

# Homework 5

Bryan Lee

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1. Find the closest point from  $\mathbf{b} = \begin{pmatrix} 1 \\ 1 \\ 2 \\ -2 \end{pmatrix}$  to the subspace spanned by

$$\begin{pmatrix} 1 \\ 2 \\ -1 \\ 0 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \\ -2 \\ -1 \end{pmatrix}, \begin{pmatrix} 1 \\ 0 \\ 3 \\ 2 \end{pmatrix}.$$

Use any MATLAB command that you think is useful to do this computation.

**Some further explanation on my computation on MATLAB:**

Since there is no solution to the original problem of  $rref([A|b])$  where A is the matrix with the three augmented vectors. We need to compute the least square solution. To do that, I compute via row operations  $A^T A x = A^T b$  where  $A^T A$  becomes a symmetric matrix and  $A^T b$  will be a vector.

$$\hat{A} = A' A = \begin{pmatrix} 6 & 4 & -2 \\ 4 & 6 & -8 \\ -2 & -8 & 14 \end{pmatrix}$$

$$\hat{b} = A' b = \begin{pmatrix} 1 \\ -1 \\ 3 \end{pmatrix}$$

$$rref([\hat{A}|\hat{b}]) = \left( \begin{array}{ccc|c} 6 & 4 & -2 & 1 \\ 4 & 6 & -8 & -1 \\ -2 & -8 & 14 & 3 \end{array} \right) = \left( \begin{array}{ccc|c} 1 & 0 & 1 & \frac{1}{2} \\ 0 & 1 & -2 & -\frac{1}{2} \\ 0 & 0 & 0 & 0 \end{array} \right)$$

The rref shows that there is a free variable for the third unknown variable. We can assign that variable, let's say,  $z$ , as an arbitrary value  $t$ . Thus, we get the three equations:  $x = \frac{1}{2} - t$ ,  $y = -\frac{1}{2} + 2t$ , and  $z = t$ . Now, putting the equation together as a vector:

$$v = \begin{pmatrix} \frac{1}{2} - t \\ -\frac{1}{2} + 2t \\ t \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ 0 \end{pmatrix} + t \begin{pmatrix} -1 \\ 2 \\ 1 \end{pmatrix}$$

Since  $t$  is an arbitrary value and  $z$  is a linear combination of the previous two vectors, we can take the basis vector and multiply it with  $A$ , giving us the closest points:

$$A * v = \begin{pmatrix} 1 & 0 & 1 \\ 2 & 1 & 0 \\ -1 & -2 & 3 \\ 0 & -1 & 2 \end{pmatrix} \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \\ 0 \end{pmatrix} = \begin{pmatrix} \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \\ \frac{1}{2} \end{pmatrix}$$

Running MATLAB `A\b` yields the same solution.

**4.** Let  $f(x) = x^2$  on the interval  $[0, 2\pi]$ . In this exercise, you will compute the discrete Fourier coefficients  $c_0, c_1, \dots, c_7$  of  $f$  from the sample vector

$$\mathbf{f} = \begin{pmatrix} f_0 \\ f_1 \\ \vdots \\ f_7 \end{pmatrix}$$

where  $f_j = f(j2\pi/8)$  for  $j = 0, \dots, 7$ .

Part d) Explanation of computing  $p(x)$  is explained as a comment in the MATLAB code.

**e)** Find out how you can plot the graph of a function in MATLAB. Then plot the graphs of  $f(x)$  and  $p_1(x)$  on the interval  $[0, 2\pi]$ . What do you see?

Graph is rendered on Matlab code.

Analysis of the  $p_1(x)$  graph:

The graph has a sinusoidal wave that has a few points that agree with  $f(x) = x^2$ . However, it does have a lot of "noise" and roughly follows the original  $f(x)$  line. One peculiar aspect of the  $p_1(x)$  graph is the sinusoidal wave alternation from being above the original  $x^2$  to following it and ending up below it as it approached  $2\pi$ . Another noteworthy aspect of the  $p_1(x)$  graph is the sudden drop off at  $7\pi/4$  from following the  $x^2$  line to 0. Overall, the graph approximately follows the original signal line, but only by agreeing at specific points.

**h)** Plot the graph of  $f(x)$  and  $q_1(x)$  on the interval  $[0, 2\pi]$ . Now, what do you observe?

Graph is rendered on Matlab code.

Analysis of the  $q_1(x)$  graph:

The graph is still a tiny bit wavy, but it follows the original  $x^2$  graph much more

closely. Especially between the points  $\pi/2$  and  $3\pi/2$ , the  $q_1(x)$  graph hovers/on the  $x^2$  line. The points between 0 and  $\pi/2$  also seem to be a shifted sinusoidal wave before seemingly being forced to wrap on the  $x^2$  graph afterward. There is still a sudden drop off at around  $7\pi/4$  from following the  $x^2$  line to 0. Overall, the  $q_1(x)$  graph better represents the  $x^2$  graph but is still only an approximation that is more accurate than  $p_1(x)$ .