

# LIE ALGEBRA OF A LIE GROUP

Zih-Yu Hsieh, mentored by Arthur Jiang  
University of California Santa Barbara



## Tangent Vectors as Derivations

When embedding smooth manifolds into  $\mathbb{R}^n$ , tangent vectors are associated with directional derivatives. To generalize tangent vectors into abstract smooth manifold, we need an analogy:

### Definition

Any point  $u \in M$ , a **Derivation at  $u$** , is a linear map  $v_u : C^\infty(M) \rightarrow \mathbb{R}$ , that satisfies the product rule:

$$\forall f, g \in C^\infty(M), \quad v_u(fg) = f(u)(v_u g) + g(u)(v_u f)$$

Which, the set of all derivations at  $u$ , denoted as  $T_u(M)$ , is the **Tangent Space** of  $M$  at  $u$ , and each derivation  $v_u \in T_u(M)$  is a **Tangent Vector** of  $u$ .

## Vector Fields & Smooth Conditions

### Definition

a vector field is a map  $X : M \rightarrow TM$  ( $TM$  denotes the **Tangent Bundle**), with  $X(u) = X_u \in T_u(M)$ .

Which,  $X$  is a **Smooth Vector Field**, if  $X : M \rightarrow TM$  is a smooth map.

A collection of smooth vector fields on  $M$  is denoted as  $\mathfrak{X}(M)$ , which is an  $\mathbb{R}$ -vector space.

An equivalent condition of saying a vector field  $X$  is smooth, is through smooth functions  $f \in C^\infty(M)$ : For all  $u \in M$ ,  $X(u) = X_u \in T_u(M)$  is a derivation at  $u$ , define  $Xf : M \rightarrow \mathbb{R}$  by  $Xf(u) = X_u(f)$ , then  $X$  is a smooth vector field iff  $Xf \in C^\infty(M)$ . Which, a smooth vector field can be viewed as a **Derivation**:

### Property

For all  $f, g \in C^\infty(M)$ , given  $X \in \mathfrak{X}(M)$ , any  $u \in M$  satisfies product rule:

$$\begin{aligned} X(fg)(u) &= X_u(fg) = f(u)(X_u g) + g(u)(X_u f) = f(u)Xg(u) + g(u)Xf(u) \\ \implies X(fg) &= f(Xg) + g(Xf) \end{aligned}$$

## Vector Fields of Different Manifolds

Given  $M, N$  two smooth manifolds, and smooth map  $F : M \rightarrow N$ . Let  $X \in \mathfrak{X}(M)$ , an ideal situation is mapping  $X$  to a smooth vector field of  $N$  through  $F$ . Yet, this requires  $F$  to be bijective:

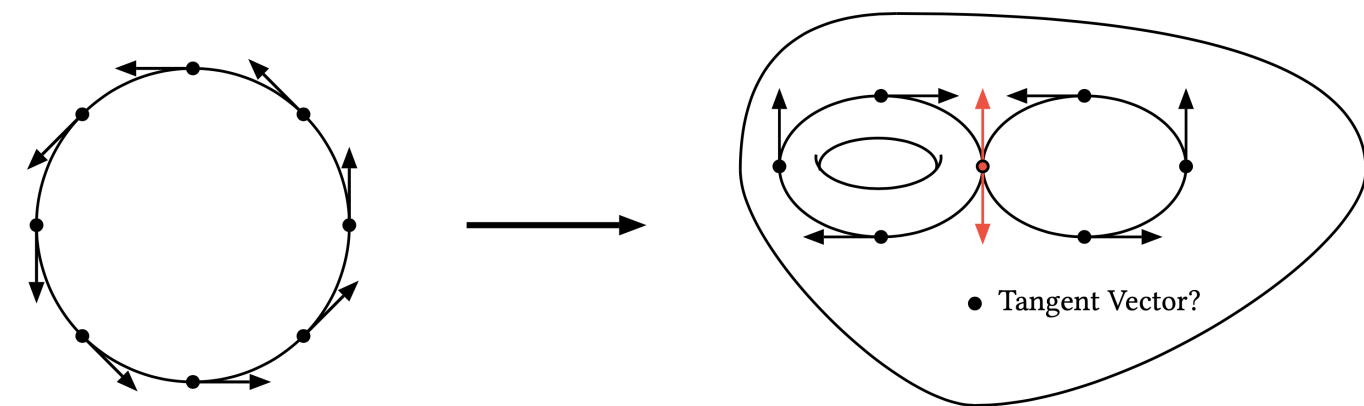


Figure 1: Example of Conflicting Tangent Vectors

So, we'll consider a weaker notion:

### Definition

Given  $X \in \mathfrak{X}(M)$  and  $Y \in \mathfrak{X}(N)$ , the two are **F-related**, if for all  $u \in M$ , the following is true:

$$dF_u(X_u) = Y_{F(u)}$$

Simply speaking,  $F$  maps the tangent vectors collected by  $X$ , to be compatible with tangent vectors collected by  $Y$ .

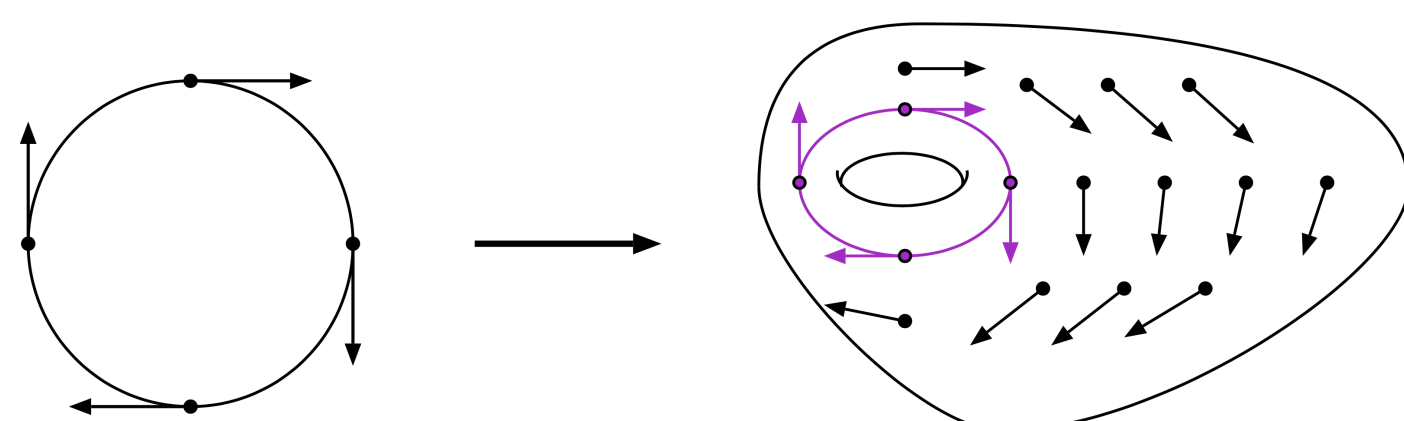


Figure 2: A demonstration of  $F$ -Relation

## Lie Brackets of Vector Fields

The initial motivation is to combine two vector fields  $X, Y \in \mathfrak{X}(M)$  to be another vector field. For all  $f \in C^\infty(M)$ , since  $Yf \in C^\infty(M)$ , then  $XYf := X(Yf) \in C^\infty(M)$ . But, in general  $XY$  is not a derivation, hence not a vector field:

### Example

Define vector fields  $X = \frac{\partial}{\partial x}$ ,  $Y = x\frac{\partial}{\partial y}$  on  $\mathbb{R}^2$ . Take smooth functions  $f(x, y) = x$  and  $g(x, y) = y$ , then we get the following:

$$XY(fg) = X\left(x\frac{\partial}{\partial y}(xy)\right) = \frac{\partial}{\partial x}(x^2) = 2x$$

But, product rule doesn't hold for this example:

$$f(XYg) + g(XYf) = x\left(X\left(x\frac{\partial}{\partial y}(y)\right)\right) + y\left(X\left(x\frac{\partial}{\partial y}(x)\right)\right) = x$$

So, we need to define a new operation on vector fields:

### Definition

The **Lie Bracket**  $[\cdot, \cdot] : \mathfrak{X}(M) \times \mathfrak{X}(M) \rightarrow \mathfrak{X}(M)$ , is defined as:

$$\forall X, Y \in \mathfrak{X}(M), \quad [X, Y] = XY - YX$$

Which, the output  $[X, Y] \in \mathfrak{X}(M)$ , since it satisfies product rule:

$$\begin{aligned} [X, Y](fg) &= X(Y(fg)) - Y(X(fg)) = X(f(Yg) + g(Yf)) - Y(f(Xg) + g(Xf)) \\ &= f(XYg) + (Yg)(Xf) + g(XYf) + (Yf)(Xg) - f(YXg) - (Xg)(Yf) - g(YXf) - (Xf)(Yg) \\ &= f(XYg - YXg) + g(XYf - YXf) = f[X, Y](g) + g[X, Y](f) \end{aligned}$$

Lie Bracket also satisfies these properties:

- **Bilinearity**:  $[aX + bY, Z] = a[X, Z] + b[Y, Z]$
- **Antisymmetry**:  $[X, Y] = -[Y, X]$
- **Jacobi's Identity**:  $[X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]] = 0$

Moreover, Lie Bracket inherits relation of smooth maps:

### Property

Given smooth map  $F : M \rightarrow N$ , if  $X_1, X_2 \in \mathfrak{X}(M)$  and  $Y_1, Y_2 \in \mathfrak{X}(N)$  are  $F$ -related respectively, then  $[X_1, X_2] \in \mathfrak{X}(M)$  and  $[Y_1, Y_2] \in \mathfrak{X}(N)$  are also  $F$ -related.

## Lie Group & Left-Invariant Vector Fields

The initial motivation is to study group structures in some smooth manifolds.

### Definition

A **Lie Group**  $G$ , is a smooth manifold along with group structure, such that the group operation  $P : G \times G \rightarrow G$  by  $P(g, h) = gh$ , and the inversion map  $i : G \rightarrow G$  by  $i(g) = g^{-1}$  are both smooth maps between manifolds.

For all  $g \in G$ , denote the left multiplication  $L_g : G \rightarrow G$  by  $L_g(h) = gh$ , since  $L_g = P|_{\{g\} \times G}$ , it is a smooth map. Hence, there's a notion of  $X$  being  $L_g$ -related to itself:

### Definition

Given any  $X \in \mathfrak{X}(G)$  and all  $g \in G$ ,  $X$  is a **Left-Invariant Vector Field**, if for all  $g \in G$ ,  $X$  is  $L_g$ -related to itself.

The collection of Left-Invariant vector fields  $\mathfrak{g} \subseteq \mathfrak{X}(G)$ , is a linear subspace.

Recall that Lie Bracket of vector field preserves  $F$ -relation between manifolds, so:

### Property

For all  $X, Y \in \mathfrak{X}(G)$  that are left-invariant, since for all  $g \in G$ ,  $X$  and  $Y$  are  $L_g$  related to themselves, then the Lie Bracket  $[X, Y]$  is also  $L_g$  related to  $[X, Y]$ . Hence,  $[X, Y]$  is also left-invariant, so Left-Invariant vector fields  $\mathfrak{g}$  is closed under Lie Bracket's operation.

## Lie Algebra on a Lie Group

### Definition

Given a vector space  $\mathfrak{g}$  over  $\mathbb{R}$  or  $\mathbb{C}$ , with a binary operation  $[\cdot, \cdot] : \mathfrak{g} \times \mathfrak{g} \rightarrow \mathfrak{g}$ , such that the following holds:

- **Bilinearity**:  $[aX + bY, Z] = a[X, Z] + b[Y, Z]$
- **Antisymmetry**:  $[X, Y] = -[Y, X]$
- **Jacobi's Identity**:  $[X, [Y, Z]] + [Y, [Z, X]] + [Z, [X, Y]] = 0$

Then, the pair  $(\mathfrak{g}, [\cdot, \cdot])$  is a **Lie Algebra**.

In general, Lie Algebra is non-associative, which Jacobi's Identity is an alternative condition for Lie Algebra.

Finally, we can define **Lie Algebra of a Lie Group**:

### Definition

Given a lie group  $G$ , since the subset of left-invariant vector fields  $\mathfrak{g} \subseteq \mathfrak{X}(G)$  forms a linear subspace, while closed under Lie Bracket's operation, then the pair  $(\mathfrak{g}, [\cdot, \cdot])$  forms a **Lie Algebra** of  $G$ , denoted as  $\text{Lie}(G)$ .

Here's an example of Lie Algebra on a Lie Group:

### Example

d

## Acknowledgements & Reference

I want to thank my mentor Arthur Jiang for the effort and kindness of guiding me through the materials, and provide helpful information on the project. I'd also like to thank the UCSB Math Department Directed Reading Program for this opportunity. Also, go check out Siyu Chen's poster as a continuation on its application on physics!

**Reference:** John M. Lee, Introduction to Smooth Manifolds, 2nd Edition