# Matrix Multiplication: PyTorch vs. Plain Python Performance Comparison

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### 1 Introduction

One of the well-known facts about Python is its relatively slow speed when performing large computational tasks. Compared to other popular programming languages like C++, Java, and even Node.js, Python tends to be slower in execution. One key reason for this performance difference is that Python is an interpreted language, meaning that while it first compiles code into byte code, it still executes instructions line by line at runtime rather than compiling everything into machine code beforehand. Everything is also stored as objects, even in lists. However, this limitation can be mitigated through specialized optimizations and external libraries. For instance, libraries like PyTorch use a data structure called a tensor to represent matrices. Tensors store data of a uniform type in contiguous memory, rather than as a collection of objects like Python lists. PyTorch can also leverage GPU acceleration to further improve performance compared to standard Python.

## 2 Preliminaries

Matrix multiplication is a common linear algebra operation in numerical computing and machine learning. It can be defined as a binary operation that produces a new matrix from two existing matrices. The said matrix multiplication process can be described as follows:

Let  $A \in \mathbb{R}^{m \times n}$ ,  $B \in \mathbb{R}^{n \times p}$ , and  $C \in \mathbb{R}^{m \times p}$ ,

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \begin{bmatrix} b_{11} & b_{12} & \cdots & b_{1p} \\ b_{21} & b_{22} & \cdots & b_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ b_{n1} & b_{n2} & \cdots & b_{np} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & \cdots & c_{1p} \\ c_{21} & c_{22} & \cdots & c_{2p} \\ \vdots & \vdots & \ddots & \vdots \\ c_{m1} & c_{m2} & \cdots & c_{mp} \end{bmatrix}$$

The product C consist of:

$$c_{ij} = a_{i1}b_{1j} + a_{i2}b_{2j} + \dots + a_{in}b_{nj} = \sum_{k=1}^{n} a_{ik}b_{kj},$$

```
for i = 1, ..., m and j = 1, ..., p.
```

#### Matrix multiplication implementation in plain Python:

As we can see, the algorithm runs in  $O(n^3)$  time complexity, which is an expensive operation. Additionally, the space complexity is also a concern, as each element in a plain Python list is stored as a separate object, leading to increased memory occupation. That begs the differ, how can we improve the computational speed of doing matrix multiplication?

As previously discussed, PyTorch has become a prominent tool in deep learning due to its flexibility and efficiency. While NumPy arrays are similar to PyTorch's tensor, NumPy is more suited for general-purpose array computing. It has limitations in deep learning applications, particularly because it lacks support for automatic differentiation and GPU acceleration. On the other hand, PyTorch's tensor is specifically designed for deep learning applications, so that will be the focus of our comparison.

## 3 Approach

To start, we will define a helper function that will generate two matrices, W and X, where W is a  $90 \times m$  matrix, and X is a  $m \times 110$  matrix, where  $m \in \{10, 20, ..., 100\}$ .

#### Creating the randomized matrices:

```
import random

def generateMatrices(m: int) -> tuple[list[list[float]], list[list[float]]]:
    W = [[random.random() for _ in range(m)] for _ in range(90)];
    X = [[random.random() for _ in range(110)] for _ in range(m)];
    return W, X;
```

The main experiment script iterates through each pair of generated W and X matrices, corresponding to different m values, and constructs their tensor counterparts. It then utilizes IPython's timeit magic command to conduct seven runs of matrix multiplication for both the plain Python and vectorized implementations. The average runtime from these runs provides a more precise estimate of each implementation's runtime performance.

#### Running the 10 timing experiments:

```
import torch
def convertToTensor(W, X):
   W_t = torch.tensor(W);
   X_t = torch.tensor(X);
   return W_t, X_t;
m_vals = [m for m in range(10, 110, 10)];
matrices = [generateMatrices(m) for m in m_vals];
pyTimeResults = [];
tensorTimeResults = [];
for W, X in matrices:
   # Create the tensor matrices
   W_t, X_t = convertToTensor(W, X);
   # Time the plain Python matrix multiplication
   pythonTime = %timeit -o multiplyMatrices(W, X);
   pyTimeResults.append(pythonTime.average);
   # Time the torch matrix multiplication
   tensorTime = %timeit -o W_t.matmul(X_t);
   tensorTimeResults.append(tensorTime.average);
```

The timeit function produces an output for each iteration, shown below. The table reveals that, in the plain Python implementation, the magic function is executed only 10 times, while PyTorch runs it 10,000 times. Additionally, the time per loop is considerably lower for the PyTorch implementation, highlighting its superior speed for matrix multiplication.

Iteration with m value	Per loop (mean $\pm$ std. dev.)		
	10 loops each (Plain Python)	10,000 loops each (PyTorch)	
10	$21.9 \text{ ms} \pm 1.63 \text{ ms}$	$24.7 \ \mu s \pm 7.46 \ \mu s$	
20	$40.7 \text{ ms} \pm 4.84 \text{ ms}$	$24.4 \ \mu s \pm 1.44 \ \mu s$	
30	$55.6 \text{ ms} \pm 813 \mu \text{s}$	$24.9 \ \mu s \pm 1.05 \ \mu s$	
40	$72.6 \text{ ms} \pm 635 \mu \text{s}$	$27.1 \ \mu s \pm 2.72 \ \mu s$	
50	$92.0 \text{ ms} \pm 4.04 \text{ ms}$	$29.1 \ \mu s \pm 1.48 \ \mu s$	
60	$109~\mathrm{ms}\pm4.53~\mathrm{ms}$	$30.8 \ \mu s \pm 1.64 \ \mu s$	
70	$126~\mathrm{ms}\pm1.54~\mathrm{ms}$	$33.3 \ \mu s \pm 1.86 \ \mu s$	
80	$144~\mathrm{ms}\pm3.98~\mathrm{ms}$	$35.3 \ \mu s \pm 1.68 \ \mu s$	
90	$162~\mathrm{ms}\pm4.22~\mathrm{ms}$	$38.9 \ \mu s \pm 3.51 \ \mu s$	

Table 1: Performance metrics for different m values.

There is an edge case for the last iteration with m = 100, where the plain Python implementation executes only 1 loop. This is likely due to performance and bottleneck considerations when handling such a large computation.

Iteration with m value	Per loop (mean $\pm$ std. dev.)	
	1 loop (Plain Python)	10,000 loops (PyTorch)
100	$179~\mathrm{ms}\pm2.87~\mathrm{ms}$	$41.8 \ \mu s \pm 8.09 \ \mu s$

Table 2: Performance metrics for m value of 100.

We can also see the significant difference between plain Python and PyTorch when we print out the average of the timeit function below.

#### Displaying the average time results for the matrix multiplication experiment:

Average Time results for timeit tests on tensor matrices: [2.469240571476153e-05, 2.4358931428495062e-05, 2.4857308571725818e-05,

- 2.7050777142825868e-05, 2.912901999994314e-05, 3.0784302856981025e-05,
- 3.328427285700205e-05, 3.5271571428373656e-05, 3.8860460000536737e-05,
- 4.182551857167189e-05]

# 4 Visualizing the Results

Using the retrieved data, we will plot the speed improvement ratio between the plain Python and PyTorch implementations, calculated using the following formula:

speed improvement ratio = 
$$\sum_{i=0}^{i < n} \frac{\text{pyTimeResults[i]}}{\text{tensorTimeResults[i]}}$$

Additionally, I will also compute the line of best fit for the data points using the least squares method. It will be computed as follows:

$$A = \begin{bmatrix} 1 & 10 \\ 1 & 20 \\ \vdots & \vdots \\ 1 & 100 \end{bmatrix}, \quad b = \begin{bmatrix} \text{speed\_improvement\_ratio}[0] \\ \text{speed\_improvement\_ratio}[1] \\ \vdots \\ \text{speed\_improvement\_ratio}[9] \end{bmatrix}$$

Where A is a vertical matrix with the first column consisting of all ones, and the second column consisting of the m values. On the other hand, b is a vertical vector of the speed improvement ratio values. Now for the computation:

$$x^* = (A^T A)^{-1} A^T b$$

Giving us the line of best fit line:

$$bestFitLine(m) = \alpha + \beta * m$$

#### Plotting the speed improvement graph:

```
import matplotlib.pyplot as plt
import numpy as np
speedImprovementRatio = [py / tensor for py, tensor in zip(pyTimeResults,
   tensorTimeResults)];
# Compute the line of best fit using least squares solution
A = np.column_stack((np.ones(len(m_vals)), m_vals)); # Col of 1s and m_vals
b = np.array(speedImprovementRatio); # Vertical vector of ratios
x_star = np.linalg.inv(A.T @ A) @ (A.T @ b); # x* = (A' * A)^-1 * A' * b
alpha = x_star[0];
beta = x_star[1];
bestFitLine = [alpha + beta * m for m in m_vals]; # Formulate the best fit line
plt.plot(m_vals, speedImprovementRatio, color='b', label="Speed Improvement");
plt.plot(m_vals, bestFitLine, color='r', label="Best Fit Line");
plt.xlabel("Matrix Size (m)");
plt.ylabel("Speed Improvement Ratio (Plain / Vectorized)");
plt.title("Speed Improvement of PyTorch Vectorized Multiplication Over Plain
   Python");
plt.legend();
plt.show();
```

### Speed Improvement of PyTorch Vectorized Multiplication Over Plain Python

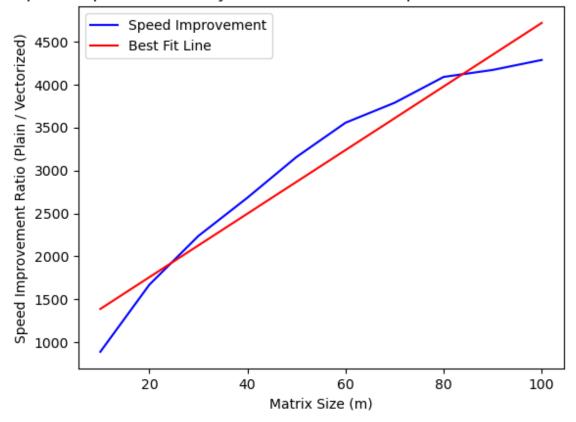


Figure 1: Speed improvement ratio of PyTorch over Plain Python.

Additionally, for a more adherent difference, we will be plotting the time difference between the two implementations.

#### Plotting the time difference:

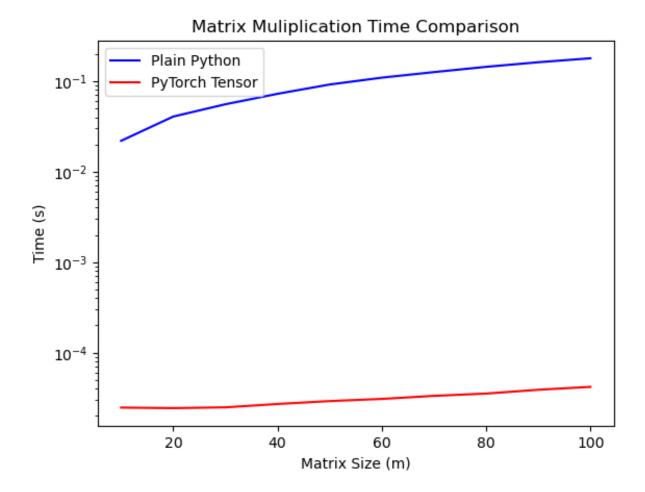


Figure 2: Time difference between PyTorch over Plain Python.

We can see that tensors appear to be operating with a run time speed closer to a logarithmic scale (flatter line), meaning that it has better performance for large matrices.

### 5 Conclusion

In conclusion, the experiments clearly demonstrate that using PyTorch tensors for matrix multiplication provides a substantial performance boost compared to the plain Python implementation. While some variation exists due to standard deviations, the PyTorch implementation consistently outperforms its plain Python counterpart. By enforcing a homogeneous data type for tensors, computation time is significantly reduced. Additionally, this approach minimizes the need to reference new objects for each matrix element and compacts data storage by nearly sixfold. These optimizations are crucial for deep learning applications, where efficient matrix operations are essential for handling large-scale computations.

## References

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