Recorded at time: 3.704 world Broadcaster: /ground truth to tf Average rate: 100.272 Hz Most recent transform: 3.691 (0.013 sec old) Buffer length: 3.680 sec base footprint Broadcaster: /ground truth to tf Average rate: 100.272 Hz Most recent transform: 3.691 (0.013 sec old) Buffer length: 3.680 sec $base_stabilized$ Broadcaster: /ground truth to tf Average rate: 100.272 Hz Most recent transform: 3.691 (0.013 sec old) Buffer length: 3.680 sec base link Broadcaster: /robot state publisher Broadcaster: /robot state publisher Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Average rate: $1\overline{0}000.\overline{00}0$ Hz Most recent transform: 0.000 (3.704 sec old) Most recent transform: 0.000 (3.704 sec old) Most recent transform: 0.000 (3.704 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec Buffer length: 0.000 sec laser0 frame front cam link sonar_link Broadcaster: /robot state publisher Average rate: $1\overline{0}000.\overline{0}0$ Hz Most recent transform: 0.000 (3.704 sec old) Buffer length: 0.000 sec front cam optical frame

view frames Result