



# **SENG3320/6320:**

## **Software Verification and Validation**



# Basis Path Coverage

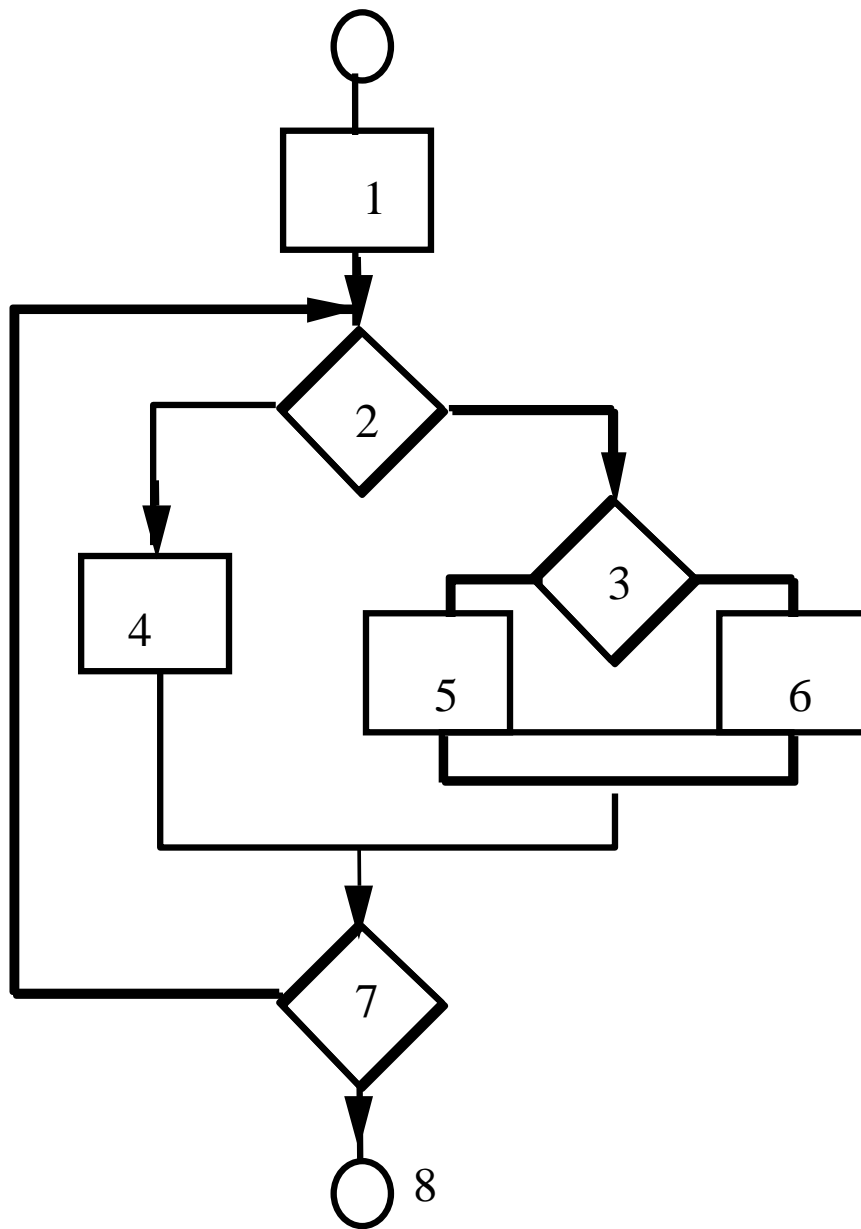
# Basis Path Testing

- A testing mechanism proposed by McCabe.
- A testing criterion between branch coverage and all path coverage.
- Basis Path testing is a software testing that fulfills the requirements of branch testing & also tests all of the **independent paths** that could be used to construct **any arbitrary path** through the computer program. [NIST]

Arthur H. Watson and Thomas J. McCabe (1996). "Structured Testing: A Testing Methodology Using the Cyclomatic Complexity Metric". NIST Special Publication 500-235.

Thomas J. McCabe: A Complexity Measure. IEEE Trans. Software Eng. 2(4): 308-320 (1976)

# Independent Path



A path through the system is independent from other paths only if it includes some vertices or edges that are not covered in the other path.

Path 1: 1,2,3,6,7,8

Path 2: 1,2,3,5,7,8

Path 3: 1,2,4,7,8

Path 4: 1,2,4,7,2,4,...7,8

# Cyclomatic Complexity

- A program's complexity can be measured by the cyclomatic number of the program flowgraph
- For a program with the program flowgraph  $G$ , the cyclomatic complexity  $v(G)$  is measured as:

$$v(G) = e - n + 2p$$

- $e$  : number of edges
  - Representing branches and cycles
- $n$  : number of nodes
  - Representing block of sequential code
- $p$  : number of connected components
  - For a single component,  $p=1$

# Simplified Complexity Calculation

- For a program with the program flowgraph  $G$ , the cyclomatic complexity  $v(G)$  is measured as:

$$v(G) = 1 + d$$

- $d$  : number of predicate nodes (i.e., nodes with out-degree other than 1)
  - $d$  represents number of loops in the graph or number of decision points in the program

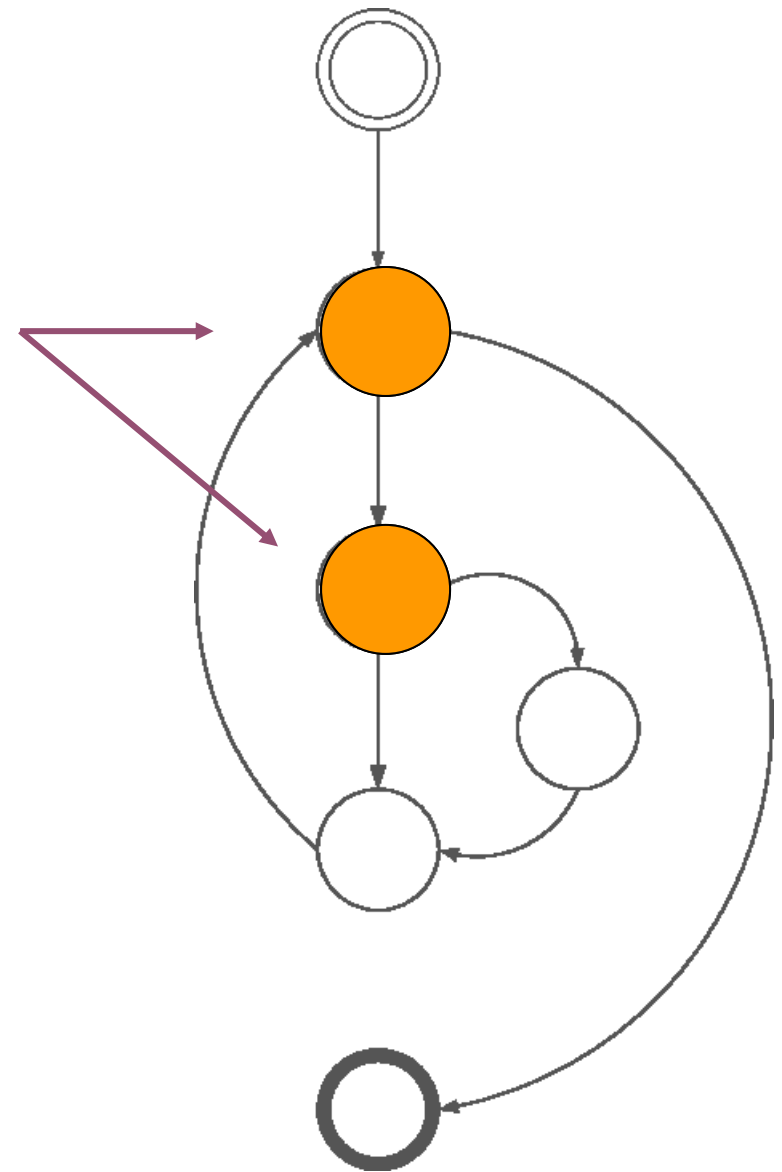
# Example 1

$$\begin{aligned}v(G) &= e - n + 2p \\&= 7 - 6 + 2 \times 1 \\&= 3\end{aligned}$$

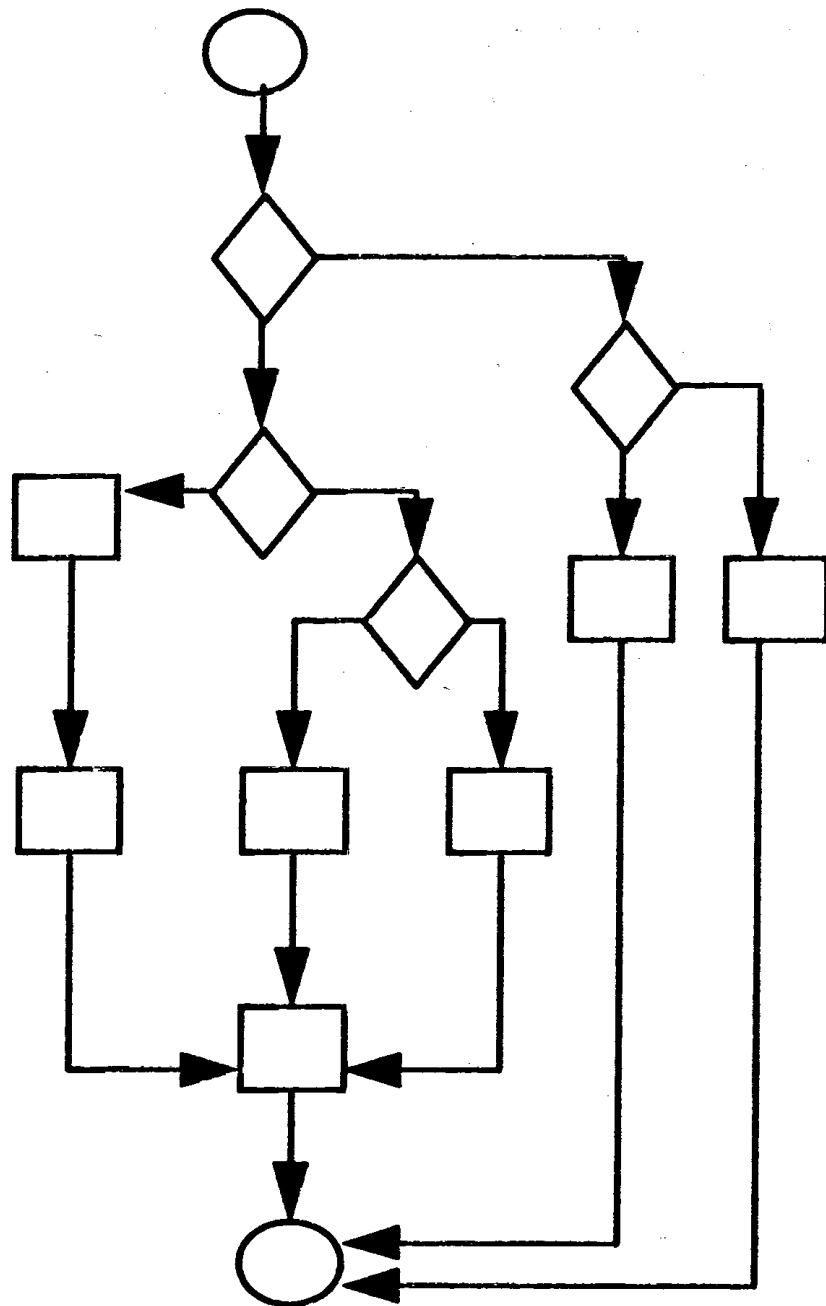
Or

$$\begin{aligned}v(G) &= 1 + d \\&= 1 + 2 = 3\end{aligned}$$

**Predicate  
nodes  
(decision  
points)**



# Example 2



$$v(G) = 16 - 13 + 2 = 5$$

*or*

$$v(G) = 4 + 1 = 5$$



# Cyclomatic Complexity: Usage

- **A useful indicator of software quality**
  - McCabe (1976) suggested that a module may be problematic if  $v(G)$  exceeds 10.
  - Grady (1994) concluded that 15 should be maximum value of  $v(G)$
  - Bennett (1994) suggested that a modules be rejected if its  $v(G)$  exceeds 20.
- **Useful in white-box testing**
  - It provides an upper bound on the number of test cases that will be required to guarantee coverage of all program statements.

# McCabe's Basis Path Testing

1. Generate control flow graph
2. Compute cyclomatic complexity
3. Determine a basis set of linearly independent paths
4. Generate tests for the basis paths

*All Path Testing*  $\geq$  *Basis Path Testing*  $\geq$  *Branch Testing*

# Basis Path Testing

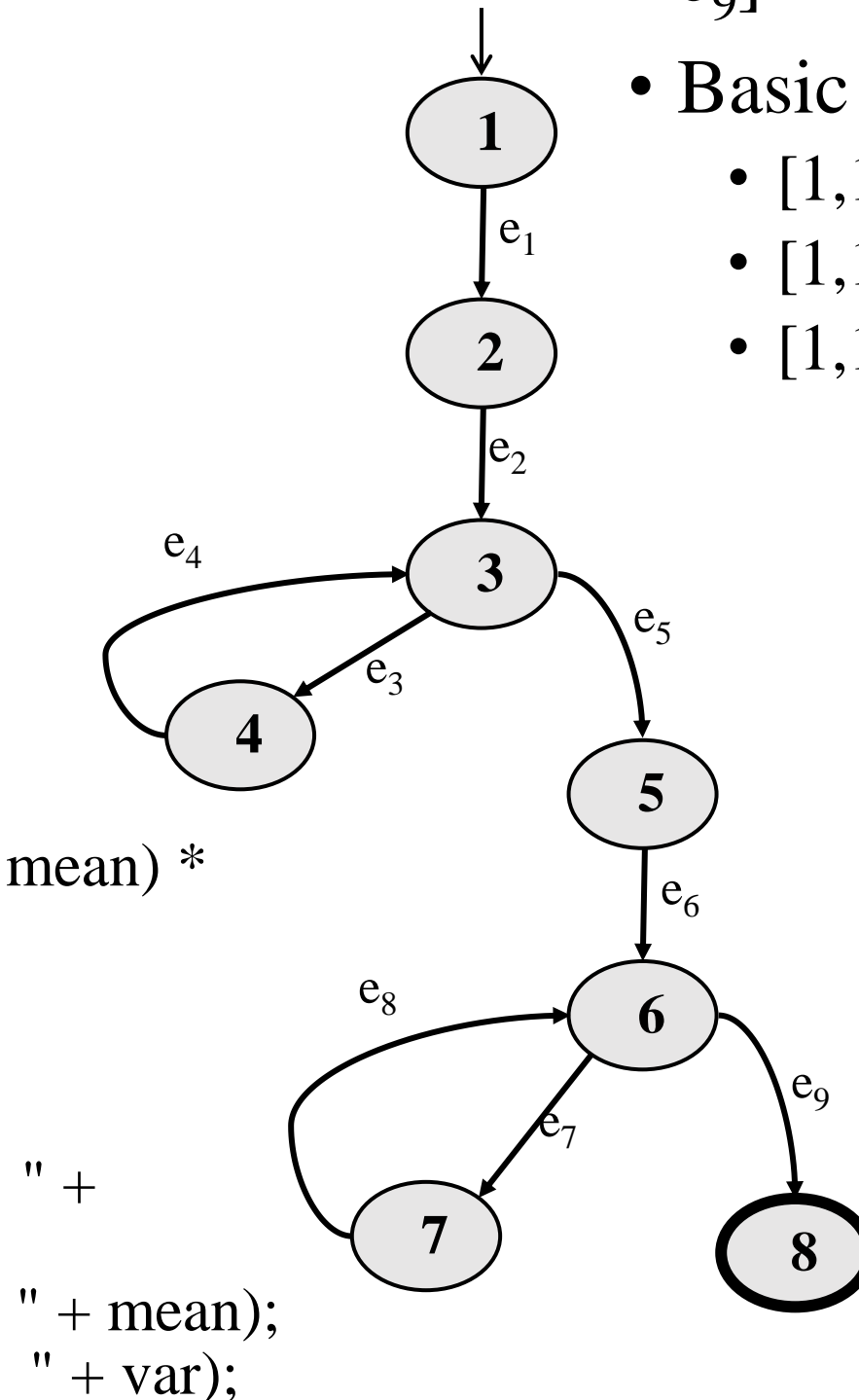
```
public static void CSta (int [ ] numbers)
{
    int length = numbers.length;
    double var, mean, sum, varsum;

    sum = 0.0;
    for (int i = 0; i < length; i++)
    {
        sum += numbers [ i ];
    }
    mean = sum / (double) length;

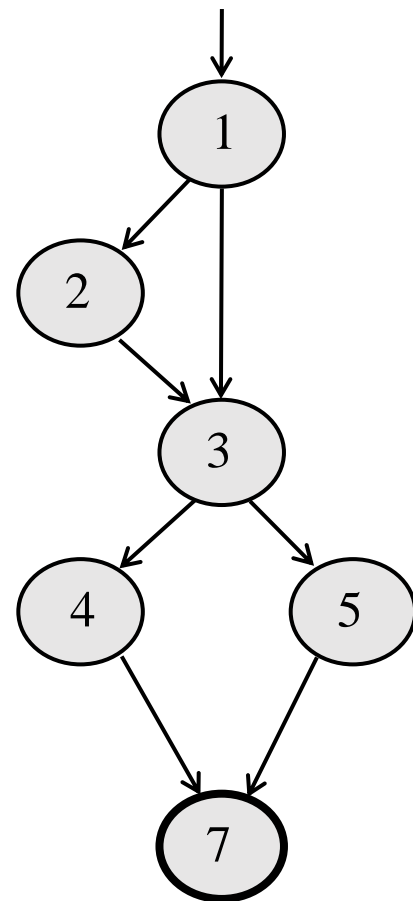
    varsum = 0.0;
    for (int i = 0; i < length; i++)
    {
        varsum = varsum + ((numbers [i] - mean) *
        (numbers [i] - mean));
    }
    var = varsum / ( length - 1.0 );

    System.out.println ("length:
length);
    System.out.println ("mean:
    System.out.println ("variance:
}
```

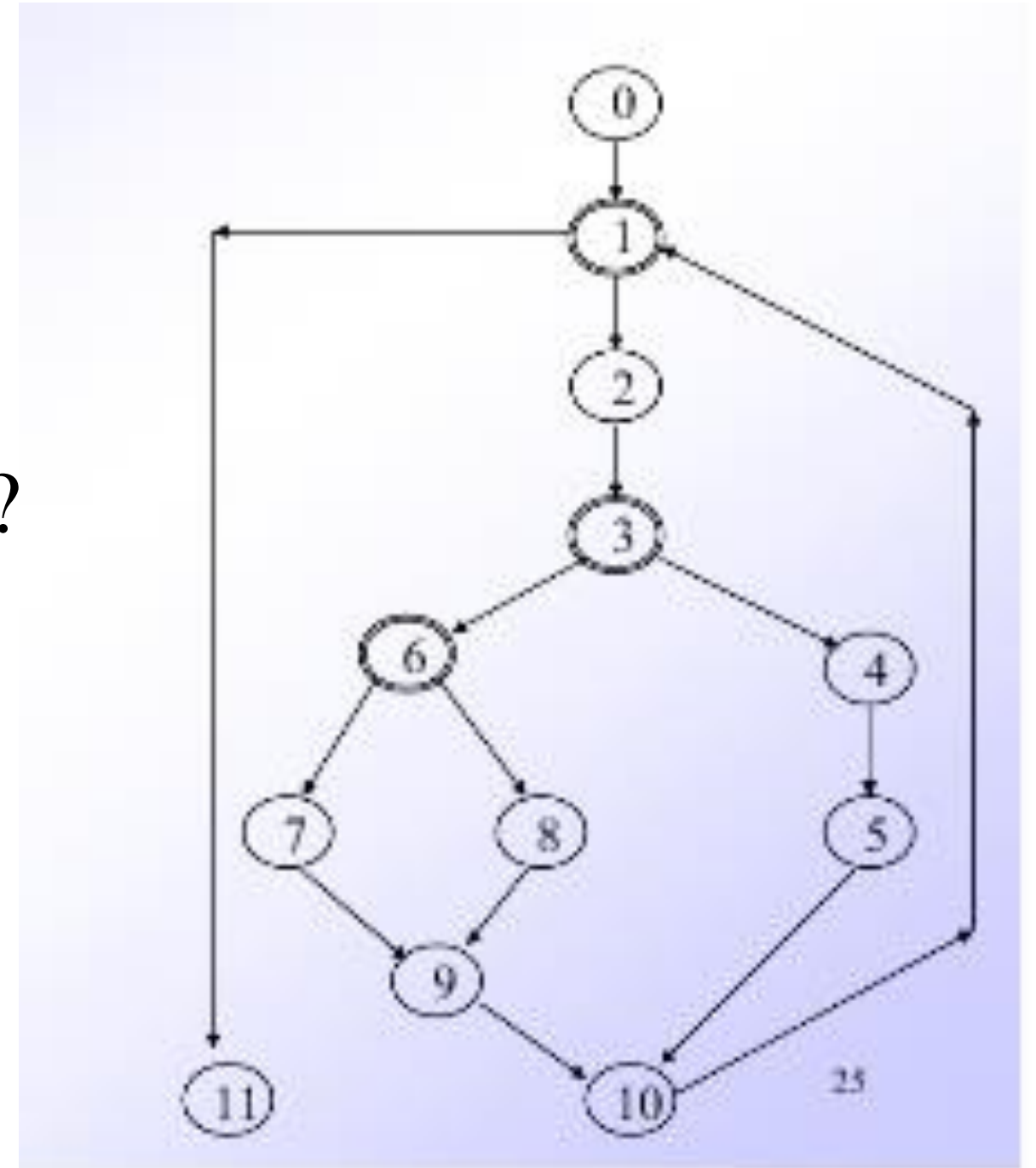
- $V(g) = 9 - 8 + 2 = 3$
- $[e_1, e_2, e_3, e_4, e_5, e_6, e_7, e_8, e_9]$
- Basic Path Set
  - $[1, 1, 0, 0, 1, 1, 0, 0, 1]$
  - $[1, 1, 1, 1, 1, 1, 0, 0, 1]$
  - $[1, 1, 0, 0, 1, 1, 1, 1, 1]$



# Quiz



Basis Path Set ?



# Quiz

```
#include <stdio.h>
main()
{
    int a ;
    scanf ("%d", &a);
    if ( a >= 10 )
        if ( a < 20 )
            printf ("10 < a< 20 %d\n" , a);
        else
            printf ("a >= 20      %d\n" , a);
    else
        printf ("a <= 10      %d\n" , a);
}
```

Basis Path Set ?

# Decision and Condition Coverage

# Logic in Program

`((x>5) && (y>0))`

Decision

Condition

# Decision Coverage

- Decision Coverage (DC):  
Executing *true* and *false* of decision.
- Also called Branch Decision Coverage

Example:  $((x > 5) \ \&\& \ (y > 0))$ : *true* and *false*

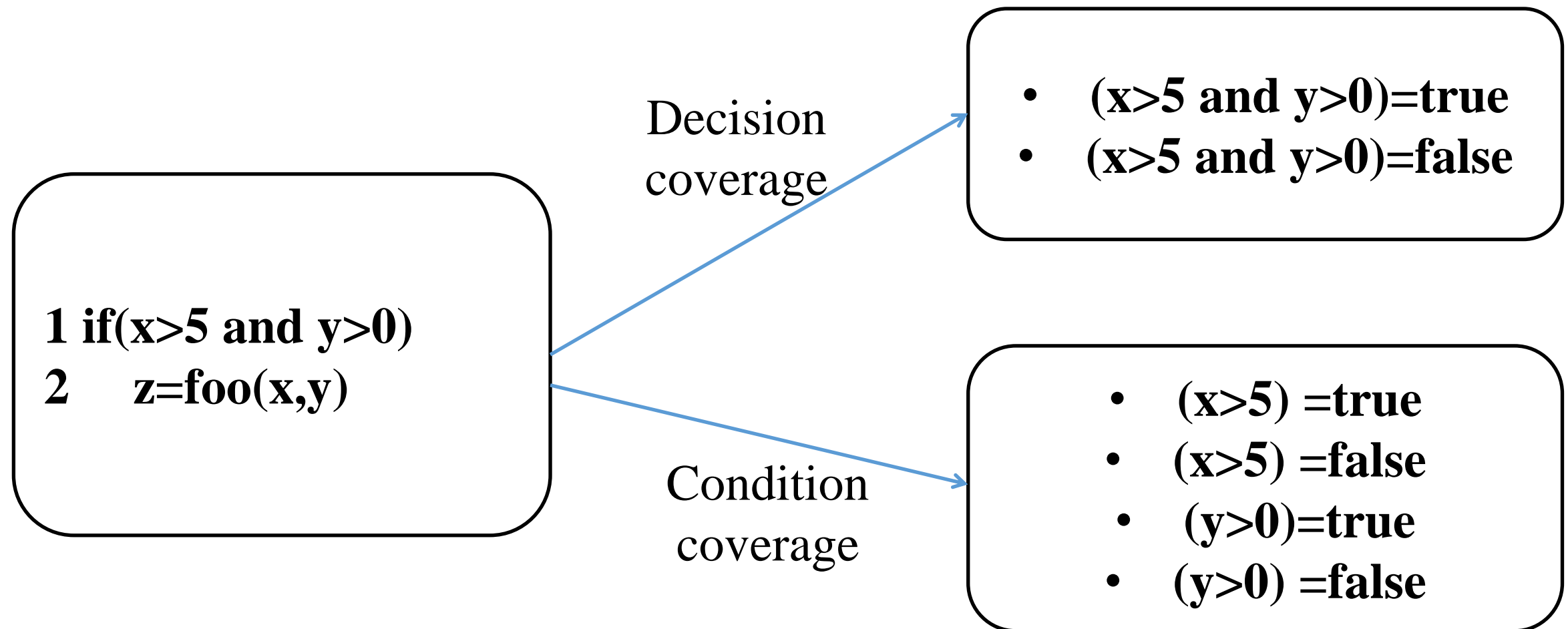
```
// {(6, 1), (1,1)} --- 100% Decision Coverage
int foo(int x, int y) {
    int z = y;
    if ((x > 5) && (y > 0)) {
        z = x;
    }
    return x*z;
}
```



# Condition Coverage

- Condition Coverage (CC):  
Executing *true* and *false* of each condition
- $(x > 5)$  : *true* and *false*
- $(y > 0)$  : *true* and *false*

```
// {(6, 0), (0,1)} --- 100% Condition Coverage
int foo(int x, int y) {
    int z = y;
    if ((x > 5) && (y > 0)) {
        z = x;
    }
    return x*z;
}
```



# An Example

```
1 begin
2   int x,y,z;
3   input(x,y);
4   if(x<0 and y<0)
5     z=foo1(x,y)
6   else
7     z=foo2(x,y);
8   output(z);
9 end
```

**$T = \{t_1: \langle x = -3, y = -2 \rangle, t_2: \langle x = -4, y = 2 \rangle\}$**

- **Decision coverage?**
- **Condition coverage?**

- **100% Condition coverage does not mean 100% Decision coverage**

```
1 begin
2   int x,y,z;
3   input(x,y);
4   if(x<0 and y<0)
5     z=foo1(x,y)
6   else
7     z=foo2(x,y);
8   output(z);
9 end
```

$T = \{t_1: \langle x=-3, y=2 \rangle, t_2: \langle x=4, y=-2 \rangle\}$

- **Decision coverage?**
- **Condition coverage = 100%**

- **100% Decision coverage does not mean 100% Condition coverage**

```
1 begin
2   int x,y,z;
3   input(x,y);
4   if(x<0 and y<0)
5     z=foo1(x,y)
6   else
7     z=foo2(x,y);
8   output(z);
9 end
```

$T = \{t_1: \langle x=-3, y=-2 \rangle, t_2: \langle x=-4, y=2 \rangle\}$

- **Decision coverage = 100%**
- **Condition coverage?**

# Condition/Decision Coverage

- Condition/Decision Coverage (C/DC): Combining DC and CC.
- Overcomes the limitation of Decision Coverage (DC) and Condition Coverage (CC)
  - $C/DC \geq CC$
  - $C/DC \geq DC$

```
1 begin
2   int x,y,z;
3   input(x,y);
4   if(x<0 and y<0)
5     z=foo1(x,y)
6   else
7     z=foo2(x,y);
8   output(z);
9 end
```

$T=\{t_1:<x=-3,y=-2>,t_2:<x=4,y=2>\}$

- **Decision coverage = 100%**
- **Condition coverage = 100%**

# Multiple Condition Coverage

- Multiple condition coverage (MCC) reports whether every possible combination of Boolean sub-expressions occurs.
- The test cases required for full multiple condition coverage of a condition are essentially given by the logical operator truth table for the condition.

$$D = (A < B) \text{ or } (A > C)$$

	$A < B$	$A > C$	$D$
1	true	true	true
2	true	false	true
3	false	true	true
4	false	false	false

$T = \{t1: \langle A=2, B=3, C=1 \rangle, t2: \langle A=2, B=1, C=3 \rangle\}$

- Covers all decisions and conditions
- Covers only two combinations of Boolean sub-expressions.



# An Example

- Requirements for a program:

*Given three integers  $A$ ,  $B$ , and  $C$ , produce  $S$  according to the following table:*

	<b><math>A &lt; B</math></b>	<b><math>A &gt; C</math></b>	<b><math>S</math></b>
<b>1</b>	<b>true</b>	<b>true</b>	<b>f1(A,B,C)</b>
<b>2</b>	<b>true</b>	<b>false</b>	<b>f2(A,B,C)</b>
<b>3</b>	<b>false</b>	<b>true</b>	<b>f3(A,B,C)</b>
<b>4</b>	<b>false</b>	<b>false</b>	<b>f4(A,B,C)</b>

```

1 begin
2   int A,B,C,S=0;
3   input(A,B,C);
4   if(A<B and A>C)
      S=f1(A,B,C);
5   if(A<B and A≤C)
      S=f2(A,B,C);
6   if(A≥B and A≤C)
      S=f4(A,B,C);
7   output(S);
9 end

```

	A<B	A>C	S
1	true	true	f1(A,B,C)
2	true	false	f2(A,B,C)
3	false	true	f3(A,B,C)
4	false	false	f4(A,B,C)

A buggy  
implementation !

```

1 begin
2   int A,B,C,S=0;
3   input(A,B,C);
4   if(A<B and A>C)
      S=f1(A,B,C);
5   if(A<B and A≤C)
      S=f2(A,B,C);
6   if(A≥B and A≤C)
      S=f4(A,B,C);
7   output(S);
9 end

```

	A<B	A>C	S
1	true	true	f1(A,B,C)
2	true	false	f2(A,B,C)
3	false	true	f3(A,B,C)
4	false	false	f4(A,B,C)

**T={t<sub>1</sub>:<A=2,B=3,C=1>, t<sub>2</sub>:<A=2,B=1,C=3>}**

- **100% condition coverage**
- **Bug not found**

```

1 begin
2   int A,B,C,S=0;
3   input(A,B,C);
4   if(A<B and A>C) S=f1(A,B,C);
5   if(A<B and A≤C) S=f2(A,B,C);
6   if(A≥B and A≤C) S=f4(A,B,C);
7   output(S);
9 end

```

	A<B	A>C	S
1	true	true	f1(A,B,C)
2	true	false	f2(A,B,C)
3	false	true	f3(A,B,C)
4	false	false	f4(A,B,C)

$T = \{t_1 : \langle A=2, B=3, C=1 \rangle,$   
 $t_2 : \langle A=2, B=1, C=3 \rangle,$   
 $t_3 : \langle A=2, B=3, C=5 \rangle\}$

- 100% condition coverage
- 100% decision coverage
- Bug not found

```

1 begin
2   int A,B,C,S=0;
3   input(A,B,C);
4   if(A<B and A>C) S=f1(A,B,C);
5   if(A<B and A≤C) S=f2(A,B,C);
6   if(A≥B and A≤C) S=f4(A,B,C);
7   output(S);
9 end

```

$T = \{t_1 : \langle A=2, B=3, C=1 \rangle,$   
 $t_2 : \langle A=2, B=1, C=3 \rangle,$   
 $t_3 : \langle A=2, B=3, C=5 \rangle,$   
 $t_4 : \langle A=2, B=1, C=1 \rangle\}$

- 100% Multiple Condition Coverage
- Bug found

	A<B	A>C	T	A<B	A≤C	T	A≥B	A≤C	T
1	true	true	t1	true	true	t3	true	true	t2
2	true	false	t3	true	false	t1	true	false	t4
3	false	true	t4	false	true	t2	false	true	t3
4	false	false	t2	false	false	t4	false	false	t1

# Quiz – C/DC

How to achieve 100% condition/decision coverage?

```
// ??  
int foo(int x, int y) {  
    int z = y;  
    if ((x>5) && (y>0)) {  
        z = x; }  
    return x*z;  
}
```

# Quiz- MCC

How to achieve 100% multiple condition coverage?

```
// ??  
int foo(int x, int y) {  
    int z = y;  
    if ((x>5) && (y>0)) {  
        z = x; }  
    return x*z;  
}
```

# Limitation of MCC

- Assuming  $n$  conditions,  $2^n$  test cases are required.
- Assuming each test case needs 1ms to execute:

Conditions $n$	Test cases $2^n$	Test case execution time
1	2	2ms
4	16	16ms
8	256	256ms
16	65536	65.5s
32	4294967296	49.5 days



# Modified condition/decision (MC/DC)

- Motivation: Effectively test **important combinations** of conditions, without exponential blowup in test suite size
  - “Important” combinations means: Each basic condition independently affects the outcome of each decision
  - $MC/DC \geq C/DC$
- Requires:
  - For each basic condition C, two test cases,
  - values of all evaluated conditions except C are the same
  - compound condition as a whole evaluates to true for one and false for the other

# Modified condition/decision (MC/DC)

- **MC/DC coverage:**
  - Each entry and exit point is invoked
  - Each decision takes every possible outcome
  - Each condition in a decision takes every possible outcome
  - Each condition in a decision is shown to independently affect the outcome of the decision.
  - Independence of a condition is shown by proving that only one condition changes at a time.
- MC/DC is used in avionics software development guidance [DO-178B](#) and [DO-178C](#) to ensure adequate testing of the most critical (Level A) software.

[https://en.wikipedia.org/wiki/Modified\\_condition/decision\\_coverage](https://en.wikipedia.org/wiki/Modified_condition/decision_coverage)

# MC/DC

- $((x > 5) \ \&\& \ (y > 0))$  Decision

<b>T</b>	<b>T</b>	T
T	<b>F</b>	F
<b>F</b>	T	F
F	F	F

```
// ??  
int foo(int x, int y) {  
    int z = y;  
    if ((x > 5) && (y > 0)) {  
        z = x; }  
    return x*z;  
}
```

# Comparison

Table 1. Types of Structural Coverage

Coverage Criteria	Statement Coverage	Decision Coverage	Condition Coverage	Condition/ Decision Coverage	MC/DC	Multiple Condition Coverage
Every point of entry and exit in the program has been invoked at least once		•	•	•	•	•
Every statement in the program has been invoked at least once	•					
Every decision in the program has taken all possible outcomes at least once		•		•	•	•
Every condition in a decision in the program has taken all possible outcomes at least once			•	•	•	•
Every condition in a decision has been shown to independently affect that decision's outcome					•	• <sup>8</sup>
Every combination of condition outcomes within a decision has been invoked at least once						•

# References

- J.J. Chilenski and S.P. Miller, “**Applicability of Modified Condition/Decision Coverage to Software Testing**,” *Software Eng. J.*, vol. 9, no. 5, pp. 193-200, 1994.
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Thanks!

