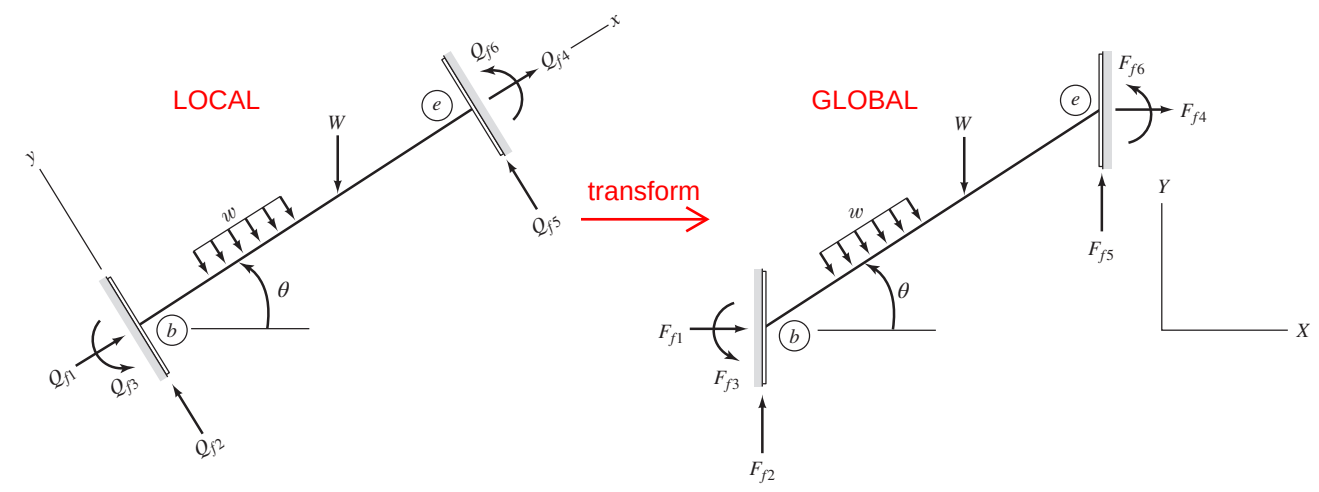
LOCAL
GLOBAL
transform
y
x
Y
X
W
w
θ
e
b
Q_{f1}
Q_{f2}
Q_{f3}
Q_{f4}
Q_{f5}
Q_{f6}
F_{f1}
F_{f2}
F_{f3}
F_{f4}
F_{f5}
F_{f6}