

Lec 10

- Summary of Diff Pair Operation

- Small-Signal Analysis

$$V_x - V_y = -R_c I_{EE} \tanh \frac{V_{in_1} - V_{in_2}}{2V_T}$$

- Summary of Diff Pair Properties

① If $|V_{in_1} - V_{in_2}|$ is large, all of the tail current is "steered" to one side.

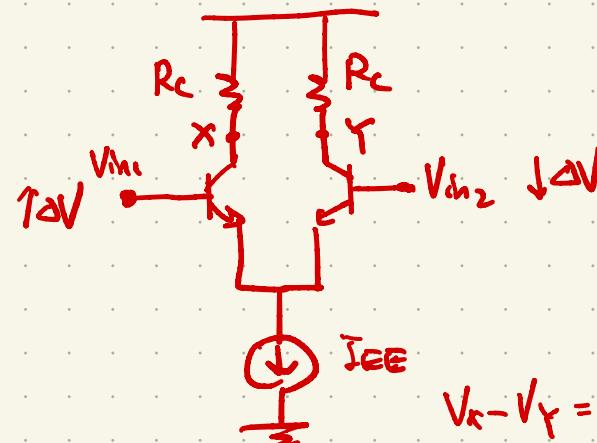
→ "current-steering" circuits

② if $V_{in_1} = V_{in_2}$ and $V_{CM,in}$ goes up and down → the currents & voltages do not change.

③ If $|V_{in_1} - V_{in_2}| \ll 2V_T$

$$\Rightarrow \text{slope} = -\frac{R_c I_{EE}}{2V_T}$$

Ques: Can this circuit amplify?



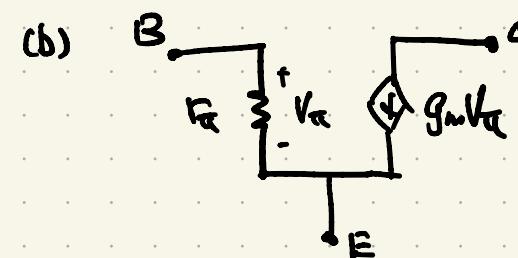
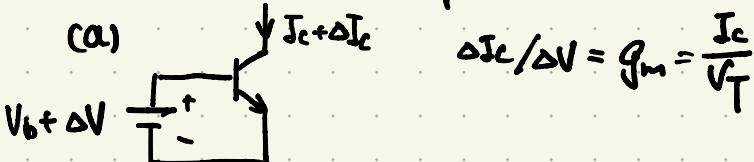
$$V_x - V_y = -R_c I_{EE} \tanh \frac{2\Delta V}{V_T}$$

$$\approx -R_c I_{EE} \frac{2\Delta V}{V_T}$$

if greater than 1 ⇒ amp

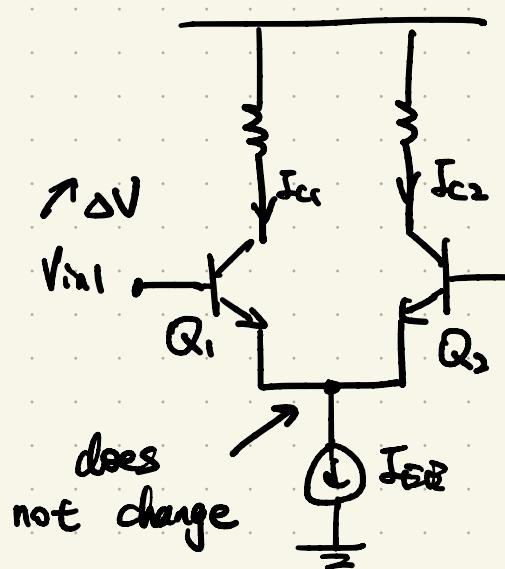
- Small-Signal Analysis

Two Basic Concepts:



Lemma

If V_{in1} and V_{in2} change by equal and opposite amount and the change is small, then the tail node voltage does not change



$$V_x - V_y = -R_c I_{EE} \frac{2\Delta V}{2V_T}$$

$$V_R = V_{cc} - R_c I_{c1}$$

$$V_Y = V_{cc} - R_c I_{c2}$$

$$V_R - V_Y = -R_c (I_{c1} - I_{c2})$$

$$\left. \begin{aligned} I_{c1} - I_{c2} &= I_{EE} \frac{\Delta V}{V_T} \\ I_{c1} + I_{c2} &= I_{EE} \end{aligned} \right\}$$

$$\Rightarrow I_{c1} = \frac{I_{EE}}{2} \left(1 + \frac{\Delta V}{V_T} \right)$$

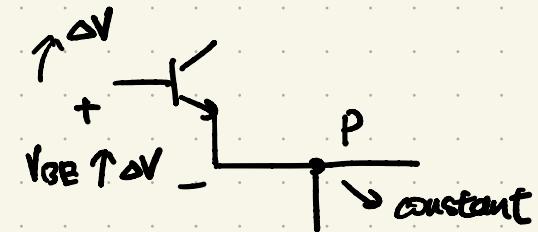
$$g_m = \frac{\partial I_c}{\partial V_{BE}}$$

$$\Delta I_{c1} = \frac{I_{EE}}{2V_T} \Delta V$$

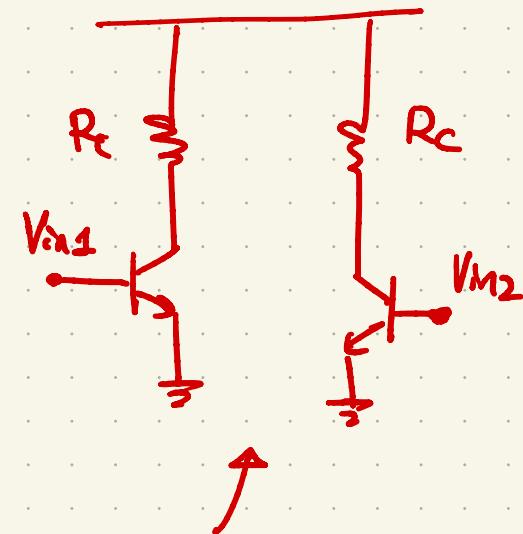
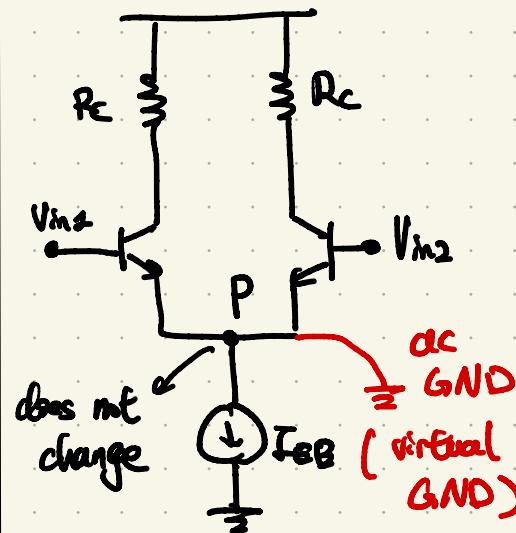
$$\Delta I_c = g_m \Delta V_{BE}$$

then

$$\Delta V_{RE} = \frac{\frac{I_{EE}}{2V_T} \Delta V}{\frac{I_{EE}}{2V_T}} = \Delta V$$

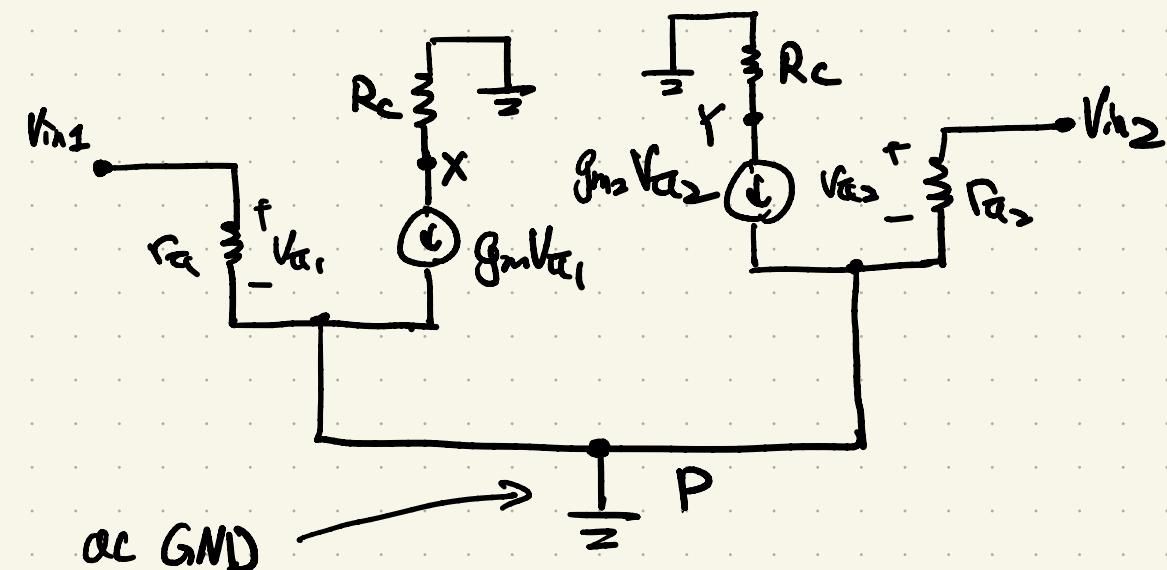


Small-Signal Behavior



for small-signal analysis

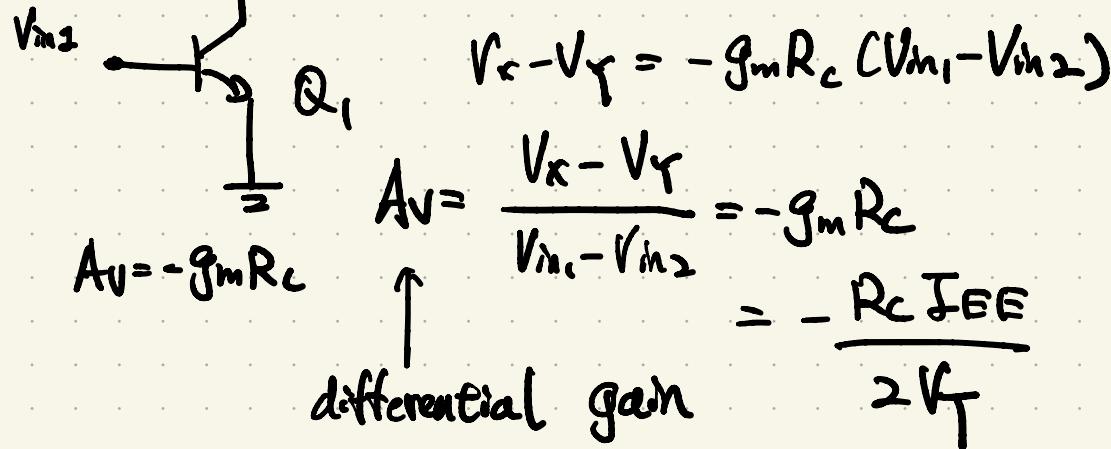
Actual Small-Signal Model



Half Circuit

$$V_x = -g_m R_c V_{m1}$$

$$\text{similarly: } V_y = -g_m R_c V_{m2}$$



$$A_V = -g_m R_c$$

$$A_V = \frac{V_x - V_y}{V_{m1} - V_{m2}} = -g_m R_c$$

$$= -\frac{R_c I_{DSS}}{2V_T}$$

differential gain