

# Math 118C HW3

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**Question 1** *Rudin Pg. 241 Problem 19:*

*Show that the system of equations*

$$3x + y - z + u^2 = 0$$

$$x - y + 2z + u = 0$$

$$2x + 2y - 3z + 2u = 0$$

*can be solved for  $x, y, u$  in terms of  $z$ ; for  $x, z, u$  in terms of  $y$ ; for  $y, z, u$  in terms of  $x$ ; but not for  $x, y, z$  in terms of  $u$ .*

**Pf:**

## 2

**Question 2** *Rudin Pg. 242 Problem 23:*

Define  $f$  in  $\mathbb{R}^3$  by

$$f(x, y_1, y_2) = x^2 y_1 + e^x + y_2$$

Show that  $f(0, 1, -1) = 0$ ,  $(D_1 f)(0, 1, -1) \neq 0$ , and that there exists therefore a differentiable function  $g$  in some neighborhood of  $(1, -1)$  in  $\mathbb{R}^2$ , such that  $g(1, -1) = 0$  and

$$f(g(y_1, y_2), y_1, y_2) = 0$$

Find  $(D_1 g)(1, -1)$  and  $(D_2 g)(1, -1)$ .

**Pf:**

### 3

**Question 3** *Rudin Pg. 242 Problem 24:*

For  $(x, y) \neq (0, 0)$ , define  $f = (f_1, f_2)$  by

$$f_1(x, y) = \frac{x^2 - y^2}{x^2 + y^2}, \quad f_2(x, y) = \frac{xy}{x^2 + y^2}$$

Compute the rank of  $f'(x, y)$ , and find the range of  $f$ .

**Pf:**

**Question 4** Rudin Pg. 242 Problem 25:

Suppose  $A \in \mathcal{L}(\mathbb{R}^n, \mathbb{R}^m)$ , let  $r$  be the rank of  $A$ .

(a) Define  $S$  as in the proof of Theorem 9.32. Show that  $SA$  is a projection in  $\mathbb{R}^n$  whose null space is  $\text{null}(A)$  and whose range is  $\text{range}(S)$ .

(b) Use (a) to show that

$$\dim(\text{null}(A)) + \dim(\text{range}(A)) = n$$

**Pf:**

- (a) Given that  $A$  has rank  $r$ , then its range  $\text{range}(A) \subseteq \mathbb{R}^m$  is an  $r$ -dimensional linear subspace, hence there exists  $y_1, \dots, y_r \in \text{range}(A)$  that forms a basis of it.

Then, by the text in Rudin, choose  $z_1, \dots, z_r \in \mathbb{R}^n$ , so for each index  $i \in \{1, \dots, r\}$ ,  $Az_i = y_i$ . Which, the collection  $z_1, \dots, z_r \in \mathbb{R}^n$  is linearly independent, since if  $a_1, \dots, a_r \in \mathbb{R}$  satisfies  $\sum_{i=1}^r a_i z_i = \bar{0}$ , then the following is true:

$$A \left( \sum_{i=1}^r a_i z_i \right) = \sum_{i=1}^r a_i (Az_i) = \sum_{i=1}^r a_i y_i$$

By the linear independence of  $y_1, \dots, y_r \in \text{range}(A)$ , each  $a_i = 0$ , which proves the linear independence of  $z_1, \dots, z_r \in \mathbb{R}^n$ .

Now, define  $S \in \mathcal{L}(\text{range}(A), \mathbb{R}^n)$  the same as in the text, which has the following formula:

$$\forall c_1, \dots, c_r \in \mathbb{R}, \quad S \left( \sum_{i=1}^r c_i y_i \right) = \sum_{i=1}^r c_i z_i$$

Then, for all  $x \in \mathbb{R}^n$ , since  $Ax \in \text{range}(A)$ , it is spanned by  $y_1, \dots, y_r$ , hence there exists unique  $a_1, \dots, a_r \in \mathbb{R}$ , such that the following is true:

$$Ax = \sum_{i=1}^r a_i y_i$$

Hence, we get the following:

$$SAx = S \left( \sum_{i=1}^r a_i y_i \right) = \sum_{i=1}^r a_i z_i$$

Hence, applying  $SA$  twice, we get:

$$SA(SAx) = SA \left( \sum_{i=1}^r a_i z_i \right) = S \left( \sum_{i=1}^r a_i y_i \right) = \sum_{i=1}^r a_i z_i$$

This shows that  $SA(SAx) = SAx$  for all  $x \in \mathbb{R}^n$ , hence  $SA$  is a projection on  $\mathbb{R}^n$ .

Now, to find the null space and range, consider the following:

- For all  $x \in \text{null}(A)$ , since  $Ax = 0$ , then  $SAx = S(0) = 0$ , so  $x \in \text{null}(SA)$ , or  $\text{null}(A) \subseteq \text{null}(SA)$ .

On the other hand, for all  $x \in \text{null}(SA)$ , since  $S(Ax) = 0$ ,  $Ax \in \text{null}(S)$ . But, since  $Ax \in \text{range}(A)$ , there exists unique  $a_1, \dots, a_r \in \mathbb{R}$ , with  $Ax = \sum_{i=1}^r a_i y_i$ . Hence, we have the following:

$$0 = S(Ax) = S\left(\sum_{i=1}^r a_i y_i\right) = \sum_{i=1}^r a_i z_i$$

Hence, by linear independence of  $z_1, \dots, z_r \in \mathbb{R}^n$ , we must have  $a_i = 0$  for all index  $i \in \{1, \dots, r\}$ . This proves that  $Ax = \sum_{i=1}^r a_i y_i = 0$ , so  $x \in \text{null}(A)$ . Hence,  $\text{null}(SA) \subseteq \text{null}(A)$ , showing that  $\text{null}(SA) = \text{null}(A)$ .

- For all  $z \in \text{range}(SA)$ , there exists  $x \in \mathbb{R}^n$  with  $SAx = z$ . Since  $z = S(Ax) \in \text{range}(S)$ , then  $\text{range}(SA) \subseteq \text{range}(S)$ .

Similarly, for all  $z \in \text{range}(S)$ , there exists  $y \in \text{range}(A)$  (the domain of  $S$ ), with  $Sy = z$ ; then because there exists  $x \in \mathbb{R}^n$ , with  $Ax = y$  by the definition of range, we have  $SAx = S(Ax) = Sy = z$ , hence  $z \in \text{range}(SA)$ , proving that  $\text{range}(S) \subseteq \text{range}(SA)$ , or  $\text{range}(S) = \text{range}(SA)$ .

Hence, the above two cases prove that  $\text{null}(SA) = \text{null}(A)$ , while  $\text{range}(S) = \text{range}(SA)$ . So,  $SA$  is a projection in  $\mathbb{R}^n$  with null space being  $\text{null}(A)$ , and range being  $\text{range}(S)$ .

(b)

**Question 5** *Rudin Pg. 242 Problem 26:*

*Show that the existence (and even the continuity) of  $D_{12}f$  does not imply the existence of  $D_1f$ . For example, let  $f(x, y) = g(x)$ , where  $g$  is nowhere differentiable.*

**Pf:**

Consider the Weierstrass Function  $g : \mathbb{R} \rightarrow \mathbb{R}$ , which is uniformly continuous, while being differentiable nowhere.

Then, given the function  $f : \mathbb{R}^2 \rightarrow \mathbb{R}$  by  $f(x, y) = g(x)$ , since  $g$  is not differentiable with respect to its variable  $x$ , then  $D_1f$  does not exist; yet, since  $D_2f \equiv 0$  (due to the fact that  $g$  is a constant when  $x$  is fixed), then  $D_{12}f = D_1(D_2f) = 0$ .

Hence, even though  $D_{12}f$  is continuous,  $D_1f$  doesn't exist in this case.