Math 118C HW3

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Question 1 Rudin Pg. 241 Problem 19:

Show that the system of equations

$$3x + y - z + u^2 = 0$$

$$x - y + 2z + u = 0$$

$$2x + 2y - 3z + 2u = 0$$

can be solved for x, y, u in terms of z; for x, z, u in terms of y; for y, z, u in terms of x; but not for x, y, z in terms of u.

Pf:

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Question 2 Rudin Pg. 242 Problem 23:

Define f in \mathbb{R}^3 by

$$f(x, y_1, y_2) = x^2 y_1 + e^x + y_2$$

Show that f(0,1,-1) = 0, $(D_1f)(0,1,-1) \neq 0$, and that there exists therefore a differentiable function g in some neighborhood of (1,-1) in \mathbb{R}^2 , such that g(1,-1) = 0 and

$$f(g(y_1, y_2), y_1, y_2) = 0$$

Find $(D_1g)(1,-1)$ and $(D_2g)(1,-1)$.

Pf:

f and Df at (0,1,-1):

Question 3 Rudin Pg. 242 Problem 24:

For $(x, y) \neq (0, 0)$, define $f = (f_1, f_2)$ by

$$f_1(x,y) = \frac{x^2 - y^2}{x^2 + y^2}, \quad f_2(x,y) = \frac{xy}{x^2 + y^2}$$

Compute the rank of f'(x,y), and find the range of f.

Pf:

Rank of f'(x,y) = Df(x,y):

Given f_1 and f_2 , their partial derivatives are given as follow:

$$\frac{\partial f_1}{\partial x} = \frac{2x(x^2 + y^2) - 2x(x^2 - y^2)}{(x^2 + y^2)^2} = \frac{4xy^2}{(x^2 + y^2)^2}, \quad \frac{\partial f_1}{\partial y} = \frac{-2y(x^2 + y^2) - 2y(x^2 - y^2)}{(x^2 + y^2)^2} = \frac{-4x^2y}{(x^2 + y^2)^2}$$

$$\frac{\partial f_2}{\partial x} = \frac{y(x^2 + y^2) - 2x(xy)}{(x^2 + y^2)^2} = \frac{y^3 - x^2y}{(x^2 + y^2)^2}, \quad \frac{\partial f_2}{\partial y} = \frac{x(x^2 + y^2) - 2y(xy)}{(x^2 + y^2)^2} = \frac{x^3 - xy^2}{(x^2 + y^2)^2}$$

Hence, the differential Df is given as:

$$Df(x,y) = \begin{pmatrix} \frac{\partial f_1}{\partial x} & \frac{\partial f_1}{\partial y} \\ \frac{\partial f_2}{\partial x} & \frac{\partial f_2}{\partial y} \end{pmatrix} = \frac{1}{(x^2 + y^2)^2} \begin{pmatrix} 4xy^2 & -4x^2y \\ (y^3 - x^2y) & (x^3 - xy^2) \end{pmatrix}$$

• If x = 0, the matrix is given by:

$$Df(0,y) = \frac{1}{y^4} \begin{pmatrix} 0 & 0 \\ y^3 & 0 \end{pmatrix}$$

Which, with $y \neq 0$ (due to the condition $(x, y) \neq (0, 0)$), the above matrix has rank 1.

• If y = 0, the matrix is given by:

$$Df(x,0) = \frac{1}{x^4} \begin{pmatrix} 0 & 0 \\ 0 & x^3 \end{pmatrix}$$

Which again, with $x \neq 0$, the above matrix has rank 1.

• If both $x, y \neq 0$, then consider any vector r(x, -y) for $r \in \mathbb{R}$, we get::

$$Df(x,y)r\begin{pmatrix} x \\ -y \end{pmatrix} = \frac{1}{(x^2 + y^2)^2} \begin{pmatrix} xy^2 & -x^2y \\ (y^3 - x^2y) & (x^3 - xy^2) \end{pmatrix} r \begin{pmatrix} x \\ -y \end{pmatrix}$$
$$\frac{r}{(x^2 + y^2)^2} \begin{pmatrix} x^2y^2 - x^2y^2 \\ (xy^3 - x^3y) - (-x^3y + xy^3) \end{pmatrix} = \bar{0}$$

So the span $\{(x, -y)\}$ is within the null space of Df(x, y), so the dimension of null space is at least 1. On the other hand, consider $(1,0) \in \mathbb{R}^2$ (that is linearly independent with (x, -y), since (x, -y) has both entries being nonzero), it has the following:

$$Df(x,y)\begin{pmatrix} 1\\ 0 \end{pmatrix} = \frac{1}{(x^2+y^2)^2}\begin{pmatrix} xy^2 & -x^2y\\ (y^3-x^2y) & (x^3-xy^2) \end{pmatrix}r\begin{pmatrix} 1\\ 0 \end{pmatrix} = \frac{1}{(x^2+y^2)^2}\begin{pmatrix} xy^2\\ (y^3-x^2y) \end{pmatrix} \neq \bar{0}$$

Which, it shows that the range of Df(x,y) is nontrivial, hence it has dimension at least 1 also.

Because both the null space and the range have dimension ≥ 1 , while \mathbb{R}^2 has dimension 2, by Rank Nullity Theorem, it enforces both the null space and the range must have dimension precisely 1 (since the sum of the dimension of the null space and the range must be 2). So, the rank of Df(x,y) is again 1.

So, regardless of the case, Df(x, y) has rank 1.

Range of f:

When fixing $(x,y) \neq (0,0)$ in \mathbb{R}^2 , there exists r > 0, and $\theta \in [0,2\pi)$, such that $x = r\cos(\theta)$ and $y = r\sin(\theta)$ (under polar coordinates). Then, we get the output of f_1, f_2 as:

$$f_1(x,y) = \frac{(r\cos(\theta))^2 - (r\sin(\theta))^2}{(r\cos(\theta))^2 + (r\sin(\theta))^2} = \frac{r^2(\cos^2(\theta) - \sin^2(\theta))}{r^2} = \cos^2(\theta) - \sin^2(\theta) = \cos(2\theta)$$

$$f_2(x,y) = \frac{(r\cos(\theta))(r\sin(\theta))}{(r\cos(\theta))^2 + (r\sin(\theta))^2} = \frac{r^2\cos(\theta)\sin(\theta)}{r^2} = \sin(\theta)\cos(\theta) = \frac{1}{2}\sin(2\theta)$$

Hence, for all $(x,y) \neq (0,0)$, $f = (f_1,f_2)$ satisfies the following equation:

$$f_1^2 + 4f_2^2 = \cos^2(2\theta) + 4 \cdot \frac{1}{4}\sin^2(2\theta) = \cos^2(2\theta) + \sin^2(2\theta) = 1$$

Hence, (u, v) = f(x, y) is a solution to $u^2 + 4v^2 = 1$, so the range of f is contained in the ellipse characterized by $u^2 + 4v^2 = 1$.

On the other hand, for all point (u, v) satisfying $u^2 + 4v^2 = 1$, there exists $\theta \in [0, 2\pi)$, such that $u = \cos(\theta)$ and $v = \frac{1}{2}\sin(\theta)$. Then, consider the point $(\cos(\frac{\theta}{2}), \sin(\frac{\theta}{2})) \in \mathbb{R}^2$, we have:

$$f(\cos(\frac{\theta}{2}), \sin(\frac{\theta}{2})) = (f_1(\cos(\frac{\theta}{2}), \sin(\frac{\theta}{2})), f_2(\cos(\frac{\theta}{2}), \sin(\frac{\theta}{2}))) = \left(\cos\left(2 \cdot \frac{\theta}{2}\right), \frac{1}{2}\sin\left(2 \cdot \frac{\theta}{2}\right)\right)$$
$$= \left(\cos(\theta), \frac{1}{2}\sin(\theta)\right) = (u, v)$$

Hence, (u, v) is also in the range of f. This proves that f has the range precisely described by the ellipse $u^2 + 4v^2 = 1$.

Question 4 Rudin Pg. 242 Problem 25:

Suppose $A \in \mathcal{L}(\mathbb{R}^n, \mathcal{R}^m)$, let r be the rank of A.

- (a) Define S as in the proof of Theorem 9.32. Show that SA is a projection in \mathbb{R}^n whose null space is null(A) and whose range is range(S).
- (b) Use (a) to show that

$$\dim(null(A)) + \dim(range(A)) = n$$

Pf:

(a) Given that A has rank r, then its range range(A) $\subseteq \mathbb{R}^m$ is an r-dimensional linear subspace, hence there exists $y_1, ..., y_r \in \text{range}(A)$ that forms a basis of it.

Then, by the text in Rudin, choose $z_1, ..., z_r \in \mathbb{R}^n$, so for each index $i \in \{1, ..., r\}$, $Az_i = y_i$. Which, the collection $z_1, ..., z_r \in \mathbb{R}^n$ is linearly independent, since if $a_1, ..., a_r \in \mathbb{R}$ satisfies $\sum_{i=1}^r a_i z_i = \bar{0}$, then the following is true:

$$A\left(\sum_{i=1}^{r} a_{i} z_{i}\right) = \sum_{i=1}^{r} a_{i} (A z_{i}) = \sum_{i=1}^{r} a_{i} y_{i}$$

By the linear independence of $y_1, ..., y_r \in \text{range}(A)$, each $a_i = 0$, which proves the linear independence of $z_1, ..., z_r \in \mathbb{R}^n$.

Now, define $S \in \mathcal{L}(\text{range}(A), \mathbb{R}^n)$ the same as in the text, which has the following formula:

$$\forall c_1, ..., c_r \in \mathbb{R}, \quad S\left(\sum_{i=1}^r c_i y_i\right) = \sum_{i=1}^r c_i z_i$$

Then, for all $x \in \mathbb{R}^n$, since $Ax \in \text{range}(A)$, it is spanned by $y_1, ..., y_r$, hence there exists unique $a_1, ..., a_r \in \mathbb{R}$, such that the following is true:

$$Ax = \sum_{i=1}^{r} a_i y_i$$

Hence, we get the following:

$$SAx = S\left(\sum_{i=1}^{r} a_i y_i\right) = \sum_{i=1}^{r} a_i z_i$$

Hence, applying SA twice, we get:

$$SA(SAx) = SA\left(\sum_{i=1}^{r} a_i z_i\right) = S\left(\sum_{i=1}^{r} a_i y_i\right) = \sum_{i=1}^{r} a_i z_i$$

This shows that SA(SAx) = SAx for all $x \in \mathbb{R}^n$, hence SA is a projection on \mathbb{R}^n .

Now, to find the null space and range, consider the following:

- For all $x \in \text{null}(A)$, since Ax = 0, then SAx = S(0) = 0, so $x \in \text{null}(SA)$, or $\text{null}(A) \subseteq \text{null}(SA)$.

On the other hand, for all \in null(SA), since S(Ax) = 0, $Ax \in$ null(S). But, since $Ax \in$ range(A), there exists unique $a_1, ..., a_r \in \mathbb{R}$, with $Ax = \sum_{i=1}^r a_i y_i$. Hence, we have the following:

$$0 = S(Ax) = S\left(\sum_{i=1}^{r} a_i y_i\right) = \sum_{i=1}^{r} a_i z_i$$

Hence, by linear independence of $z_1, ..., z_r \in \mathbb{R}^n$, we must have $a_i = 0$ for all index $i \in \{1, ..., r\}$. This proves that $Ax = \sum_{i=1}^r a_i y_i = 0$, so $x \in \text{null}(A)$. Hence, $\text{null}(SA) \subseteq \text{null}(A)$, showing that null(SA) = null(A).

- For all $z \in \text{range}(SA)$, there exists $x \in \mathbb{R}^n$ with SAx = z. Since $z = S(Ax) \in \text{range}(S)$, then $\text{range}(SA) \subseteq \text{range}(S)$.

Similarly, for all $z \in \text{range}(S)$, there exists $y \in \text{range}(A)$ (the domain of S), with Sy = z; then because there exists $x \in \mathbb{R}^n$, with Ax = y by the definition of range, we have SAx = S(Ax) = Sy = z, hence $z \in \text{range}(SA)$, proving that $\text{range}(S) \subseteq \text{range}(SA)$, or range(S) = range(SA).

Hence, the above to cases proves that null(SA) = null(A), while range(S) = range(SA). So, SA is a projection in \mathbb{R}^n with null space being null(A), and range being range(S).

(b) With the linearly independent set $z_1, ..., z_r \in \mathbb{R}^n$ given in **part** (a), we'll consider an extra list $x_1, ..., x_k \in \text{null}(A) \subseteq \mathbb{R}^n$ that forms a basis of null(A). Our goal is to prove that $x_1, ..., x_k, z_1, ..., z_r$ forms a basis of \mathbb{R}^n .

First, consider $a_1, ..., a_k, b_1, ..., b_r \in \mathbb{R}$, suppose the vector $\sum_{i=1}^k a_i x_i + \sum_{j=1}^r b_j z_j = \bar{0} \in \mathbb{R}^n$, then we have the following:

$$0 = A(\overline{0}) = A\left(\sum_{i=1}^{k} a_i x_i + \sum_{j=1}^{r} b_j z_j\right) = A\left(\sum_{i=1}^{k} a_i x_i\right) + A\left(\sum_{j=1}^{r} b_j z_j\right) = \sum_{j=1}^{r} b_j (Az_j) = \sum_{j=1}^{r} b_j y_j$$

Which, by the linear independence of $y_1, ..., y_r \in \text{range}(A)$ assumed in **part** (a), we must have $b_j = 0$ for all $j \in \{1, ..., n\}$. So, $\sum_{i=1}^k a_i x_i + \sum_{j=1}^r b_j z_j = \sum_{i=1}^k a_i x_i = \bar{0}$. But again, based on the linear independence ov $x_1, ..., x_k$ by assumption, we get $a_i = 0$ for all $i \in \{1, ..., k\}$. This proves that all $a_i, b_j = 0$, which the collection $x_1, ..., x_k, z_1, ..., z_r$ is linearly independent.

Then, for all $x \in \mathbb{R}^n$, since $Ax \in \text{range}(A)$, then there exists unique $b_1, ..., b_r \in \mathbb{R}$, with $Ax = \sum_{j=1}^r b_j y_j$. Hence, we get the following:

$$Ax = \sum_{j=1}^{r} b_j y_j = \sum_{j=1}^{r} b_j (Az_j) = A \left(\sum_{j=1}^{r} b_j z_j \right)$$

So, we can reduce to the following:

$$Ax - A\left(\sum_{j=1}^{r} b_j z_j\right) = A\left(x - \sum_{j=1}^{r} b_j z_j\right) = 0, \quad x - \sum_{j=1}^{r} b_j z_j \in \text{null}(A)$$

Then, since $x_1, ..., x_k$ forms a basis of null(A), then there exists unique $a_1, ..., a_k \in \mathbb{R}$, with:

$$x - \sum_{j=1}^{r} b_j z_j = \sum_{i=1}^{k} a_i x_i, \quad x = \sum_{i=1}^{k} a_i x_i + \sum_{j=1}^{r} b_j z_j$$

So, $x \in \text{span}\{x_1, ..., x_k, z_1, ..., z_r\}$, proving that $\mathbb{R}^n = \text{span}\{x_1, ..., x_k, z_1, ..., z_r\}$.

Hence, since $x_1, ..., x_k, z_1, ..., z_r$ spans \mathbb{R}^n while being linearly independent, it is a basis of \mathbb{R}^n . Hence, the length of the basis, $k + r = \dim(\mathbb{R}^n) = n$.

Which, since $x_1, ..., x_k$ is a basis of null(A), then dim(null(A)) = k.

On the other hand, since $S \in \mathcal{L}(\operatorname{range}(A), \mathbb{R}^n)$ is injective (since it maps $y_1, ..., y_r$ a basis of $\operatorname{range}(A)$, to $z_1, ..., z_r \in \mathbb{R}^n$ a linearly independent set), then the domain $\operatorname{range}(A)$ and range are in fact isomorphic as vector spaces, while the range of S is precisely $\operatorname{span}\{z_1, ..., z_r\}$ (since the definition of S is maps y_i to z_i for each $i \in \{1, ..., r\}$, showing that the output value must be a linear combination of all z_i). Hence, $\operatorname{dim}(\operatorname{range}(A)) = \operatorname{dim}(\operatorname{span}\{z_1, ..., z_r\}) = r$ (since $z_1, ..., z_r$ is linearly independent, it forms a basis of the span).

So, compile the information from above, we get:

$$k+r=n, \quad k=\dim(\operatorname{null}(A)), \quad r=\dim(\operatorname{range}(A))$$

$$\implies \dim(\operatorname{null}(A))+\dim(\operatorname{range}(A))=n$$

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Question 5 Rudin Pg. 242 Problem 26:

Show that the existence (and even the continuity) of $D_{12}f$ does not imly the existence of D_1f . For example, let f(x,y) = g(x), where g is nowhere differentiable.

Pf:

Consider the Weierstrass Functon $g: \mathbb{R} \to \mathbb{R}$, which is uniformly continuous, while being differentiable nowhere.

Then, given the function $f: \mathbb{R}^2 \to \mathbb{R}$ by f(x,y) = g(x), since g is not differentiable with respect to its variable x, then $D_1 f$ does not exist; yet, since $D_2 f \equiv 0$ (due to the fact that g is a constant when x is fixed), then $D_{12} f = D_1(D_2 f) = 0$.

Hence, even though $D_{12}f$ is continuous, D_1f doesn't exist in this case.