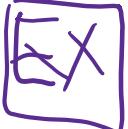


Normalization of vectors

A unit vector is vector w/ length one

 Show that the vector $v = \left(\frac{1}{2}, \frac{\sqrt{3}}{2}, 0\right)^T$ is a unit vector.

Compute the length $\|v\| = 1$

$$\|v\| = \left\| \left(\frac{1}{2}, \frac{\sqrt{3}}{2}, 0 \right)^T \right\| = \sqrt{\left(\frac{1}{2}\right)^2 + \left(\frac{\sqrt{3}}{2}\right)^2 + 0^2} = \sqrt{\frac{1}{4} + \frac{3}{4}} = \sqrt{4/4} = 1$$

Normalization

We can re-scale any vector to length 1 by normalizing it, e.g. dividing the vector by its length.

$$\text{normalize}(v) = \frac{v}{\|v\|} \leftarrow \begin{matrix} \text{an } n\text{-component} \\ \text{vector} \end{matrix}$$

$\|v\| \leftarrow \text{scalar, the length of } v$

EX Normalize the vector $v = (4, 3, 0)^T$

① Compute the length of v

$$\|v\| = \|(4, 3, 0)^T\| = \sqrt{16+9} = \sqrt{25} = 5$$

② Divide each component of v by $\|v\|$: $(4/5, 3/5, 0)^T$

Aside: Using GLM

graphics
library
math

↳ important to use floats!

0.0f

`vec3(1.0f)` ← create vector having all components = 1

`length(v)` ← returns the length (aka magnitude) of v .
watch out! DO NOT call `v.length()` + always
returns a `float` for `vec3`

`cross(u, v)` ← $u \times v$

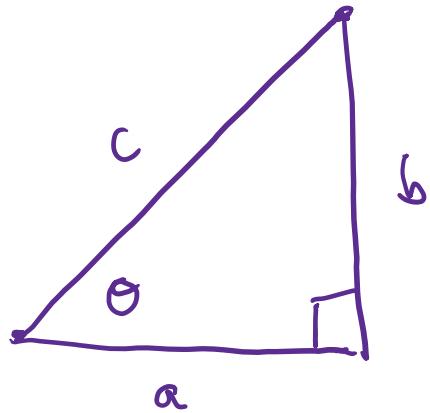
`dot(u, v)` ← $u \cdot v$

`normalize(v)`

$v - u$

$v + a$

Review: Sin/Cos/Tan

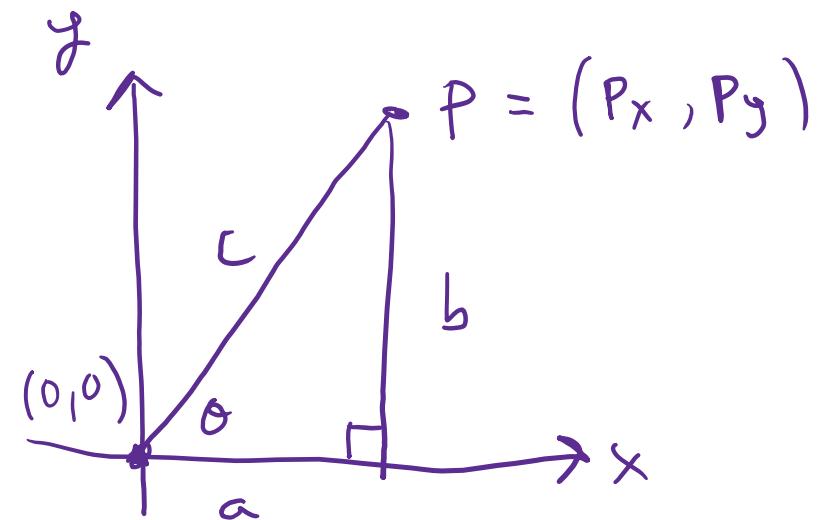


$$\sin \theta = \frac{b}{c}$$

$$\cos \theta = \frac{a}{c}$$

$$\tan \theta = \frac{b}{a}$$

Pythagorean Rule : $a^2 + b^2 = c^2$



$$P_x = a = c \cos \theta$$

$$P_y = b = c \sin \theta$$

$$c = \sqrt{a^2 + b^2} = \sqrt{P_x^2 + P_y^2} = \|P\|$$

Moving in a circle

Let's write an algorithm in terms of `setup()` & `scene()`

```
setup()
theta = 0
thetaRate = 0.1
r = 250

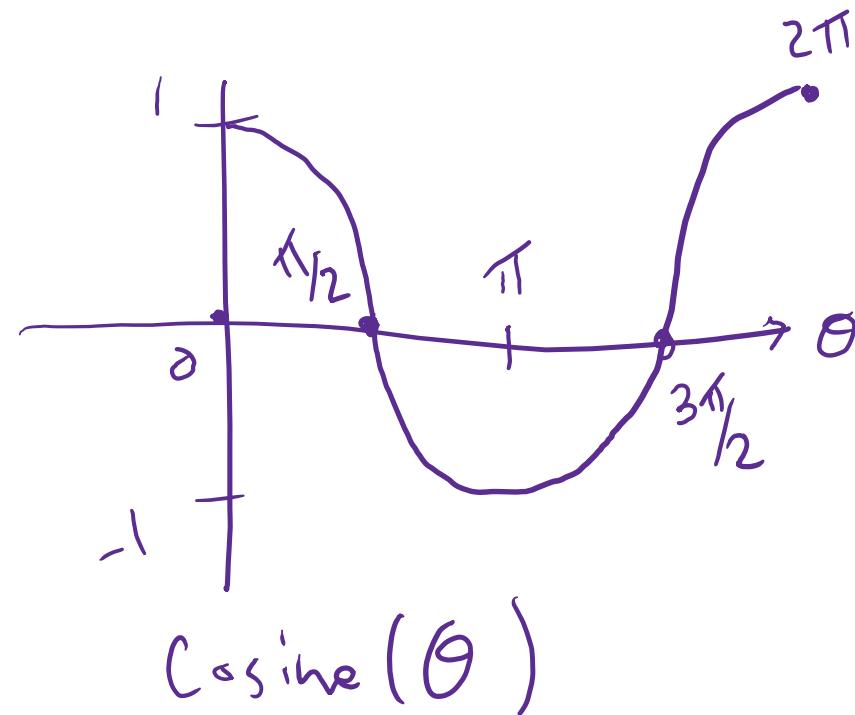
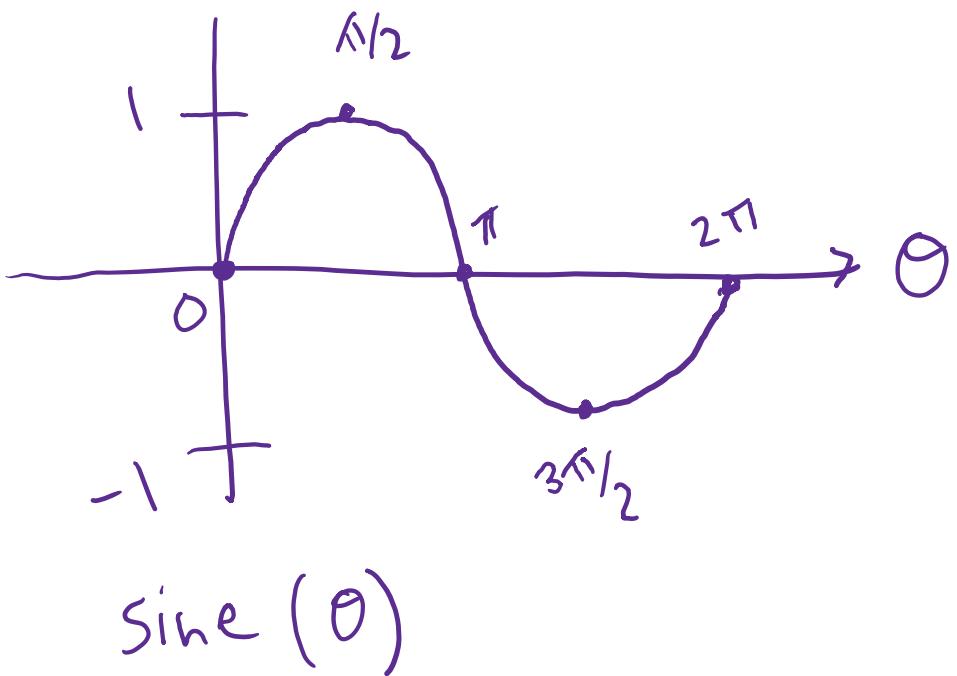
scene()
theta += thetaRate * dt() // radians
float px = r * cos(theta);
float py = r * sin(theta);
drawSphere(vec3(px, py, 0));

dt()
float theta;
float thetaRate;
float r; // distance from (0,0,0)
```

Idea: $p_x = r \cos \theta$ ↑ increase of each frame:
 $p_y = r \sin \theta$
 $p_z = 0$
↑ formulated rotate around (0,0,0)
 $\theta = \theta + dt() * \Delta\theta$
where $\Delta\theta = \text{rate of rotation}$

Oscillating movement

Recall: the curves for sine & cosine



Oscillating movement

Let's animate the height of an object sine

setup:

```
thetaRate = 0.5  
theta = 0
```

Idea: each frame, update

$$y = 200 \sin(\theta)$$

scene:

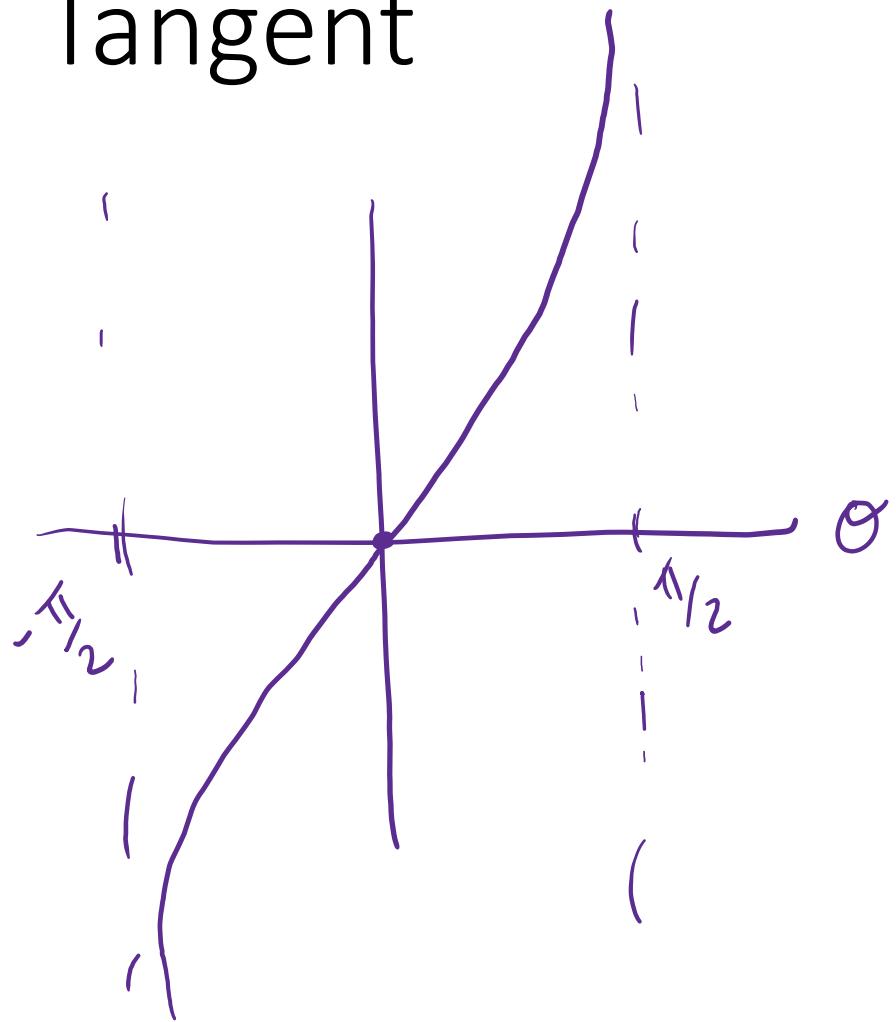
```
theta += thetaRate * dt()  
float py = 200 - * sin(theta); z = 0  
float px = 0.0  
drawSphere(vec3(px, py, 0), 100);
```

$$x = 0$$

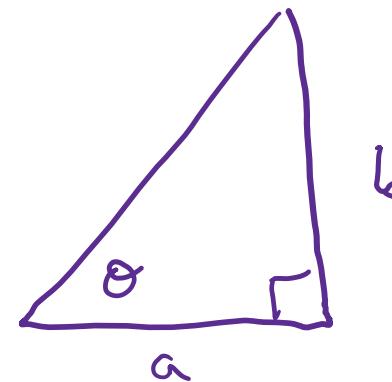
data

```
float theta  
float thetaRate
```

Tangent



Recall: $\tan \theta = b/a$



Inverses of Sin/Cos/Tan

cos/sin take on angle $\in [-\infty, \infty]$ & outputs α values
in range $[-1, 1]$

asin "arcsine" takes a value in range $[-1, 1]$ and
returns an angle $\in [-\frac{\pi}{2}, \frac{\pi}{2}]$

acos "arccosine" has domain $[-1, 1]$ & returns an
angle $\in [0, 2\pi]$

e.g. has domain $[-1, 1]$

watch out! there are undefined outside range $\leftarrow \text{NaN}$
 $\rightarrow \text{not a number}$

Arctangent

$\text{atan}(b/a)$

↳ outputs an angle in range $\in [-\frac{\pi}{2}, \frac{\pi}{2}]$

domain is $[-\infty, \infty]$

→ better to use

$\text{atan2}(b, a)$

↳ outputs

angle in range $\in [0, 2\pi]$

↳ uses the signs of $a + b$ to deduce the quadrant of the angle

