# Math 118C HW4

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Question 1 Rudin Pg. 242 Problem 27:

Put f(0,0) = 0, and

$$f(x,y) = \frac{xy(x^2 - y^2)}{x^2 + y^2}$$

if  $(x,y) \neq (0,0)$ . Prove that

- (a) f,  $D_1 f$ ,  $D_2 f$  are continuous in  $\mathbb{R}^2$ .
- (b)  $D_{12}f$  and  $D_{21}f$  exist at every point of  $\mathbb{R}^2$ , and are continuous except at (0,0).
- (c)  $D_{12}f(0,0) = 1$ , and  $D_{21}f(0,0) = -1$ .

Pf:

For all  $(x,y) \in \mathbb{R}^2$  with  $(x,y) \neq (0,0)$ , using polar coordinates,  $(x,y) = (r\cos(\theta), r\sin(\theta))$  for some r > 0 and  $\theta \in [0,2\pi)$ . Which, |(x,y)| = r, when consider limit definition, we'll use polar coordinates instead.

### (a) f is continuous:

For  $(x,y) \neq (0,0)$ , since f is a defined rational function, it is continuous, so it suffices to show f is continuous at 0. For all  $\epsilon > 0$ , choose  $\delta = \sqrt{\frac{\epsilon}{2}} > 0$ , then for all (x,y) satisfying  $0 < |(x,y)| = r < \delta$ , we get the following:

$$|f(x,y) - f(0,0)| = \left| \frac{(r\cos(\theta))(r\sin(\theta))((r\cos(\theta))^2 - (r\sin(\theta))^2)}{(r\cos(\theta))^2 + (r\sin(\theta))^2} - 0 \right|$$

$$= \left| \frac{r^4\sin(\theta)\cos(\theta)(\cos^2(\theta) - \sin^2(\theta))}{r^2} \right| \le r^2|\sin(\theta)| \cdot |\cos(\theta)| \cdot (|\cos(\theta)|^2 + |\sin(\theta)|^2)$$

$$\le 2r^2 < 2\left(\sqrt{\frac{\epsilon}{2}}\right)^2 = 2 \cdot \frac{\epsilon}{2} = \epsilon$$

This shows that f is continuous at (0,0), hence f in continuous in  $\mathbb{R}^2$ .

#### $D_1 f$ is continuous:

First, using basic differentiation rule, for  $(x,y) \neq (0,0)$ , we get the following:

$$D_1 f(x,y) = \frac{\partial}{\partial x} \left( \frac{xy(x^2 - y^2)}{x^2 + y^2} \right) = \frac{(3x^2y - y^3)(x^2 + y^2) - xy(x^2 - y^2)2x}{(x^2 + y^2)^2} = \frac{x^4y + 4x^2y^3 - y^5}{(x^2 + y^2)^2}$$

Which, at (0,0),  $D_1 f$  could be obtained through limit:

$$D_1 f(0,0) = \lim_{h \to 0} \frac{f(h,0) - f(0,0)}{h} = \lim_{h \to 0} \frac{h \cdot 0(h^2 - 0^2)}{(h^2 + 0^2)h} = \lim_{h \to 0} 0 = 0$$

Which,  $D_1 f(x,y)$  for  $(x,y) \neq (0,0)$  is again a rational function, which is continuous, so to verify continuity, it suffices to check (0,0). For all  $\epsilon > 0$ , choose  $\delta = \frac{\epsilon}{6} > 0$ , then for all (x,y) satisfying  $0 < |(x,y)| = r < \delta$ , we get the following:

$$|D_1 f(x,y) - D_1 f(0,0)| = \left| \frac{(r\cos(\theta))^4 (r\sin(\theta)) + 4(r\cos(\theta))^2 (r\sin(\theta))^3 - (r\sin(\theta)^5)}{((r\cos(\theta))^2 + (r\sin(\theta))^2)^2} - 0 \right|$$

$$= \left| \frac{r^5 (\cos^4(\theta)\sin(\theta) + 4\cos^2(\theta)\sin^3(\theta)) - \sin^5(\theta)}{r^4} \right| \le r(|\cos^4(\theta)\sin(\theta)| + 4|\cos^2(\theta)\sin^3(\theta)| + |\sin^5(\theta)|)$$

$$\le r(1 + 4 + 1) < 6 \cdot \frac{\epsilon}{6} = \epsilon$$

This proves the continuity of  $D_1 f$  at (0,0), so  $D_1 f$  is continuous in  $\mathbb{R}^2$ .

## $D_2f$ is continuous:

Using differentiation rule, for  $(x,y) \neq (0,0)$ , we get the following:

$$D_2 f(x,y) = \frac{\partial}{\partial y} \left( \frac{xy(x^2 - y^2)}{x^2 + y^2} \right) = \frac{(x^3 - 3xy^2)(x^2 + y^2) - xy(x^2 - y^2)2y}{(x^2 + y^2)^2} = \frac{x^5 - xy^4 - 4x^3y^2}{(x^2 + y^2)^2}$$

Again, at (0,0),  $D_2f$  could be obtained through limit:

$$D_2 f(0,0) = \lim_{h \to 0} \frac{f(0,h) - f(0,0)}{h} = \lim_{h \to 0} \frac{0 \cdot h(0^2 - h^2)}{(0^2 + h^2)h} = \lim_{h \to 0} 0 = 0$$

Notice that  $D_2f(x,y)$  for  $(x,y) \neq (0,0)$  is a rational function, which is continuous, so to verify continuity, it suffices to check (0,0). For all  $\epsilon > 0$ , choose  $\delta = \frac{\epsilon}{6} > 0$ , then for all (x,y) satisfying  $0 < |(x,y)| = r < \delta$ , we get the following:

$$|D_2 f(x,y) - D_2 f(0,0)| = \left| \frac{(r\cos(\theta))^5 - (r\cos(\theta))(r\sin(\theta))^4 - 4(r\cos(\theta))^3(r\sin(\theta))^2}{((r\cos(\theta))^2 + (r\sin(\theta))^2)^2} - 0 \right|$$

$$= \left| \frac{r^5(\cos^5(\theta) - \cos(\theta)\sin^4(\theta) - 4\cos^3(\theta)\sin^2(\theta))}{r^4} \right| \le r(|\cos^5(\theta)| + |\cos(\theta)\sin^4(\theta)| + 4|\cos^3(\theta)\sin^2(\theta)|)$$

$$\le r(1+1+4) < 6 \cdot \frac{\epsilon}{6} = \epsilon$$

This proves the continuity of  $D_2f$  at (0,0), hence  $D_2f$  is continuous in  $\mathbb{R}^2$ .

## (b) Function $D_{21}f$ :

Given that  $D_1 f(x,y) = \frac{x^4 y + 4x^2 y^3 - y^5}{(x^2 + y^2)^2}$  for  $(x,y) \neq (0,0)$  and  $D_1 f(0,0) = 0$ , apply differentiation rule for  $(x,y) \neq (0,0)$ , we get:

$$D_{21}f(x,y) = \frac{\partial}{\partial y} \left( \frac{x^4y + 4x^2y^3 - y^5}{(x^2 + y^2)^2} \right) = \frac{(x^4 + 12x^2y^2 - 5y^4)(x^2 + y^2)^2 - (x^4y + 4x^2y^3 - y^5)2(x^2 + y^2)2y}{(x^2 + y^2)^4}$$

Which,  $D_{21}f(x,y)$  is continuous for  $(x,y) \neq (0,0)$  (since it's a rational function).

Now, to get  $D_{21}f(0,0)$ , we'll use limit definition:

$$D_{21}f(0,0) = \lim_{h \to 0} \frac{D_1f(0,h) - D_1f(0,0)}{h} = \lim_{h \to 0} \frac{0^4 \cdot h + 4 \cdot 0^2 \cdot h^3 - h^5}{(0^2 + h^2)^2 h} = \lim_{h \to 0} -\frac{h^5}{h^5} = -1$$

Hence,  $D_{21}f$  exists on the whole  $\mathbb{R}^2$ , and is continuous at all  $(x, y) \neq (0, 0)$ . But, it is not continuous at (0, 0), since choosing  $x \neq 0$  and y = 0,  $D_{21}f$  becomes:

$$D_{21}f(x,0) = \frac{x^8}{x^8} = 1$$

Hence,  $\lim_{x\to 0} D_{21}f(x,0) = 1 \neq -1 = D_{21}f(0,0)$ , showing the discontinuity at (0,0).

So,  $D_{21}f$  exists on  $\mathbb{R}^2$ , while being continuous on  $\mathbb{R}^2 \setminus \{0\}$ .

## Function $D_{12}f$ :

Given that  $D_2 f(x,y) = \frac{x^5 - xy^4 - 4x^3y^2}{(x^2 + y^2)^2}$  for  $(x,y) \neq (0,0)$  and  $D_2 f(0,0) = 0$ , apply differentiation rule for  $(x,y) \neq (0,0)$ , we get:

$$D_{12}f(x,y) = \frac{\partial}{\partial x} \left( \frac{x^5 - xy^4 - 4x^3y^2}{(x^2 + y^2)^2} \right) = \frac{(5x^4 - y^4 - 12x^2y^2)(x^2 + y^2)^2 - (x^5 - xy^4 - 4x^3y^2)2(x^2 + y^2)2x^2}{(x^2 + y^2)^4}$$

Hence,  $D_{12}f$  is continuous for  $(x,y) \neq (0,0)$ , since it's also a rational function.

Now, to get  $D_{12}f(0,0)$ , we'll again use limit definition:

$$D_{12}f(0,0) = \lim_{h \to 0} \frac{D_2f(h,0) - D_2f(0,0)}{h} = \lim_{h \to 0} \frac{h^5 - h \cdot 0^4 - 4h^3 \cdot 0^2}{(h^2 + 0^2)^2h} = \lim_{h \to 0} \frac{h^5}{h^5} = 1$$

Hence,  $D_{12}f$  exists on the whole  $\mathbb{R}^2$ , and is continuous at all  $(x,y) \neq (0,0)$ . But again, it's not continuous at (0,0), since choosing x=0 and  $y\neq 0$ ,  $D_{12}f$  becomes:

$$D_{12}f(0,y) = \frac{-y^8}{y^8} = -1$$

Hence,  $\lim_{y\to 0} D_{12}f(0,y) = -1 \neq 1 = D_{12}f(0,0)$ , showing the discontinuity at (0,0).

So,  $D_{12}f$  exists on  $\mathbb{R}^2$ , while being continuous on  $\mathbb{R}^2 \setminus \{0\}$ .

(c) From **part** (b), when verifying that the existence of  $D_{12}f(0,0)$  and  $D_{21}f(0,0)$ , we've shown that  $D_{12}f(0,0) = 1$ , and  $D_{21}f(0,0) = -1$ .

Question 2 Rudin Pg. 242 Problem 28:

For  $t \geq 0$ , put

$$\varphi(x,t) = \begin{cases} x & 0 \le x \le \sqrt{t} \\ -x + 2\sqrt{t} & \sqrt{t} \le x \le 2\sqrt{t} \\ 0 & otherwise \end{cases}$$

and put  $\varphi(x,t) = -\varphi(x,|t|)$  if t < 0.

Show that  $\varphi$  is continuous on  $\mathbb{R}^2$ , and  $D_2\varphi(x,0)=0$  for all x. Define

$$f(t) = \int_{-1}^{1} \varphi(x, t) dx$$

Show that f(t) = t if  $|t| < \frac{1}{4}$ . Hence

$$f'(0) \neq \int_{-1}^{1} D_2 \varphi(x,0) dx$$

#### Pf:

## Continuity of $\varphi$ :

First, for the open half plane x < 0, since  $\varphi(x,t) = 0$ , then  $\varphi$  is continuous.

### $D_2\varphi$ when t=0:

For all  $x \in \mathbb{R}$ , if  $x \leq 0$ , then we get  $\varphi(x,t) = 0$  regardless of  $t \in \mathbb{R}$ , showing that  $D_2\varphi(x,0) = \frac{\partial \varphi}{\partial t}(x,0) = 0$ . Now for x > 0, since for all  $t \in \mathbb{R}$  satisfying  $4|t| < x^2$ , we have  $2\sqrt{|t|} < x$ , then  $\varphi(x,t) = 0$  when  $t \in (-\frac{x^2}{4}, \frac{x^2}{4})$ . So,  $D_2\varphi(x,0) = 0$  (since  $\lim_{t\to 0} \frac{\varphi(x,t) - \varphi(x,0)}{t} = \lim_{t\to 0} 0 = 0$ , because for small enough t, it lies in the range  $(-\frac{x^2}{4}, \frac{x^2}{4})$ ).

So, regardless of  $x \in \mathbb{R}$ , we have  $D_2\varphi(x,0) = 0$ .

#### Function f(t):

Given  $f(t) = \int_{-1}^{1} \varphi(x,t)dt$ , when  $|t| < \frac{1}{4}$ , there are several cases to consider:

• when  $t \ge 0$ , then  $0 \le \sqrt{t} < \sqrt{\frac{1}{4}} = \frac{1}{2}$ , while  $0 \le 2\sqrt{t} < 1$ . Hence, the integral expression can be broken down as the following pieces:

$$\int_{-1}^{1} \varphi(x,t)dx = \int_{-1}^{0} 0dx + \int_{0}^{\sqrt{t}} xdx + \int_{\sqrt{t}}^{2\sqrt{t}} (-x+2\sqrt{t})dx + \int_{2\sqrt{t}}^{1} 0dx$$
$$= \frac{1}{2}x^{2} \Big|_{0}^{\sqrt{t}} + \left(-\frac{1}{2}x^{2} + 2\sqrt{t}x\right) \Big|_{\sqrt{t}}^{2\sqrt{t}} = \frac{1}{2}t + \left((4t - 2t) - (2t - \frac{1}{2}t)\right) = t$$

• when t < 0 (where t = -|t|), since  $\varphi(x,t) = -\varphi(x,|t|)$  with |t| > 0, then inheriting from the above expression, we get:

$$\int_{-1}^{1} \varphi(x,t)dx = -\int_{-1}^{1} \varphi(x,|t|)dx = -|t| = t$$

Hence, for  $|t| < \frac{1}{4}$ , we can deduce that f(t) = t, which f'(t) = 1. So, the following inequality is true:

$$f'(0) = 1 \neq 0 = \int_{-1}^{1} 0 dx = \int_{-1}^{1} D_2 \varphi(x, 0) dx$$

This shows that differentiation under integral sign fails under certain situation.

Question 3 Rudin Pq. 243 Problem 30:

Let  $f \in C^{(m)}(E)$ , where E is an open subset of  $\mathbb{R}^n$ . Fix  $a \in E$ , and suppose  $x \in \mathbb{R}^n$  is so close to 0 that the points p(t) = a + tx lie in E whenever  $0 \le t \le 1$ . Define h(t) = f(p(t)) for all  $t \in \mathbb{R}$  for which  $p(t) \in E$ .

(a) For  $1 \le k \le m$ , show (by repeated application of the chain rule) that

$$h^{(k)}(t) = \sum (D_{l_1...l_k}f)(p(t))x_{l_1}...x_{l_k}$$

The sum extends over all order k-tuples  $(l_1,...,l_k)$  in which each  $l_i$  is one of the integers 1,...,n.

#### Pf:

Given  $a, x \in \mathbb{R}^n$  (where  $x = (x_1, ..., x_n)$  for fixed  $x_1, ..., x_n \in \mathbb{R}^n$ ) and p(t) = a + tx for  $t \in [0, 1]$ , then p'(t) = x.

Now, we'll use induction to verify the formula (and we'll use matrix representation of the differentials). First, for k = 1, using chain rule, we get the following:

$$h'(t) = Df(p(t))p'(t) = \begin{pmatrix} D_1 f & \dots & D_n f \end{pmatrix} \Big|_{p(t)} \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} = \sum_{i=1}^n D_i f(p(t)) x_i$$

Since all the possible 1-tuple is included in the summation, the h'(t) satisfies the given formula.

Now, suppose for given  $1 \le k \le (m-1)$ ,  $h^{(k)}(t)$  satisfies the following formula:

$$h^{(k)}(t) = \sum (D_{l_1...l_k}f)(p(t))x_{l_1}...x_{l_k}$$

Since for each k-tuple  $(l_1, ..., l_k)$  (where each  $l_i \in \{1, ..., n\}$ ) has the function  $x_{l_1}...x_{l_k}D_{l_1...l_k}f(p(t))$  being a differentiable function from (0, 1) to  $\mathbb{R}$  (where  $D_{l_1...l_k}f(z)$  for  $z \in E$  is a differentiable function, since it has only been differentiated k < m times, while  $f \in C^{(m)}(E)$ ). Then, to calculate the  $(k+1)^{th}$  derivative, we get:

$$h^{(k+1)}(t) = \sum \frac{d}{dt} (D_{l_1...l_k} f)(p(t)) x_{l_1}...x_{l_k}$$

$$\forall (l_1, ..., l_k), \quad \frac{d}{dt} (D_{l_1...l_k} f)(p(t)) x_{l_1}...x_{l_k} = x_{l_1}...x_{l_k} D\left(D_{l_1...l_k} f\right)(p(t)) p'(t)$$

$$= x_{l_1}...x_{l_k} \sum_{i=1}^n D_i \left(D_{l_1...l_k} f\right)(p(t)) x_i = \sum_{i=1}^n D_{il_1...l_k} f(p(t)) x_i x_{l_1}...x_{l_k}$$

$$\implies h^{(k+1)}(t) = \sum \left(\sum_{i=1}^n D_{il_1...l_k} f(p(t)) x_i x_{l_1}...x_{l_k}\right)$$

Which, the first summation indicates all possible k-tuple  $(l_1,...,l_k)$  for  $l_i \in \{1,...,n\}$ .

Now, for all (k+1)-tuple  $(j_0, j_1, ..., j_k)$  where each  $j_l \in \{1, ..., n\}$ , choose the unique k-tuple  $(j_1, ..., j_k)$ , then  $D_{j_0j_1...j_k}f(p(t))x_{j_0}x_{j_1}...x_{j_k}$  appears precisely once in the summation of  $h^{(k+1)}(t)$  given above; similarly, since each k-tuple  $(l_1, ..., l_k)$  and  $i \in \{1, ..., n\}$  corresponds to a unique (k+1)-tuple  $(i, l_1, ..., l_k)$ , so the summation in  $h^{(k+1)}(t)$  has a 1-to-1 correspondance to all (k+1)-tuple. Then, the summation  $h^{(k+1)}(t)$  can also be described as:

$$h^{(k+1)}(t) = \sum D_{l_1...l_k l_{k+1}} f(p(t)) x_{l_1}...x_{l_k} x_{l_{k+1}}$$

Where each  $(l_1, ..., l_k, l_{k+1})$  is a (k+1)-tuple with entries from  $\{1, ..., n\}$ .

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Question 4 Rudin Pg. 288 Problem 2:

For i=1,2,3,..., let  $\varphi_i\in\mathcal{C}(\mathbb{R})$  have support in  $(2^{-i},2^{1-i})$ , such that  $\int \varphi_i=1$ . Put

$$f(x,y) = \sum_{i=1}^{\infty} (\varphi_i(x) - \varphi_{i+1}(x))\varphi_i(y)$$

Then f has compact support in  $\mathbb{R}^2$ , f is cotinuous except at (0,0), and

$$\int dy \int f(x,y)dx = 0, \quad but \int dx \int f(x,y)dy = 1$$

Observe that f is unbounded in every neighborhood of (0,0).

Pf:

The function f is well-defined: