

# BRYCE MCKINLEY

(978) 302-1677, [bryce.j.mckinley@gmail.com](mailto:bryce.j.mckinley@gmail.com)  
Groton, MA  
[LinkedIn Profile](#)

---

## SKILLS

**Programming:** Python, Java, MATLAB, C++, C, Robot-C, Racket

**Software:** SolidWorks, Mathcad, Jira, Robot Operating System (ROS), Ubuntu Linux, Git, Gazebo Simulator, RViz, Scene Builder, Artificial Intelligence, Machine Learning

**Robotics:** Actuation, Manipulation, Sensing, Navigation

**General:** Scrum Workflow, Front-End GUI Development, Embedded Application Development, 3D Printing, Laser Cutting

## EDUCATION

**Worcester Polytechnic Institute (WPI), Worcester MA**  
Bachelor of Science in Robotics Engineering  
Bachelor of Science in Computer Science

May 2025  
GPA 3.76/4.0

## ACADEMIC PROJECTS

**Autonomous Mapping, Worcester MA**

Oct. - Dec. 2023

- Utilizing Python and ROS Noetic mapped an unknown field with LiDAR by identifying frontiers, calculating c-space, and navigating with A\*.
- Employed Monte Carlo localization to locate the robot after it was moved to a random location.

**Finding Purpose, Backpacking in Panama, Panama City Panama**

Aug. - Oct. 2023

- Investigated the connection between backpacking and developing a sense of purpose by conducting archival research, surveys, interviews, and an ethnography in Panama.

**Kiosk Application, Worcester MA**

Mar. - May. 2023

- Specialized in front-end in a group of ten software engineers designing a prospective informational kiosk application for use at Brigham and Women's Hospital.
- Utilized software engineering practices such as Jira, Scrum, and weekly sprints to ensure efficient workflow.

**Robotic Sensors, Worcester MA**

Nov. - Dec. 2022

- Designed, built, and coded in C++ three coordinated robots that communicated via an MQTT Broker to navigate a randomized field.
- Used PID control, ICC kinematics, inverse kinematics, IMU sensors, and vision processing of AprilTags.

**Pizza Delivery Robots, Worcester MA**

Sept. - Oct. 2022

- Designed in SolidWorks and 3D printed two distinct four-bar mechanism and grabber robots.
- Performed mechanical analysis of the systems, including linkage synthesis, force analysis, and cost.
- Coded in C++ a dynamic state machine that could adapt to changing starting conditions.

## WORK EXPERIENCE

**Lowe's: Outside Lawn & Garden Sales Associate, Lowell MA**

5/22 - 8/22

## ACTIVITIES AND INTERESTS

Mechanical Team Lead for Team 1277, FIRST Robotics  
Competitive Climbing Club, WPI

2020 - 2021  
2021 - Present

## AWARDS AND ACCOMPLISHMENTS

WPI Dean's List  
National Honor Society  
BSA Eagle Scout Award

2023 - 2024  
May 2020  
Sept. 2020