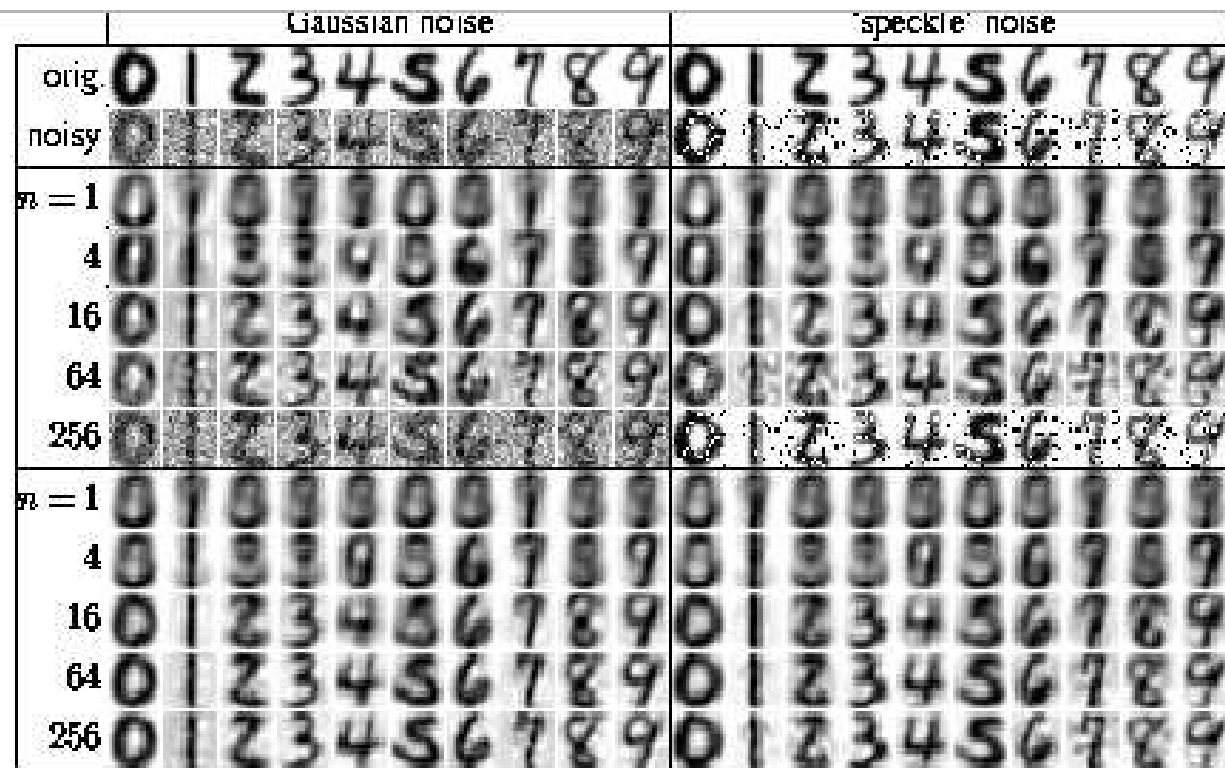


Figure 4: De-Noising of USPS data (see text). The left half shows: *top*: the first occurrence of each digit in the test set, *second row*: the upper digit with additive Gaussian noise ($\sigma = 0.5$), *following five rows*: the reconstruction for linear PCA using $n = 1, 4, 16, 64, 256$ components, and, *last five rows*: the results of our approach using the same number of components. In the right half we show the same but for 'speckle' noise with probability $p = 0.4$.

Density estimation by kernel PCA (1)

- A link between kernel PCA and orthogonal series density estimation has been established [Girolami, 2002].
- One can then take the scores resulting from kernel PCA as basis functions for a density estimator. Therefore, one considers the eigenvalue decomposition of the centered kernel matrix

$$\Omega_c U = U \tilde{\Lambda}$$

where $\tilde{\Lambda} = \text{diag}([\tilde{\lambda}_1; \dots; \tilde{\lambda}_N])$ contains the eigenvalues and $U = [u_1 \dots u_N] \in \mathbb{R}^{N \times N}$ the corresponding eigenvectors.

Density estimation by kernel PCA (2)

- This can be used in order to estimate the eigenfunctions $\phi_i(x)$ and eigenvalues λ_i for the integral equation (Karhunen-Loeve expansion)

$$\int K(x, x') \phi_i(x) p(x) dx = \lambda_i \phi_i(x')$$

with the estimates (Nyström method)

$$\hat{\lambda}_i = \frac{1}{N} \tilde{\lambda}_i, \quad \hat{\phi}_i(x_k) = \sqrt{N} u_{ki}, \quad \hat{\phi}_i(x') = \frac{\sqrt{N}}{\tilde{\lambda}_i} \sum_{k=1}^N u_{ki} K(x_k, x')$$

where u_{ki} denotes the ki -th entry of the matrix U .

Density estimation by kernel PCA (3)

- Using the eigenvectors as finite sample estimates of the corresponding eigenfunctions, the truncated estimate of the probability density function at point x' is given by

$$\begin{aligned}\hat{p}_M(x') &= \frac{1}{N} \mathbf{1}_v^T \sum_{i=1}^M \sqrt{\tilde{\lambda}_i} u_i \sum_{k=1}^N \frac{1}{\sqrt{\tilde{\lambda}_i}} u_{ki} K(x_k, x') \\ &= \frac{1}{N} \mathbf{1}_v^T U_M U_M^T \theta(x')\end{aligned}$$

where $\theta(x') = [K(x', x_1); K(x', x_2); \dots; K(x', x_N)]$, $\mathbf{1}_v = [1; 1; \dots; 1]$ and $U_M \in \mathbb{R}^{N \times M}$ is the matrix with eigenvectors of Ω_c consisting of the eigenvectors corresponding to the M largest eigenvalues. (Note: normalizations are done for the kernel K).

- For the case of $M = N$ this reduces to the well-known Parzen window density estimator $p(x') = \frac{1}{N} \mathbf{1}_v^T \theta(x')$.

Density estimation by kernel PCA (4)

- Cutoff value for determination of the value of M :

$$\left(\frac{1}{N}1_v^T u_i\right)^2 > \frac{2N}{1+N}.$$

An estimate for the overall integrated square truncation error $\sum_{i=M+1}^{\infty} c_i^2$ is given by

$$c_i^2 \simeq \tilde{\lambda}_i \left(\frac{1}{N}1_v^T u_i\right)^2.$$

This can also be related to the quadratic Renyi entropy

$$H_R = -\log \int p(x)^2 dx$$

Density estimation by kernel PCA (5)

- One can show that

$$\int \hat{p}(x)^2 dx = \sum_{i=1}^N \tilde{\lambda}_i \left(\frac{1}{N} \mathbf{1}_v^T u_i \right)^2.$$

Large contributions to the entropy come from components that have small values of $\tilde{\lambda}_i \left(\frac{1}{N} \mathbf{1}_v^T u_i \right)^2$ and are related to elements with little or no structure, caused by observation noise or diffuse regions in the data. Large values of $\tilde{\lambda}_i \left(\frac{1}{N} \mathbf{1}_v^T u_i \right)^2$ on the other hand indicate regions of high density or compactness.

- More generally (beyond RBF kernels):

$$\int \hat{p}(x)^2 dx = \frac{1}{N^2} \mathbf{1}_v^T K \mathbf{1}_v$$

Canonical Correlation Analysis

- CCA analysis has applications e.g. in system identification, signal processing, bioinformatics and textmining.
- **Objective:** find a maximal correlation between the projected variables $z_x = w^T x$ and $z_y = v^T y$ where $x \in \mathbb{R}^{n_x}, y \in \mathbb{R}^{n_y}$ (zero mean).
- Maximize the **correlation coefficient**

$$\max_{w,v} \rho = \frac{\mathcal{E}[z_x z_y]}{\sqrt{\mathcal{E}[z_x z_x]} \sqrt{\mathcal{E}[z_y z_y]}} = \frac{w^T C_{xy} v}{\sqrt{w^T C_{xx} w} \sqrt{v^T C_{yy} v}}$$

with $C_{xx} = \mathcal{E}[xx^T]$, $C_{yy} = \mathcal{E}[yy^T]$, $C_{xy} = \mathcal{E}[xy^T]$. This is formulated as the constrained optimization problem

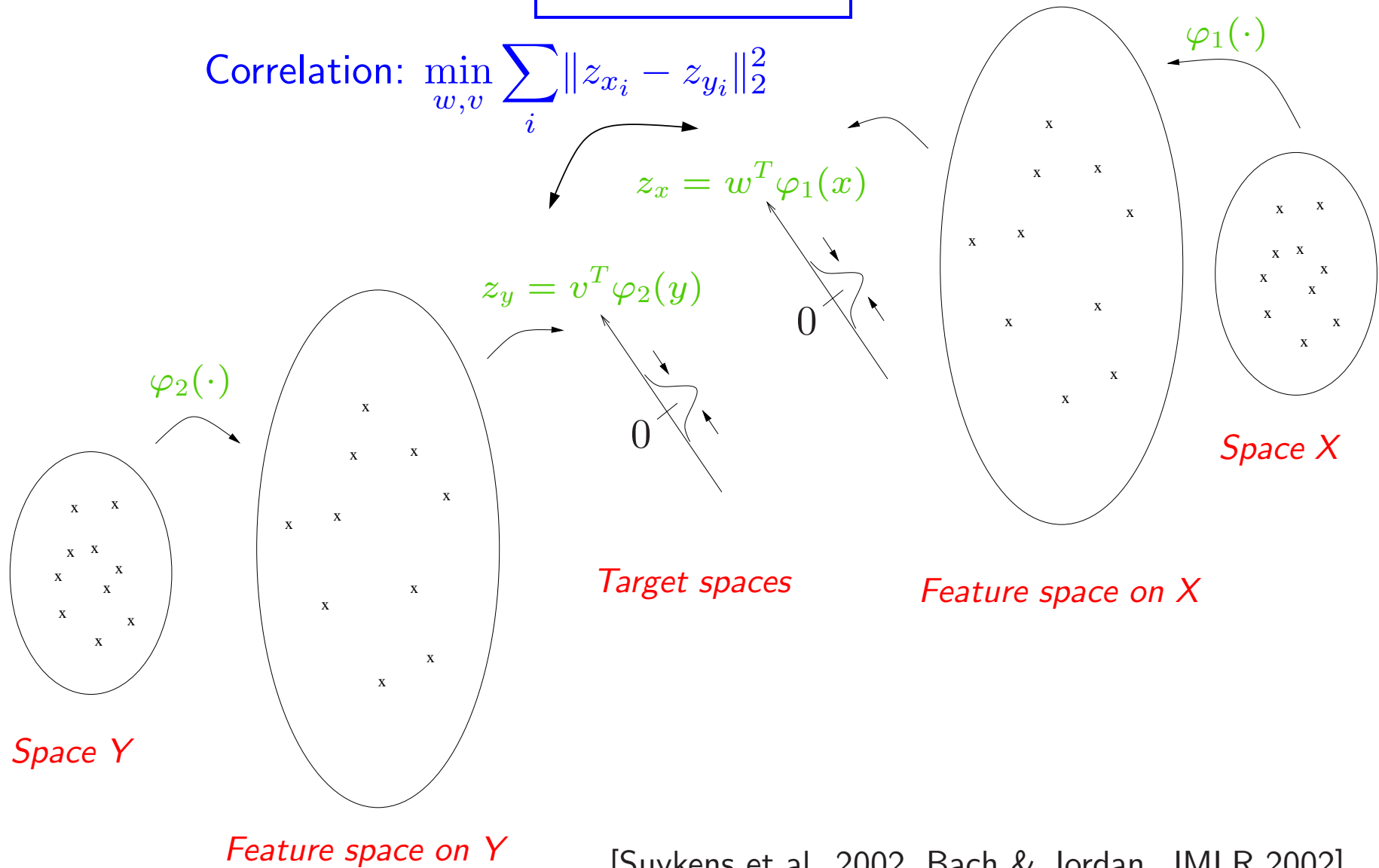
$$\max_{w,v} w^T C_{xy} v \quad \text{s.t.} \quad w^T C_{xx} w = 1 \quad \text{and} \quad v^T C_{yy} v = 1$$

which leads to the **generalized eigenvalue problem**

$$C_{xy} v = \eta C_{xx} w, \quad C_{yx} w = \nu C_{yy} v.$$

Kernel CCA

Correlation: $\min_{w,v} \sum_i \|z_{x_i} - z_{y_i}\|_2^2$



[Suykens et al. 2002, Bach & Jordan, JMLR 2002]

LS-SVM formulation to Kernel CCA

- **Score variables:** $z_x = w^T(\varphi_1(x) - \hat{\mu}_{\varphi_1})$, $z_y = v^T(\varphi_2(y) - \hat{\mu}_{\varphi_2})$

Feature maps φ_1, φ_2 , kernels $K_1(x_i, x_j) = \varphi_1(x_i)^T \varphi_1(x_j)$, $K_2(y_i, y_j) = \varphi_2(y_i)^T \varphi_2(y_j)$

- **Primal problem:** (Kernel PLS case: $\nu_1 = 0, \nu_2 = 0$ [Hoegaerts et al., 2004])

$$\max_{w, v, e, r} \quad \gamma \sum_{i=1}^N e_i r_i - \nu_1 \frac{1}{2} \sum_{i=1}^N e_i^2 - \nu_2 \frac{1}{2} \sum_{i=1}^N r_i^2 - \frac{1}{2} w^T w - \frac{1}{2} v^T v$$

$$\text{subject to} \quad e_i = w^T(\varphi_1(x_i) - \hat{\mu}_{\varphi_1}), \quad r_i = v^T(\varphi_2(y_i) - \hat{\mu}_{\varphi_2}), \quad \forall i$$

$$\text{with } \hat{\mu}_{\varphi_1} = (1/N) \sum_{i=1}^N \varphi_1(x_i), \quad \hat{\mu}_{\varphi_2} = (1/N) \sum_{i=1}^N \varphi_2(y_i).$$

- Dual problem: **generalized eigenvalue problem** [Suykens et al. 2002]

$$\begin{bmatrix} 0 & \Omega_{c,2} \\ \Omega_{c,1} & 0 \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix} = \lambda \begin{bmatrix} \nu_1 \Omega_{c,1} + I & 0 \\ 0 & \nu_2 \Omega_{c,2} + I \end{bmatrix} \begin{bmatrix} \alpha \\ \beta \end{bmatrix}, \quad \lambda = 1/\gamma$$

$$\text{with } \Omega_{c,1ij} = (\varphi_1(x_i) - \hat{\mu}_{\varphi_1})^T (\varphi_1(x_j) - \hat{\mu}_{\varphi_1}), \quad \Omega_{c,2ij} = (\varphi_2(y_i) - \hat{\mu}_{\varphi_2})^T (\varphi_2(y_j) - \hat{\mu}_{\varphi_2})$$

Obtaining solution from Lagrangian

- Lagrangian $\mathcal{L}(w, v, e, r; \alpha, \beta) = \gamma \sum_{i=1}^N e_i r_i - \nu_1 \frac{1}{2} \sum_{i=1}^N e_i^2 - \nu_2 \frac{1}{2} \sum_{i=1}^N r_i^2 - \frac{1}{2} w^T w - \frac{1}{2} v^T v - \sum_{i=1}^N \alpha_i [e_i - w^T (\varphi_1(x_i) - \hat{\mu}_{\varphi_1})] - \sum_{i=1}^N \beta_i [r_i - v^T (\varphi_2(y_i) - \hat{\mu}_{\varphi_2})]$

- Conditions for optimality (eliminate w, v, e, r)

$$\left\{ \begin{array}{ll} \frac{\partial \mathcal{L}}{\partial w} = 0 & \rightarrow w = \sum_{i=1}^N \alpha_i (\varphi_1(x_i) - \hat{\mu}_{\varphi_1}) \\ \frac{\partial \mathcal{L}}{\partial v} = 0 & \rightarrow v = \sum_{i=1}^N \beta_i (\varphi_2(y_i) - \hat{\mu}_{\varphi_2}) \\ \frac{\partial \mathcal{L}}{\partial e_i} = 0 & \rightarrow \gamma v^T (\varphi_2(y_i) - \hat{\mu}_{\varphi_2}) = \nu_1 w^T (\varphi_1(x_i) - \hat{\mu}_{\varphi_1}) + \alpha_i \quad i = 1, \dots, N \\ \frac{\partial \mathcal{L}}{\partial r_i} = 0 & \rightarrow \gamma w^T (\varphi_1(x_i) - \hat{\mu}_{\varphi_1}) = \nu_2 v^T (\varphi_2(y_i) - \hat{\mu}_{\varphi_2}) + \beta_i \quad i = 1, \dots, N \\ \frac{\partial \mathcal{L}}{\partial \alpha_i} = 0 & \rightarrow e_i = w^T (\varphi_1(x_i) - \hat{\mu}_{\varphi_1}) \quad i = 1, \dots, N \\ \frac{\partial \mathcal{L}}{\partial \beta_i} = 0 & \rightarrow r_i = v^T (\varphi_2(y_i) - \hat{\mu}_{\varphi_2}) \quad i = 1, \dots, N \end{array} \right.$$

Kernel CCA applications - textmining

- A. Vinokourov, J. Shawe-Taylor, N. Cristianini, Inferring a semantic representation of text via cross-language correlation analysis, NIPS 2002.
- Learning a semantic representation of a text document from data in a cross-lingual setting.
- Corpus of unlabelled paired documents. Each pair is formed by an English document and its French translation.
- Learning correlation between the two spaces by kernel CCA and bag-of-words approach.
- Certain patterns of English words that relate to a specific meaning correlate with patterns of French words with the same meaning across the corpus.

Kernel CCA applications - bioinformatics

- [Vert & Kanehisa, Bioinformatics 2003]:
For kernels related to spaces X and Y

K_1 : graph from gene network

K_2 : gene expression profiles

Study correlation between gene network and set of profiles

Able to extract biologically relevant expression patterns and pathways with related activity.

- [Yamanishi et al., Bioinformatics 2003]:
Extract correlated gene clusters from multiple genomic data. Successfully tested on the ability to recognize operons in the *Escherichia coli* genome, from the comparison of three data sets:
 1. functional relationships between genes in metabolic pathways
 2. geometrical relationships along the chromosome
 3. co-expression relationships as observed by gene expression data

Kernel CCA applications - system identification (1)

- Given I/O data, estimate parameter vector θ of the nonlinear state space model:

$$\begin{cases} x_{k+1} &= f(x_k, u_k; \theta) \\ y_k &= g(x_k, u_k; \theta) \end{cases}$$

- Conceptually 2 steps:
 - **Step 1**: estimate state vector sequence $\{\hat{x}_k\}$ from the I/O data
 - **Step 2**: given I/O data and $\{\hat{x}_k\}$, solve a set of nonlinear equations to estimate θ .
- Estimation of state vector sequence using **Kernel CCA**
[Verdult et al., MTNS 2004]

Kernel CCA applications - system identification (2)

- **Kernel CCA**: primal formulation [Suykens et al., 2002]

$$\min_{w,v,b,d,e,r} w^T w + v^T v + \nu \sum_i (e_i - r_i)^2 \text{ s.t. } \begin{cases} e_i = w^T \varphi_1(x_i) + b, \forall i \\ r_i = v^T \varphi_2(z_i) + d, \forall i \end{cases}$$

- Data $\{x_i\}$: **past of time-series**
 - Data $\{z_i\}$: **future of time-series**
 - **State vector sequence from kernel CCA**
 - System order estimate from kernel CCA
- Dual problem: generalized eigenvalue problem