distributed? realtime? batch? highest level, design is affected by hardware and type of system users goal and system goal 

OS design OS timer for preemptive processes is a mechanism, the exact tick time is policy mechanism & policy: mehcanism: how to do it, policy: what specially will be done status info file modification system program: provide a convenient environment for program compilers, assemblers, debuggers and interpreters programming language support execution, interface to system calls prgram loading and execution communication dont pertain to system application prgram programming interface to the services provided by OS, accessd by high level API libraries rather than direct system call user application mode system call interface kernel mode Implementatio system call a number associated with each system call, system call interface maintains an indexed table according to these numbers, caller dont know how system call implemented and details, just need to obey API and the result call 1. simplest, pass parameters in reg, but regs are limited and parameters may be more than reg 2. parameters stored in a block in memory and addr of block passed as a parameter passing 3. parameters pushed onto the stack by program and popped off the stack by create, end, load, wait for time/event...!! debugger, locks device managment get time, date, system data information in message passing model, processes send and receive message to host name/ process name(pid), typically for short message communications in shared memory model, processes can access to memory regions owned by other processes, for large message commands are built into shell command are name of other programs that execute the command communication: via shared memory or through message passing(packets or messages moved by OS) API library, compilers and build tools, user interface, program execution, I/O operations error detection file-system manipulation user and other system programs GUI batch command line & build user interfaces provide environment and services to programs and users system calls OS services protection operating system hardware resource allocating, including CPU cycles, main memory, file storage, I/O device accounting:keep track of which user/process use how much resources provide functions to eusure the efficient and secure operation of system protection and security, protection: ensuring all access to system resources is controlled, security: requires authentication from outside of system, defending external I/O devices hardware interrupt: timer interrupt caused by an on-chip timer, used to preempt app and invoke OS kernel on regular intervals(OS tick, 1-50ms) software interrupt: exception, OS services are requested by trap mode bit to distinguish user mode or kernel mode OS operations: OS is invoked via interrupts and thus is interrupt some instructions designated as priviledged and some memory location may be accessible in kernel mode duel mode operation(user mode and kernel mode) kernel sets timer to prevent infinit loop, for the next interrupt system call(using trap instruction) change mode to kernel mode return from a system call by reseting mode bit back to user multiprogramming batch system: a bit historical, a job selected and run via job scheduling, none preemptive=cooperative multitasking timesharing/interactive system: logical extension in which CPU switches jobs that users interact with each job -> interactive computing, preemptive layered approach: OS is divided into a number of layers/levels, each built on top of lower layers, layers are selected such that each uses functions/operations and OS structure services of lower level layers microkernel kernel has a set of core components linked to additional services via modules modules talk to each other over known interfaces loaded as needed within kernel, preferred similar to layers but with more flexibility linux has loadable modules primarily for device drivers and file systems

before scheduling a process



