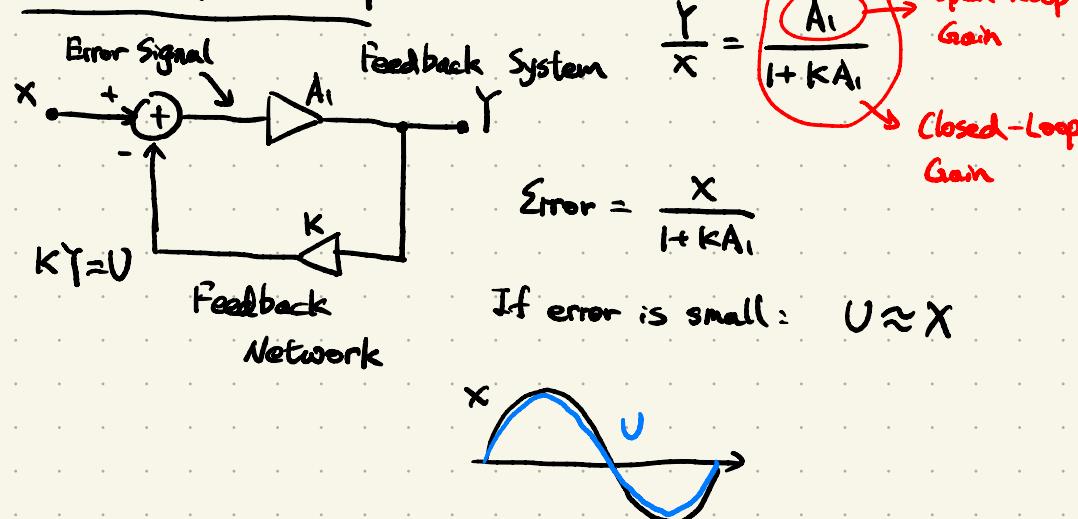


## Lec 28

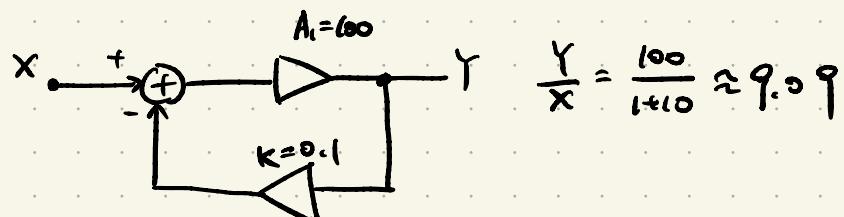
- Feedback Examples
- The Concept of Loop Gain
- Properties of Negative-Feedback Systems

### Review of Lec. 27



- In a well-designed negative-feedback System, the feedback signal is a good copy (replica) of the input signal.

- Example



Example What happens if  $A_1$  drops to 50 in the previous example?

$$A_1 = 50 \quad \frac{Y}{X} = \frac{50}{1+5} = \underline{\underline{8.33}}$$

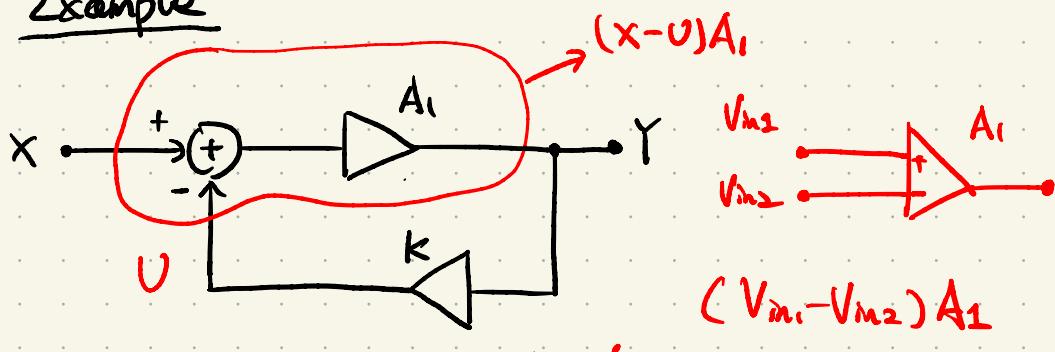
∅ Even though the open loop gain changed by a factor of 2, the closed loop gain changed by only 10%

Observation: If  $KA_1 \gg 1 \Rightarrow$

$\frac{Y}{X} \approx \frac{1}{K} \Rightarrow$  closed-loop gain is relatively independent of the open-loop gain  
 $\Rightarrow$  we should maximize  $KA_1$ .

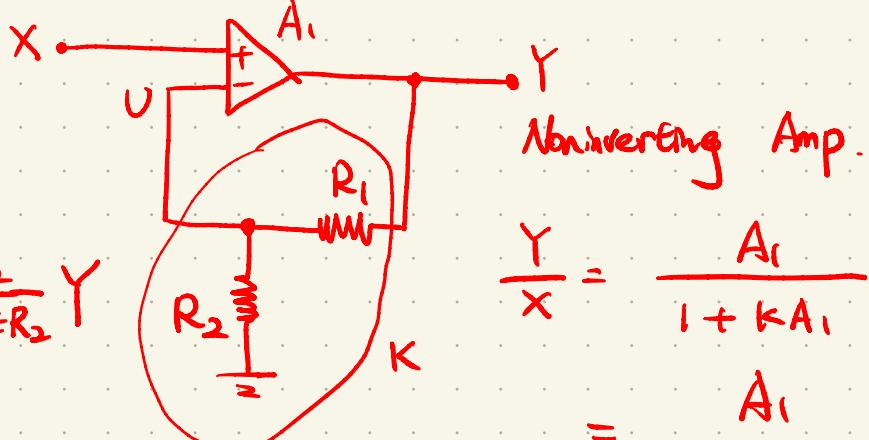
Observation:  $K$  is usually chosen  $\leq 1$

### Example



$$(V_{in1} - V_{in2})A_1$$

$k < 1$



$$\begin{aligned} \frac{Y}{X} &= \frac{A_1}{1 + kA_1} \\ &= \frac{A_1}{1 + \frac{R_2}{R_1 + R_2} A_1} \end{aligned}$$

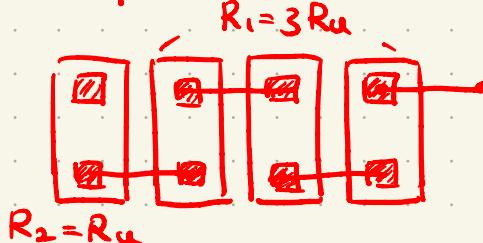
In a well designed negative-feedback circuit,

$$kA_1 \gg 1 \Rightarrow \frac{R_2}{R_1 + R_2} A_1 \gg 1 \Rightarrow \frac{Y}{X} \approx \frac{1}{k} = 1 + \frac{R_1}{R_2}$$

Even if  $R_1, R_2$  vary with temperature, etc.

$1 + \frac{R_1}{R_2}$  is accurate.

$$\frac{Y}{X} = 4.0, \text{ so } \frac{R_1}{R_2} = 3$$



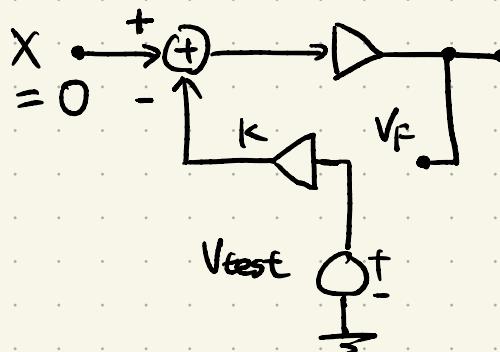
- Loop Gain  $kA_1$ : in a well designed negative-feedback system, loop-gain  $\gg 1$   
 $\Rightarrow$  closed-loop gain  $\approx \frac{1}{k}$

### Example

Find the loop gain in the noninverting amp:

$$kA_1 = \frac{R_2}{R_1 + R_2} A_1$$

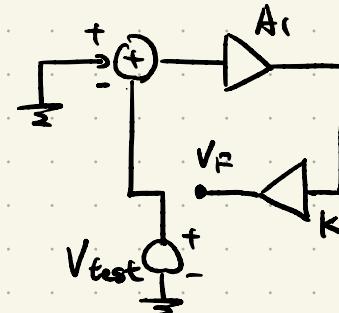
- Loop Gain Calculation



$$\text{Loop Gain} = -\frac{V_F}{V_{test}}$$

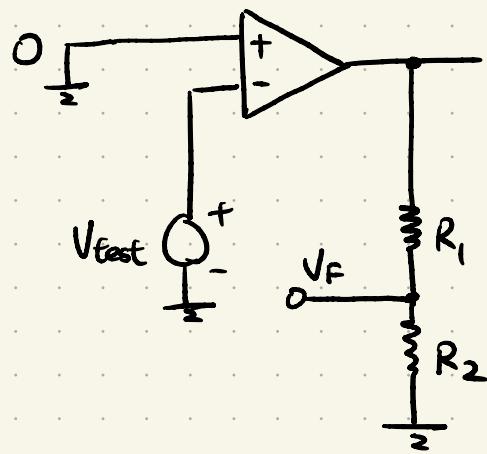
$$-V_{test} k A_1 = V_F \Rightarrow -\frac{V_F}{V_{test}} = k A_1$$

### Example



$$-V_{test} A_1 k = V_F$$

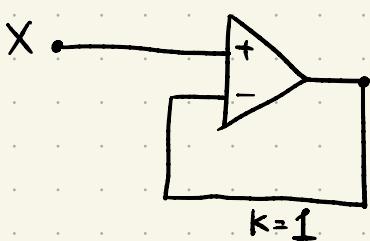
### Example



$$V_{\text{test}} \times (-A_i) \frac{R_2}{R_1 + R_2} = V_F$$

$$-\frac{V_F}{V_{\text{test}}} = \frac{R_2}{R_1 + R_2} A_i$$

### Example



$$\frac{Y}{X} = \frac{A_i}{1 + kA_i}$$

$$= \frac{A_i}{1 + A_i} \approx 1$$

Unity - Gain Buffer

Loop Gain =  $A_i$

Φ

One Important Property: If  $kA_i \gg 1 \Rightarrow$

$\frac{Y}{X} \approx \frac{1}{k}$  and relatively indep. of  $A_i$