

Homework 4

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1. Recall that an $n \times n$ matrix Q is orthogonal if the columns of Q form an orthonormal basis of \mathbb{R}^n . This is equivalent to $Q^T Q = Q Q^T = I_n$.

a) Show that the product of two $n \times n$ orthogonal matrices is an orthogonal matrix.

Let $Q = Q_1 Q_2$, then we have

$$Q^T = (Q_1 Q_2)^T = Q_2^T Q_1^T$$

Now, to verify orthogonality (multiplying both sides with Q):

$$\begin{aligned} Q^T Q &= (Q_2^T Q_1^T)(Q_1 Q_2) \\ Q^T Q &= Q_2^T (Q_1^T Q_1) Q_2 \\ Q^T Q &= Q_2^T I_n Q_2 \\ Q^T Q &= I_n \end{aligned}$$

Thus, the product of the two $n \times n$ orthogonal matrices is an orthogonal matrix because $Q^T Q = I_n$ where Q is the product of the two $n \times n$ orthogonal matrices.

b) Prove that if Q is an orthogonal matrix, so is Q^T . Deduce that the rows of an orthogonal matrix also form an orthonormal basis.

Suppose that Q^T is an orthogonal matrix, then:

$$(Q^T)^T Q^T = Q Q^T = I_n \Leftrightarrow Q^T (Q^T)^T = Q^T Q = I_n$$

This shows that if Q is an orthogonal matrix, so is Q^T . We know that if Q is orthogonal, then its columns form an orthonormal basis for \mathbb{R}^n . Now, since we have just proven that Q^T is also orthogonal, we can consider the columns of Q^T . The columns of Q^T are exactly the rows of Q , due to transpose swapping the rows and columns. Thus, the rows of Q also form an orthonormal basis of \mathbb{R}^n .

c) Show that $\begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$ is an orthogonal matrix for any $0 \leq \theta < 2\pi$.
What does this matrix do?

$$\text{Let } Q = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$$

Now, to show that it is orthogonal:

$$i) Q^T = \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix}$$

$$\begin{aligned} ii) Q^T Q &= \begin{pmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} = \\ &= \begin{pmatrix} \cos \theta \cos \theta + \sin \theta \sin \theta & \cos \theta (-\sin \theta) + \sin \theta \cos \theta \\ (-\sin \theta) \cos \theta + \cos \theta \sin \theta & (-\sin \theta)(-\sin \theta) + \cos \theta \cos \theta \end{pmatrix} = \\ &= \begin{pmatrix} \cos^2 \theta + \sin^2 \theta & 0 \\ 0 & \sin^2 \theta + \cos^2 \theta \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} = I_n \end{aligned}$$

Thus, $Q = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix}$ is an orthogonal matrix for any $0 \leq \theta < 2\pi$ as $Q^T Q = I_n$. The matrix represents a rotational matrix. If we apply Q to a vector v , it will rotate it counterclockwise by θ .

$$Qv = \begin{pmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} x \cos \theta - y \sin \theta \\ x \sin \theta + y \cos \theta \end{pmatrix}$$

For example, taking vector

$$v = \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

and flipping it across the y-axis by rotating v by $\theta = \pi$

$$\begin{pmatrix} \cos \pi & -\sin \pi \\ \sin \pi & \cos \pi \end{pmatrix} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = \begin{pmatrix} -1 \\ -2 \end{pmatrix}$$

d) Prove that if Q is an $n \times n$ orthogonal matrix then $\|Qx\| = \|x\|$ for any $x \in \mathbb{R}^n$.

The norm of a vector $x \in \mathbb{R}^n$ is defined as:

$$\|x\| = \sqrt{x^T x}$$

$$\|Qx\| = \sqrt{(Qx)^T (Qx)}$$

Note: $(Qx)^T \Leftrightarrow x^T Q^T$

$$\|Qx\| = \sqrt{x^T Q^T Q x}$$

$$\|Qx\| = \sqrt{x^T x} = \|x\|$$

Thus, if Q is an $n \times n$ orthogonal matrix then $\|Qx\| = \|x\|$ for any $x \in \mathbb{R}^n$.

2c) Just to be implicitly clear: The answer to part 2c is above the myHouseholder function as a print statement in the MATLAB code.